

Lecture 23:

Calculus of Variations

Euler-Lagrange Equation

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0.$$

Using the Euler equation

For any variables

$$\int F(r, \theta, \theta') dr \quad \text{where} \quad \theta' = d\theta / dr,$$

$$\frac{d}{dr} \left(\frac{\partial F}{\partial \theta'} \right) - \frac{\partial F}{\partial \theta} = 0.$$

$$\int F(t, x, x') dt \quad \text{where} \quad x' = dx/dt,$$

$$\frac{d}{dt} \left(\frac{\partial F}{\partial x'} \right) - \frac{\partial F}{\partial x} = 0.$$

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0.$$

Imp.

1. The first derivative is with respect to the integration variable in the integral.
2. The partial derivatives are with respect to the other variables and its derivatives.

Summary : finding an extremum

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- Solutions to many physical problems → maximizing or minimizing some **parameter I** .

- Distance
- Time
- Surface Area

- **Parameter I** dependent on **selected path u** and domain of interest D .

$$I = \int_D F(x, u, u_x) dx$$

1. The parameter I to be maximized or minimized
2. Extremal → The solution path u that maximizes or minimizes I

Examples

- Geodesic: a curve for a shortest distance between two points along a surface

- 1) On a plane, a straight line
- 2) On a sphere, a circle with a center identical to the sphere
- 3) On an arbitrary surface → we can use the calculus of the variation.

Because the geodesic is the shortest value, finding the geodesic is relevant to finding the max. or min. values.

Geodesics

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A locally length-minimizing curve on a surface

Find the equation $y = y(x)$ of a curve joining points (x_1, y_1) and (x_2, y_2) in order to minimize the arc length

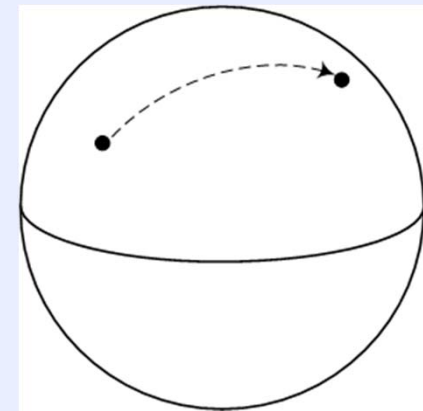
$$ds = \sqrt{dx^2 + dy^2} \quad \text{and} \quad dy = \frac{dy}{dx} dx = y'(x) dx$$

so

$$ds = \sqrt{1 + y'(x)^2} dx$$

$$L = \int_C ds = \int_C \sqrt{1 + y'(x)^2} dx$$

Geodesics minimize path length



Shortest Path Between Two Points

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- The problem of the shortest path between two points can be expressed as

$$L = \int_1^2 ds = \int_{x_1}^{x_2} \sqrt{1 + y'(x)^2} dx.$$

- The integrand contains our function

$$f(y, y', x) = \sqrt{1 + y'(x)^2}.$$

- The two partial derivatives in the Euler-Lagrange equation are:

$$\frac{\partial f}{\partial y} = 0 \quad \text{and} \quad \frac{\partial f}{\partial y'} = \frac{y'}{\sqrt{1 + y'^2}}.$$

- Thus, the Euler-Lagrange equation gives us

$$\frac{d}{dx} \frac{\partial f}{\partial y'} = \frac{d}{dx} \frac{y'}{\sqrt{1 + y'^2}} = 0.$$

- This says that $\frac{y'}{\sqrt{1 + y'^2}} = C$, or $y'^2 = C^2(1 + y'^2)$.

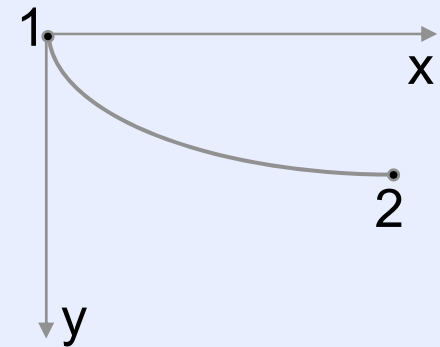
- The final result: $y'^2 = \text{constant}$ (call it m^2), so
 $y(x) = mx + b$. In other words, a straight line is the shortest path.

The Brachistochrone

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- Statement of the problem:

Given two points 1 and 2, with 1 higher above the ground, in what shape could we build a track for a frictionless roller-coaster so that a car released from point 1 would reach point 2 in the shortest possible time? See the figure, which takes point 1 as the origin, with y positive downward.



- Force on the particle is constant, ignore friction.
- Field is conservative. Total energy is constant.
- $KE = \frac{1}{2}mv^2$; $PE = -mgy$

The Brachistochrone

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➤ Solution:

- The time to travel from point 1 to 2 is $\tau = \int_1^2 \frac{ds}{v}$, where $v = \sqrt{2gy}$ from kinetic energy considerations.
- Since this depends on y , we will take y as the independent variable, hence

$$ds = \sqrt{dx^2 + dy^2} = \sqrt{x'(y)^2 + 1} dy.$$

- Our integral now becomes:
$$\tau = \frac{1}{\sqrt{2g}} \int_0^{y_2} \frac{\sqrt{x'^2 + 1}}{\sqrt{y}} dy.$$

- From the Euler-Lagrange equation:

$$\frac{\partial f}{\partial x} = \frac{d}{dy} \frac{\partial f}{\partial x'}.$$

Since we are using y as the independent variable, we swap x and y

- Since $f = \frac{\sqrt{x'^2 + 1}}{\sqrt{y}}$, clearly $\frac{\partial f}{\partial x} = 0$, and so $\frac{\partial f}{\partial x'} = \text{constant}$

- Evaluating this derivative and squaring it, we will have

$$\frac{x'^2}{y(x'^2 + 1)} = \text{constant} = \frac{1}{2a}$$

where the constant is renamed $1/2a$ for future convenience.

- Solving for x' we have: $x' = \sqrt{\frac{y}{2a - y}}$. Finally, to get x we integrate: $x = \int \sqrt{\frac{y}{2a - y}} dy$.

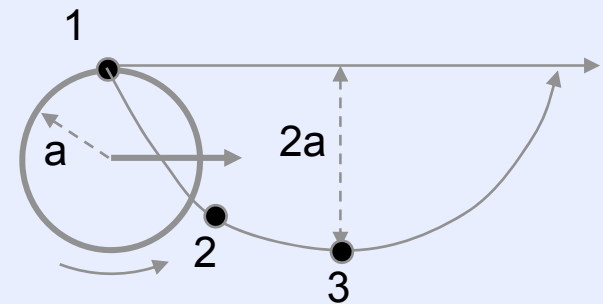
- Change of variable, by the substitution $y = a(1 - \cos \theta)$, which gives dy

- The two equations that give the path are then: $x = a(\theta - \sin \theta)$ in terms of θ .
 $y = a(1 - \cos \theta)$

$$x = a \int (1 - \cos \theta) d\theta = a(\theta - \sin \theta) + \text{const.}$$

➤ Solution, cont'd:

- *This curve is called a cycloid, and is a very special curve.*
- *it is the curve traced out by a wheel rolling (upside down) along the x axis.*
- *Constant of integration $\rightarrow 0$*
- *Another remarkable thing is that the time it takes for a cart to travel this path from 2 \rightarrow 3 is the same, no matter where 2 is placed, from 1 to 3! Thus, oscillations of the cart along that path are exactly isochronous (period perfectly independent of amplitude).*



Fermat's Principle

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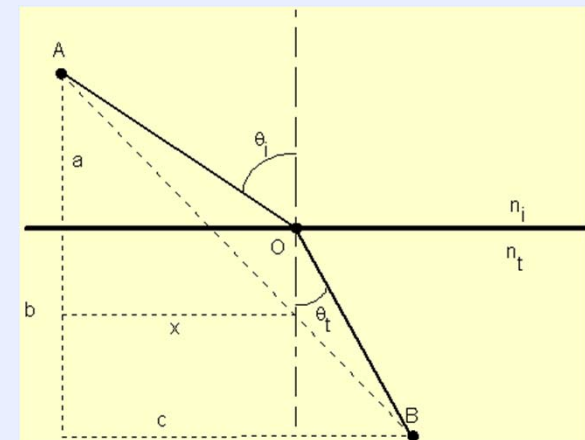
Refractive index of light in an inhomogeneous medium

$v = \frac{c}{n}$, where v = velocity in the medium and n = refractive index

$$\text{Time of travel} = T = \int_C dt = \int_C \frac{ds}{v} = \frac{1}{c} \int_C n ds$$

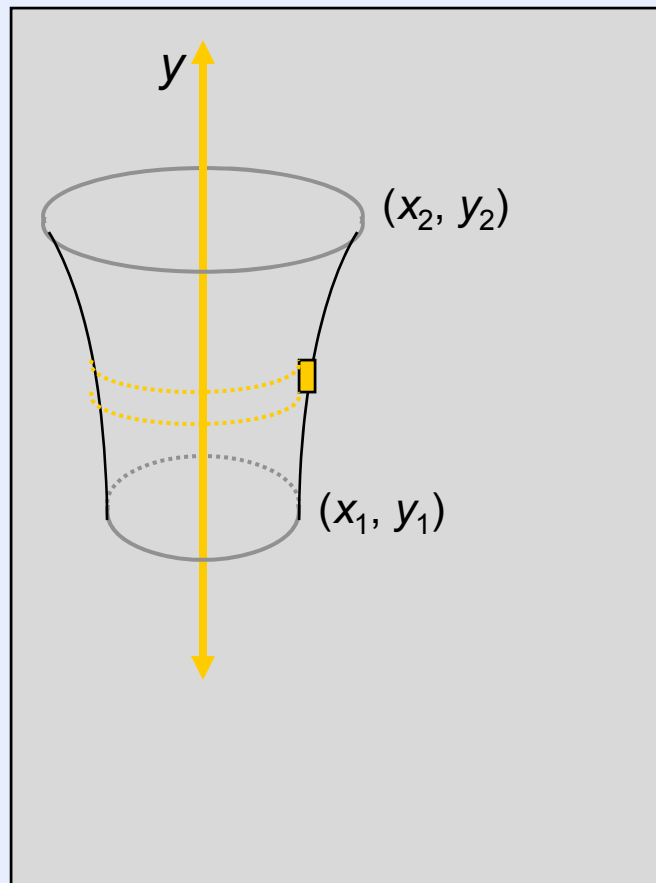
$$T = \int_C n(x, y) \sqrt{1 + y'(x)^2} dx$$

Fermat's principle states that the path must minimize the time of travel.



Soap Film – Find the solution

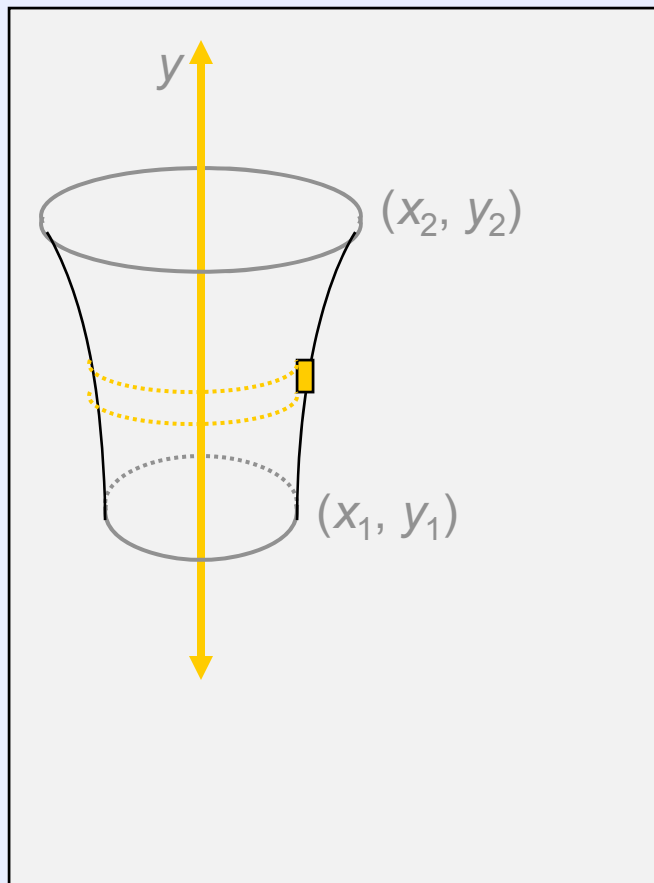
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- A soap film forms between two horizontal rings that share a common vertical axis. Find the curve that defines a film with the minimum surface area.

Soap Film

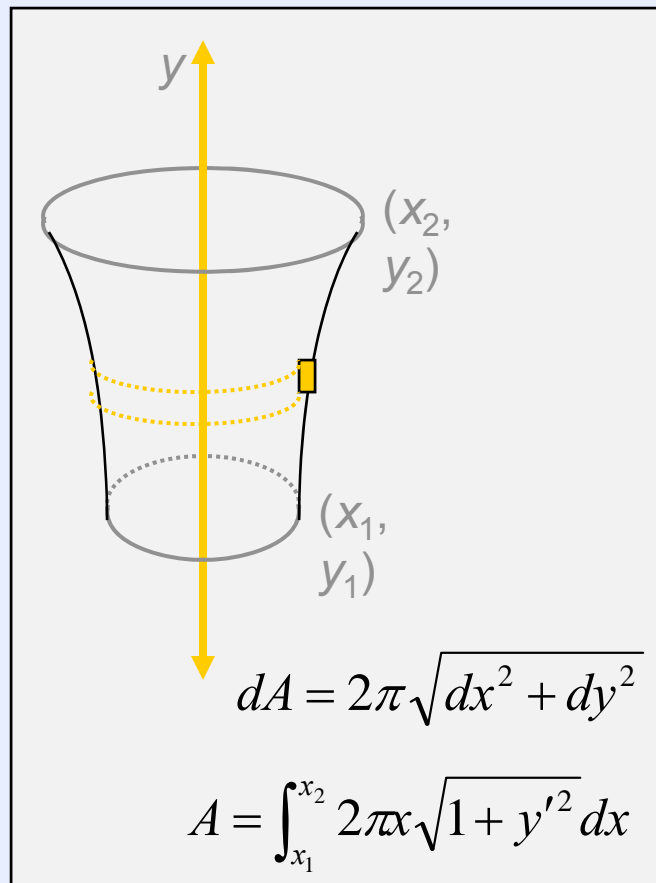
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- A soap film forms between two horizontal rings that share a common vertical axis. Find the curve that defines a film with the minimum surface area.
- Define a function y .
- The area A can be found as a surface of revolution.

Soap Film

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Euler Applied

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- The area is a functional of the curve.
 - *Define functional*
- Use Euler's equation to find a differential equation.
 - *Zero derivative implies constant*
 - *Select constant a*
- The solution is a hyperbolic function.

$$A = \int_{x_1}^{x_2} 2\pi x \sqrt{1 + y'^2} dx = \int_{x_1}^{x_2} f(y, y'; x) dx$$

$$f = 2\pi x \sqrt{1 + y'^2}$$

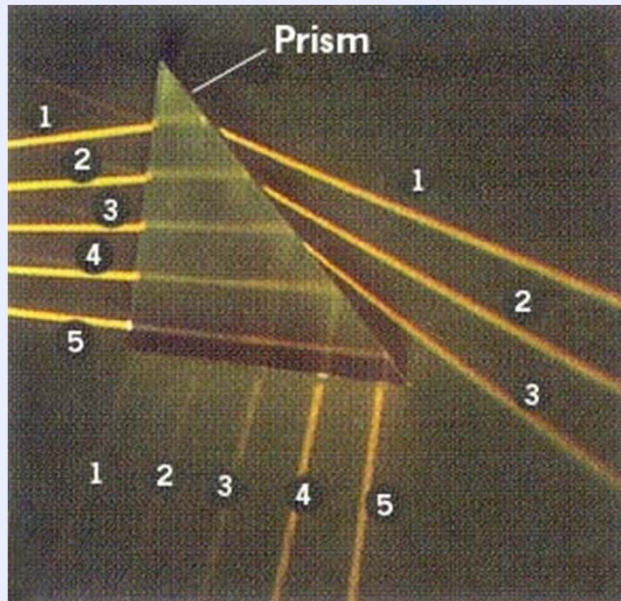
$$\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) = 0 - \frac{d}{dx} \left(\frac{-xy'}{\sqrt{1 + y'^2}} \right) = 0$$

$$\frac{xy'}{\sqrt{1 + y'^2}} = a$$

$$y' = \frac{a}{\sqrt{x^2 - a^2}} \quad x = a \cosh \left(\frac{y - b}{a} \right)$$

Least Action

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In optics, light is seen to take the minimum time path between two points (Fermat's principle).

What is Action?

- Action = $s = \int (KE - PE) dt$ [(from t_1 - t_2)]
- $KE - PE$ is known as the Lagrangian
- Commonly written as:
 - $L(x, v, t) = T(v) - V(x)$

Motion of a particle \rightarrow the path that minimizes the action.

Nature follows the path where s is smallest

Lagrangian

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Summary → Euler and Lagrange reformulated classical mechanics in terms of least action. The most important quantity is the **Lagrangian** which is simply the kinetic energy minus the potential energy.

Consider a object moving vertically in a gravitational field, then; Write the Lagrangian

Euler-Lagrange Equation

$$L = \frac{1}{2}m\dot{y}^2 - mgy$$

$$\dot{y} = \frac{dy}{dt}$$

Euler and Lagrange showed that the least action path obeys the Euler-Lagrange equation;

$$\frac{\partial L}{\partial y} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{y}} \right) = 0$$

Object in a gravitational field, this is

$$-mg - m \frac{d\dot{y}}{dt} = 0$$

$$\ddot{y} = a_y = -g$$

- The time integral of the Lagrangian is the *action*.
 - *Action is a functional*
 - *Extends to multiple coordinates*
- The Euler-Lagrange equations are equivalent to finding the least time for the action.
 - *Multiple coordinates give multiple equations*
- This is ***Hamilton's principle***.

$$S = \int_{t_1}^{t_2} L(q, \dot{q}; t) dt$$

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0$$

Of all the possible paths along which a dynamical system may move from one point to another within a specified time interval, the actual path followed is that which minimizes the time integral of the difference between the kinetic and potential energy.

- *Write down the Lagrangian function*
- *Apply Lagrange eqs. Of motion*

Simple Harmonic Oscillator

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$$T = \frac{1}{2} m \dot{x}^2$$

$$V = \frac{1}{2} k x^2$$

$$L = T - V = T = \frac{1}{2} m \dot{x}^2 - \frac{1}{2} k x^2$$

$$\frac{\partial L}{\partial \dot{x}} = m \dot{x}$$

$$\frac{\partial L}{\partial x} = -kx$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{x}} = m \ddot{x}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{x}} - \frac{\partial L}{\partial x} = m \ddot{x} + kx = 0$$

- The 1-D simple harmonic oscillator has one force.
 - $F = -kx$
 - *Conservative force*

- Select x as the generalized coordinate.
 - *T, V in terms of generalized coordinate and velocity*

- Use Lagrange's EOM.
 - *Usual Newtonian equation*