Nonlinear Dynamics and Chaos I. Problem set 5

1. Consider a planar Hamiltonian system

$$\dot{x} = \frac{\partial H(x,y)}{\partial y} + f_1(x,y),$$

$$\dot{y} = -\frac{\partial H(x,y)}{\partial x} + f_2(x,y),$$

where the twice continuously differentiable function H(x,y) is the Hamiltonian associated with the system (say, the energy in classical mechanics, or the stream function in fluid mechanics), and the continuously differentiable $\mathbf{f} = (f_1, f_2)$ is a dissipative term (say, damping in classical mechanics, or compressible terms in fluid mechanics). Assume that $\nabla \cdot \mathbf{f} \neq 0$ for all $(x,y) \in \mathbb{R}^2$. (Linear damping, for instance has this property.)

Show that the above system can have no limit cycles.

2. (Accuracy of averaging) Show that on times scales of $\mathcal{O}(1/\epsilon)$, a solution $\mathbf{x}(t)$ with $\mathbf{x}(0) = \mathbf{x}_0$ of the dynamical system

$$\dot{\mathbf{x}} = \epsilon \mathbf{f}(\mathbf{x}, t, \epsilon), \qquad \mathbf{x} \in \mathbb{R}^n,$$
 (1)

(ϵ is a small parameter and \mathbf{f} is a smooth function that is T-periodic in time) remains $\mathcal{O}(\epsilon)$ -close to any solution $\mathbf{y}(t)$ with $\mathbf{y}(0) = \mathbf{x}_0 + \mathcal{O}(\epsilon)$ of the averaged system

$$\dot{\mathbf{y}} = \epsilon \overline{\mathbf{f}}_0(\mathbf{y}), \qquad \mathbf{y} \in \mathbb{R}^n,$$
 (2)

where $\overline{\mathbf{f}}_0(\mathbf{y}) = \frac{1}{T} \int_0^T f(y, t, 0) dt$.

Hint: Subtract (2) from (1) and integrate to obtain an expression for $|\mathbf{x}(t) - \mathbf{y}(t)|$. Estimate $|\mathbf{x}(t) - \mathbf{y}(t)|$ from above using the facts that $\bar{\mathbf{f}}$ is Lipschitz and $|\hat{f} - \bar{f}|/\epsilon$ is uniformly bounded, where \hat{f} is the right-hand side of the system into wich (1) is transformed by the averaging transformation $\mathbf{x} = \mathbf{y} + \epsilon \mathbf{w}(\mathbf{y}, t)$. Then use the following generalized Gronwall inequality:

If u(t), v(t), c(t) are nonnegative functions, c(t) is differentiable, and

$$v(t) \le c(t) + \int_0^t u(s) \, v(s) \, ds,$$

then

$$v(t) \le c(0)e^{\int_0^t u(s)ds} + \int_0^t c'(s) e^{\int_s^t u(\tau) d\tau} ds.$$

3. (Unsteady separation in time-periodic fluid flows) Fluid trajectories $\mathbf{x}(t) = (x(t), y(t))$ in a two-dimensional time-periodic flow satisfy the differential equations

$$\dot{x} = u(x, y, t), \qquad u(x, y, t) = u(x, y, t + T),$$

 $\dot{y} = v(x, y, t), \qquad v(x, y, t) = v(x, y, t + T),$
(3)

where T > 0 is the period, u and v are smooth velocity components satisfying the incompressibility condition $u_x + v_y \equiv 0$. Assume that a the fluid is bounded by a wall at y = 0, on which the velocity

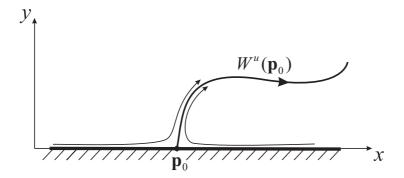


Figure 1: Unsteady separation from a no-slip wall

field satisfies the no-slip boundary conditions u(x, 0, t) = v(x, 0, t) = 0. As a result, all boundary points are nonhyperbolic fixed points for (3).

We say that a boundary point $\mathbf{p}_0 = (x_0, 0)$ is a separation point for the flow (3) if \mathbf{p}_0 admits an unstable manifold $W^u(\mathbf{p}_0)$. Physically, $W^u(\mathbf{p}_0)$ is a time-dependent curve of fluid particles that shrinks to \mathbf{p}_0 is backward time. In forward time, $W^u(\mathbf{p}_0)$ attracts fluid particles, then ejects them from the vicinity of the wall (see Fig. 1). Show that separation points satisfy the criteria

$$\int_0^T u_y(x_0, 0, t) dt = 0, \qquad \int_0^T v_{yy}(x_0, 0, t) dt > 0,$$

i.e., separation takes place where the average of the wall-shear is zero and the average of v_{yy} is positive. Hint: Use incompressibility and the boundary conditions to show that (3) can be rewritten as

To focus on the vicinity of the boundary, introduce the scaled variable $y = \epsilon \eta$, where $0 \le \epsilon \ll 1$. Show that the resulting $(\dot{x}, \dot{\eta})$ equations are slowly varying and find the corresponding averaged equations. For the averaged equations, rescale time on trajectories by letting $d\tau/dt = \eta(t)$ in order to remove the common η factor from the right-hand side, and look for a hyperbolic fixed point with an unstable manifold off the wall. Use the averaging theorem to relate your results to the original system (3).