# Commutator width of the Grigorchuk Group

## Thorsten Groth

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#### Abstract

Let G be the Grigorchuk group. In [LMU13] it was shown that the commutator width of G is finite but not explicit bound was given. In the present paper we show that in fact each element of the derived subgroup  $g \in G'$  is a product of two commutators. This means that all equations of the form  $[x_1, x_2][x_3, x_4]g = 1$  are solvable for  $g \in G'$ . The computer algebra system [GAP14] is used to derive a series of equations with increasing genus.

## Contents

1	Equations		
	1.1	Quadratic equations	2
	1.2	Normal form of quadratic equations	3
	1.3	Constrainted equations	4
2	Grigorchuks Group		
	2.1	Good Pairs	6
	2.2	Main proposition	7
		2.2.1 Product of 3 commutators	12
	2.3	Product of 2 commutators	13
References			14

## 1 Equations

In this section some standard notations similar to the ones introduced in [JE81] are established. X is a set of *variables*. As it should always be infinite countable it can be assumed to be equal to  $\mathbb{N}$ . G is some arbitrary group and  $F_X$  denotes the free group on the generating set X.

A G-equation E is an element of the group  $F_X * G$  regarded as reduced word. A G-homomorphism from  $F_X * G$  to H \* G is a homomorphism which is the identity on G. Define:

 $\operatorname{Var}: F_X * G \to \mathbb{P}(X), E \mapsto \operatorname{Var}(E), \quad x \in \operatorname{Var}(E) \text{ iff the symbol } x \text{ occurs in } w$ 

An evaluation is a G-endomorphism  $e : F_X * G \to G$ . A solution of an equation E is an evaluation s with s(E) = 1. If a solution exists the equation is called solvable.

The set of elements  $x \in X$  such that  $s(x) \neq 1$  is called the *support* of the solution. Often the support of a solution for an equation E is assumed to be minimal and thus a subset of  $F_{\text{Var}(E)}$ . As the solution is uniquely described by the image of X the data of a minimal solution is equivalent to a map  $\text{Var}(E) \to G$ . The question of whether an equation E is solvable will be referred to as the *diophantine* problem of E. Any homomorphism  $\varphi \colon G \to H$  extends to a homomorphism  $\varphi^* \colon F_X \ast G \to F_X \ast H$  by extending it as the identity on  $F_X$ .

**Definition 1.1.** Two equations  $E, F \in F_X * G$  are equivalent if there is a G-automorphism  $\varphi$  which maps E to F.

**Lemma 1.2.** Let  $\varphi$  be a G-homomorphism and E an equation. If  $\varphi(E)$  is solvable, then so is E.

*Proof.* Let s be the solution of  $\varphi(w)$ . Write E as  $E = \prod_{i=1}^m g_i x_i$  where  $g_i \in G$  and  $x_i \in X$ . Define the evaluation s' by  $x \mapsto s(\varphi(x))$ . Then

$$s'(E) = \prod_{i=1}^{m} g_i s'(x_i) = \prod_{i=1}^{m} g_i s(\varphi(x_i)) = s\left(\prod_{i=1}^{m} g_i \varphi(x_i)\right) = s(\varphi(E)) = 1.$$

So s' is a solution for E.

Corollary 1.3. The diophantine problem is the same for equivalent equations.

## 1.1 Quadratic equations

A G-equation E is called quadratic if each  $x \in Var(E)$  occurs exactly twice in E regarded as reduced word.

It is called *oriented* if for each variable  $x \in Var(E)$  the number of occurrences with positive and with negative sign coincide. Otherwise the word is called *unoriented*.

**Lemma 1.4.** Being oriented or not is invariant under G-automorphisms.

*Proof.* Let  $\varphi$  be some G-homomorphism. Fix some  $x \in X$ . Let  $n_{+,y}$  be the number of positive occurrences of x in  $\varphi(y)$  and  $n_{-,y}$  accordingly. If E is an oriented word then

$$\sum_{y \in \operatorname{Var}(E)} n_{+,y} = \sum_{y \in \operatorname{Var}(E)} n_{-,y^{-1}} = \sum_{y \in \operatorname{Var}(E)} n_{-,y} \ .$$

So  $\varphi(E)$  is oriented too.

#### 1.2 Normal form of quadratic equations

**Definition 1.5.** For  $x_i, y_i, z_i \in F$  and  $c_i \in G$  the following two kind of equations are called in *normal form*:

$$O_{n,m}: [x_1, y_1][x_2, y_2] \cdots [x_n, y_n] c_1^{z_1} \cdots c_{m-1}^{z_{m-1}} c_m$$

$$U_{n,m}: x_1^2 x_2^2 \cdots x_n^2 c_1^{z_1} \cdots c_{m-1}^{z_{m-1}} c_m .$$

$$(1)$$

$$U_{n,m}: \qquad x_1^2 x_2^2 \cdots x_n^2 c_1^{z_1} \cdots c_{m-1}^{z_{m-1}} c_m \ . \tag{2}$$

The form  $O_{n,m}$  is called the oriented case and  $U_{n,m}$  for n > 0 the unoriented. The parameter n is referred to as *genus* of the normal form of an equation.

We are going to prove the following theorem:

**Theorem 1.6** ([JE81]). Each quadratic equation  $E \in F_X * G$  is equivalent to an equation in normal form and the isomorphism can be effectively computed.

*Proof.* The proof goes through an induction on the number of variables. Starting with the oriented case: If the reduced equation E has no variables then it is already in normal form  $O_{0,1}$ . If there is a variable  $x \in X$  occurring in E then it does also appear with opposite sign. So the equation has the form  $E = ux^{-1}vxw$  or can be brought to this form by applying the automorphism  $x \mapsto x^{-1}$ . Choose  $x \in X$  in a way such that Var(v) is minimal.

We're distinguish between multiple cases:

Case 1.0  $v \in G$ . The word uw has less variables then E and can thus be brought into normal form  $N \in O_{r,s}$  by G-isomorphism  $\varphi$ . If N ends with a variable we can use the G-isomorphism  $\varphi \circ (x \mapsto xw^{-1})$  to map E to the equation  $Nv^x \in O_{r,s+1}$ .

> If N ends with a group constant b, N = Mb we can use the isomorphism  $\varphi \circ (x \mapsto xbw^{-1})$  to map E to the equation  $Mv^xb \in O_{r,s+1}$ .

- Case 1.1  $v \in X \cup X^{-1}$ . For simplicity let us assume that  $v \in X$ . In the other case we can apply  $v \mapsto v^{-1}$ . Now there are two possibilities: Either  $v^{-1} \in u$  or  $v^{-1} \in w$ . In the first case  $E = u_1 v^{-1} u_2 x^{-1} v x w$  then the isomorphism  $x \mapsto x^{u_1}u_2, v \mapsto v^{u_1}$  results in the equation  $[v, x]u_1u_2w$ . In the second case  $E = ux^{-1}vxw_1v^{-1}w_2$  is transformed to  $[x,v]uw_1w_2$  by the isomorphism  $x \mapsto x^{uw_1}w_1^{-1}$ ,  $v \mapsto v^{-uw_1}$ . In both cases  $u_1u_2w$ , resp.  $uw_1w_2$  are of less variable and so composition with the corresponding isomorphism results the normal form.
  - Case 2 Length(v) > 1. Then v is a word consisting of elements  $X \cup X^{-1}$  with each symbol occurring at most once as v was chosen with minimal variable set, and some elements of G. If v starts with a constant  $b \in G$ we can use the homomorphism  $x \mapsto bx$  to achieve that v starts with a variable  $y \in X$  by eventually using  $y \mapsto y^{-1}$ . Like in case 1.1 there are two possibilities either  $y^{-1}$  is part of u or part of w. In the first place  $E = u_1 y^{-1} u_2 x^{-1} y v_1 x w$  we can use the isomorphism  $x \mapsto x^{u_1 v_1} u_2$ ,

 $y \mapsto y^{u_1v_1}v_1^{-1}$  to obtain  $[y,x]u_1v_1u_2w$ . In the second take the isomorphism

$$x \mapsto x^{uw_1v_1}v_1^{-1}w_1^{-1}, \qquad y \mapsto y^{-uw_1v_1}v_1^{-1}$$

to get  $[x, y]uw_1v_1w_2$ . In both cases the second subword has again less variable and can be brought into normal form by induction.

Therefore each oriented equation can be brought to normal form by G-isomorphisms. For the unoriented case decompose the equation into E = uxvxw with again v with a minimal number of variables. The shorter word  $uv^{-1}w$  is equivalent by  $\varphi$  to a normal form N by induction.

The G-isomorphism  $\varphi \circ (x \mapsto x^u v^{-1})$  maps E to  $x^2 N$ . If  $N \in U_{r,s} \cup O_{0,t}$  for some r, s, t, nothing else is to do. Otherwise N = [y, z]M. Then the homomorphism

$$x\mapsto xyz, \hspace{1cm} y\mapsto z^{-1}y^{-1}x^{-1}yzxyz, \hspace{1cm} z\mapsto z^{-1}y^{-1}x^{-1}z$$

maps  $x^2N$  to  $x^2y^2z^2M$ . This homomorphism is indeed an isomorphism as

$$x \mapsto x^2 y^{-1} x^{-1}, \qquad y \mapsto xyx^{-1} z^{-1} x^{-1}, \qquad z \mapsto xz$$

is an inverse homomorphism. If M is still not in  $O_{0,s}$  this procedure can be repeated with z instead of x.

For an quadratic equation E we denote by  $\mathfrak{nf}(E) := \mathfrak{nf}_E(E)$  the image of the such constructed isomorphism  $\mathfrak{nf}_E$  of E.

From now on we will consider oriented equations  $O_{(n,1)}$ . For this we will use the abbreviation

$$R_n(x_1,\ldots,x_{2n}) = \prod_{i=1}^n [x_{2i-1},x_{2i}]$$

and often write  $R_n = R_n(x_1, \dots, x_{2n})$  if the  $x_i$  are the first generators of  $F_X$ .

## 1.3 Constrainted equations

**Definition 1.7** ([LMU13]). Given an equation  $E \in F_X * G$ , a group H, a homomorphism  $\pi: G \to H$  and a homomorphism  $\gamma: F_X \to H$  then the pair  $(E, \gamma)$  is called a *constrainted* equation and  $\gamma$  a constraint for the equation E on H.

A solution for  $(E, \gamma)$  is a solution s for E with the additional property, that  $s(x)^{\pi} = \gamma(x)$  for all  $x \in F_X$ .

## 2 Grigorchuks Group

Let  $T_n$  be an infinite regular rooted n-ary tree. The group  $Aut(T_n)$  consists of all root preserving graph automorphisms of the tree  $T_n$ . Note that  $T_n$  is

isomorphic to any n-ary subtree and therefore  $\operatorname{Aut}(T_n) \simeq \operatorname{Aut}(T) \wr S_n$  where  $S_n$  is the symmetric group of n symbols.

A self similar subgroup of  $\operatorname{Aut}(T_n)$  is a group G with an embedding  $G \hookrightarrow G \wr P$  where  $P < S_n$ . For the sake of an easy notation we will identify elements with the image of these embedding and will write  $g = \langle g_1, \ldots, g_n \rangle \pi$  for elements  $g \in G$ . Furthermore we will call the  $g_i$  states of the element g and write  $g@i := g_i$ 

The Grigorchuk 2-group is a finitely generated self-similar group with finite state generators:

$$a = \langle \langle 1, 1 \rangle \rangle (1, 2), \quad b = \langle \langle a, c \rangle \rangle, \quad c = \langle \langle a, d \rangle \rangle, \quad d = \langle \langle 1, b \rangle \rangle.$$

Some useful identities are

- $a^2 = b^2 = c^2 = d^2 = 1$
- $b^a = \langle \langle c, a \rangle \rangle, c^a = \langle \langle d, a \rangle \rangle, d^a = \langle \langle b, 1 \rangle \rangle$
- $(ad)^4 = (ac)^8 = (ab)^{16} = 1$ .

**Lemma 2.1.** The Grigorchuk group is regular branched with branching subgroup  $K := \langle (ab)^2, (bada)^2, (abad)^2 \rangle$ . The Quotient Q := G/K is of order 16.

**Lemma 2.2** ([LMU13]). Given  $n \in \mathbb{N}$  and any homomorphism  $\gamma \colon F_X \to Q$  with  $\operatorname{supp}(\gamma) \subset \langle x_1, \dots x_{2n} \rangle$  there is an element  $\varphi \in \operatorname{Stab}(R_n) < \operatorname{Aut}(F_X)$  such that  $\operatorname{supp}(\gamma \circ \varphi) \in \langle x_1, \dots, x_5 \rangle$ .

**Remark.** Implemented in GAP: GammaSimplify.

**Lemma 2.3.** Identify the group of homomorphisms  $\{\gamma \colon F_X \to Q \mid \operatorname{supp}(\gamma) \subset \langle x_1, \dots x_6 \rangle \}$  with  $Q^6$ . Then

$$\left| Q^6 \middle/_{\operatorname{Stab}(R_3)} \right| = 90.$$

*Proof.* Shown by GAP calculation.

**Definition 2.4.** Fix some representative system  $\mathfrak{R}$  of the above 90 orbits and for  $\gamma \colon F_X \to Q$  with finite support denote by  $\varphi_{\gamma}$  the G-homomorphism in  $\operatorname{Stab}(R_{\mathbb{N}})$  such that  $\gamma \circ \varphi_{\gamma} \in \mathfrak{R}$ .

The element  $\gamma \circ \varphi_{\gamma}$  will be called reduced constraint.

Corollary 2.5. The solvability of a constrainted equation  $(R_n g, \gamma)$  is equivalent to the solvability of  $(R_n g, \gamma \circ \varphi_{\gamma})$ .

*Proof.* If s is a solution for  $(R_n g, \gamma)$  then  $s \circ \varphi_{\gamma}$  is a solution for  $(R_n g, \gamma \circ \varphi_{\gamma})$ .  $\square$ 

**Definition 2.6** ([BGS03]). A branch structure of a group  $G \hookrightarrow G \wr P$  consists of

- a branching subgroup  $K \subseteq G$  of finite index.
- the corresponding Quotient Q = G/K and the factor homomorphism  $\pi: G \to Q$ .
- A group  $Q_1 \subset Q \wr P$  such that  $\langle q_1, q_2 \rangle \sigma \in Q_1$  if and only if  $\langle g_1, g_2 \rangle \sigma \in G$  for all  $g_i \in \pi^{-1}(q_i)$ .
- A map  $\omega: Q_1 \to Q$  with the following property. If  $g = \langle \langle g_1, g_2 \rangle \rangle \sigma \in G$  then  $\omega(\langle \langle \pi(g_1), \pi(g_2) \rangle \rangle \sigma) = \pi(g)$ .

**Lemma 2.7.** The Grigorchuk Group has a branch structure.

**Theorem 2.8** ([LMU13]). The Grigorchuk group has finite commutator width. That is there exists an  $N \in \mathbb{N}$  such that for all  $g \in G'$  the equation  $R_N g$  is solvable.

**Remark.** This is not true for constrainted equations: For example

$$R_n((ab)^2), \gamma \colon x_i \mapsto 1 \ \forall i$$

is not solvable for any n because otherwise it would be  $ac, ca \in G'$ .

### 2.1 Good Pairs

**Definition 2.9.** Given  $g \in G'$  and  $\gamma \in \mathfrak{R}$ . The tuple  $(g, \gamma)$  is called a *good pair* if there exists an n such that  $(R_n g, \gamma)$  is solvable.

Lemma 2.10. Denote by

$$\tau\colon G o {}^G\!\!/_{\!K'} \quad and \quad \varpi\colon {}^G\!\!/_{\!K'} \, o {}^{G\!\!/\!K'}\!\!/_{\!K\!/\!K'} \, \simeq {}^G\!\!/_{\!K}$$

the natural projections.

The pair  $(g, \gamma)$  is a good pair if and only if there is a solution  $s: F_X \to G/K'$  for  $R_3 g^{\tau}$  with  $s(x_i) \in \varpi^{-1}(\gamma(x_i))$ .

Proof. If  $(g, \gamma)$  is a good pair, s a solution for  $R_n g, \gamma$  then  $s(x_i) \in K$  for  $i \geq 6$ , so  $s(R_n) = s(R_3) \cdot k'$  for some  $k' \in K'$  therefore there is a solution  $\tau \circ s$  for  $R_3 g^{\tau}$  with  $s(x_i) = \gamma(x_i)$ .

On the other hand if there is a solution  $s: F_X \to G/K'$  for  $R_3g^{\tau}$  with for each  $s(x_i) \in \varpi^{-1}(\gamma(x_i))$  then for  $g_i \in \tau^{-1}(s(x_i))$  there is some  $k' \in K'$  such that  $R_n(x_1, \ldots, x_6)gk' = 1$  and so  $(g, \gamma)$  is a good pair.

The previous lemma shows that the question if  $(g, \gamma)$  is a good pair depends only on the image  $q = g^{\tau}$  in G/K'. So  $(q, \gamma)$  will be called a good pair if  $(g, \gamma)$  is a good pair for one (and hence all) preimages of q under  $\tau$ .

Corollary 2.11. The following are equivalent:

- a) K is of finite commutator width.
- b) There is a  $N \in \mathbb{N}$  uniform for all good pairs  $(g, \gamma), g \in G', \gamma \in \mathfrak{R}$  such that  $(R_N g, \gamma)$  is solvable.

*Proof.* First the easy direction: If  $k \in K'$  then (k, 1) is a good pair. So  $(R_n k, 1)$  is solvable in G for an  $n \leq N$  but the constraints ensures that it is solvable in K. Therefore the commutator width of K is at most N.

If  $(g, \gamma)$  is a good pair there is an  $m \in \mathbb{N}$  and a solution s for  $R_m g, \gamma$ . As  $s(x_i)^{\pi} = 1$  for all  $i \geq 6$  there is some  $k \in K'$  such that s is a solution for  $R_3 k g, \gamma$ . By a) there is an N such that all  $k \in K'$  can be written as product of N commutators of elements of K and therefore there is a solution for  $(R_{N+3}g, \gamma)$ .

This motivates to study K' and G/K' further.

**Lemma 2.12.** Denote by  $k_1 := (ab)^2, k_2 := \langle (1, k_1) \rangle = (abad)^2$  and  $k_3 := \langle (k_1, 1) \rangle = (bada)^2$  then

$$G' = \langle k_1, k_2, k_3, (ad)^2 \rangle,$$

$$K = \langle k_1, k_2, k_3 \rangle,$$

$$K \times K = \{ \langle k, k' \rangle \mid k, k' \in K \}$$

$$= \langle k_2, k_3, k_2 k_1^{-1} k_2^{-1} k_1, (k_2 k_1^{-1} k_2^{-1} k_1)^a, k_2 k_1 k_2 k_1^{-1}, (k_2 k_1 k_2 k_1^{-1})^a \rangle,$$

$$K' = \langle [k_1, k_2] \rangle^G$$

$$= \langle (dacabaca)^2 (baca)^4, ((ca)^2 baca)^2, (dacabaca)^2 c(acab)^3 acad,$$

$$((ac)^3 ab)^2, bacadacab(ac)^2 (acab)^3, (acadacab)^2 (acab)^4 \rangle^{1,a}.$$

Furthermore we have this chain of indices:

$$[G:G'] = 8, \quad [G':K] = 2, \quad [K:K \times K] = 4, \quad [K \times K:K'] = 16.$$

## 2.2 Main proposition

**Definition 2.13.** We define the activity of an element  $q \in Q$  as the activity of an arbitrary element of  $\pi^{-1}(q)$ . This is well defined as K < Stab(1). Consider a constraint  $\gamma \colon F_X \to Q$ . Define  $Act(\gamma) := x \mapsto Act(\gamma(x))$ . Denote by  $\mathfrak{R}_{act}$  the reduced constraints which have a nontrivial activity.

**Lemma 2.14.** For each  $q \in G'/K'$  there is  $\gamma \in \mathfrak{R}_{act}$  such that  $(q, \gamma)$  is a good pair.

Proof. Assert(ForAll(GPmodKP,q->ForAny(AGPnontrivial,L->q in L)))

**Proposition 2.15.** For each good pair  $(q, \gamma)$  with  $q \in G'/K'$  and  $\gamma \in \mathfrak{R}_{act}$  there is a pair  $(\gamma', x)$ , with  $\gamma' \in \mathfrak{R}_{act}$  and

$$x \in \{1,a,b,c,d,ab,ad,ba\}$$

such that for all g with  $g^{\tau} = q$  the following holds

- $(\gamma', (g@2)^x \cdot g@1)$  is a good pair.
- The solvability of  $(R_{2n-1}(g@2)^x \cdot g@1, \gamma')$  implies the solvability of  $(R_ng, \gamma)$ .

This pair  $(\gamma', x)$  can be effectively computed.

For fixed  $g \in G'/K'$  and  $\gamma \in \mathfrak{R}_{act}$  such that  $(g,\gamma)$  is a good pair denote by  $(g_k,\gamma_k)_{k\in\mathbb{N}}$  the following sequence of pairs: First set  $(g_1,\gamma_1)=(g,\gamma)$  then define  $(g_k,\gamma_k)$  recursively by apply Proposition 2.15 to the pair  $(g_{k-1},\gamma_{k-1})$  and fix a pair  $(\gamma',x)$  with the described properties. Then set  $\gamma_k:=\gamma'$  and  $g_k:=(g_{k-1}@2)^x\cdot g_{k-1}@1$ .

Corollary 2.16. If K has finite commutator width, this implies that the commutator width of G is at most 3.

*Proof.* Starting with some element  $g \in G'$  there is a  $\gamma \in \mathfrak{R}_{act}$  such that  $(g, \gamma)$  is a good pair. (Lemma 2.14).

By Proposition 2.15 there exist good pairs  $(g_k, \gamma_k)_{k \in \mathbb{N}}$  such that  $(R_3 g, \gamma)$  is solvable if one (and hence all) of the constrainted equations  $(R_{2^k+1}g_k, \gamma_k)$  is solvable.

If K is of finite commutator width then by Corollary 2.11 there is an  $N \in \mathbb{N}$  such that all for all good pairs  $(h, \gamma)$  and  $n \geq N$  the constrainted equations  $(R_n g, \gamma)$  are solvable. Therefore the sequence of good pairs  $(g_k, \gamma_k)$  is a sequence of solvable equations  $(R_{2^k+1}g_k, \gamma_k)$ .

**Corollary 2.17.** If for each  $g \in G'$  the set  $\{h \in G' \mid \exists \gamma' : (h, \gamma') \in (g_k, \gamma_k)_{k \in \mathbb{N}}\}$  is finite, then the commutator width of G is at most 3.

Proof. If the sequence  $g_k$  is finite then as  $\mathfrak{R}_{act}$  is finite there is a circle in the sequence of  $(g_k, \gamma_k)$  say  $(g_k, \gamma_k) = (g_l, \gamma_l)$  for some  $k \neq l$ . Thus the solvability of  $(R_n g_k, \gamma_k)$  is equivalent to the solvability of  $(R_m g_k, \gamma_k)$  for arbitrary large m but the latter is solvable since  $(g_k, \gamma_k)$  is a good pair.

**Remark.** If the "x" in Proposition 2.15 would be always trivial then the assumption of the previous lemma would be true as the sequence  $g_1 = g, g_k = g_{k-1}@2 \cdot g_{k-1}@1$  is finite for all g.

**Remark.** Computer experiments of "random" elements of G' (words of at most 100 generators) did always result in finite sequences  $(g_k, \gamma_k)$  of size at most 30.

Proof of Proposition 2.15. The proof constructs for each good pair  $(q, \gamma)$  a set  $\Gamma^q(\gamma) \subset \mathfrak{R}_{act} \times Q$  where the elements fulfill the asked properties by replacing Q by a fixed representative system in G. Then GAP is used to show that for all choices  $q \in G'/K'$ ,  $\gamma \in \mathfrak{R}_{act}$  the constructed sets are never empty.

Take the branching structure  $(K, Q, \pi, Q_1, \omega)$  of the Grigorchuk group as before and the representative system

$$S = \{1, a, b, c, d, ab, ad, ba\}$$

for Q in G. Denote by rep:  $Q \to S$  the map such that  $\operatorname{rep}(q)^{\pi} = q$ . Denote  $x_i \in X$  such that  $\operatorname{supp}(\gamma) \subset \langle x_1, \dots, x_6 \rangle$  and choose  $y_1, \dots, y_{12} \in X \setminus \{x_1, \dots, x_6\}$ .

$$\Gamma_1(\gamma) = \{ \gamma' : \langle y_1, \dots, y_{12} \rangle \to Q \mid \langle \gamma'(y_{2i-1}), \gamma'(y_{2i}) \rangle \in w^{-1}(\gamma(x_i)) \}$$

Let  $F_1 = \langle g \rangle$ ,  $F_2 = \langle g_1, g_2 \rangle$  be free groups. Now define a homomorphism

$$\Phi_{\gamma} \colon F_X * F_1 \to (F_X * F_2) \wr C_2$$

$$g \mapsto \langle \langle g_1, g_2 \rangle \rangle,$$

$$x_i \mapsto \langle \langle x_i^{(1)}, x_i^{(2)} \rangle \rangle \mathcal{A}\mathbf{ct}(\gamma(x_i)).$$

Take  $q_1, q_2 \in Q, n > 3 \in \mathbb{N}$  arbitrary and define

$$\Gamma_2^{q_1,q_2,n}(\gamma) = \left\{ \gamma' \in \Gamma_1(\gamma) \middle| \substack{\pi \colon F_2 \to Q \\ g_1 \mapsto q_1 \\ g_2 \mapsto q_2}, (\gamma' * \pi)^2(\Phi_\gamma(R_n g)) = \langle 1, 1 \rangle \right\}.$$

Denote by  $v, w = v_n, w_n$  the elements such that  $\Phi_{\gamma}(R_n g) = \langle v, w \rangle \langle g_1, g_2 \rangle$ . By the following Lemma 2.18 there is  $x \in X \cup X^{-1}$  such that  $v = v_1 x v_2$  and  $w = w_1 x^{-1} w_2$ . Then the homomorphism

$$l_x \colon F_X * F_2 \to F_X * F_2, x_i \mapsto \begin{cases} x_i & \text{if } x_i \neq x \\ w_2 g_2 w_1 & \text{if } x_i = x \end{cases}$$

maps  $vg_1 \mapsto v_1w_2g_2w_1v_1g_1$  and  $wg_2 \mapsto 1$ . For  $\gamma' \in \Gamma_2^{q_1,q_2,n}(\gamma)$  it is  $x^{\gamma'*\pi} = (w_2g_2w_1)^{\gamma'*\pi}$  so with  $X' = X \setminus x$  there is no loss of information if we consider  $\gamma'|_{F_{X'}}$  instead of  $\gamma'$ . From section 1.2 remember the normalization automorphism  $\mathfrak{nf}_{\gamma,n,x} := \mathfrak{nf}_{v_1w_2g_2w_1v_1g_1} \colon F_{X'} * F_2 \to F_{X'} * F_2$  and note that  $\mathfrak{nf}_{\gamma,n,x}(l_x(v)) = R_{2n-1}g_2^{x_{4n-1}}g_1$ . This leads to the following definition.

$$\Gamma_3^{q_1,q_2,n,x}(\gamma) = \left\{ (\gamma''|_{X \setminus \{x_{4n-1}\}}, \gamma''(x_{4n-1})) \ \middle| \gamma'' = \gamma'|_{X'} \circ \mathfrak{nf}_{\gamma,n,x}, \gamma' \in \Gamma_2^{q_1,q_2,n} \right\}.$$

A solution for the constrainted equation

$$(R_{2n-1}(g@2)^{\operatorname{rep}(y)}(g@1), \gamma''')$$
 for  $(\gamma''', y) \in \Gamma_3^{(g@1)^{\pi}, (g@2)^{\pi}, n, x}$ 

can be extended by sending  $x_{4n-1} \mapsto \operatorname{rep}(y)$  to a solution s' of the equation  $(R_{2n-1}g@2^{x_{4n-1}}g@1, \gamma'')$ . The map  $s' \circ \mathfrak{nf}_{\gamma,n,x}^{-1}$  is a solution for the constrainted

equation  $(v_1w_2g_2w_1v_1g_1, \gamma'|_{X'})$ . Which can be extended by the mapping  $x \mapsto w_2(g@2)w_1$  to a solution s of  $(\Phi_{\gamma}(R_ng), \gamma')$ . By definition of  $\omega$  it is  $t_i := \langle s(y_{2i-1}), s(y_{2i}) \rangle \operatorname{Act}(\gamma(x_i)) \in G$  for all i. So the mapping  $x_i \mapsto t_i$  is a solution for  $(R_ng, \gamma)$ .

The map  $\Gamma_3^{q_1,q_2,n,x}$  does not depend on the value of n: Choose fitting v,w such that  $\Phi_{\gamma}(R_3g) = \langle v,w \rangle \langle g_1,g_2 \rangle$  then  $\Phi_{\gamma}(R_ng) = \langle v,w \rangle \langle R_{n-3}g_1,R'_{n-3}g_2 \rangle$  then after applying the homomorphism  $l_x$  the word which needs to be normalized is  $v_1w_2R_{n-3}g_2w_1v_1R'_{n-3}g_1$ . The automorphisms

$$\psi_1 \colon F_X \ast F_2 \to F_X \ast F_2, \qquad \psi_2 \colon F_X \ast F_2 \to F_X \ast F_2$$

$$y \mapsto y^{g_1^{-1}}, \qquad y \mapsto y^{g_2^{x_{11}}g_1}, \quad \text{for } y \in \text{Var}(R'_{n-3})$$

$$z \mapsto z^{(g_2w_1v_1g_1)^{-1}} \qquad z \mapsto z^{g_2^{x_{11}}g_1} \qquad \text{for } z \in \text{Var}(R_{n-3})$$

$$x \mapsto x \qquad \qquad \text{for all other generators}$$

have the property that  $\mathfrak{nf}_{v_1w_2R_{n-3}g_2w_1v_1R'_{n-3}g_1} = \psi_2 \circ \mathfrak{nf}_{v_1w_2g_2w_1v_1g_1} \circ \psi_1$  and  $\gamma' \circ \psi_i = \gamma'$ . The map  $\Gamma_3^{q_1,q_2,n,x}$  does depend on x, therefore we take the union of all of them and define

$$\Gamma_4^{q_1,q_2}(\gamma) := \left\{ (\gamma''' = \gamma'' \circ \varphi_{\gamma''}, y) \, \middle| (\gamma'',y) \in \bigcup_{x \in \operatorname{Var}(v) \cap \operatorname{Var}(w)} \Gamma_3^{q_1,q_2,n}(\gamma) \right\}.$$

Note now that  $q_1, q_2 \in Q$  are determined by  $q \in G'/K'$  in the sense that there is a map  $\bar{@}i: G'/K' \to Q$  such that if  $g^{\tau} = q$  and  $g_i = g@i$  then  $q_i = q@i$  (Lemma 2.21). So we can write  $\Gamma_4^{q_1,q_2}$  as  $\Gamma_4^q$  instead and finally define

$$\Gamma^q(\gamma) := \{ \gamma' \in \Gamma^q_4(\gamma) \mid \operatorname{Act}(\gamma') \neq 1 \}.$$

As a next step we want to make sure that for all preimages g of q under  $\tau$  there are good pairs among the resulting pairs  $((g@2)^{\text{Rep}(y)} \cdot g@1, \gamma''')$ .

Define for  $h \in G$  maps  $p_h \colon G \to G$  by  $g \mapsto \left( (g@2)^h \cdot g@1, \gamma''' \right)$  this maps are in general not homomorphisms but by Lemma 2.19 we see that for  $g \in G'$  that  $p_h(g) \in G'$  for all  $h \in G$  thus there is a chance that these elements form good pairs with the correct choices of  $\gamma$ .

We can show even better: For each fixed  $q \in G'/K'$  and fixed  $\gamma \in \mathfrak{R}_{act}$  there is  $(\gamma', x) \in \Gamma^q(\gamma)$  such that for all g such that  $g^{\tau} = q$  the element  $(p_{\text{rep}(x)}(g), \gamma')$  is a good pair.

For this purpose we need to reduce this to a finite number of checks. By Lemma 2.20 we can define the map  $\bar{p}_h \colon G'/K' \to G'/(K \times K)$  and the natural homomorphism

$$\varpi' \colon G' /_{K'} \to (G'/K') /_{(K \times K/K')} \simeq G' /_{K \times K}$$

and now only need to show that there is a  $(\gamma', x) \in \Gamma^q(\gamma)$  such that all preimages of  $\bar{p}_{\text{rep}(x)}(q)$  under  $\varpi'$  form good pairs with  $\gamma'$ . In formulas what needs to be checked is:

$$\forall q \in G'/_{K'} \ \forall \gamma \in \mathfrak{R}_{act} \exists (\gamma', x) \in \Gamma^q(\gamma) \forall r \in \varpi'^{-1}(\bar{p}_{rep(x)}) : (r, \gamma') \text{ is a good pair.}$$

This last formula quantifies only over finite sets and is implemented in GAP and can be verified there.  $\Box$ 

**Lemma 2.18.** If  $\gamma$  is a constraint with nontrivial activity, and  $\Phi_{\gamma}(R_n g) = \langle w_1, w_2 \rangle$  then  $\operatorname{Var}(w_1) \cap \operatorname{Var}(w_2) \neq \emptyset$ .

*Proof.* Let x be generator of  $F_X$  with non vanishing constraint activity. Then  $R_n$  contains either a factor [x,y] or [y,x] for another generator y. Assume without loss of generality the first case. Let further be  $\Phi_{\gamma}(x) = \langle\!\langle x_1, x_2 \rangle\!\rangle (1,2)$  and  $\Phi_{\gamma}(y) = \langle\!\langle y_1, y_2 \rangle\!\rangle \sigma$ . Then  $\Phi_{\gamma}(R_n g)$  contains a factor

$$[\langle\!\langle x_1, x_2 \rangle\!\rangle (1, 2), \langle\!\langle y_1, y_2 \rangle\!\rangle \sigma] = \begin{cases} \langle\!\langle x_2^{-1} y_2^{-1} x_2 y_1, x_1^{-1} y_1^{-1} x_1 y_2 \rangle\!\rangle & \text{if } \sigma = \mathbb{1} \\ \langle\!\langle x_2^{-1} y_1^{-1} x_1 y_2, x_1^{-1} y_2^{-1} x_2 y_1 \rangle\!\rangle & \text{if } \sigma = (1, 2). \end{cases}$$

So in both cases  $y_1, y_2 \in Var(w_1) \cap Var(w_2)$ .

**Lemma 2.19.** Let  $h \in G$  and  $p_h \colon G \to G$  be the map  $g \mapsto ((g@2)^h \cdot g@1, \gamma''')$ . It holds that  $p_h(G') \subset G'$  for all  $h \in G$  and  $p_1(K) \subset K$ .

*Proof.* Denote first by  $p := p_1$  then each element  $g \in G'$  is a word in generators  $w((ab)^2, (abad)^2, (bada)^2, (ad)^2)$ . The generators have the following form:

$$(ab)^2 = \langle (ca, ac) \rangle, (abad)^2 = \langle (1, (ab)^2) \rangle, (bada)^2 = \langle (ab)^2, 1 \rangle, (ad)^2 = \langle (b, b) \rangle.$$

Therefore it is

$$p(g) = w(ac, (ab)^2, 1, b) \cdot w(ca, 1, (ab)^2, b)$$
  

$$\equiv w(ac, 1, 1, 1) \cdot w(ca, 1, 1, 1) \cdot w(1, 1, 1, b)^2 \equiv 1 \mod G'.$$

For  $h \in G$  it is  $p_h(g) = [h, (g@2)^{-1}]p(g)$  and therefore  $p_h(g) \in G'$  for all  $g \in G'$ . An element  $g \in K$  is a word  $w((ab)^2, (abad)^2, (bada)^2, )$  and therefore

$$p(g) = w(ac, (ab)^2, 1) \cdot w(ca, 1, (ab)^2)$$
  
 $\equiv w(ac, 1, 1) \cdot w(ca, 1, 1) \equiv 1 \mod K.$ 

**Lemma 2.20.** The map

$$\bar{p}_h \colon G'/_{K'} \to G'/_{K \times K}$$

$$gK' \mapsto (g@2)^h \cdot g@1) K \times K$$

is well defined.

*Proof.* It's easy to verify by GAP that  $k@i \in K \times K$  for i = 1, 2 and  $k \in K'$  using Lemma 2.12. Then for  $k \in K'$  it is

$$p_h(gk) = ((gk)@2)^h \cdot (gk)@1 = (g@2)^h \cdot (k@2)^h \cdot g@1 \cdot k@1 \in (g@2)^h \cdot g@1K \times K.$$

**Lemma 2.21.** The maps  $@i: G \to G, g \mapsto g@i$  induce well defined maps  $@i: G/K' \to G/K$ 

*Proof.* Either by same brute-force argument as before that  $k'@i \in K \times K < K$  or:

Note that  $@i|_{G'}$  is a group homomorphism then consider the following diagram:

Where the map  $\varphi$  exists because the group  $K/K \times K$  has order 4 and hence is abelian. So there need to be a homomorphism  $G'/K' \to G'/K \times K$  which makes all cells commute.

#### 2.2.1 Product of 3 commutators

We will prove that every element  $g \in G'$  is a product of three commutators by proving that the assumptions of Corollary 2.17 are always satisfied. For this purpose remember the map  $p_x \colon g \mapsto (g@2)^x g@1$  from the proof of Proposition 2.15. We will show that for each  $g \in G'$  the sequence of sets

$$Suc_1^g = \{g\}, \ Suc_n^g = \{p_x(h) \mid h \in Suc_{n-1}^g, x \in S\}$$

stagnates in a finite set.

In [Bar98] there is a choice of weights on generators which result in a length on G with good properties.

**Lemma 2.22** ([Bar98]). Let  $\eta \approx 0.811$  be the real root of  $x^3 + x^2 + x - 2$  and set the weights

$$\omega(a) = 1 - \eta^3 \qquad \qquad \omega(c) = 1 - \eta^2$$
  

$$\omega(b) = \eta^3 \qquad \qquad \omega(d) = 1 - \eta$$

then

$$\eta(\omega(b) + \omega(a)) = \omega(c) + \omega(a)$$
$$\eta(\omega(c) + \omega(a)) = \omega(d) + \omega(a)$$
$$\eta(\omega(d) + \omega(a)) = \omega(b).$$

The next lemma is a small variation of a lemma in [Bar98].

**Lemma 2.23.** Denote by  $\partial_{\omega}$  the length on G induced by the weight  $\omega$ . Then  $\partial_{\omega}(p_x(g)) \leq \delta \partial_{\omega}(g)$  for all  $x \in S, g \in G$  with  $\partial_{\omega}(g) > C$  some constant  $C \in \mathbb{N}, \delta < 1$ .

Corollary 2.24. The sequences of sets

$$Suc_1^g = \{g\}, \ Suc_n^g = \{p_x(h) \mid h \in Suc_{n-1}^g, x \in S\}$$

stagnates at a finite step for all  $g \in G$ .

Proof of Lemma.([Bar98]). Each element  $g \in G$  can be written in a word of minimal length of the form  $g = a^{\varepsilon}x_1ax_2a\dots x_na^{\delta}$  where  $x_i \in \{b, c, d\}$  and  $\varepsilon, \delta \in \{0, 1\}$ . Denote by  $n_b, n_c, n_d$  the number of occurrences of b, c, d accordingly. Then

$$\partial_{\omega}(g) = (n - 1 + \varepsilon + \delta)\omega(a) + n_{b}\omega(b) + n_{c}\omega(c) + n_{d}\omega(d)$$

$$\partial_{\omega}(p_{x}(g)) \leq (n_{b} + n_{c})\omega(a) + n_{b}\omega(c) + n_{c}\omega(d) + n_{d}\omega(b) + 2\partial_{\omega}(x)$$

$$= \eta \left( (n_{b} + n_{c} + n_{d})\omega(a) + n_{b}\omega(b) + n_{c}\omega(c) + n_{d}\omega(d) \right) + 2\partial_{\omega}(x)$$

$$= \eta(\partial_{\omega}(g) + (1 - \varepsilon - \delta)\omega(a)) + 2\partial_{\omega}(x)$$

$$\leq \eta(\partial_{\omega}(g) + \omega(a)) + 2(\omega(a) + \omega(b))$$

$$= \eta(\partial_{\omega}(g) + \omega(a)) + 2.$$

Thus the length of  $p_x(g)$  growths with a linear factor smaller 1 in terms of the length of g. Therefore the claim holds. For instance one could take  $\delta = 0.86$  and C = 50 or  $\delta = 0.96$  and C = 16.

Corollary 2.25. K has commutator width 3.

Proof. To show that K has commutator width 3 it is sufficient, to show that the constrainted equations  $(R_3g, 1)$  have solutions for all  $g \in K'$ . Since 1 has trivial activity one cannot simply apply Proposition 2.15. But one can check that all pairs  $(h, \gamma_1), (f, \gamma_2)$  such that  $g = \langle h, f \rangle$  and  $\gamma_1, \gamma_2 = (1, 1, 1, 1, (bad)^{\pi}, 1), \gamma_2 = (1, 1, 1, 1, (ca)^{\pi})$  are good pairs with active constraints and hence the equations  $(R_3g, 1)$  have solutions for all  $g \in K'$ .

#### 2.3 Product of 2 commutators

If it were true that for each  $q \in G'/K'$  there is a  $\gamma \in \mathfrak{R}_{act}$  with  $(q, \gamma)$  a good pair and  $\gamma(x_i) = 1$  for  $i \geq 4$  then it would follow immediately that under the assumptions of either Corollary 2.16 or Corollary 2.17 that each  $g \in G'$  is a product of two commutators. But unfortunately this isn't the case.

In fact there are 8 elements of  $G'\!/\!K'$  which are no good pairs for active  $\gamma$ 's with trivial activity in the 5<sup>th</sup> component.  $G'\!/\!K'$  is generated by the following elements  $q_1 = ((ab)^2)^{\tau}$ ,  $q_2 = ((bada)^2)^{\tau}$ ,  $q_3 = ((abad)^2)^{\tau}$ ,  $q_4 = ((ad)^2)^{\tau}$ .

Fortunately there are inactive  $\gamma$ 's with support inside the first 4 coordinates such that all descendant problems are in none of these problematic cases.

For instance the table below shows all problematic  $q \in G'/K'$  and a choice of  $\gamma$  such that  $(q, \gamma)$  is a good pair and  $(g@i)^{\tau}, \gamma_i)$  are good pairs with active constraints for i = 1, 2 and all g such that  $g^{\tau} = q$ . Furthermore the solvability of  $(R_2g@i, \gamma_i)$  implies the solvability of  $(R_2g, \gamma)$  and the latter is solvable by the previous section.

```
\gamma_1
                                                                                                                           \gamma_2
                        (1,1,\overline{b^{\pi}},\overline{dada^{\pi},1,1})
                                                                 (1, bad^{\pi}, a^{\pi}, ad^{\pi}, 1, 1)
                                                                                                           (1, ca^{\pi}, c^{\pi}, da^{\pi}, 1, 1)
      q_2q_1^2
q_2^{-1}q_4q_1^{-1}
                        (1, 1, b^{\pi}, dada^{\pi}, 1, 1)
                                                                 (1, bad^{\pi}, a^{\pi}, ad^{\pi}, 1, 1)
                                                                                                           (1, ca^{\pi}, c^{\pi}, da^{\pi}, 1, 1)
                           (1,1,c^{\pi},b^{\pi},1,1)
                                                                 (1, 1, a,^{\pi} bada^{\pi}, 1, 1)
                                                                                                           (1, 1, d^{\pi}, dad^{\pi}, 1, 1)
                            (1,1,c^{\pi},b^{\pi},1,1)
                                                                  (1, 1, a^{\pi}, bada^{\pi}, 1, 1)
                                                                                                            (1, 1, d^{\pi}, dad^{\pi}, 1, 1)
                          (1, 1, b, dada^{\pi}, 1, 1)
                                                                 (1, bad^{\pi}, a^{\pi}, ad^{\pi}, 1, 1)
                                                                                                           (1, ca^{\pi}, c^{\pi}, da^{\pi}, 1, 1)
                        (1, 1, b^{\pi}, dada^{\pi}, 1, 1)
                                                                 (1, bad^{\pi}, a^{\pi}, ad^{\pi}, 1, 1)
                                                                                                           (1, ca^{\pi}, c^{\pi}, da^{\pi}, 1, 1)
                            (1,1,c^{\pi},b^{\pi},1,1)
                                                                 (1, 1, a^{\pi}, bada^{\pi}, 1, 1)
                                                                                                            (1, 1, d^{\pi}, dad^{\pi}, 1, 1)
                            (1,1,c^{\pi},b^{\pi},1,1)
                                                                 (1, 1, a^{\pi}, bada^{\pi}, 1, 1)
                                                                                                            (1, 1, d^{\pi}, dad^{\pi}, 1, 1)
```

Corollary 2.26. All elements  $g \in G'$  are products of two commutators.

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