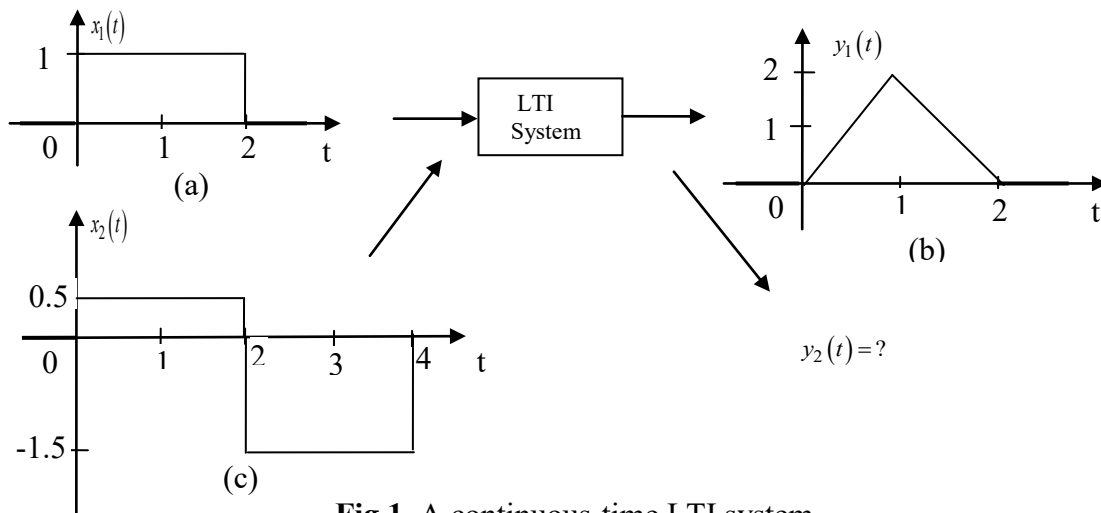


# Signals and Systems (CT 203)

Tutorial Sheet-05

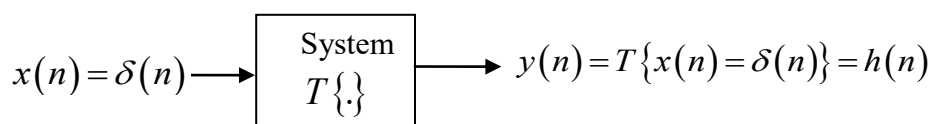
DA-IICT, Gandhinagar.

1. Consider a linear time-invariant (LTI) system whose response to the signal  $x_1(t)$  in Fig. 1a is the signal  $y_1(t)$  in Fig. 1b. Determine and sketch carefully response of the system to the input  $x_2(t)$  shown in Fig. 1c.



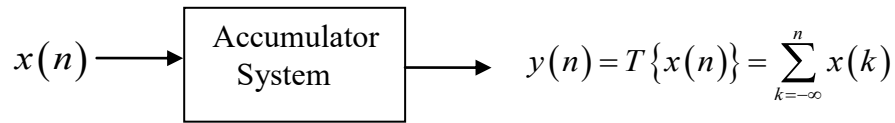
**Fig.1.** A continuous-time LTI system

2. Find the impulse response,  $h(n)$  of following systems

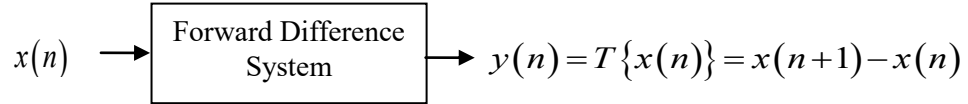


**Fig.2a.** Concept of Impulse Excitation

- Ideal Delay System,  $y(n) = T\{x(n)\} = x(n - n_d)$
- Moving Average System,  $y(n) = T\{x(n)\} = \frac{1}{N_1 + N_2 + 1} \sum_{k=-N_1}^{N_2} x(n - k)$
- Accumulator System,  $y(n) = T\{x(n)\} = \sum_{k=-\infty}^n x(k)$
- Forward Difference system,  $y(n) = T\{x(n)\} = x(n + 1) - x(n)$
- Backward Difference system,  $y(n) = T\{x(n)\} = x(n) - x(n - 1)$
- Linear interpolator system,
 
$$y(n) = T\{x(n)\} = x(n) + \frac{1}{2}\{x(n - 1) - x(n + 1)\}$$



**Fig.2b.** Ideal Delay System



**Fig.2c.** Moving Average (MA) System

3. Consider an input  $x(n]$  and a unit impulse response  $h(n]$  given by,

$$x(n) = \left(\frac{1}{2}\right)^{n-2} u(n-2)$$

$$h(n) = u(n+2)$$

Determine and plot output,  $y(n) = x(n) * h(n)$ .

4. Let  $x(t) = u(t-3) - u(t-5)$  and  $h(t) = e^{-3t}u(t)$ , then compute following,

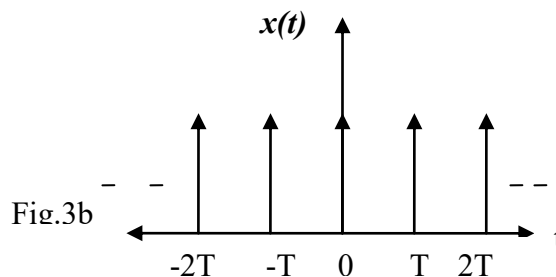
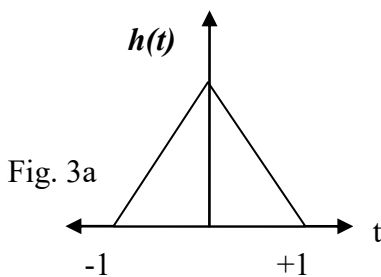
(a)  $y(t) = x(t) * h(t)$

(b)  $g(t) = \frac{d}{dt}[x(t)] * h(t)$

(c) How is  $g(t)$  related to  $y(t)$  ?

5. Consider a causal LTI system whose input  $x(n]$  and output  $y(n]$  are related by the difference equation.  $y(n) = \frac{1}{4}y(n-1) + x(n)$ . Determine  $y(n]$  if  $x(n) = \delta(n-1)$ .

6. Let  $h(t)$  be the triangular pulse shown in Fig. 3(a) and let  $x(t)$  be the impulse train shown in fig. 3(b)



Determine and sketch  $y(t) = x(t) * h(t)$  for the following values of T.

(a)  $T=4$

(b)  $T=2$

(c)  $T=3/2$

(d)  $T=1$