

**IE 404 – Digital Image Processing**  
**Dhirubhai Ambani Institute of Information and Communication Technology (DA-IICT)**  
**End-Sem Examination, November 2019**

[Time – 2 Hour 30 Minutes]

[Total Marks - 65]

**Instructions:**

- There are 2 double sided pages (4 printed pages). Ensure that you have all the pages.
- Question paper contains 2 sections (A, and B).
  - Section A contains 20 multiple choice questions, 1 mark will each question.
  - Section B contains 3 descriptive questions, 15 marks for each question.
- Answer all question. All questions are self-explanatory and understanding of question is a part of evaluation.
- No query regarding questions will entertained during examination by course instructor or invigilator.

**Section A**

1. Formula  $p_r = n/MN$  represents the
  - A. **Coding redundancy**
  - B. Spatial redundancy
  - C. Temporal redundancy
  - D. Irrelevant info
2. Histogram equalization refers to image
  - A. Sampling
  - B. Quantization
  - C. Framing
  - D. **Normalization**
3. Redundancy of data can be found using formula
  - A.  **$1-(1/c)$**
  - B.  $1+(1/c)$
  - C.  $1-(-1/c)$
  - D.  $(1/c)$
4. Image can be blurred using
  - A. **Low pass filter**
  - B. Contouring
  - C. Erosion
  - D. High pass filter
5. Brightness of light is a subject
  - A. Oriented
  - B. **Descriptor**
  - C. Matter
  - D. Defined
6. Color of an object is determined by light
  - A. Refracted
  - B. Transmitted
  - C. **Reflected**
  - D. Absorbed

7. Visible spectrum ranges
  - A. 300-600 nm
  - B. 400-700 nm**
  - C. 500-800 nm
  - D. 600-900 nm
8. For line detection we use mask that is
  - A. Gaussian
  - B. Laplacian**
  - C. Ideal
  - D. Butterworth
9. Gradient magnitude images are more useful in
  - A. Point detection
  - B. Line detection
  - C. Area detection
  - D. Edge detection**
10. For noise reduction we use
  - A. Image smoothing**
  - B. Image contouring
  - C. Image enhancement
  - D. Image recognition
11. For edge detection we use
  - A. First derivative**
  - B. Second derivative
  - C. Third derivative
  - D. Both A and B
12. Sobel gradient is not that good for detection of
  - A. Horizontal lines
  - B. Vertical lines
  - C. Diagonal lines**
  - D. Edges
13. Example of similarity approach in image segmentation is
  - A. Edge based segmentation
  - B. Boundary based segmentation
  - C. Region based segmentation**
  - D. Both A and B
14. Reflection and translation of image objects are based on
  - A. Pixels
  - B. Frames
  - C. Structuring elements**
  - D. Coordinates
15. With dilation process images get
  - A. Thinner
  - B. Thickened**
  - C. Shrunked
  - D. Sharpened
16. Power law transformation is useful in
  - A. Purification
  - B. Industry
  - C. Radar
  - D. MRI**

17. Product of two functions in spatial domain is what, in frequency domain
- Correlation
  - Convolution**
  - Fourier transform
  - Fast Fourier transform
18. Types of imaging sensors are
- Two
  - Three**
  - Four
  - Five
19. Image linear interpolation is given by formula
- $v(x,y) = ax+by+cxy+d$**
  - $v(x,y) = ax+by+cxy$
  - $v(x,y) = ax+by+d$
  - $v(x,y) = by+cxy+d$
20. Visible red light is used in
- Soil moisture
  - Mineral mapping
  - Water penetration
  - Vegetation discrimination**

## Section B

21. Consider the following image A, and let the structuring element be B.

$$A = \begin{bmatrix} 23 & 21 & 32 & 31 & 28 & 26 \\ 88 & 45 & 29 & 51 & 67 & 39 \\ 64 & 23 & 33 & 35 & 32 & 24 \\ 15 & 20 & 125 & 190 & 143 & 120 \\ 34 & 255 & 24 & 0 & 26 & 123 \\ 75 & 145 & 29 & 51 & 67 & 39 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

Perform the following operations

(I)  $A^c$

$$\begin{bmatrix} -22 & -20 & -31 & -30 & -27 & -25 \\ -87 & -44 & -28 & -50 & -66 & -38 \\ -63 & -22 & -32 & -34 & -31 & -23 \\ -14 & -19 & -124 & -189 & -142 & -119 \\ -33 & -254 & -23 & 1 & -25 & -122 \\ -74 & -144 & -28 & -50 & -66 & -38 \end{bmatrix}$$

(II)  $A \oplus B$

$$\begin{bmatrix} 88 & 45 & 32 & 51 & 67 & 39 \\ 88 & 88 & 51 & 67 & 67 & 67 \\ 88 & 64 & 125 & 190 & 143 & 120 \\ 64 & 255 & 190 & 190 & 190 & 143 \\ 255 & 255 & 255 & 190 & 143 & 123 \\ 145 & 255 & 145 & 67 & 67 & 123 \end{bmatrix}$$

(III)  $A \ominus B$

21	21	21	28	26	26
23	21	29	29	28	24
15	20	23	32	24	24
15	15	20	0	26	24
15	20	0	0	0	26
34	29	24	0	26	39

(IV)  $A^c \oplus B$

-20	-20	-20	-27	-25	-25
-22	-20	-28	-28	-27	-23
-14	-19	-22	-31	-23	-23
-14	-14	-19	1	-25	-23
-14	-19	1	1	1	-25
-33	-28	-23	1	-25	-38

(V)  $A^c \ominus B$

-87	-44	-31	-50	-66	-38
-87	-87	-50	-66	-66	-66
-87	-63	-124	-189	-142	-119
-63	-254	-189	-189	-189	-142
-254	-254	-254	-189	-142	-122
-144	-254	-144	-66	-66	-122

(VI)  $(A \ominus B) \oplus B$

23	21	29	29	28	26
23	29	29	32	29	28
23	23	32	32	32	24
15	20	23	32	26	26
34	29	24	0	26	39
34	34	29	26	39	39

(VII)  $(A \oplus B) \ominus B$

23	21	32	31	28	26
88	45	32	51	67	39
64	64	51	67	67	24
15	64	125	190	143	120
34	255	145	67	67	123
75	145	29	51	67	39

22. (A). 4 x 4 original image with 4 bits per pixel is given by [10,12,8,9; 10,12,12,14; 12,13,10,9; 14,12,10,12]

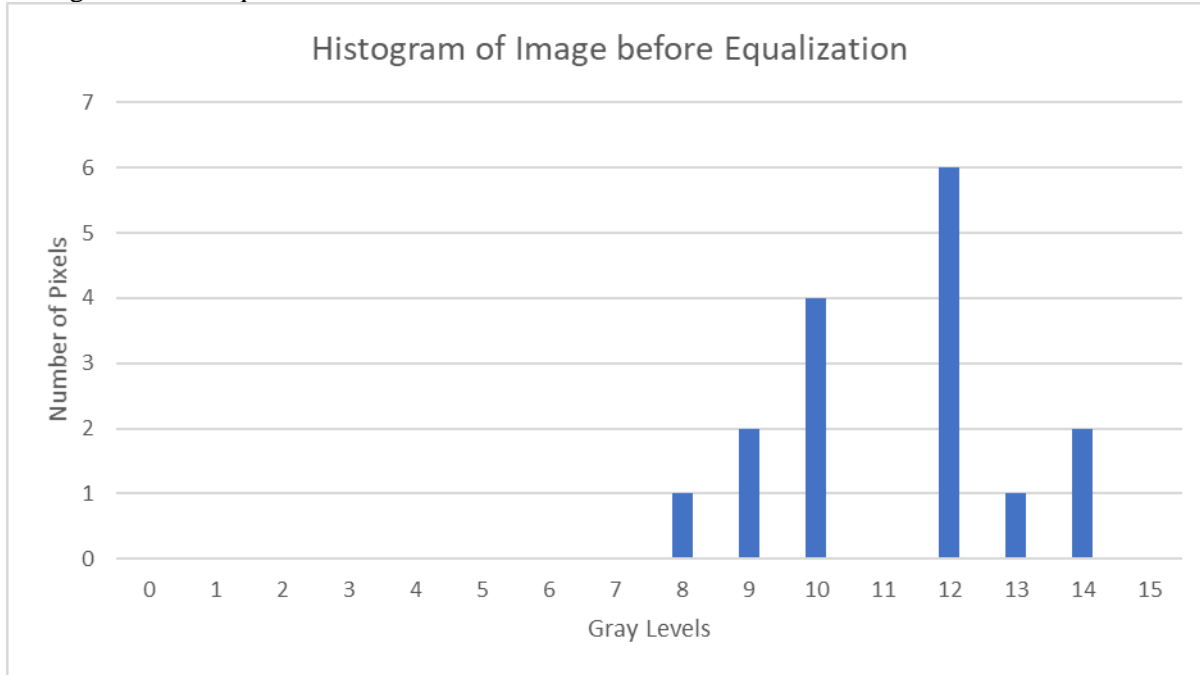
(i). Apply histogram equalization to the image by rounding image pixels to integers.

(ii). Sketch the histogram of the original image and histogram equalized image

10	12	8	9
10	12	12	14
12	13	10	9
14	12	10	12

Gray Level	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
No. of Pixels	0	0	0	0	0	0	0	0	1	2	4	0	6	1	2	0

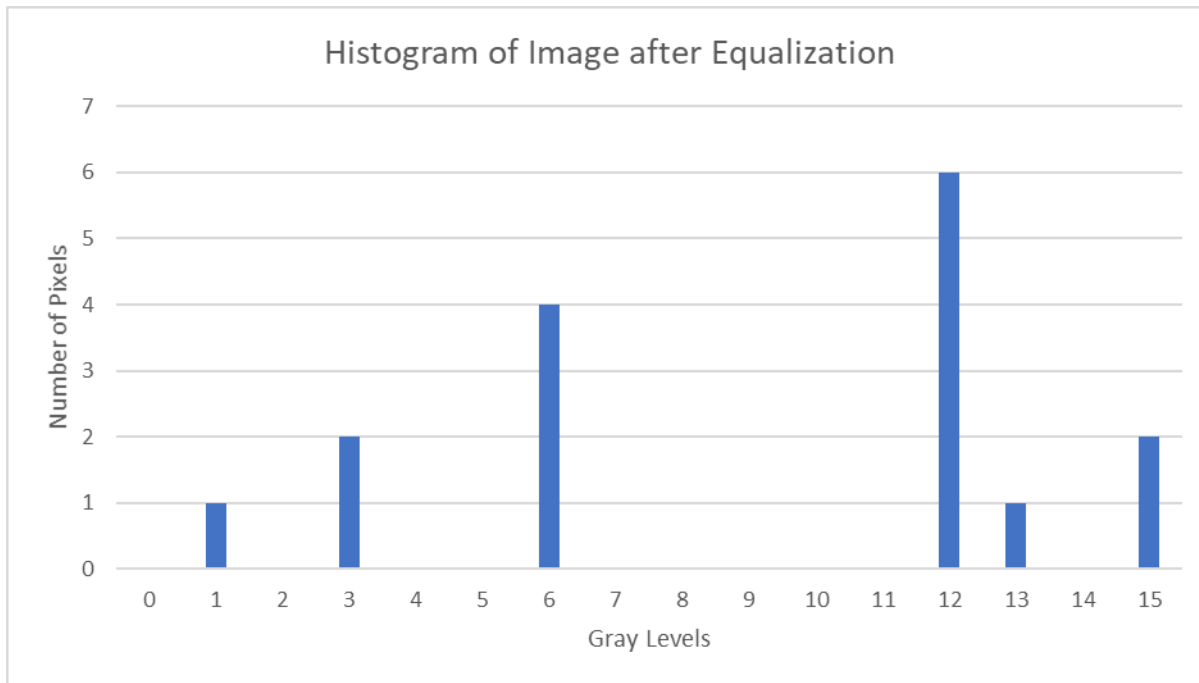
Histogram before equalization



Gray Level	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
No. of Pixels	0	0	0	0	0	0	0	0	1	2	4	0	6	1	2	0
$\sum_{j=0}^k n_j$	0	0	0	0	0	0	0	0	1	3	7	7	13	14	16	16
$s = \sum_{j=0}^k \frac{n_j}{n}$	0/16	0/16	0/16	0/16	0/16	0/16	0/16	0/16	1/16	3/16	7/16	7/16	13/16	14/16	16/16	16/16
	0	0	0	0	0	0	0	0	0.06	0.19	0.44	0.44	0.81	0.87	1	1
S * 15	0	0	0	0	0	0	0	0	0.9	2.85	6	6	12.15	13.05	15	15
	0	0	0	0	0	0	0	0	1	3	6	6	12	13	15	15

After Equalization

Gray Level	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
No. of Pixels	0	1	0	2	0	0	4	0	0	0	0	0	6	1	0	2



**(B). Determine the Convolution and Correlation between the following two images  $f(x, y)$  and  $g(x, y)$**

$$f(x, y) = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad g(x, y) = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

**Convolution**

0	0	0	0	0	0	0
0	0	0	1	2	3	0
0	0	1	6	8	6	0
0	1	6	16	16	12	0
0	4	12	18	15	8	3
0	7	8	16	12	14	6
0	0	0	0	7	8	9

**Correlation**

0	0	0	0	0	0	0
0	0	0	9	8	7	0
0	0	9	14	12	4	0
0	9	14	24	14	8	0
0	6	8	12	15	12	7
0	3	2	4	8	6	4
0	0	0	0	3	2	1

23. (A). Consider an image that uses a window of size  $5 \times 5$ . The gray level values inside the  $5 \times 5$  Sub-image are 15,17,15,17,16,10,8,9,18,15,16,12,14,11,15,14,15,11,100,15,14,13,12,12,17

What values could Assign to the central pixel of this sub-image by using following filter

- 1) A local averaging filter (mean)
- 2) A median filter
- 3) A mode filter
- 4) A max filter
- 5) A min filter

(i). Mean Filter	17.24
(ii). Median Filter	15
(iii). Mode Filter	15
(iv). Max Filter	100
(v). Min Filter	8

(B). Find the DFT transform of the image shown below:

$$f(x, y) = \begin{bmatrix} 0 & 1 & 2 & 1 \\ 1 & 2 & 3 & 2 \\ 2 & 3 & 4 & 3 \\ 1 & 2 & 3 & 2 \end{bmatrix}$$

## 2D Discrete Fourier Transform (DFT)

$$F[k, l] = \frac{1}{MN} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} f[m, n] e^{-j2\pi \left( \frac{k}{M}m + \frac{l}{N}n \right)}$$