Adding new distributions in hmmTMB

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The package hmmTMB includes many possible distributions for the observation model:

```
names(hmmTMB:::dist list)
                                  "cat"
                                                "dir"
 [1] "beta"
                    "binom"
                                                               "exp"
 [6] "foldednorm" "gamma"
                                  "gamma2"
                                                "lnorm"
                                                               "mvnorm"
[11] "nbinom"
                    "norm"
                                  "pois"
                                                "t"
                                                               "truncnorm"
[16] "tweedie"
                    "vm"
                                  "weibull"
                                                               "zibinom"
                                                "wrpcauchy"
[21] "zigamma"
                    "zigamma2"
                                  "zinbinom"
                                                "zipois"
                                                               "zoibeta"
[26] "ztnbinom"
                    "ztpois"
```

This vignette provides a technical description of the steps required to add a new distribution to the package. If the distribution you want is not implemented, you can contact us about it; of course, you can also fork the Github repository, add the distribution, and submit a pull request.

1 R code

1.1 Create a Dist object (R/dist_def.R)

In hmmTMB, a distribution is an object of the Dist class, which stores information such as the number of parameters, probability density function, and link functions. To add a new distribution, a new Dist object must be created using Dist\$new() in the file R/dist_def.R. The chunk below shows the code required to create an object for the exponential distribution.

```
dist_norm <- Dist$new(
  name = "norm",
  name_long = "normal",
  pdf = dnorm,</pre>
```

```
cdf = pnorm,
  rng = rnorm,
  link = list(mean = identity, sd = log),
  invlink = list(mean = identity, sd = exp),
  npar = 2,
  parnames = c("mean", "sd"),
  parapprox = function(x) {
    return(c(mean(x), sd(x)))
}
```

Our convention is to name the Dist object as dist_name where name is the name of the distribution. The arguments passed to Dist\$new() are the following.

- name: Name of the distribution, which will be used to define the observation model.
- name long: Expanded form of the name of the distribution (optional).
- pdf: A function object for the probability density function (or probability mass function). If there is a built-in R function, like dnorm, this can be used directly; otherwise, a custom function must be written. This should take as inputs x (the value at which to evaluate the pdf), the parameters of the function, and log (TRUE/FALSE to indicate whether the log-pdf is required). It should be vectorised with respect to x; that is, if x is a vector of length n, then this function outputs the vector of n evaluations of the pdf at those values.
- cdf: A function object for the cumulative distribution function, with similar arguments as the pdf (except log).
- rng: A function object to generate random values, with inputs n (the number of random values) and the distribution parameters.
- link: A named list of function objects, with one entry for the link function of each distribution parameter. Common choices include identity $(\theta \in \mathbb{R})$, log $(\theta > 0)$, and glogis $(0 < \theta < 1)$.
- invlink: A named list of function objects, with one entry for the inverse link function of each distribution parameter. These should be the inverse functions of the entries of link. Common choices include identity $(\theta \in \mathbb{R})$, exp $(\theta > 0)$, and plogis $(0 < \theta < 1)$.
- npar: Number of parameters.
- parnames: Names of parameters. This should match the inputs of pdf, cdf and rng, and the names of the elements of link and invlink.
- parapprox: A function object that takes a vector of observations, and returns estimates for the parameters of the distribution. This is only used to suggest initial parameter

values in Observation\$suggest_initial(), and can be defined as a function that returns NA if there is no simple heuristic to return point estimates.

1.2 Add distribution to dist_list (R/dist_def.R)

All Dist objects are stored in a list named dist_list, which is defined at the bottom of the file R/dist_def.R. The new distribution should be added to this list as an entry of the form name = dist_name. As we will see in Section 2.2, the order of distributions in this list matters to link the R and C++ sides of the code, so the simplest option is to add the new distribution to the end of the list.

2 C++ code

2.1 Create a distribution class (src/dist_def.hpp)

On the C++ side, distributions are defined as classes that inherit from a parent class named Dist. A new such class must be defined for the new distribution. The C++ distribution has fewer elements than its R counterpart because only the log-likelihood function is implemented in C++ (and the log-likelihood doesn't need to know the cumulative distribution function, or to be able to generate random numbers, for example). The new class must be added to the file src/dist_def.hpp, and the chunk below shows what the format should be.

```
template < class Type >
class Normal : public Dist < Type > {
public:
    // Constructor
    Normal() {};
    // Link function
```

```
vector<Type> link(const vector<Type>& par, const int& n states) {
    vector<Type> wpar(par.size());
    // mean
    for (int i = 0; i < n states; ++i) wpar(i) = par(i);
    // sd
    for (int i = n states; i < 2 * n states; ++i) wpar(i) = log(par(i));
    return(wpar);
 // Inverse link function
 matrix<Type> invlink(const vector<Type>& wpar, const int& n states) {
    int n par = wpar.size()/n states;
   matrix<Type> par(n states, n par);
   // mean
    for (int i = 0; i < n states; ++i) par(i, 0) = wpar(i);
    for (int i = 0; i < n_states; ++i) par(i, 1) = exp(wpar(i + n states));
    return(par);
 }
 // Probability density/mass function
 Type pdf(const Type& x, const vector<Type>& par, const bool& logpdf) {
    Type val = dnorm(x, par(0), par(1), logpdf);
    return(val);
 }
};
```

The class should be given an informative name (Normal in the example), which doesn't have to match the name chosen in R. Then, the following four functions need to be implemented.

- The name of the constructor (e.g., Normal) should be updated to match the name of the new distribution.
- The link function takes as inputs a vector of parameters on the natural scale and the number of HMM states, and returns a vector of parameters on the link scale. In the normal example, the input is a vector with n_states means (identity link) and n_states standard deviations (log link).
- The invlink function takes as inputs a vector of parameters on the link scale and the number of HMM states, and returns a matrix of parameters on the natural scale. The matrix should have one row for each state and one column for each parameter.
- The pdf function takes as inputs the point x at which the pdf should be evaluated, a

vector of parameters **par** on the natural scale, and a logical variable indicating whether the log-pdf should be returned. In the example, we directly use the **dnorm** function implemented in TMB, but this might require custom code if the pdf is not standard.

The names of these functions and the lists of arguments should not be modified; only their content should be changed for the new distribution.

2.2 Add distribution to list (src/dist.hpp)

There needs to be a way to link the distribution on the R side to its C++ implementation. For this purpose, an integer code is automatically generated in dist_def.R for each distribution, starting at 0 and in the order defined in the dist_list object (see Section 1.2). In C++, each distribution is associated with its code in the file src/dist.hpp in a switch statement. The new distribution should be added following the same format as other distributions, simply changing the number after case and the naem of the distribution after new. The code should match the R code, so this list needs to be in the same order as the R object dist_list. If you added the distribution to the end of dist_list in Section 1.2, you can add the distribution to the end of the switch statement here.

```
template <class Type>
std::unique_ptr<Dist<Type>> dist_generator(const int& code) {
 switch (code) {
 case 0:
    return(std::unique_ptr<Dist<Type>>(new Beta<Type>));
  case 1:
    return(std::unique ptr<Dist<Type>>(new Binomial<Type>));
    return(std::unique ptr<Dist<Type>>(new Categorical<Type>));
 case 3:
    return(std::unique_ptr<Dist<Type>>>(new Dirichlet<Type>>);
  case 4:
    return(std::unique_ptr<Dist<Type>>(new Exponential<Type>));
 case 23:
    return(std::unique ptr<Dist<Type>>(new ZeroInflatedPoisson<Type>));
 case 24:
    return(std::unique ptr<Dist<Type>>(new ZeroOneInflatedBeta<Type>));
 case 25:
    return(std::unique_ptr<Dist<Type>>(new ZeroTruncatedNegativeBinomial<Type>));
```

```
case 26:
    return(std::unique_ptr<Dist<Type>>>(new ZeroTruncatedPoisson<Type>));
    default:
        return(std::unique_ptr<Dist<Type>>>(new Normal<Type>));
    }
}
```

3 Test in a simulation study

The best way to check that all components of the new distribution were implemented correctly is to run a simulation. That is, you can generate data from an HMM, and check whether hmmTMB can recover the model parameters. (This might not detect some errors, but is a good sanity check anyway.) The code below demonstrates what such a simulation could look like, for the distribution "norm". A more extensive simulation study (over many simulated data sets) could be used to investigate the performance of the model in more detail.

```
####################
## Simulate data ##
####################
n < -1e4
# Simulate state process (2-state Markov chain)
tpm \leftarrow matrix(c(0.95, 0.1, 0.05, 0.9), 2, 2)
S \leftarrow rep(NA, n)
S[1] < -1
for(i in 2:n) {
  S[i] \leftarrow sample(1:2, size = 1, prob = tpm[S[i-1],])
}
# Simulate observation process (normal distributions)
means \leftarrow c(1, 3)
sds \leftarrow c(1, 2)
Z \leftarrow rnorm(n = n, mean = means[S], sd = sds[S])
# Data frame for hmmTMB
data <- data.frame(Z = Z)</pre>
```

```
###############
## Fit model ##
###############
library(hmmTMB)
# State model
hid <- MarkovChain$new(data = data, n states = 2)
# Observation model
par0 \leftarrow list(Z = list(mean = c(0, 4), sd = c(0.5, 2)))
obs <- Observation$new(data = data, dists = list(Z = "norm"), par = par0)</pre>
# Create and fit HMM
hmm <- HMM$new(obs = obs, hid = hid)</pre>
hmm$fit(silent = TRUE)
# Check that parameters were recovered
lapply(hmm$par(), round, 3)
$obspar
, , 1
       state 1 state 2
Z.mean 0.991 3.000
Z.sd 0.996 1.983
$tpm
, , 1
        state 1 state 2
state 1 0.943 0.057
state 2 0.111 0.889
```