

Nonlinear Dynamics & Chaos I

Exercise Set 6 Questions

Question 1

Which quantity is conserved along the trajectories of $\ddot{x} - x + x^3 = 0$?

- (a) $H(x, \dot{x}) = \dot{x}^2 - x^2 + \frac{1}{4}x^4$
- (b) $H(x, \dot{x}) = \dot{x}^2 - x^2 + \frac{1}{8}x^4$
- (c) $H(x, \dot{x}) = \frac{1}{2}\dot{x}^2 - \frac{1}{2}x^2 + \frac{1}{4}x^3$
- (d) $H(x, \dot{x}) = \dot{x}^2 - x^2 + \frac{1}{2}x^4$

Question 2

Consider the dynamical system

$$\begin{cases} \dot{x} = y + f(x, y) \\ \dot{y} = x + g(x, y) \end{cases}$$

Where $x, y \in \mathbb{R}$. Which condition is sufficient for this dynamical system not to have a limit cycle?

- (a) $f(x, y)g(x, y) < 0, \quad \forall x, y$
- (b) $\frac{\partial f}{\partial y} - \frac{\partial g}{\partial x} < 0, \quad \forall x, y$
- (c) $\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} < 0, \quad \forall x, y$
- (d) None of the above

Question 3

Consider the system

$$\begin{cases} \dot{r} = r(1 - r) \\ \dot{\theta} = \sin^2\left(\frac{\theta}{2}\right) \end{cases}$$

written in polar coordinates (r, θ) . With the phase portrait depicted in the figure below, which statement is correct ?

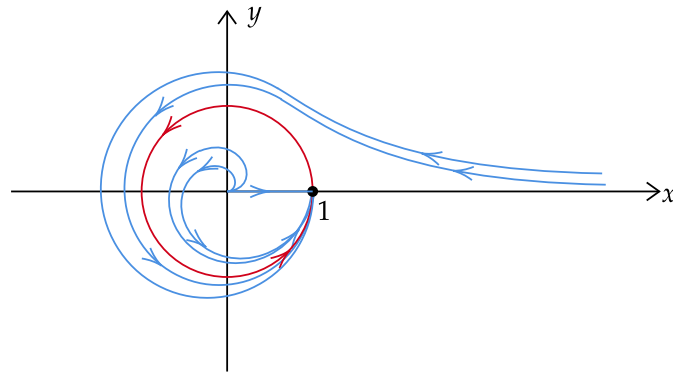
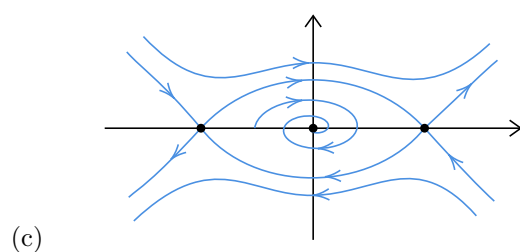
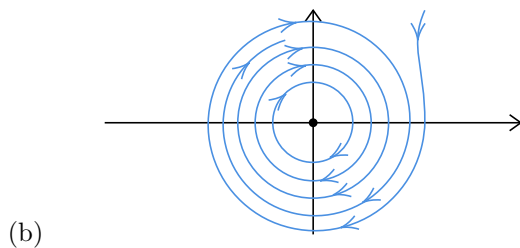
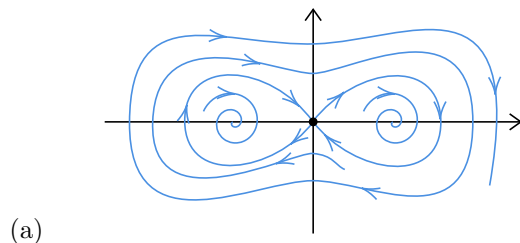


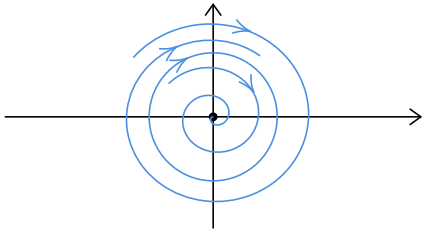
Figure 1: Phase portrait of the system.

- (a) The fixed point $(x = 0, y = 0)$ is the α -limit point for any (x_0, y_0) .
- (b) The fixed point $(x = 1, y = 0)$ is asymptotically stable.
- (c) The fixed point $(x = 1, y = 0)$ is the ω -limit point for any $(x_0, y_0) \neq (0, 0)$.
- (d) The invariant curve $r = 1$ is the ω -limit point for any (x_0, y_0) with $x^2 + y^2 = 1$.

Question 4

The phase portrait of four dynamical systems are depicted below. Which phase portrait is robust under small enough perturbations?





(d)

Question 5

A one-degree-of-freedom mechanical system has a first integral

$$E(x, \dot{x}) = \frac{1}{2} \dot{x}^2 + V(x)$$

where the graph of $V(x)$ is shown below. Which figure may correspond to the phase portrait of the mechanical system?

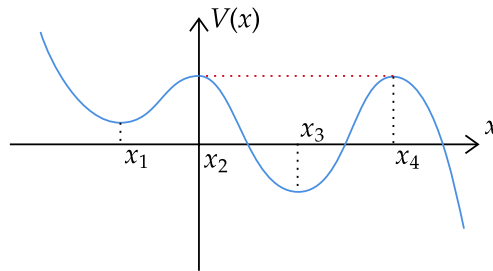
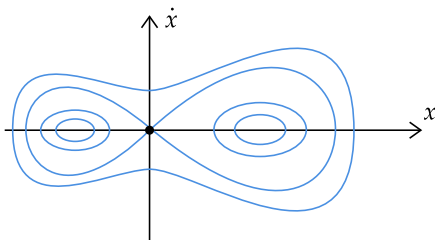
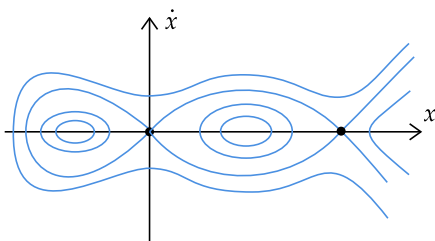


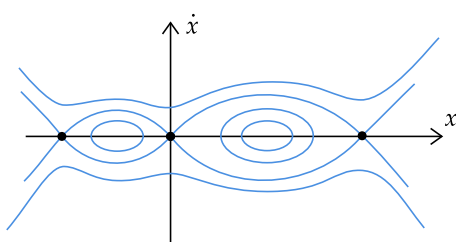
Figure 2: Potential function $V(x)$ of the mechanical system.



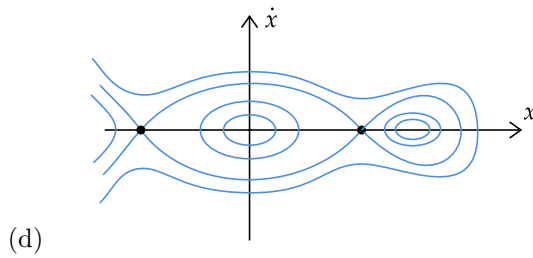
(a)



(b)



(c)



Question 6

Consider a planar dynamical system with the following phase portrait:

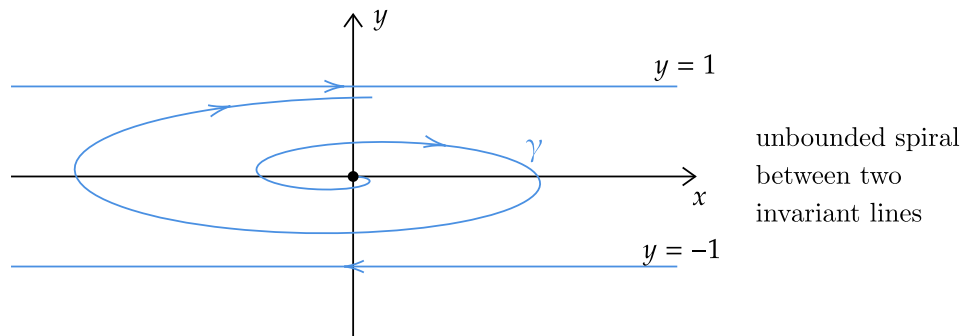


Figure 3: Phase portrait of the planar dynamical system

Which of the following statement is true?

- (a) The ω -limit set of γ is empty.
- (b) By the Poincaré-Bendixson theorem, the ω -limit set of γ is composed of the lines $y = 1$ and $y = -1$.
- (c) The Poincaré-Bendixson theorem does not apply to γ .
- (d) None of the above

Question 7

Consider the Van der Pol equation

$$\ddot{x} + \alpha(x^2 - 1)\dot{x} + x = 0, \quad \alpha > 0, \quad x \in \mathbb{R}$$

Which of the following statements are true?

- (a) This equation cannot have limit cycles.
- (b) Any limit cycle of this equation must intersect at least one of the two lines $\{x = 1\}$, $\{x = -1\}$.
- (c) Any limit cycles of this equation is necessarily unstable.
- (d) None of the above

Question 8

Consider a particle sliding frictionlessly on the following terrain:

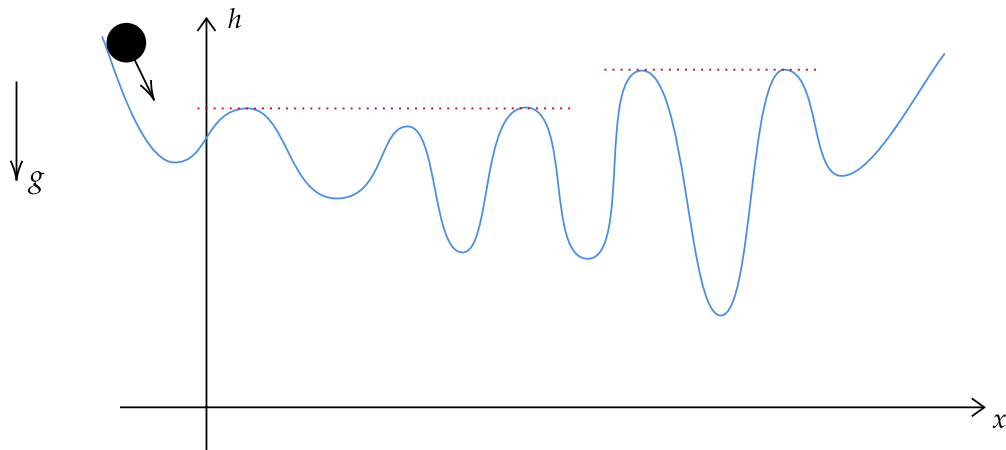
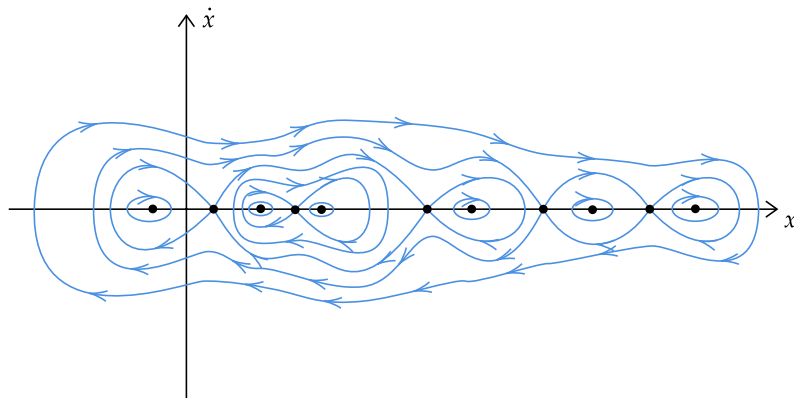


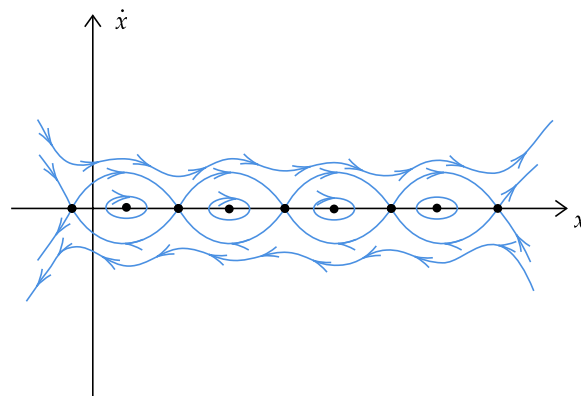
Figure 4: Terrain on which the particle slides

Which of the following statements are true?

- (a) The phase portrait of the dynamical system describing the motion of this particle cannot be drawn, as the available information is insufficient.
- (b) A qualitative sketch of the phase portrait is as follows:



- (c) A qualitative sketch of the phase portrait is as follows:



- (d) This dynamical system must have at least one attracting limit cycle.