

# Lecture 14

## Newtonian Mechanics : Oscillations

## Equation of Motion of Single Particle

- Position  $r(t)$
- Velocity  $v(t)=dr(t)/dt$
- Acceleration  $a(t)=dv(t)/dt=d^2r(t)/dt^2$
- Momentum  $p(t)=mv(t)$

**Newton's second Law (Inertial Frame) → the equation of motion that is position of the particle as a function of time.**

$$F(r,v,t)=dp(t)/dt$$

$$F = -kx = m\ddot{x} \rightarrow \boxed{\ddot{x} + \omega^2 x = 0}$$

This is a homogenous, linear DE

We solve it in general by inserting a solution of the form:  $x = B \exp(rt)$

$$\ddot{x} + \omega^2 x = r^2 B \exp(rt) + \omega^2 B \exp(rt) = 0$$

This leads to an **auxillary equation** of form  $\boxed{r^2 + \omega^2 = 0}$  which has two roots:

$r_{1,2} = \pm \sqrt{-\omega^2} = \pm i\omega$ . We construct the general solution as the sum of terms

$$\boxed{x(t) = B_1 \exp(i\omega t) + B_2 \exp(-i\omega t)}$$

X is real by demanding  $x = x^*$

$$x = B_1 \exp(i\omega t) + B_2 \exp(-i\omega t)$$

$$x^* = B_1^* \exp(-i\omega t) + B_2^* \exp(i\omega t)$$

$$x^* = x \text{ if and only if } \boxed{B_2 = B_1^*}$$

$$x(t) = B_1 \exp(i\omega t) + B_1^* \exp(-i\omega t)$$

Choose  $B_1 = \alpha \exp(-i\delta)$  where  $\alpha$  and  $\delta$  are real numbers corresponding to the phase and modulus of  $B_1$ .

$$\begin{aligned} x(t) &= \alpha e^{-i\delta} \exp(i\omega t) + \alpha e^{i\delta} \exp(-i\omega t) \\ &= \alpha \exp[i(\omega t - \delta)] + \alpha \exp[-i(\omega t - \delta)] \\ &= 2\alpha \frac{\exp[i(\omega t - \delta)] + \exp[-i(\omega t - \delta)]}{2} \end{aligned}$$

$$x = 2\alpha \cos(\omega t - \delta) \rightarrow \boxed{x = A \cos(\omega t - \delta)}$$

## Summary of (SHM : ideal case)

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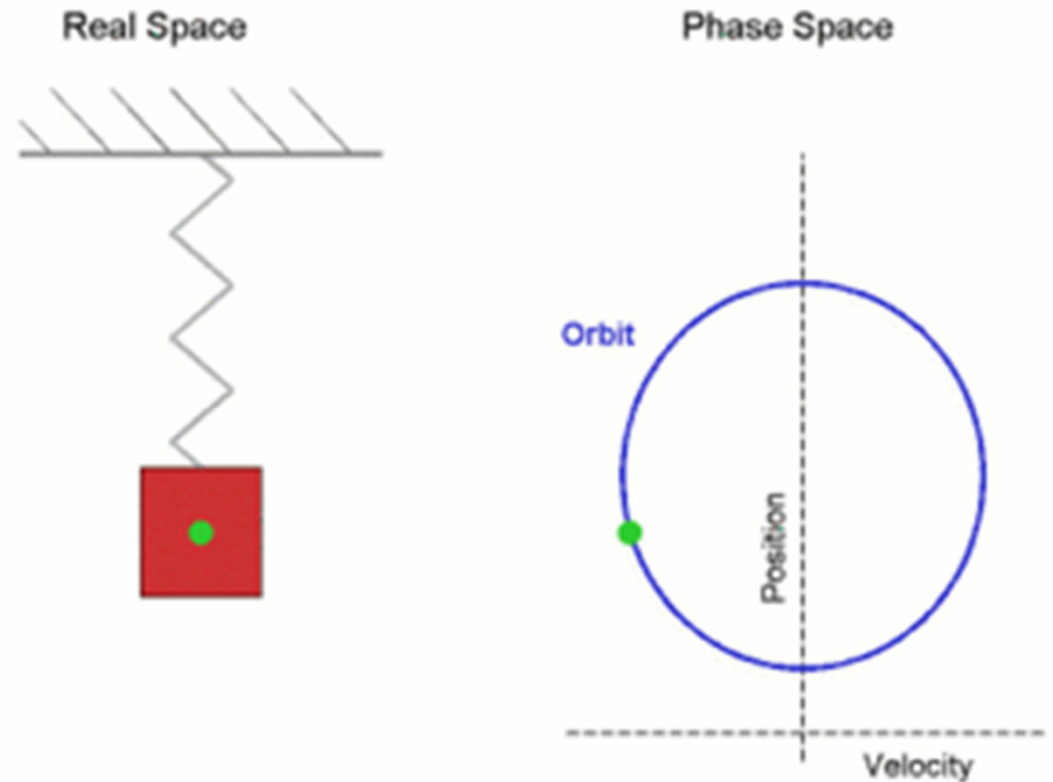
- Oscillations → perturbation from equilibrium.
- Simplest approximation of restoring force  $F = -kx$
- (Hookes Law within elastic limit)
- So if we make “x” n times larger , F will be n times larger.
- Spring constant  $k = \text{del } F / \text{del } x$ .
- Equation of motion of SHM →  **$d^2x/dt^2 + w^2x = 0$** ;  
where  $w^2 = k/m$
- General Solution →  $x = A \cos(wt - \phi)$
- Total energy is proportional to square of the amplitude.  $E = .5 kA^2$
- Time period does not depend on amplitude.
- Phase Space behavior.

# SHM

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$$F = -k(x - x_e) = -k x'$$

$$U(x) = \frac{k}{2} x'^2 ; T = \frac{m}{2} \dot{x}'^2$$



# Linear Drag Force

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$m \ddot{x} = -k x - b\dot{x}$  or writing

$\omega = \sqrt{k/m}$  and  $\beta = b/2m$  we have

$$\ddot{x} + 2\beta\dot{x} + \omega^2 x = 0$$

Auxillary eq by substituting

$$x = B \exp(rt)$$

$$B \exp(rt) (r^2 + 2\beta r + \omega^2) = 0$$

$$r^2 + 2\beta r + \omega^2 = 0$$

$$r_{1,2} = -\beta \pm \sqrt{\beta^2 - \omega^2}$$

# 3 possible cases

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$$r_{1,2} = -\beta \pm \sqrt{\beta^2 - \omega^2}$$

$$x = B_1 \exp(r_1 t) + B_2 \exp(r_2 t)$$

There are three cases:

$\beta^2 - \omega^2 < 0$  under damped

$\beta^2 - \omega^2 = 0$  critically damped

$\beta^2 - \omega^2 > 0$  over damped

# Underdamp

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Define  $\omega_1 = \sqrt{\omega^2 - \beta^2}$   $r_{1,2} = -\beta \pm i\omega_1$

$$x = e^{-\beta t} (B_1 \exp(i\omega_1 t) + B_2 \exp(-i\omega_1 t))$$

We force a real x via  $x^* = x$  which

$$x^* = e^{-\beta t} (B_1^* \exp(-i\omega_1 t) + B_2^* \exp(i\omega_1 t))$$

$$\therefore x = e^{-\beta t} (B_1 \exp(i\omega_1 t) + B_1^* \exp(-i\omega_1 t))$$

Choose  $B_1 = \frac{A}{2} \exp(-i\delta)$  real amp & phase

$$x = e^{-\beta t} \frac{A}{2} (e^{i(\omega_1 t - \delta)} + e^{-i(\omega_1 t - \delta)})$$

$$x = Ae^{-\beta t} \cos(\omega_1 t - \delta) \text{ or } e^{-\beta t} \sin(\omega_1 t - \delta)$$

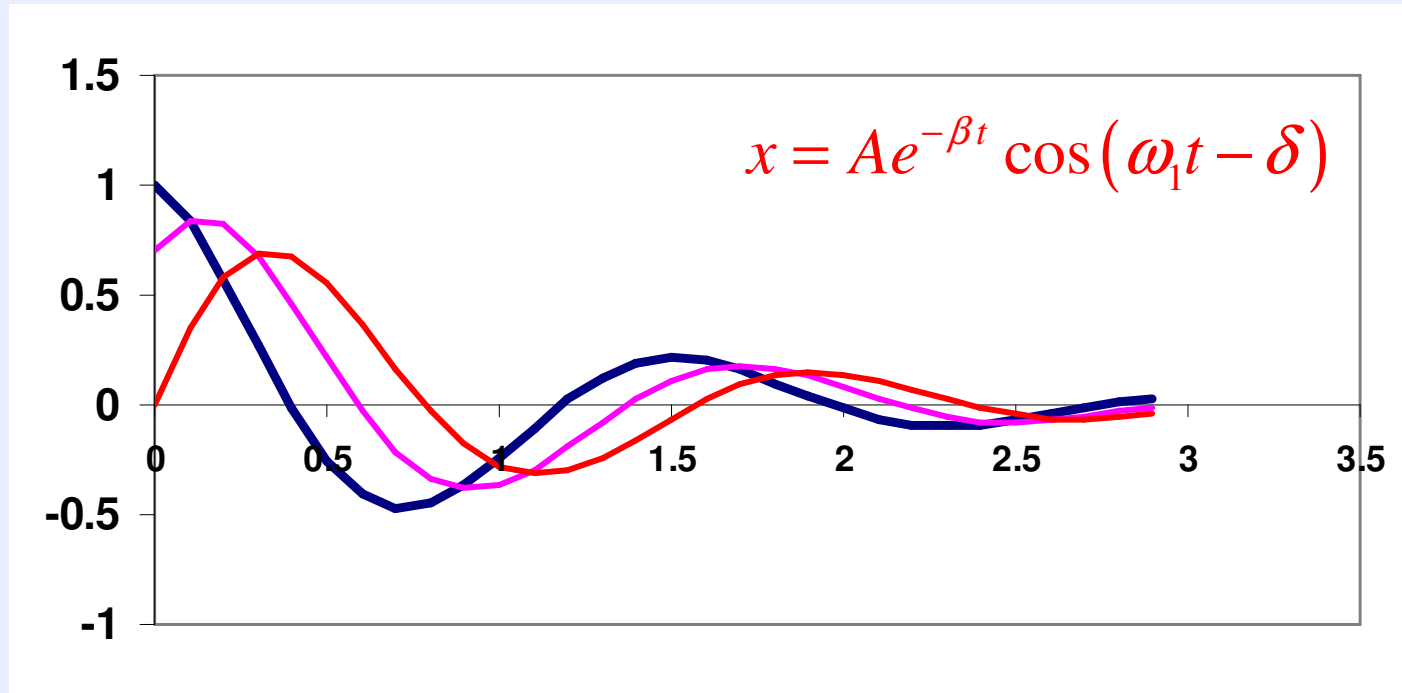
The under damped oscillator has two constants (phase and amplitude) to match initial position and velocity.

The solution dies away while oscillating but with a frequency other than  $\omega = (k/m)^{1/2}$ .



# Under damped

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$$\boxed{\omega_1 = 4\beta}$$

# Over damped

$$r_{1,2} = -\beta \pm \sqrt{\beta^2 - \omega^2}$$

$$x = B_1 \exp(r_1 t) + B_2 \exp(r_2 t)$$

$$\omega_2 = \sqrt{\beta^2 - \omega^2} \quad r_{1,2} = -\beta \pm \omega_2$$

$$x = B_1 \exp(-(\beta + \omega_2)t) + B_2 \exp(-(\beta - \omega_2)t)$$

Defining  $\lambda_1 = \beta + \omega_2$  and  $\lambda_2 = \beta - \omega_2$

$$x = B_1 \exp(-\lambda_1 t) + B_2 \exp(-\lambda_2 t)$$