

# An Automatic Face Attendance Checking System using Deep Facial Recognition Technique

Thuy Nguyen-Chinh, Thien Do-Tieu, Sy Nguyen-Tan, Phuong Le-Van-Hoang, Qui Nguyen-Van, Phu Nguyen-Tan

**Abstract**—Nowadays, as computers are powerful enough for implementing complex algorithms, there are numerous applications that people utilize computers to run. In which, facial recognition is one of the most active fields of applications. In fact, computers can not only automatically identify who a person is, but also operate 24/7, which human beings cannot endure. This leads to the replacement of people by computers in some repetitive and real-time applications.

In this work, we apply the facial recognition into an attendance checking system that uses faces of registered people to check their attendance. This system has a GUI which allows easy user-to-system interaction. The core of the system is a deep facial recognition technique, which has four stages (e.g., removing motion-blur frames, detecting faces, removing non-frontal-view faces, and recognizing). Particularly, in the recognition phase, we consider this stage as an open-set facial recognition problem, so the system is able to detect people who have not registered in the database before. Also, we boost the performance of the system by utilizing hardware resources of users' computers. Although the system is designed to run with a low-resolution webcam, its performance is reasonably accurate on our private dataset.

**Index Terms**—Face Attendance Checking, Facial Recognition, Deep Learning

## I. INTRODUCTION

Face recognition systems are being applied widely in real life such as tracking, managing employees, finding information about celebrities, and so forth. There are many approaches to design a face recognition system, but such these systems are frequently affected by light, non-frontal faces, resolution of cameras, etc. Thus, each method has specific challenges. Overall, a face recognition has two main stages which are face detection and face recognition, yet we want to create constraints on blur-clean and frontal-view faces of users that leads our system to have four stages: blur detection, face detection, landmark detection, and face recognition.

### A. Face detection

The face detector proposed by Viola and Jones [1] used Haar-Like features and AdaBoost to train cascaded classifiers, which achieve good performance with real-time efficiency. However, a few works [2],[3],[4] indicate that this detector

may degrade considerably in real-world applications with larger visual variations of human faces even with more advanced features. Besides the cascade structure, [5],[6],[7] introduce deformable part models (DPM) for face detection and achieve remarkable performance. However, they need a high computational expense and may usually require expensive annotation in the training stage. Recently, convolutional neural networks (CNN) achieve remarkable progress in a variety of computer vision tasks, especially face detection task. Li et al. [8] use cascaded CNN for face detection, but it requires bounding box calibration from face detection with an extra computational expense and ignores the correlation between facial landmarks localization and bounding box regression. Face alignment also attracts extensive interests. Regression-based methods [9],[10],[11] and template fitting approaches [7][12][13] are two popular categories.

However, most of the available face detection and face alignment methods ignore the correlation between these two tasks. Though there exist several works attempt to jointly solve them, there are still limitations in these works. For example, Chen et al. [14] jointly show alignment and detection with random forest using features of pixel value difference. But, the handcraft features used limits its performance. From those previous experiments, we choose a new approach which integrates these two tasks using unified cascaded CNN by multi-task learning called Multi-task Convolutional Network in section III-D.

### B. Landmark detection

The locations of the fiducial facial landmark points around facial components and facial contour capture the rigid and non-rigid facial deformations due to head movements and facial expressions. They are hence important for various facial analysis tasks. Many facial landmark detection algorithms have been developed to automatically detect those key points over the years. In this paper, we use Dlib library which is a powerfull source for face and facial landmark detection. We will discuss our implement in detail in section III-C.

### C. Face recognition

After face detection and alignment, those regions of a face are extracted to get feature vectors. Conventionally, one of the most popular features for face recognition is Gabor feature. Tudor Barbu [15] used Gabor transform to extract features, and then applied K-Nearest Neighbour (K-NN) based on clustering features to predict identity of a face. This implementation achieved a quite impressed performance with an accuracy

This work is a final project in the course "Artificial Intelligence in Control Engineering" (Aug-Dec 2018) guided by Dr. Cuong Pham-Viet (email: pvcuong@hcmut.edu.vn), Faculty of Electrical and Electronics Engineering, HoChiMinh city University of Technology.

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of 90% on the Yale Face Database B [22]. OpenCV [16], which is an open-source library focusing on Computer Vision algorithms, introduced a method called Local Binary Patterns (LBP) based on Haar-Like feature. In term of speed, LBP has a remarkably real-time efficiency, whereas it is not stable in term of accuracy. In particular, this method cannot face noise which is a reason why LBP and Haar-Like feature are rarely applied in practical systems. Because of limitations of conventional features, approaches exploiting deep learning have gradually developed instead. Yi Sun, Xiaogang Wang, and Xiaoou Tang [17] built a deep model named Deep hidden IDentity (DeepID) which used Convolutional Neural Network (CNN) to extract face features. The advantage of this method was using a small dataset for training that was considerably relevant for applications which cannot collect a large dataset of users. Nevertheless, to reach a high accuracy, DeepID model became really complex with many neural network branches for each person. There were 10 patches of a face, which contain interesting information, chosen from each image, then they were scaled with three figures in RGB and gray channel. Totally, the model had 60 different networks to extract features for an image, then feedforwarded extracted features into a classifier using Joint Bayesian. DeepID achieved an excellent accuracy of 97.45% on Labeled Faces in the Wild (LFW) [23]. In 2014, the authors of DeepID introduced DeepID2 [18] which was an improved version of its predecessor. In the new version, interesting regions were built to eliminate useless patches which cannot provide high-level features. That work really helpfully affected the accuracy, specifically there was an increase in accuracy at 99.63%. In 2015, Google Inc. [19] exploited a deep CNN Inception [20] and a triplet loss function to form the FaceNet model, which was to extract features. Their outstanding point was using a hard triplet loss to separate features for each person, so FaceNet feature is robust in both face verification and face recognition. The accuracy of 99.63% on LFW and 95.12% on Youtube Faces DB [24] were high enough to represent the perfection of the model.

## II. PROPOSED SYSTEM

In this paper, we apply deep facial recognition techniques to the problem of face attendance checking. A system is built in order to manage appearances of students in a class, which is revealed in Fig. 1. Normally, a facial recognition system is organized as a pipeline of typical stages such as face detection, landmark detection, and face recognition. However, to ensure input frames for underlying algorithms are high quality, we append an early filter (the Blur detection stage) that are able to discard blur frames, which are caught by motions of people in front of a webcam. Then, clean frames are passed through the Face detection block for counting the number of faces existing inside these frames. In our specific constraint, there is only one face per frame allowed to be processed, so frames that contain more than one faces are rejected. Afterward, the Landmark detection is to localize statistic-salient points in the face in order to verify whether the face is in the frontal view of the camera. This frontal-view check will help improve the accuracy of the face recognition algorithm. Finally, the

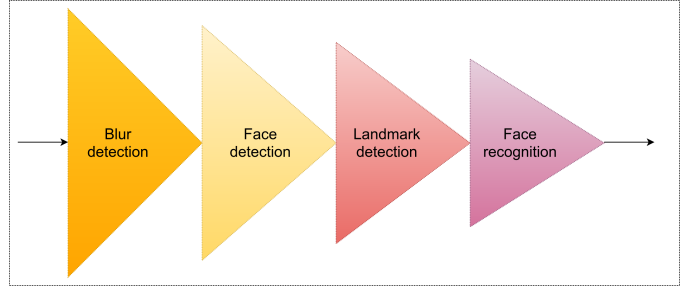


Fig. 1: The system pipeline. There are four stages, namely blur detection, face detection, landmark detection, and face recognition. These four blocks are in the descending order of size in the direction from input to output. This points out that our system is tougher to input frames from the camera when such frames passed through the system. Therefore, best frames are likely to be processed, which may improve the final recognition accuracy.

Face recognition uses blur-clean, one-face, and frontal-view frames from previous stages to extract relevant features and then perform a classification task to indicate which category the input most likely belong to.

In addition, to leverage the ease of use, we design a friendly graphic user interface (GUI) so that people who want to use the system to manage (teachers) or check (students) attendance can interact with the application without any specialized knowledge. To make the system more robust, we carefully analyze the distribution outlier of features representing for registered accounts. Therefore, the algorithm has ability to detect people who have not registered in the application before, which is equivalent to the open-set problem in face recognition.

Our work is organized as follows. In section III, stages of the proposed system are described clearly, including motion-blur detection, face detection, frontal-view detection, and face recognition. Then, section IV is for reporting some experimental results.

## III. IMPLEMENTATION

### A. Motion-blur detection

The first stage of this system is detecting blurred image and rejecting them out of next stage. We know that the blurred image means each pixel in the source image gets spread out and mixed into surrounding neighbour pixels. For our attendance checking system, the motion blur happens when an object (namely face or webcam) moves during the exposure. So as to detect whether an image is blurred, we use the 2D-FFT (2D-Fast Fourier Transform) method.

We will review about Fourier Transform of Images. To compute the Fourier transform of an image, you need to:

- Compute DFT of each row, in place.
- Compute DFT of each column, in place.

When a signal is discrete and periodic, we use the discrete Fourier transform, or DFT. Suppose our signal is  $a_n$  for  $n = 0 \dots N-1$ , and  $a_n = a_{n+jN}$  for all  $n$  and  $j$ . The spectrum of  $a$  is:

$$A_k = \sum_{n=0}^{N-1} W_N^{kn} a_n \quad (1)$$

where

$$W_N = e^{-i\frac{2\pi}{N}}$$

and  $W_N^k$  for  $k = 0 \dots N-1$  are called the  $N$ th roots of unity. The sequence  $A_k$  is the discrete Fourier transform of the sequence  $a_n$ . Each is a sequence of  $N$  complex numbers.

The FFT is a fast algorithm for computing the DFT. If we take the 2-point DFT and 4-point DFT and generalize them to 8-point, 16-point, ...,  $2^m$ -point ( $n$  is an integer), we get the FFT algorithm.

There are several ways to write an FFT. For instance, let  $m$  be an integer and let  $N = 2^m$ . Suppose that  $x = [x_0, \dots, x_{N-1}]$  is an  $N$  dimensional complex vector. Let  $\omega = \exp(-\frac{2\pi i}{N})$ . Then the DFT,  $c = F_N(x)$  is given by

$$c_k = \frac{1}{N} \sum_{j=0}^{N-1} x_j \omega^{jk}. \quad (2)$$

Let  $n = N/2$ , let  $u$  and  $v$  be  $n$  dimensional vectors defined by

$$u_j = x_j + x_{j+n}, \quad j = 0, \dots, n-1 \quad (3)$$

$$v_j = (x_j - x_{j+n})\omega^j, \quad j = 0, \dots, n-1. \quad (4)$$

Then

$$c_{2j} = \frac{1}{2}(F_n(u))_j, \quad j = 0, \dots, n-1 \quad (5)$$

$$c_{2j+1} = \frac{1}{2}(F_n(v))_j, \quad j = 0, \dots, n-1. \quad (6)$$

To compute the DFT of an  $N$ -point sequence using equation (1) would take  $(N^2)$  multiplies and adds. The FFT algorithm computes the DFT using  $(N \log N)$  multiplies and adds.

Practical issues: We translate the picture so that pixel (0,0), which now contains frequency  $(\omega_x, \omega_y) = (0, 0)$ , moves to the center of the image. Then, we display pixel values proportional to  $\log(\text{magnitude})$  of each complex number. For color images, do the above to each of the three channels (R, G, and B) independently.

Apply to our system, firstly, we calculate FFT of image. Secondly, we will compute mean amplitude spectrum value of entire pixel in image and. Finally, the result of this operation is compared to an optimal threshold which distinguishes blurred and non-blurred image as accurate as possible. The image is called non-blurred if and only if its average value greater than the threshold value, and vice versa. After that, non-blurred images are applied to face detection stage of system.

### B. Face detection

In this paper, we have used Histogram of Oriented Gradients method for extracting features of the face and Linear Support Vector Machine (SVM) method for face detections.

The implementation of this method using sliding window technique with the different sizes of the windows. Using the sliding window technique we could complete the calculation of HOG features, applied to detect and differentiate the face and the false face recognition using the SVM technique. All of the pre-processing steps are automatically implemented

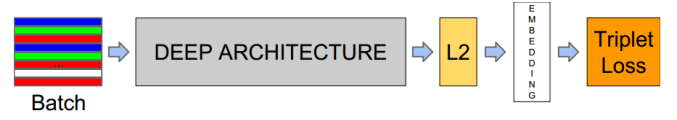


Fig. 2: Model structure. Our network consists of a batch input layer and a deep CNN followed by L2 normalization, which results in the face embedding. This is followed by the triplet loss during training.

before using Dlib library with the input of being given facial images and the output of localization the identified faces.

### C. Frontal-view detection

To check whether the shape of the faces has to be frontal, we implement these 3 following steps: Step 1.

- 1) Focusing on the center of the image. Only accept these faces that locate in the most central of the images.  $((120 - 360), (90, 360))$
- 2) Identify the skew of the image: calculate the coordinate of these eyes and the angle deviation between two eyes in the horizontal direction. If the angle deviation is larger than 10 degree, the image will be ignored.
- 3) Identify the rotation of the image: choose the point which is the midpoint of the right and the left eye. If the nose which is deviated from the selected point is greater than 10 pixels in the horizontal direction, the image is ignored.

These steps are implemented based on 5-point facial landmark technique with Dlib library instead of 68-point facial landmark in order to improve performance. If the image satisfies the condition, it will be accepted.

### D. Face recognition

In this stage, faces in raw images are detected and aligned by Multi-task CNN, we use convenient pre-trained FaceNet model to extract feature (in Figure 2) and then feedforward it to a SVM classifier for recognition.

1) *Multi-task Convolution Network*: The overall pipeline Multi-task CNN is shown in Figure 3. An image is initially resized to different scales to build an image pyramid, which is the input of the following three-stage cascaded framework with CNN architectures in Figure 4:

**Stage 1:** A fully convolutional network is exploited, called Proposal Network (P-Net), to obtain the candidate windows and their bounding box regression vectors. Then using the estimated bounding box regression vectors to calibrate the candidates. After that, employing non-maximum suppression (NMS) to merge highly overlapped candidates.

For each candidate window, P-CNN predict the offset between it and the nearest ground truth (i.e., the bounding boxes left top, height, and width). The learning objective is formulated as a regression problem, and the Euclidean loss is employed for each sample  $x_i$ :

$$L_i^{box} = \|y_i^{prediction} - y_i^{truth}\|_2^2 \quad (7)$$

The figure illustrates the architecture of the proposed face detection framework, which consists of three main components: P-Net, R-Net, and O2-Net. Each component takes an input image and processes it through a series of convolutional and pooling layers to produce a bounding box and facial landmark localization.

- P-Net:** Takes an input of size  $12 \times 12 \times 3$ . It consists of two convolutional layers (Conv:  $3 \times 3$ ) and a max pooling layer (MP:  $3 \times 3$ ). The output is a  $5 \times 5 \times 10$  feature map, which is then processed by another convolutional layer (Conv:  $3 \times 3$ ) to produce a  $3 \times 3 \times 16$  feature map. The output is used for face classification, bounding box regression, and facial landmark localization.
- R-Net:** Takes an input of size  $24 \times 24 \times 3$ . It consists of two convolutional layers (Conv:  $3 \times 3$ ) and a max pooling layer (MP:  $3 \times 3$ ). The output is a  $4 \times 4 \times 48$  feature map, which is then processed by another convolutional layer (Conv:  $3 \times 3$ ) to produce a  $3 \times 3 \times 64$  feature map. The output is used for face classification, bounding box regression, and facial landmark localization.
- O2-Net:** Takes an input of size  $48 \times 48 \times 3$ . It consists of three convolutional layers (Conv:  $3 \times 3$ ) and a max pooling layer (MP:  $3 \times 3$ ). The output is a  $10 \times 10 \times 64$  feature map, which is then processed by another convolutional layer (Conv:  $3 \times 3$ ) to produce a  $4 \times 4 \times 64$  feature map. The output is used for face classification, bounding box regression, and facial landmark localization.

The output of P-Net is used to generate a bounding box and facial landmark localization, which are then used as input for R-Net. The output of R-Net is used to generate a bounding box and facial landmark localization, which are then used as input for O2-Net. The output of O2-Net is used to generate a bounding box and facial landmark localization.

$$loss = \sum_{j=1}^m (max(0, z_j - (z_i - \Delta))) \quad (12)$$



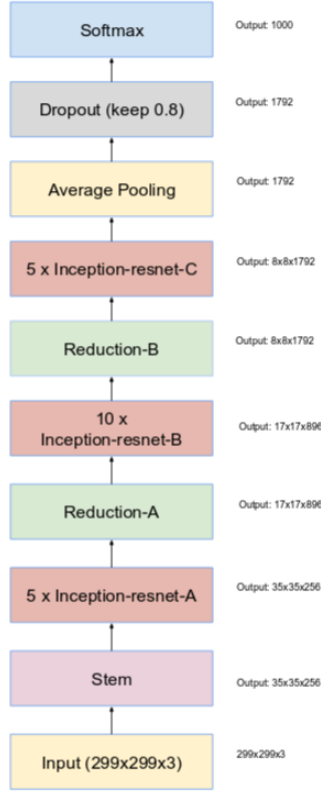


Fig. 6: Schema for Inception-ResNet-v1 and Inception-ResNet-v2 networks. This schema applies to both networks but the underlying components differ.

In dataset which has  $n$  embeddings, total loss value is:

$$loss^{total} = \sum_{i=1}^n \sum_{j=1}^m (max(0, z_j - (z_i - \Delta))) \quad (13)$$

This loss function will make  $z_i$  is maximum. Thus, anchor is determined by choose which identity has maximum probability, that suffer from mistakes when faces of strangers appear. To solve open-set problem, we combine both two subsets: training and validating to training threshold. This threshold helps us to eliminate "unknown" people, additionally ensure that the result of system achieves higher accuracy.

### E. Graphic User Interface

The sections that follow describe how to create GUIs with PyQt5. This includes laying out the components, programming them to do specific things in response to user actions, and saving and launching the GUI; in other words, the mechanics of creating GUIs.

PyQt5 implements GUIs as figure windows containing various styles of uicontrol objects. You must program each object to perform the intended action when activated by the user of the GUI. In addition, you must be able to save graphical user interface development environment.

#### GUI Development Environment

The process of implementing a GUI involves two basic tasks:

- Laying out the GUI components

- Programming the GUI components

GUIDE primarily is a set of layout tools. However, you must create a PY-file that contains code to handle the initialization and launching of the GUI. This PY-file provides a framework for the implementation of the callbacks - the functions that execute and launch your GUI.

#### The Implementation of A GUI

##### Laying out the GUI components

While it is possible to write an PY-file that contains all the commands to lay out a GUI, it is easier to use GUIDE to lay out the components interactively and to generate one file that save the GUI:

UI-file -contains a complete description of the GUI figure and all of its children (uicontrols and axes), as well as the values of all object properties.

##### Programming the GUI components

Once you have the UI-file, you will use PyQt5 to extract the UI-file to PY-file to execute the program. PY-file -contains the functions that launch and control the GUI and the callbacks, which are defined as sub functions. This PY-file is referred to as the application PY-file in this documentation. Note that the application PY-file does not contain the code that lays out the uicontrols; this information is saved in the UI-file. The following diagram illustrates the parts of a GUI implementation.

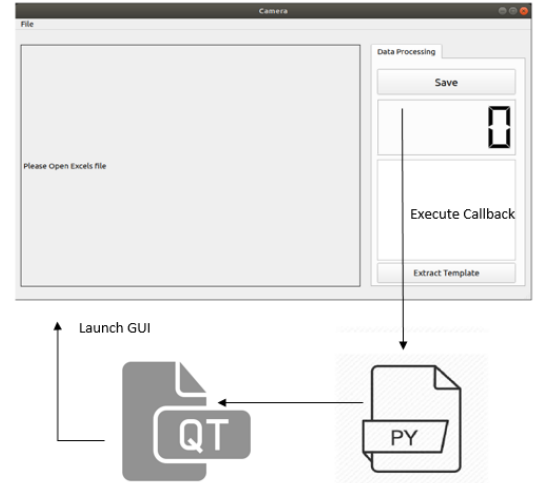


Fig. 7: Parts of GUI Implementation

The GUI are available from the QtDesigner shown in the figure below. The design is described briefly below. Subsequent sections show you how to use them.

### F. Attendance management

This is the final phase of Face Attendance Checking System. It was designated to mark the presence of one resulted from our algorithm in a file of excel format, namely xlsx extension. To be used by the system, the excel file must meet a stringent format made up of essential contents and be generated by the GUI.

Fig. 9 depicts a new standard empty excel table generated by our GUI. After obtaining a new file, we should fill in the

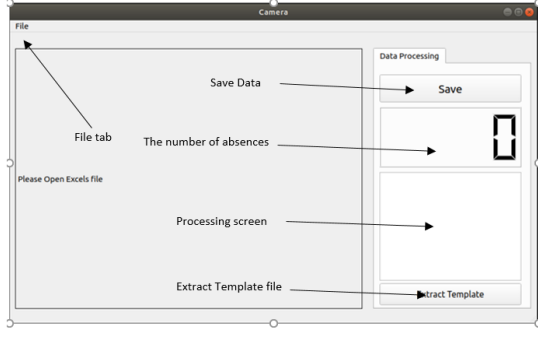


Fig. 8: GUI layout

uicontrols	function
<b>Open File Option</b>	We use this option to open the existing file. Open option appears and you can choose to open the file.
<b>Start Camera</b>	Open camera to start checking process
<b>Stop Camera</b>	Stop camera
<b>Exit</b>	We use this option to close the program. We can follow the steps: Click on File tab > Exit, active file will be closed. When we close the file, we get the confirmation message to save the file or not or cancel the command.
<b>Save</b>	Store completely-checked student IDs on the document. Once program exits, this process will be automatically started so that you won't lose your work that has been completed. If there is a power interruption or other system malfunction, the first time you Save, it will take you to the Save File dialog box.
<b>Extract Template</b>	We use this option to export the template in XLSX document. To Extract the file, we can follow the steps: Click Extract Template. And then we can export it as per our requirement.

TABLE I. USER GUIDE

table with the desired data (Fig. 10). The most special things in this table are column ID and Total. ID is considered a primary key because the algorithm will mark the presence of a specific person via his ID. To help the host in easy attendance management, we designed the column Total with a view to showing the number of absences in all.

Fig. 11 depicts an excel file's content after a checking progress finished. The GUI will automatically insert the only one new day column between Group and Total ones and in the tail of previous checked day. Letter 1 will be marked as presence in a cell of this column according to an ID. After attendance checking process is completed, the Total column will display the number of absences of previous days and the current one. Smartly can it display as we specially assigned a size-dynamic sum function to each cell of this column.

#### IV. EXPERIMENTAL RESULT

In this section, we first evaluate the effectiveness of the features extracted from FaceNet. Then, we compare our system in different contexts such as background, illumination, and resolution of camera, before examining the computational efficiency of our system.

DANH SÁCH SINH VIÊN				
YOUR COURSE/SUBJECT/TITLE				
			1 = present	
			blank = absent	
ID	Last Name	First Name	Group	Total

Fig. 9: New standard excel form

DANH SÁCH SINH VIÊN				
TRÍ TUỆ NHÂN TẠO TRONG ĐIỀU KIỆN				
			1 = present	
			blank = absent	
ID	Last Name	First Name	Group	Total
1511844	Lương Hữu Phú	Lộc	1	
1512221	Phạm Ngọc Khôi	Nguyễn	1	
1512396	Bùi Tấn	Phát	1	
1512534	Nguyễn Trọng	Phúc	1	

Fig. 10: Excel form contain pre-inputed data

#### A. Embeddings

As mentioned above, features representing for faces play a crucial role in a robust face recognition algorithm. A good kind of feature is a way of representing input data so that data points belonging to a same category are close together, whereas, those ones which are different from their categories need to be as far as possible. Therefore, before training the model, we start evaluating how separate samples of different classes stand in a vector space.

In this work, we utilize the pre-trained model FaceNet because of its spectacular demonstration over the recent period. Embedding or the feature vector of FaceNet has size of 128. Therefore, in a 128-dimensional space, embeddings of samples should form clusters, in which, a cluster is a set of samples in a same class. Nevertheless, the 128-dimensional space is beyond human's vision and awareness. Therefore, to have a prior look on these embeddings, we use visualization methods so that embeddings are converted into a new vector space, which human can understand.

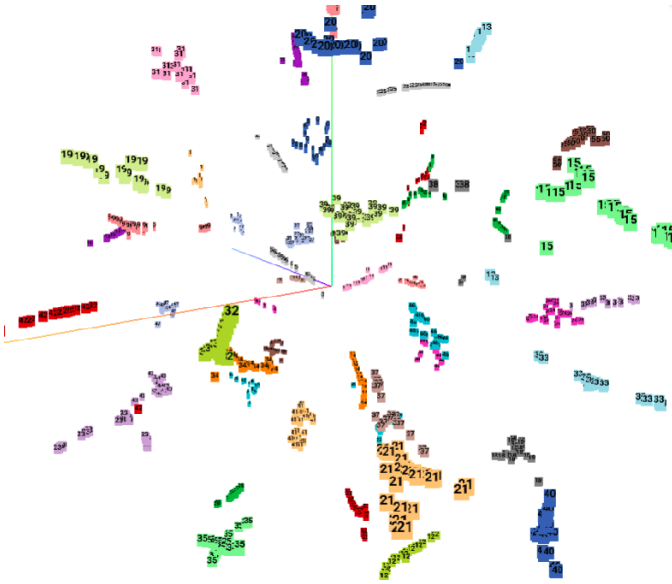
Here we exploit the Principal Component Analysis (PCA) and t-SNE [25] to complete this task. The two methods project embeddings from the original size into the 3D space. The result of projection is depicted in Fig. 12. In particular, PCA visualization selects eigenvectors corresponding to the highest eigenvalues as basics for constructing a new 3D space. Thus, its result in Fig. 12a, although, illustrates that data points are slightly separated between distinct classes, this separation is still not clear. The reason is non-selected (residual)

DANH SÁCH SINH VIÊN					
TRÍ TUỆ NHÂN TẠO TRONG ĐIỀU KIỆN					
			1 = present		
			blank = absent		
ID	Last Name	First Name	Group	09/06/2018	Total
1511844	Lương Hữu Phú	Lộc	1		1
1512221	Phạm Ngọc Khôi	Nguyễn		1	0
1512396	Bùi Tấn	Phát	1		1
1512534	Nguyễn Trọng	Phúc	1	1	0

Fig. 11: Form is under checking



(a) Visualization using PCA.



(b) Visualization using t-SNE.

Fig. 12: 128-dimensional embeddings of the training set are projected to the 3D space using PCA (a) and t-SNE (b) techniques. In general, although samples of different classes are not totally separated, the PCA method partly reveals the separation of classes. Meanwhile, the t-SNE method provides a better view of classes as distinguished clusters. Best viewed in color.

eigenvectors still convey a significant amount of information, so by removing them, there is more spatial information is lost. Meanwhile, in Fig. 12b, the separation illustration is picturesque. Inter-class samples are closed while intra-class samples are far from each other. This is because the t-SNE method includes a clustering stage, so embeddings totally belong to their classes. If embeddings of FaceNet do not contain high-level specification, dimension reduction algorithms cannot show or cluster embeddings properly. Consequently, embeddings of the pre-trained FaceNet are sufficient for us to train a classifier for indicating the most likely class that an input belongs to, so we do not conduct a further finetuning stage to adapt the pre-trained FaceNet model in order to be compatible to our dataset.

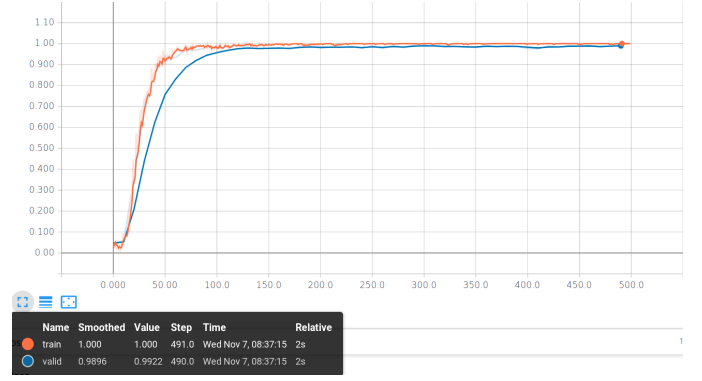


Fig. 13: Accuracy in training and validating stage.

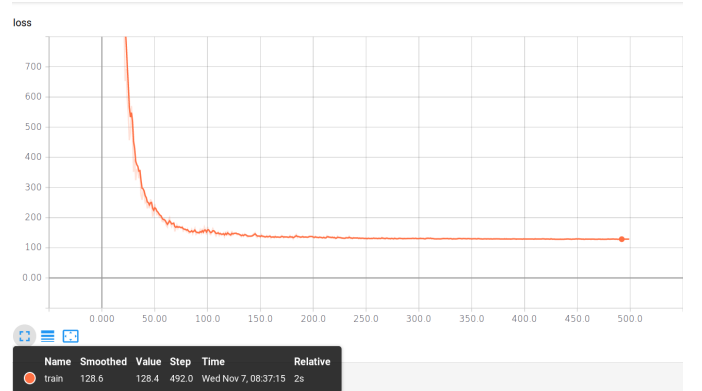


Fig. 14: Loss value of SVM with linear kernel.

### B. Training

Training data is carefully collected with different views from  $-70^\circ$  to  $70^\circ$ . This work can improve accuracy in practical system, because it is difficult for users to keep their faces in a correct position. In training data include 52 identities and 1560 images totally. The training accuracy and validating accuracy of SVM classifier is 100% and 99.22% respectively (in Figure 13). In Figure 14, the convergence of loss can indicate that this model achieves a good performance without overfitting.

We try to implement multi-class SVM by using sklearn library and the accuracy is 99.36%. After training classifier, we train to get the best threshold. We divide threshold in range  $[0; 1]$ . As a result, threshold for 52 identities is 0.18825. Testing accuracy with threshold achieve 98.85% on testing subset. In practical environment, we test on 32 identities, three are 29 identities recognized easily and 3 identities who are not recognized continuously. In Figure 15, the (a),(b) are training images and (c),(b) are testing images, the effect of different illumination lead the probabilities of testing anchor are lower than threshold, so training data have to cover many real-life cases to create the best classifier.

## V. CONCLUSION

In this work, we applied the deep facial recognition techniques to solve the problem of face attendance checking. The system has a pipeline with four stages (e.g., motion-blur detection, face detection, landmark detection, and face

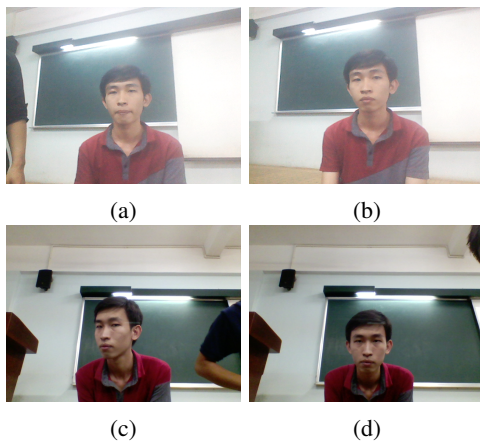


Fig. 15: Unrecognized identity, (a),(b) are training images, and (c),(d) are testing images in practical condition.

recognition). Besides, the system is also integrated a friendly GUI, which allows users both teachers and students interact with it in an easy way. On our private dataset, the application performs accurately despite the low-resolution webcam on typical laptops. This demonstrates that our underlying algorithm is effective to deal with this poor-quality input problem.

In the future, we will target to widen our dataset so that the dataset can be asymptotic to real applications. In addition, more algorithms will be considered to improve the ability of the algorithm to discriminate feature distributions of output classes.

#### ACKNOWLEDGMENT

The authors would like to acknowledge Dr. Cuong Pham-Viet for providing documents as well as promoting the chance for us to do this work. Also, the authors would like to thank volunteer students in the course EE3063 (Aug-Dec 2018, HoChiMinh city University of Technology), who donated data for us to conduct this work.

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