

NEXT 5 LECTURES: how we use statistics

Some references

- BARLOW, A Guide to the use of Stat. Methods in the Phys. Sci
- G. COWAN, Statistical Data Analysis
- K. CRAMER, "Practical Statistics for the UIC"

THESE NOTES FOLLOW Peskin (SLAC STATISTICS WEEK 2017)

HOW DO WE USE STATISTICS?

Messy, uncertain,  
imperfect

BRIDGE BETWEEN EXPERIMENTAL DATA  
& THEORETICAL MODELS

given a set of measurements,

- ... what is the value of a parameter?
- ... what is the allowed range of a parameter?
- ... is one model more consistent than another?

↓  
did i discover something?

PROBABILITY

INTIMATELY TIED TO PHYSICS

- QUANTUM
- STATISTICAL
- DATA

eg result of a coin toss,  
whether there is  
a higgs boson in  
your data, whether  
Schrödinger cat is dead or  
alive, ...

$P(A)$  is the probability for A

↑  
 $0 \leq P(A) \leq 1$

↑ DEFINITELY TRUE  
↑ DEFINITELY NOT TRUE

only the 8th deal in absolutes

$$P(A \& B) = P(A) P(B)$$

IF A & B ARE MUTUALLY EXCLUSIVE, ie have  
nothing to do w/ each other

compare to entangled states

$$P(A \& B) = P(A) = P(B)$$

↑      ↑  
 $|1\rangle_A$   $|1\rangle_B$

IF THERE ARE  $N$  POSSIBLE VALUES FOR  $A$ ,

$$A \in \{a_1, \dots, a_N\}$$

eg  $\{1, 2, \dots, 6\}$  for a 6 sided die

THEN:  $\sum_i P(a_i) = 1$  "conservation of probability"

↑ sum over all mutually exclusive outcomes.

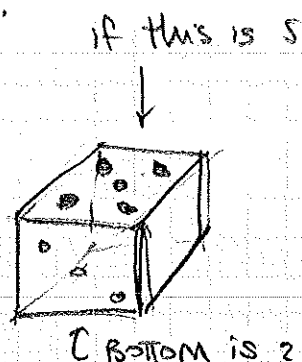
## CONDITIONAL PROBABILITY ← important

SUPPOSE  $A \nmid B$  ARE NOT INDEPENDENT.

eg. ROLL A DIE. OBSERVE  
 ① # ON TOP  
 ② # ON SIDE CLOSEST TO YOU

if you know top face is a 5,  
 then side can be  $\{1, 3, 4, 6\}$   
 w/ equal prob.;

CANNOT BE 2.



THE PROBABILITY OF  $A$  GIVEN INFORMATION  $B$  IS  
 (OR ASSUMPTION)

$$P(A|B) = \frac{P(A \nmid B)}{P(B)}$$

DIVIDING BY THE  
 PROB of  $B$  - WE'RE  
 ASSUMING  $B$  IS TRUE.

↑  $P(A)$  GIVEN THAT  $B$  IS TRUE

then if  $\{b_i\}$  IS A SET OF MUTUALLY EXCLUSIVE POSSIBILITIES

$$\sum_i P(A|b_i) P(b_i) = \sum_i P(A \nmid b_i) = P(A)$$

→ BAYES' THM:  $P(A|B)P(B) = P(A \nmid B) = P(B|A)$   
 $= P(B|A)P(A)$

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

WHY THIS IS IMPORTANT: THIS RELATES

$$P(\text{DATA} \mid \text{THEORY}) \text{ to } P(\text{THEORY} \mid \text{DATA})$$

something we can  
usually calculate

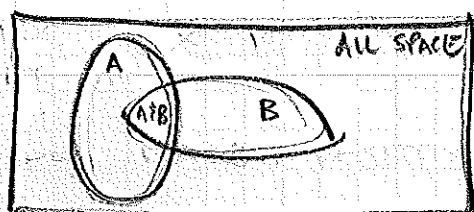
GIVEN PHYSICAL THEORY &  
INSTRUMENTAL EFFICIENCIES,  
CAN DETERMINE PROBABILITIES  
OF DIFF. EXPERIMENTAL  
OUTCOMES

we usually have this

I want to test this

but we want to answer:  
HOW LIKELY IS MY HYPOTHESIS?

VISUAL REPRESENTATION (from Bob Cousins)



$$P(A) = \frac{\text{Area of A}}{\text{Area of ALL SPACE}} \quad P(B) = \frac{\text{Area of B}}{\text{Area of ALL SPACE}}$$

$$P(A|B) = \frac{\text{Area of A} \cap B}{\text{Area of B}}$$

$$P(B|A) = \frac{\text{Area of A} \cap B}{\text{Area of A}}$$

$$P(A \cap B) = \frac{\text{Area of A} \cap B}{\text{Area of ALL SPACE}}$$

$$P(\text{USES ROOT} \mid \text{PARTICLE PHYSICIST}) \sim 50\% \quad \leftarrow \text{theorists don't use root}$$

$$P(\text{PARTICLE PHYSICIST} \mid \text{USES ROOT}) \sim 100\% \quad \leftarrow \text{only HEP (ex) uses ROOT}$$

$$P(\text{PREGNANT} \mid \text{♀}) \sim 3\%$$

$$P(\text{♀} \mid \text{PREGNANT}) \sim 100\%$$

CONTINUOUS VARIABLES :  $x$  eg mass, position, ...

$P(x=3)$  doesn't make sense ... formally 0.

↑  $x = 3.000...$

means  $x \neq 3.000... \underset{\substack{\text{many} \\ \text{decimals}}}{0.27}$

only thing that does make sense is to define a probability distribution function

$$P(x \in [3, 3+dx]) = \underbrace{p(3)}_{\substack{\text{probability} \\ \text{distribution}}} dx \quad \leftarrow \text{scales w/ } dx$$

↑  
PROBABILITY THAT  
 $x$  IS BETWEEN  
 $3 \rightarrow (3+dx)$

then you can ask about finite ranges

$$P(x \in [a, b]) = \int_a^b p(x) dx$$

NORMALIZATION:

$$\left| \int_{-\infty}^{\infty} p(x) dx = 1 \right| \leftrightarrow \sum_i P(a_i) = 1$$

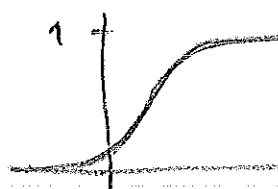
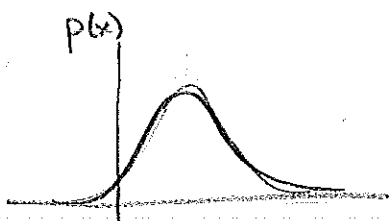
nb. pdf is a DISTRIBUTION IN THE SAME SENSE THAT THE S-FUNCTION IS A DISTRIBUTION

( $p(x)$  MAKES AS LITTLE SENSE AS  $\delta(x)$ )

they make sense only when integrated over:

$$p(x) dx \quad \S \quad S(x) dx$$

↑ like 100% probability  
(COLLAPSED WAVEFUNCTION)



$$P(x) = \int_{-\infty}^x p(y) dy$$

↑ CUMULATIVE DIST. FUNK.

## MOMENTS OF A DISTRIBUTION

$$\langle x \rangle = \int dx \, x \, p(x) \quad \checkmark \text{ remember from moments of a Gaussian?}$$

↑ "expectation value of  $x$ " - 1.

similarly for  $x^2, x^3, \dots$

s.t. the EXPECTATION VALUE OF A FUNCTION IS

$$\langle f(x) \rangle = \int dx \, f(x) \, p(x)$$

↑

eg can Taylor expand  
→ take each term as a moment

SOME IMPORTANT EXPECTATION VALUES:

$$\bar{x} = \langle x \rangle$$

is the mean / average

↑ if you took a large # of events from the prob. dist. func. then took the avg, you'd expect this value

$$\text{Var}(x) = \langle (x - \bar{x})^2 \rangle$$

$$= \langle x^2 - 2x\bar{x} + \bar{x}^2 \rangle$$

$$= \langle x^2 \rangle - 2\langle x \rangle \bar{x} + \bar{x}^2$$

$$= \langle x^2 \rangle - \bar{x}^2 \quad \uparrow \text{ just \#s}$$

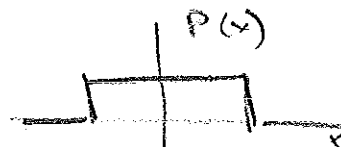
LIKE SQUARE OF STANDARD DEVIATION

↑ but we haven't said anything about data

## SOME COMMON DISTRIBUTIONS

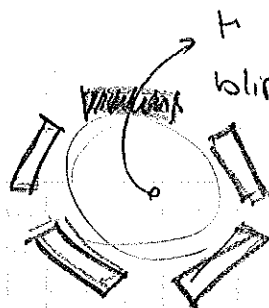
### • BOX DISTRIBUTION

$$P(x) = \begin{cases} 1/L & \text{if } -1/2 < x < 1/2 \\ 0 & \text{other.} \end{cases}$$



equal probability across a finite range.

eg. I have a detector that is made of a number of discrete elements (like con)



→ PARTICLE PASSED THROUGH SOMEWHERE ON THIS ELEMENT.

where?

$$\langle x \rangle = 0$$

$$\text{Var}(x) = \langle (x-0)^2 \rangle = \langle x^2 \rangle$$

$$= \int_{-1/2}^{1/2} dx \, x^2 \frac{1}{L}$$

$$= \frac{1}{3L} \left[ x^3 \right]_{-1/2}^{1/2}$$

$$= \frac{1}{3L} \cdot \left( \frac{L^3}{8} + \frac{L^3}{8} \right) = \boxed{\frac{L^2}{12}}$$

### • (DISCRETE) BINOMIAL DISTRIBUTION

like a coin toss  
given a binary event / trial  
prob. of a given # of positive trials

$$P(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

↑  
PROBABILITY OF  
K POSITIVE RESULTS

PROB. OF POSITIVE  
RESULT FOR EA TRIAL

$$= \frac{n!}{k!(n-k)!}$$

$$\langle k \rangle = np$$

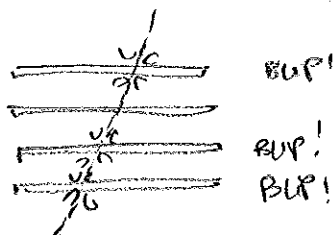
$$\text{Var}(k) = np(1-p)$$

← HW? you check.

BARLOW  
§ 3.2

## eg. DETECTOR EFFICIENCIES

SUPPOSE 'DETECTOR' IS COMPOSED OF SOME #  
OF REDUNDANT LAYERS, EACH W/ EFFICIENCY  $P = 0.95$   
↑  
PROBABILITY OF BUP GIVEN  
ACTUAL EVENTS,



} SUPPOSE 3 BUPs ARE REQUIRED  
TO DEFINE A TRAJECTORY  
("TRACK")

HOW MANY LAYERS SHOULD WE BUILD THE DETECTOR OUT OF?

if only 3:

$$P_{n=3, k=3} = \binom{3}{3} (0.95)^3 (0.05)^0 \approx 85.7\%$$

if 4 layers:

$$\begin{aligned} P_{n=4, k=3} + P_{n=4, k=4} &= \binom{4}{3} (0.95)^3 (0.05)^1 + \binom{4}{4} (0.95)^4 (0.05)^0 \\ &= 0.171 + 0.815 \\ &= \boxed{98.6\%} \\ &\quad \uparrow \text{big improvement} \end{aligned}$$

## POISSON DISTRIBUTION: discrete

Like binomial: still asking about probability of a given # of discrete events

BUT: no idea the # of trials.

instead: sharp events occurring in a continuum

eg: THUNDERSTORM: definite # of flashes ... no sense to ask how many times there was no flash.

eg. IF YOU EXPECT TO SEE AN AVERAGE of 10 EVENTS/day BUT SEE 13, IS THAT SIGNIFICANT?

IF WE EXPECT  $\lambda$  EVENTS IN SOME INTERVAL

SPIT THIS INTO  $n$  SMALL INTERVALS



$n$  BINS,  $n$  LARGE ENOUGH THAT CHANCE OF 2 IN ONE BIN IS IMPROBABLE

interval: expect 10

THEN THIS IS A BINARY DISTRIBUTION

$$P(k) = \binom{n}{k} \left(\frac{\lambda}{n}\right)^k \left(1 - \frac{\lambda}{n}\right)^{n-k}$$

$\uparrow$   $p = \lambda/n$

$\uparrow$

$\rightarrow e^{-\lambda}$  AS  $n \rightarrow \infty$

$$\frac{1}{k!} \left[ \frac{n!}{(n-k)!} \right]$$

$\rightarrow n^k$  for  $n \rightarrow \infty$

$$P(k) = \frac{1}{k!} e^{-\lambda} \lambda^k$$

$\uparrow$

PROBABILITY OF FINDING  $k$  EVENTS IF THE MEAN EXPECTATION IS  $\lambda$

$$\langle k \rangle = \lambda$$

$$\text{Var}(k) = \lambda$$



A SPECIAL DISTRIBUTION: the GAUSSIAN / NORMAL DIST

$$P(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

↑  
Var(x) =  $\sigma^2$   
this is the "σ" when we say "5σ"

↑  
 $\langle x \rangle = \mu$

why: we saw this in the last lecture

↳ PARTITION FUNCTIONS ARE GAUSSIAN TO LEADING ORDER

• EASY TO INTEGRATE & TAKE MOMENTS

• CENTRAL LIMIT THEOREM

↳ eg: for large  $\lambda$ , POISSON  $\rightarrow$  GAUSSIAN

if we make many measurements of something -  
no matter what the distribution that you  
draw from -

the measurements will be distributed  
according to a Gaussian.

(distribution of averages)

MOTIVATION: LET  $x_i$  be random variables w/ PDF  $p_i(x_i)$   
ASSUME  $\langle x_i \rangle = 0$  (shift variables as necessary)

LET  $X = \sum_{i=1}^N x_i$ ; HAS PDF

$$P(X) = \int dx_1 \dots dx_N \prod_i p_i(x_i) \delta(X - \sum_{i=1}^N x_i)$$

$$p_i(x_i) = \int dk_i e^{-ik_i x_i} \tilde{p}_i(k_i) \quad (\text{FOURIER})$$

$$\tilde{p}_i(k_i) = \int dx_i e^{ik_i x_i} p(x_i)$$

$$\tilde{p}_i(0) = \langle 1 \rangle = 1$$

$$\left(-i \frac{d}{dk_i}\right)^n \tilde{p}_i(k_i) \Big|_0 = \langle y_i^n \rangle$$

MOMENTS

WITH THESE MOMENTS

$$\hat{P}_i(k_i) = e^{a_i + ib_i k - \frac{1}{2} C_i k^2 + \dots}$$

$$a_i = b_i = 0$$

from  $\langle x_i \rangle = 0$   
 $\langle t \rangle = 0$

$$C_i = \langle x_i^2 \rangle$$

$$\hat{P}(k) = \prod_i \hat{P}_i(k) = e^{-\frac{1}{2} C k^2 + D k^3 + \dots}$$

$$P(x) = \int dk e^{-ikx} \hat{P}(k)$$

$$C = \sum_i C_i = \sum_i \langle x_i^2 \rangle$$

$$D = \sum_i d_i$$

So:  $C, D, \dots$  ARE  $O(N)$  ← large N "dimensional analysis"

s.t. when  $k \gtrsim O(1/\sqrt{N})$ ,  $\hat{P}(k)$  becomes small

BUT @ THAT SCALE OF  $k$ ,  $Dk^3 \sim 1/\sqrt{N}$  SMALLER THAN QUADRATIC TERM

$$\Rightarrow \boxed{P(x) = \frac{1}{\sqrt{2\pi \langle x^2 \rangle}} e^{-\frac{1}{2\langle x^2 \rangle} x^2}}$$

Gaussian!