

Financial Econometrics

Chapter 4: Volatility

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Why volatility?

- Important for option pricing (see the Black–Scholes option pricing formula).
- Important for risk management. Volatility modeling provides a simple approach to calculating value at risk of a financial position.
- Important for investment in options and futures.
- Modeling the volatility of a time series can improve the efficiency in parameter estimation and the accuracy in interval forecast.

Volatility models

Univariate volatility models (a partial list)

- Autoregressive conditional heteroskedastic (ARCH) model of Engle (1982)
- The generalized ARCH (GARCH) model of Bollerslev (1986)
- The exponential GARCH (EGARCH) model of Nelson (1991)
- The stochastic volatility (SV) models of Melino and Turnbull (1990), Harvey, Ruiz, and Shephard (1994), and Jacquier, Polson, and Rossi (1994)

Characteristics of volatility

- ① There exist volatility clusters.
- ② Volatility evolves over time in a continuous manner—that is, volatility jumps are rare.
- ③ Volatility varies within some fixed range. Statistically speaking, this means that volatility is often stationary.
- ④ Volatility seems to react differently to a big price increase or a big price drop (asymmetry in volatility).

Conditional expectation

For two continuous random variables, X and Y , we say that the conditional distribution of Y given $X = x$ is

$$f_{Y|X}(y|x) = \frac{f(x, y)}{f_X(x)}$$

where $f(x, y)$ is the joint distribution of X and Y and $f_X(x)$ is the marginal distribution of X .

Remark

- (i) $f_{Y|X}(y|x)$ is a function of x and possibly a different probability distribution for each x .*
- (ii) When we wish to describe the entire family of distribution we use the phrase “the distribution of $Y | X$ ”.*
- (iii) If X and Y are independent,*

$$f_{Y|X}(y|x) = f_Y(y)$$

Conditional expectation

A conditional mean is the mean of the conditional distribution and is defined by

$$E[Y|X = x] = \begin{cases} \int_y y f_{Y|X}(y|x) dy & \text{if } y \text{ is continuous} \\ \sum_y y f_{Y|X}(y|x) & \text{if } y \text{ is discrete} \end{cases}$$

Remark

(i) Note that

$$E[Y|X = x] = E[Y]$$

if X and Y are independent.

(ii) $E(Y | X)$ is a random variable whose value depends on X .

(i) Law of Iterated Expectations

$$E[Y] = E[E[Y|X]]$$

(ii)

$$E[g(Y)f(X)|X] = f(X)E[g(Y)|X]$$

Structure of volatility models

- Main motivation: The return data is either serially uncorrelated or with minor lower order serial correlations, but it is dependent.
- If r_t is *iid*,

$$\begin{aligned} & E[g(r_t) - Eg(r_t)][g(r_{t-h}) - Eg(r_{t-h})] \\ = & E[g(r_t) - Eg(r_t)] \times E[g(r_{t-h}) - Eg(r_{t-h})] = 0 \end{aligned}$$

for any function $g(\cdot)$ and $h > 0$. But if r_t is not *iid*, the first equality does not hold.

Structure of volatility models

- If r_t is just serially uncorrelated, we have

$$E[r_t - E(r_t)][r_{t-h} - E(r_{t-h})] = 0$$

for any $h > 0$.

- This does not imply $E[g(r_t) - Eg(r_t)][g(r_{t-h}) - Eg(r_{t-h})] = 0$ for any arbitrary function $g(\cdot)$.

Structure of volatility models

- Let

$$\mu_t = E(r_t \mid \mathfrak{F}_{t-1}), \sigma_t^2 = \text{Var}(r_t \mid \mathfrak{F}_{t-1}) = E[(r_t - \mu_t)^2 \mid \mathfrak{F}_{t-1}],$$

where \mathfrak{F}_{t-1} denotes the information set available at time $t - 1$.

- Typically, \mathfrak{F}_{t-1} consists of all linear functions of the past returns. Thus, we may consider the conditional variance as

$$E[(r_t - \mu_t)^2 \mid \mathfrak{F}_{t-1}] = E[(r_t - \mu_t)^2 \mid r_{t-1}, r_{t-2}, \dots].$$

Structure of volatility models

- Assume

$$r_t = \mu_t + a_t, \quad \mu_t = \phi_0 + \sum_{i=1}^p \phi_i r_{t-i} - \sum_{i=1}^q \theta_i a_{t-i}.$$

(r_t follows ARMA(p,q)). Then,

$$\sigma_t^2 = \text{Var}(a_t \mid \mathfrak{F}_{t-1}) \text{ (conditional variance of } a_t \text{)}.$$

The conditional heteroskedastic models are concerned with the evolution of σ_t^2 .

Structure of volatility models

- Two general categories of the conditional heteroskedastic models
 - ① An exact function to govern the evolution of σ_t^2 (ARCH, GARCH).
 - ② Stochastic equation to describe σ_t^2 (stochastic volatility model).
- Assume that the model for the conditional mean is given. Then, a_t is referred to as the shock or mean-corrected return of an asset return at time t .

The ARCH model

- The ARCH model:

$$a_t = \sigma_t \epsilon_t, \sigma_t^2 = \alpha_0 + \alpha_1 a_{t-1}^2 + \dots + \alpha_m a_{t-m}^2.$$

- 1 ϵ_t is a sequence of iid r.v. with mean 0 and variance 1.
- 2 $\alpha_0 > 0$ and $\alpha_i \geq 0$ for all $i > 0$.
- 3 The coefficients α_i satisfy some regularity conditions to ensure that the unconditional variance of a_t is finite.
- 4 ϵ_t is often assumed to follow the standard normal or a standardized Student-t distribution.

The ARCH model

- Large past squared shocks a_{t-i}^2 imply a large conditional variance σ_t^2 . This means that, under the ARCH framework, large shocks tend to be followed by another large shock.

The ARCH model

Properties of the ARCH models

Consider the ARCH(1) model

$$a_t = \sigma_t \epsilon_t, \quad \sigma_t^2 = \alpha_0 + \alpha_1 a_{t-1}^2,$$

where $\alpha_0 > 0$ and $\alpha_1 \geq 0$.

- $E(a_t) = E[E(a_t \mid \mathfrak{F}_{t-1})] = E[\sigma_t E(\epsilon_t)] = 0$.
- For $h \geq 1$, $E(a_{t+h} a_t) = E[E(a_{t+h} a_t \mid \mathfrak{F}_{t+h-1})] = E[a_t \sigma_{t+h} E(\epsilon_{t+h})] = 0$.

The ARCH model

Properties of the ARCH models

- Assume that $Var(a_t)$ does not change over time. Since

$$\begin{aligned} & Var(a_t) \\ = & E(a_t^2) \\ = & E[E(a_t^2 \mid \mathfrak{F}_{t-1})] \\ = & E[\sigma_t^2 E(\epsilon_t^2 \mid \mathfrak{F}_{t-1})] \\ = & E(\sigma_t^2) \\ = & \alpha_o + \alpha_1 E(a_{t-1}^2) \\ = & \alpha_o + \alpha_1 Var(a_{t-1}), \end{aligned}$$

$$Var(a_t) = \frac{\alpha_o}{1 - \alpha_1}.$$

We also require that $0 \leq \alpha_1 < 1$ for $0 < Var(a_t) < \infty$.

The ARCH model

Properties of the ARCH models

- If ϵ_t follows a normal distribution and if $E(a_t^4)$ does not change over time,

$$E(a_t^4) = \frac{3\alpha_o^2(1 + \alpha_1)}{(1 - \alpha_1)(1 - 3\alpha_1^2)}.$$

Thus we should have $0 \leq \alpha_1^2 < \frac{1}{3}$ for $0 < E(a_t^4) < \infty$. The kurtosis of a_t is

$$\frac{E(a_t^4)}{[Var(a_t)]^2} = \frac{3\alpha_o^2(1 + \alpha_1)}{(1 - \alpha_1)(1 - 3\alpha_1^2)} \times \frac{(1 - \alpha_1)^2}{\alpha_o^2} = 3 \frac{1 - \alpha_1^2}{1 - 3\alpha_1^2} > 3,$$

implying that the tail distribution of a_t is heavier than that of a normal distribution.

The ARCH model

Weakness of ARCH models

- Weakness

- 1 The model assumes that positive and negative shocks have the same effects on volatility.
- 2 The ARCH model is rather restrictive. For instance, α_1^2 of an ARCH(1) model must be in the interval $[0, 1/3]$ if the series is to have a finite and positive fourth moment.
- 3 The ARCH model is not structural model for the source of variations of a financial time series.
- 4 ARCH models are likely to overpredict the volatility because they respond slowly to large isolated shocks to the return series.

The ARCH model

Building an ARCH model

- Steps to follow

- ① Fit an ARMA model and obtain ARMA residual a_t .
- ② Select the ARCH order.
- ③ Estimate the selected ARCH model by the maximum likelihood estimation.
- ④ Model checking: The standardized shocks $\frac{a_t}{\sigma_t}$ are iid random variables. Thus, use Q-stat of standardized residuals $\frac{a_t}{\sigma_t}$.

The ARCH model

Building an ARCH model

- Order Determination

Let $\eta_t = a_t^2 - \sigma_t^2$. Then,

$$a_t^2 = \alpha_0 + \alpha_1 a_{t-1}^2 + \dots + \alpha_m a_{t-m}^2 + \eta_t,$$

where η_t is a white noise process. Thus, we may use information criteria or PACF to determine the order of the ARCH process.

The ARCH model

Building an ARCH model

- Maximum likelihood estimation

- Assume $\epsilon_t \sim iidN(0, 1)$. Then, the joint pdf of a_1, \dots, a_T is (recall: $f(x, y) = f(x | y)f(y)$)

$$\begin{aligned} & f(a_1, \dots, a_T) \\ &= f(a_T | \mathfrak{F}_{T-1})f(a_{T-1} | \mathfrak{F}_{T-2}) \dots f(a_{m+1} | \mathfrak{F}_m)f(a_1, \dots, a_m). \end{aligned}$$

- Ignoring the joint pdf of a_1, \dots, a_m , the conditional (on a_1, \dots, a_m) pdf of a_{m+1}, \dots, a_T is

$$\prod_{t=m+1}^T \frac{1}{\sqrt{2\pi\sigma_t^2}} \exp\left(-\frac{a_t^2}{2\sigma_t^2}\right).$$

The ARCH model

Building an ARCH model

- The conditional log-likelihood function is

$$\begin{aligned} l(a_{m+1}, \dots, a_T \mid a_1, \dots, a_m, \alpha_0, \dots, \alpha_m) \\ = \sum_{t=m+1}^T \left(-\frac{1}{2} \ln(2\pi) - \frac{1}{2} \ln(\sigma_t^2) - \frac{a_t^2}{2\sigma_t^2} \right). \end{aligned}$$

- The maximum likelihood estimators of $\alpha_0, \dots, \alpha_m$ maximize this function. These are the parameter values that are most probable given observations.

The ARCH model

Building an ARCH model

- We may use t-distribution instead of normal. The degree of freedom is either specified or estimated along with other parameters.

The ARCH model

Forecasting

- Consider an ARCH(m) model

$$\sigma_t^2 = \alpha_o + \alpha_1 a_{t-1}^2 + \dots + \alpha_m a_{t-m}^2.$$

The 1-step ahead forecast of σ_t^2 is

$$\sigma_t^2(1) = \alpha_o + \alpha_1 a_t^2 + \dots + \alpha_m a_{t+1-m}^2.$$

The 2-step ahead forecast is

$$\sigma_t^2(2) = \alpha_o + \alpha_1 a_t^2(1) + \dots + \alpha_m a_{t+2-m}^2.$$

The l -step ahead forecast is defined similarly.

- The GARCH model

$$\begin{aligned}a_t &= \sigma_t \epsilon_t, \\ \sigma_t^2 &= \alpha_0 + \alpha_1 a_{t-1}^2 + \dots + \alpha_m a_{t-m}^2 + \beta_1 \sigma_{t-1}^2 + \dots + \beta_s \sigma_{t-s}^2,\end{aligned}$$

where $\alpha_0 > 0$, $\alpha_i \geq 0$, $\beta_j \geq 0$, and $\sum_{i=1}^{\max(m,s)} (\alpha_i + \beta_i) < 1$ (This ensures that the unconditional variance of a_t is finite and positive).

The GARCH model

- Let $\eta_t = a_t^2 - \sigma_t^2$ so that $\sigma_t^2 = a_t^2 - \eta_t$. Then, the GARCH model is rewritten as

$$a_t^2 = \alpha_o + \sum_{i=1}^{\max(m,s)} (\alpha_i + \beta_i) a_{t-i}^2 + \eta_t - \sum_{j=1}^s \beta_j \eta_{t-j}.$$

The GARCH model

Example

Assume $m=1$ and $s=2$. Let $\eta_t = a_t^2 - \sigma_t^2$ so that $\sigma_t^2 = a_t^2 - \eta_t$. Then, the GARCH model is rewritten as

$$\sigma_t^2 = \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 \sigma_{t-1}^2 + \beta_2 \sigma_{t-2}^2$$

\Rightarrow

$$a_t^2 - \eta_t = \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 (a_{t-1}^2 - \eta_{t-1}) + \beta_2 (a_{t-2}^2 - \eta_{t-2})$$

\Rightarrow

$$a_t^2 = \alpha_o + (\alpha_1 + \beta_1) a_{t-1}^2 + \beta_1 a_{t-2}^2 + \eta_t - \beta_1 \eta_{t-1} - \beta_2 \eta_{t-2}.$$

The GARCH model

- This is an ARMA model for a_t^2 .
- Zero-mean

$$\begin{aligned} E(\eta_t) &= E(a_t^2 - \sigma_t^2) = E(E(a_t^2 - \sigma_t^2 \mid \mathfrak{F}_{t-1})) \\ &= E(\sigma_t^2 E(\epsilon_t^2 \mid \mathfrak{F}_{t-1})) - E(\sigma_t^2) = 0 \end{aligned}$$

- Constant variance

$$\begin{aligned} E(\eta_t^2) &= E(a_t^2 - \sigma_t^2)^2 = E(E(a_t^2 - \sigma_t^2)^2 \mid \mathfrak{F}_{t-1})) \\ &= E(E(a_t^4 - 2a_t^2\sigma_t^2 + \sigma_t^4 \mid \mathfrak{F}_{t-1})) \\ &= E(E(a_t^4 \mid \mathfrak{F}_{t-1})) - E(E(\sigma_t^4 \mid \mathfrak{F}_{t-1})) \\ &= E(\sigma_t^4 E(\epsilon_t^4)) - E(\sigma_t^4) \\ &= 2E(\sigma_t^4) \\ &= m \text{ (a constant), if } E(\sigma_t^4) \text{ is a constant.} \end{aligned}$$

The GARCH model

- For $h \geq 1$,

$$\begin{aligned} E(\eta_{t+h}\eta_t) &= E \left[E((a_{t+h}^2 - \sigma_{t+h}^2)(a_t^2 - \sigma_t^2) \mid \mathfrak{F}_{t+h-1}) \right] \\ &= E \left[(a_t^2 - \sigma_t^2) E((a_{t+h}^2 - \sigma_{t+h}^2) \mid \mathfrak{F}_{t+h-1}) \right]. \end{aligned}$$

But

$$\begin{aligned} E((a_{t+h}^2 - \sigma_{t+h}^2) \mid \mathfrak{F}_{t+h-1}) &= E((\sigma_{t+h}^2 \epsilon_{t+h}^2 - \sigma_{t+h}^2) \mid \mathfrak{F}_{t+h-1}) \\ &= \sigma_{t+h}^2 E(\epsilon_{t+h}^2) - \sigma_{t+h}^2 \\ &= 0, \end{aligned}$$

which gives $E(\eta_{t+h}\eta_t) = 0$.

The GARCH model

- Hence,

$$E(a_t^2) = \frac{\alpha_o}{1 - \sum_{i=1}^{\max(m,s)} (\alpha_i + \beta_i)}.$$

- Consider the GARCH(1,1) model

$$\sigma_t^2 = \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 \sigma_{t-1}^2, \quad 0 \leq \alpha_1, \beta_1 \leq 1, \quad (\alpha_1 + \beta_1) < 1.$$

- 1 A large a_{t-1}^2 or σ_{t-1}^2 gives rise to a large σ_t^2 . (volatility clustering)
- 2 The kurtosis of a_t is greater than 3.
- 3 Order for the GARCH model can be determined by using information criteria for the ARMA model of a_t^2 .

The GARCH model

- Hence,

$$E(a_t^2) = \frac{\alpha_o}{1 - \sum_{i=1}^{\max(m,s)} (\alpha_i + \beta_i)}.$$

- Consider the GARCH(1,1) model

$$\sigma_t^2 = \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 \sigma_{t-1}^2, \quad 0 \leq \alpha_1, \beta_1 \leq 1, \quad (\alpha_1 + \beta_1) < 1.$$

- 1 A large a_{t-1}^2 or σ_{t-1}^2 gives rise to a large σ_t^2 . (volatility clustering)
- 2 The excess kurtosis of a_t is greater than 3.
- 3 Order for the GARCH model can be determined by using information criteria for the ARMA model of a_t^2 .

The GARCH model

Forecasting

- Consider the GARCH(1,1) model

$$\sigma_t^2 = \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 \sigma_{t-1}^2.$$

The 1-step forecast is

$$\sigma_t^2(1) = E(\sigma_{t+1}^2 \mid \mathfrak{F}_t) = \alpha_o + \alpha_1 a_t^2 + \beta_1 \sigma_t^2.$$

The GARCH model

Forecasting

- For multi-step forecast, write

$$\sigma_{t+1}^2 = \alpha_o + (\alpha_1 + \beta_1) \sigma_t^2 + \alpha_1 \sigma_t^2 (\epsilon_t^2 - 1).$$

Then, since $E(\sigma_{t+1}^2 (\epsilon_{t+1}^2 - 1) | \mathcal{F}_t) = \sigma_{t+1}^2 E((\epsilon_{t+1}^2 - 1) | \mathcal{F}_t) = 0$,

$$\begin{aligned} \sigma_t^2(2) &= E(\sigma_{t+2}^2 | \mathfrak{F}_t) \\ &= E(\alpha_o + (\alpha_1 + \beta_1) \sigma_{t+1}^2 + \alpha_1 \sigma_{t+1}^2 (\epsilon_{t+1}^2 - 1) | \mathfrak{F}_t) \\ &= \alpha_o + (\alpha_1 + \beta_1) \sigma_t^2(1). \end{aligned}$$

In general,

$$\sigma_t^2(l) = \alpha_o + (\alpha_1 + \beta_1) \sigma_t^2(l-1).$$

The integrated GARCH model

- The impact of past squared shocks $\eta_{t-i} = a_{t-i}^2 - \sigma_{t-i}^2$ for $i > 0$ on a_t^2 is persistent.
- The IGARCH(1,1) model

$$\begin{aligned}a_t &= \sigma_t \epsilon_t, \\ \sigma_t^2 &= \alpha_o + \beta_1 \sigma_{t-1}^2 + (1 - \beta_1) a_{t-1}^2, \quad 0 < \beta_1 < 1.\end{aligned}$$

- This can be written as $a_t^2 = \alpha_o + a_{t-1}^2 + \eta_t - \beta_1 \eta_{t-1}$.¹
- The IGARCH phenomenon (persistence of volatility) might be caused by occasional level shifts in volatility.

1

$$\begin{aligned}\sigma_t^2 &= \alpha_o + (1 - \beta_1) a_{t-1}^2 + \beta_1 \sigma_{t-1}^2 \\ \Rightarrow \\ a_t^2 - \eta_t &= \alpha_o + (1 - \beta_1) a_{t-1}^2 + \beta_1 (a_{t-1}^2 - \eta_{t-1}) \\ \Rightarrow \\ a_t^2 &= \alpha_o + a_{t-1}^2 + \eta_t - \beta_1 \eta_{t-1}.\end{aligned}$$

The GARCH-M model

- The GARCH-M model assumes that the return of a security may depend on its volatility.
- The GARCH(1,1)-M model

$$\begin{aligned}r_t &= \mu + c\sigma_t^2 + a_t, \\a_t &= \sigma_t \epsilon_t, \\ \sigma_t^2 &= \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 \sigma_{t-1}^2, \quad 0 < \beta_1 < 1.\end{aligned}$$

c : risk-premium parameter

r_t is serially correlated.

The exponential GARCH model

- The exponential GARCH model allows for asymmetric effects between positive and negative asset returns.
- An EGARCH(m, s) model can be written as

$$\begin{aligned}a_t &= \sigma_t \epsilon_t, \\ \ln(\sigma_t^2) &= \alpha_0 + \frac{1 + \beta_1 B + \dots + \beta_s B^s}{1 - \alpha_1 B - \dots - \alpha_m B^m} g(\epsilon_{t-1}), \\ g(\epsilon_t) &= \theta \epsilon_t + \gamma [|\epsilon_t| - E(|\epsilon_t|)].\end{aligned}$$

Here $g(\epsilon_t)$ is asymmetric with respect to ϵ_t .

The exponential GARCH model

Example Let $m = 1$ and $s = 0$. Assume ϵ_t are iid standard normal. Then,

$$(1 - \alpha B) \ln(\sigma_t^2) = (1 - \alpha)\alpha_0 + g(\epsilon_{t-1}).$$

In this case, $E(|\epsilon_t|) = \sqrt{2/\pi}$ and

$$\begin{aligned} & (1 - \alpha B) \ln(\sigma_t^2) \\ = & \begin{cases} ((1 - \alpha)\alpha_0 - \sqrt{2/\pi}\gamma) + (\theta + \gamma)\epsilon_{t-1}, & \epsilon_{t-1} \geq 0 \\ ((1 - \alpha)\alpha_0 - \sqrt{2/\pi}\gamma) + (\theta - \gamma)\epsilon_{t-1}, & \epsilon_{t-1} < 0 \end{cases} \end{aligned}$$

The stochastic volatility model

- The model:

$$a_t = \sigma_t \epsilon_t, \quad (1 - \alpha_1 B - \dots - \alpha_m B^m) \ln(\sigma_t^2) = \alpha_o + v_t,$$

where $\epsilon_t \sim iid N(0, 1)$, $v_t \sim iid N(0, \sigma_v^2)$, ϵ_t and v_t are independent, α_o is a constant, and all zeros of the polynomial $1 - \alpha_1 z - \dots - \alpha_m z^m = 0$ are greater than one in modulus.

The stochastic volatility model

- Introducing the innovation v_t substantially increases the flexibility of the model in describing the evolution of σ_t^2 , but it also increases the difficulty in parameter estimation.
- Quasi-likelihood or Monte Carlo method can be used to estimate the model.

- Brownian motion** A Brownian motion or Wiener process is a stochastic process $[W(t); t \geq 0]$ with the following three properties
- (i) $P[W(0) = 0] = 1$.
 - (ii) If $0 \leq t_0 \leq t_1 \leq \dots \leq t_k$,

$$\begin{aligned} & P[W(t_i) - W(t_{i-1}) \in H_i, i = 1, \dots, k] \\ &= \prod_{i=1}^k P[W(t_i) - W(t_{i-1}) \in H_i] \end{aligned}$$

$(W(t_k) - W(t_{k-1}))$ is not affected by
 $W(t_1) - W(t_0), \dots, W(t_{k-1}) - W(t_{k-2}).$

$$(iii) P[W(t) - W(s) \in H] = \frac{1}{\sqrt{2\pi(t-s)}} \int_H e^{-\frac{x^2}{2(t-s)}} dx.$$

- The model we have considered is

$$r_t = \mu_t + \sigma_t \epsilon_t,$$

where μ_t and σ_t are conditional mean and variance, respectively.

- Its continuous-time version is

$$dp(t) = \mu(t)dt + \sigma(t)dW(t). \quad t \in [0, T].$$

- For small $\Delta > 0$,

$$r(t, \Delta) \equiv p(t) - p(t - \Delta) \simeq \mu(t - \Delta)\Delta + \sigma(t - \Delta)\Delta W(t),$$

where $\Delta W(t) \equiv W(t) - W(t - \Delta) \sim N(0, \Delta)$.

- In addition,

$$r^2(t, \Delta) = \mu^2(t - \Delta)\Delta^2 + 2\mu(t - \Delta)\Delta\sigma(t - \Delta)\Delta W(t) + \sigma^2(t - \Delta) [\Delta W(t)]^2.$$

- The conditional variance of $r(t, \Delta)$ is

$$\text{Var} [r(t, \Delta) \mid \mathfrak{F}_{t-\Delta}] \simeq E [r^2(t, \Delta) \mid \mathfrak{F}_{t-\Delta}] \simeq \sigma^2(t - \Delta)\Delta$$

- Thus

$$\begin{aligned} RV(t, \Delta) &= \sum_{j=1}^{1/\Delta} E \left[r^2(t - 1 + j\Delta, \Delta) \mid \mathfrak{F}_{t-1+(j-1)\Delta} \right] \\ &\simeq \sum_{j=1}^{1/\Delta} \sigma^2(t - 1 + (j - 1)\Delta)\Delta \simeq \int_{t-1}^t \sigma^2(s) ds. \end{aligned}$$

- As $\Delta \rightarrow 0$,

$$RV(t, \Delta) \xrightarrow{p} \int_{t-1}^t \sigma^2(s) ds.$$

- It has been known that $RV(t, \Delta)$ has a long memory. It is well-fitted by ARFIMA (autoregressive fractionally integrated moving average) model.

- No ARCH structure is allowed for the daily returns.
- This approach is applied to high-frequency data. For example, estimate the daily volatility by using intraday data having 5 minutes intervals.

Empirical examples

The data used are the monthly log returns of IBM stock and S&P 500 index from January 1926 to December 1999.

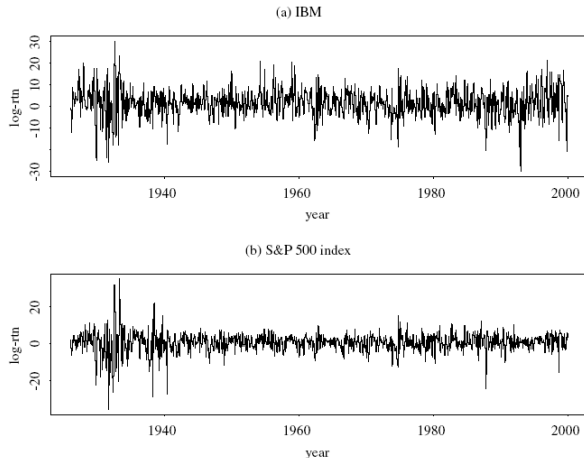


Figure 3.11. Time plots of monthly log returns for IBM stock and S&P 500 index. The sample period is from January 1926 to December 1999. The returns are in percentages and include

- GARCH(1,1) modelling of the IBM stock returns

$$\begin{aligned}r_t &= 1.23 + 0.099r_{t-1} + a_t, \quad a_t = \sigma_t \epsilon_t \\ \sigma_t^2 &= 3.206 + 0.103a_{t-1}^2 + 0.825\sigma_{t-1}^2.\end{aligned}$$

All the coefficient estimates are statistically significant.

- Using the standardized residuals $\tilde{a}_t = a_t / \sigma_t$, we obtain $Q(10) = 7.82(0.553)$ and $Q(20) = 21.22(0.325)$, where p value is in parentheses. There are no serial correlations in the residuals of the mean equation.

- The Ljung–Box statistics of the \tilde{a}_t^2 series show $Q(10) = 2.89(0.98)$ and $Q(20) = 7.26(0.99)$, indicating that the standardized residuals have no conditional heteroskedasticity.

- To study the summer effect on stock volatility of an asset, define an indicator variable

$$u_t = \begin{cases} 1 & \text{if } t \text{ is June, July, or August} \\ 0 & \text{Otherwise} \end{cases}$$

and modify the volatility equation as

$$\sigma_t^2 = \alpha_o + \alpha_1 a_{t-1}^2 + \beta_1 \sigma_{t-1}^2 + u_t(\alpha_{o0} + \alpha_{10} a_{t-1}^2 + \beta_{10} \sigma_{t-1}^2).$$

- The coefficients α_{10} and β_{10} are statistically insignificant. Thus, the estimation results are:

$$\begin{aligned}r_t &= 1.21 + 0.099r_{t-1} + a_t, \quad a_t = \sigma_t\epsilon_t \\ \sigma_t^2 &= 4.539 + 0.113a_{t-1}^2 + 0.816\sigma_{t-1}^2 - 5.154u_t.\end{aligned}$$

The summer effect on stock volatility is statistically significant at the 1% level. Furthermore, the volatility of IBM monthly log stock returns is indeed lower during the summer.

- For the monthly log return series of S&P 500 index, fit a GARCH(1,1) model

$$r_t = 0.609 + a_t, \quad a_t = \sigma_t \epsilon_t, \quad \sigma_t^2 = 0.717 + 0.147a_{t-1}^2 + 0.839\sigma_{t-1}^2.$$

Based on the standardized residuals $\tilde{a}_t = a_t / \sigma_t$, we have $Q(10) = 11.51(0.32)$ and $Q(20) = 23.71(0.26)$, where the number in parentheses denotes p value. For the \tilde{a}_t^2 series, we have $Q(10) = 9.42(0.49)$ and $Q(20) = 13.01(0.88)$. Therefore, the model seems adequate at the 5% significance level.