

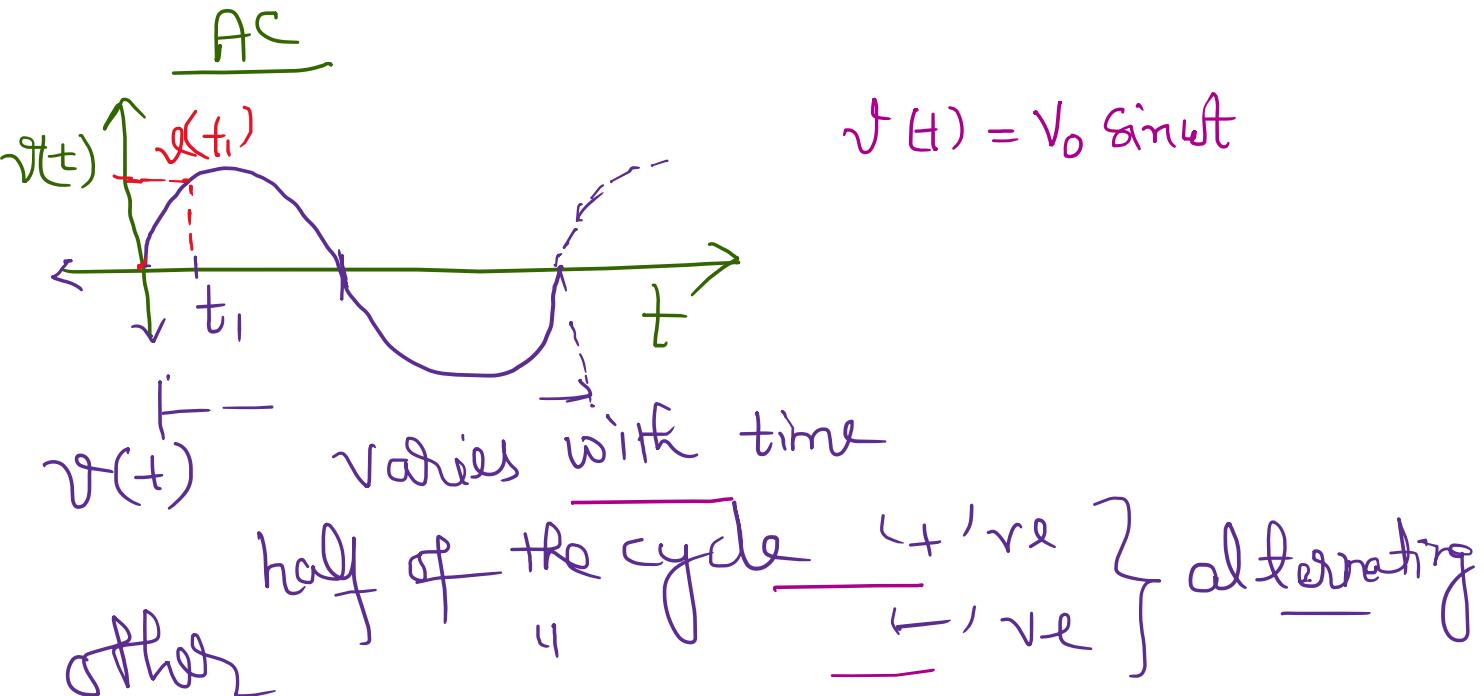
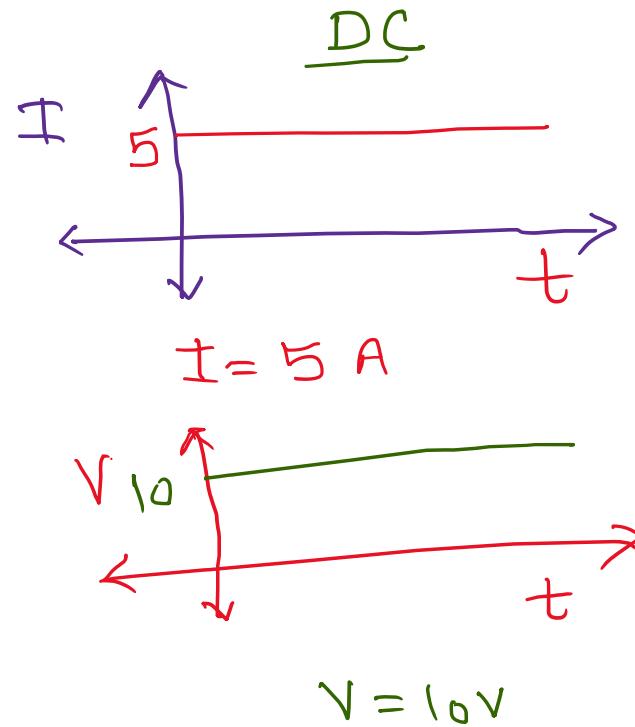
Unit-2

AC ckt Analysis (1-Φ ccts)

DC ccts: $E_S(DC)$, R

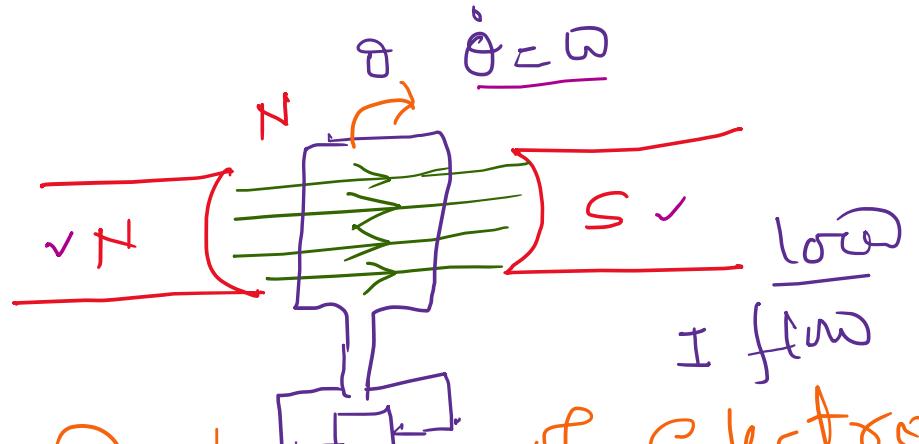
AC ccts: $E_S(AC)$, R, L, C

R, L, C, R-L, R-C, R-L-C



$$v(t) = ?$$

$v(t) \rightarrow$ instantaneous voltage

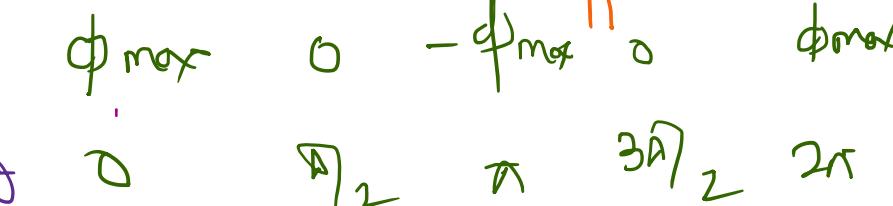
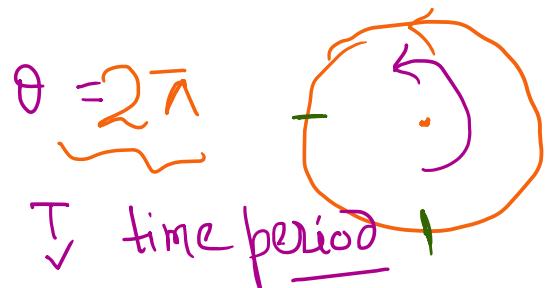


✓ Faraday's Law of Electromagnetic Induction:

Induction:

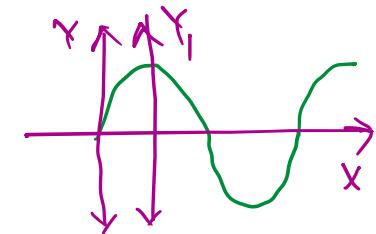
$$\text{1st law: } e = \frac{d\phi(t)}{dt}$$

emf
 $\propto \frac{d\phi}{dt}$



- ✓ B : mag field system
- ✓ C : coil/conductor
- ✓ R : Relative motion
betw field & cond

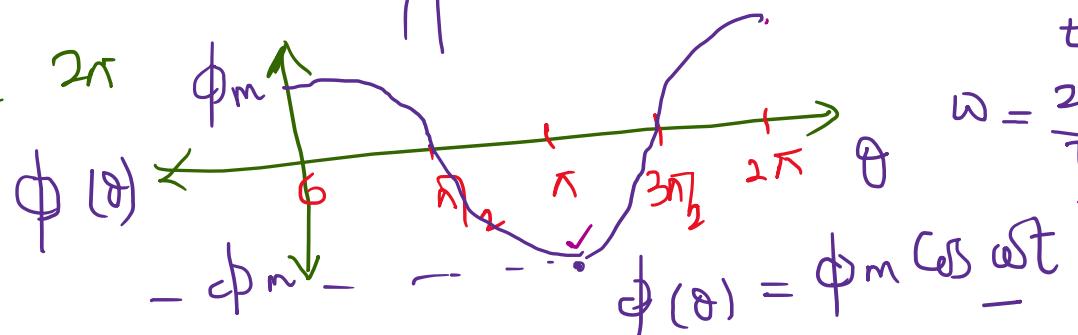
ϕ, flux



$$\omega \theta \rightarrow \sin \theta$$

$$\theta = \omega t$$

$$\omega = \frac{2\pi}{T}$$



$$\omega = \frac{2\pi}{T}$$

$$f = \frac{1}{T}$$

$$\omega = 2\pi f$$

F. 2ⁿ Law :
Lenz's law

$\theta \rightarrow$ angular displacement
 $\omega \rightarrow$ angular speed
 $T \rightarrow$ Time period
 $f \rightarrow$ frequency

time period T sec \rightarrow 1 rev
 1 sec \rightarrow $\frac{1}{T}$ rev

$$f = \frac{1}{T}$$

$$e = - \frac{d\phi}{dt}$$

$N \rightarrow$ no. of turns
 $\text{total } \phi = \frac{N\phi}{\text{turns}}$

$$\omega t = \theta$$

$$\phi(t) = \phi_m \cos \omega t$$

$$e = - \frac{d(N\phi(t))}{dt} = - \frac{d}{dt} \{ N\phi_m \cos \omega t \}$$

$$e = + \underbrace{N\phi_m \omega}_{\text{Emax}} \sin \omega t$$

$$\frac{\text{Emax}}{\text{Emax}} = 1$$

$$\text{for AC} \\ v(t) = V_0 \sin(\omega t - \phi)$$

$$e(t) = E_m \sin \omega t$$

$$E_{\max} = N\phi_m \omega = N\phi_m 2\pi f \\ = 2\pi N\phi_m \cdot f$$

$$v(t) = V_0 \sin(\omega t - \phi)$$

↑
max
 $V_0 \sin \theta$

inst
volt

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$f = \frac{1}{T}$$

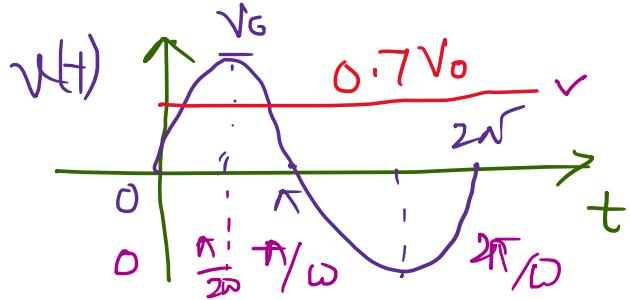
$\underbrace{10V}_{DC}$ $\overbrace{10V}^{V_0} \leftarrow AC$	$\overbrace{7V}^{AC}$ $\overbrace{7V}^{V_0}$
--	---

$\theta = \omega t$

$t = \theta / \omega$

$t \propto \theta$

$$i(t) = I_0 \sin(\omega t - \phi)$$



Effective value = $\sqrt{\text{RMS Value}}$

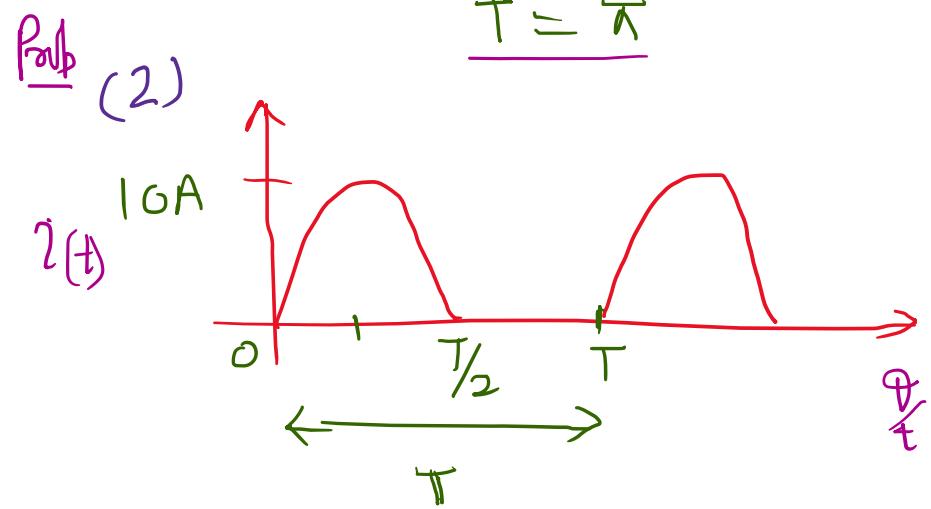
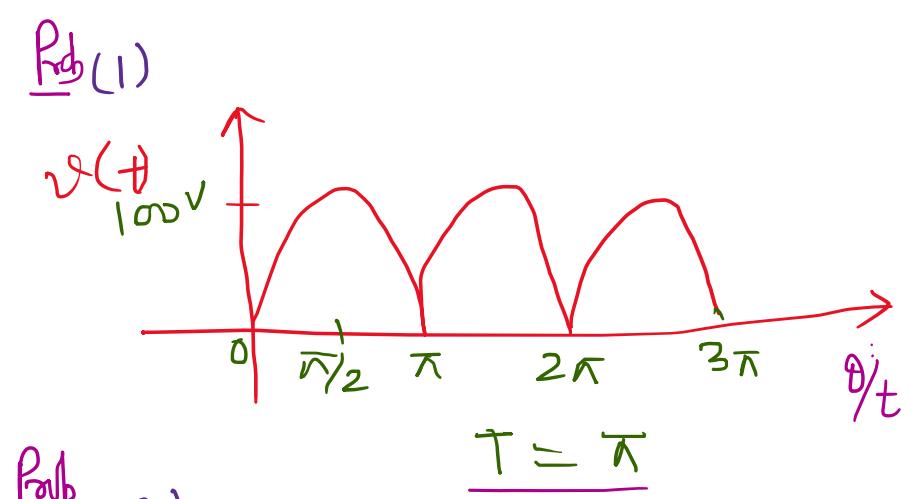
for sin wave $V_{rms} = \sqrt{\frac{1}{T} \int_0^T v^2(t) dt}$

$$V_{av} = \frac{1}{T} \int_0^T v(t) dt$$

$$V_{rms}^2 = \frac{1}{T} \int_0^T v^2(t) dt$$

7A/DC 10A/AC

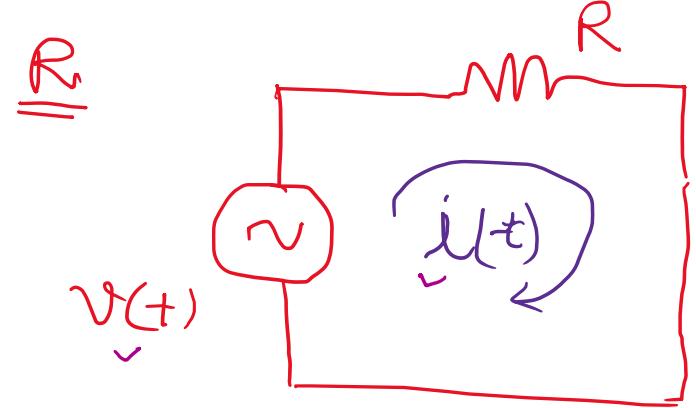
70% of V_0



- ✓ (1) RMS value
- ✓ (2) Average value
- (3) Form factor = $\frac{\text{RMS}}{\text{Average}}$
- (4) Peak factor = $\frac{\text{Max}}{\text{RMS}}$

1-φ AC circuits :

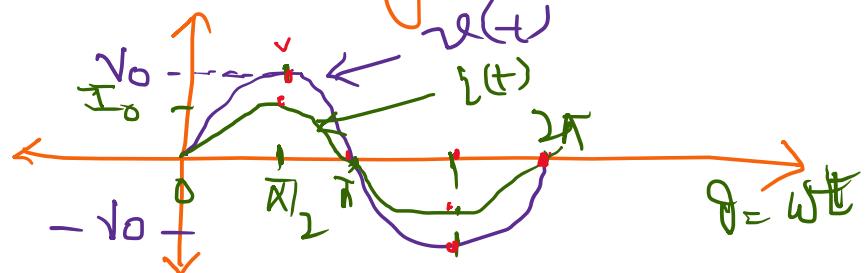
$$V(t) = V_0 \sin \omega t$$



$$V(t) = V_0 \sin(\omega t) \equiv V_0 \angle 0^\circ$$

$$i(t) = I_0 \sin \omega t \equiv I_0 \angle 0^\circ$$

Wave diagram



V & i
are in same phase

$$V^i = 0^\circ$$

$$V_{rms} \equiv V \text{ effective}$$

$$I_{rms} = I$$

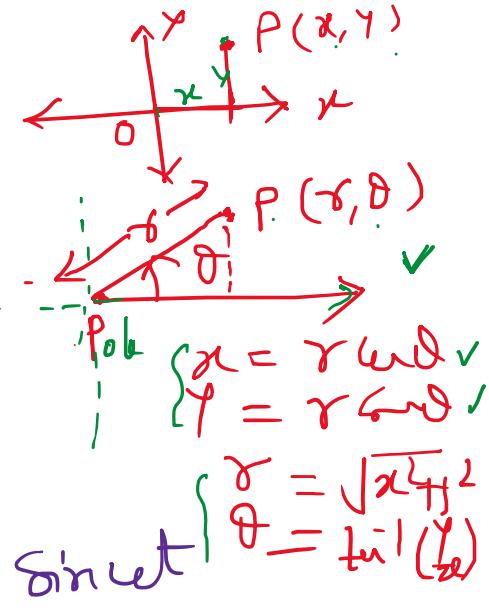
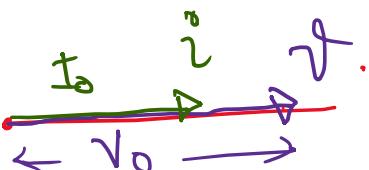
$$\underline{\text{DC}} \rightarrow V = I \cdot R$$

$$\underline{\text{AC}} \rightarrow V(t) = R \cdot i(t)$$

$$i(t) = \frac{V(t)}{R} = \left(\frac{V_0}{R} \right) \sin \omega t = \underline{I_0 \sin \omega t}$$

$$\left\{ \begin{array}{l} I_0 = \frac{V_0}{R} \end{array} \right.$$

phasor diagram



Power in Resistive Ckt:

$$\text{instantaneous power} \quad p(t) = \underline{V(t)} \cdot \underline{i(t)}$$

$$p(t) = V_0 \sin \omega t \cdot I_0 \sin \omega t$$

$$= \frac{V_0 I_0}{2} \cdot 2 \sin^2 \omega t$$

$$p(t) = \left(\frac{V_0}{\sqrt{2}}\right) \left(\frac{I_0}{\sqrt{2}}\right) (1 - \cos 2\omega t)$$

$$\boxed{\sqrt{p(t)} = \sqrt{V} \cdot \sqrt{I} \cdot (1 - \cos 2\omega t)}$$

$$P_{av} = \frac{1}{T} \int_0^T p(t) dt = VI$$

$$V_{rms} = V$$

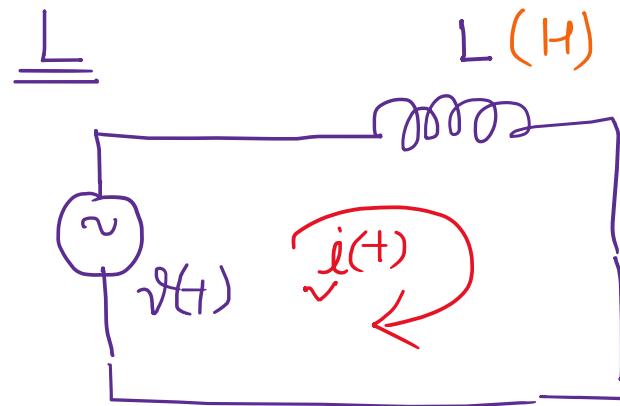
$$I_{rms} = I$$

DC Power

$$\left. \begin{aligned} P &= V \cdot I \\ &= \frac{V^2}{R} \\ &= I^2 R \end{aligned} \right\}$$

pulsating/alternating
with double the supply f.

$$\boxed{P = V \cdot I} = V_{rms} I_{rms}$$



$$v(t) = V_0 \sin \omega t \quad \checkmark$$

$$i(t) = \frac{1}{L} \int v(t) dt$$

$$= \frac{1}{L} \int V_0 \sin \omega t dt$$

$$= \frac{V_0}{L} \left(-\frac{\cos \omega t}{\omega} \right)$$

(A) $i(t) = \frac{V_0}{\omega L} \cdot \sin(\omega t - \pi/2)$

(B) $i_R(t) = \frac{V_0}{R} I_0 \sin \omega t$

$$\left\{ \begin{array}{l} v = L \frac{di}{dt} \\ i = \frac{1}{L} \int v dt \end{array} \right. \quad \checkmark$$

$$\rightarrow v(t) = V_0 \sin \omega t$$

$$\rightarrow i(t) = I_0 \sin(\omega t - \pi/2)$$

$$\begin{aligned} &= V_0 \angle 0^\circ \quad \checkmark \\ &\equiv I_0 \angle -\pi/2 \quad \checkmark \end{aligned}$$

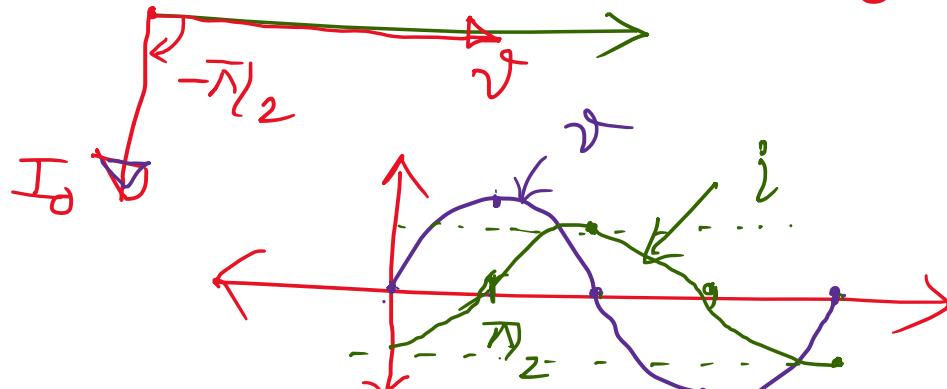
$$\sqrt{X_L} = \omega L = \frac{2\pi f L}{\text{Hz}} \rightarrow X_L \propto f$$

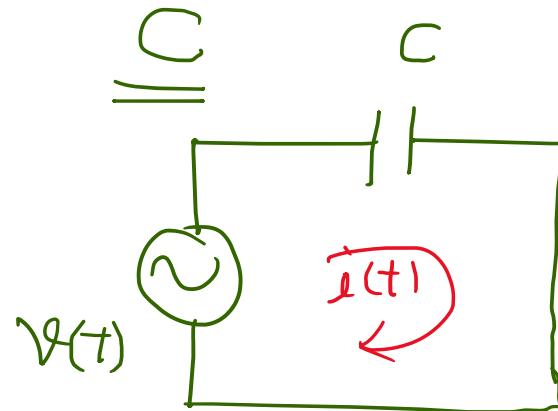
$$I_0 = \frac{V_0}{X_L} = \frac{V_0}{\omega L}$$

Phasor

i lags the v by $\pi/2$

Wave





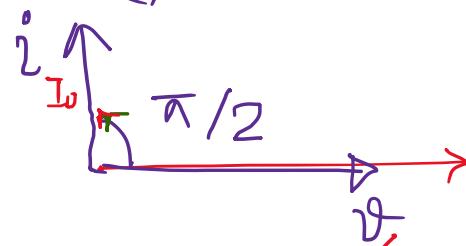
$$i(t) = C \frac{dV(t)}{dt} \quad \checkmark$$

$$= C \frac{d(V_0 \sin \omega t)}{dt}$$

$$= C V_0 \omega \cos \omega t -$$

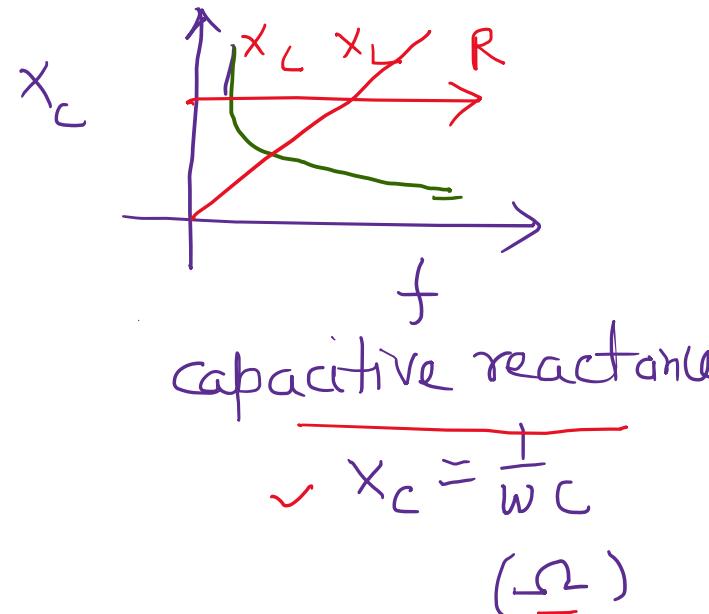
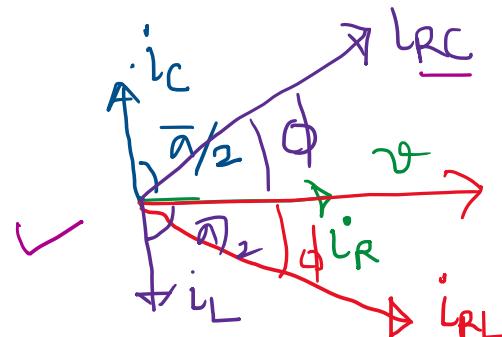
$\checkmark V(t) = V_0 \sin \omega t = V_0 \angle 0^\circ$

$i_L(t) = \frac{V_0}{(1/\omega C)} \sin(\omega t + \pi/2) = I_0 \angle \pi/2 = \frac{V_0}{X_C} \sin(\omega t + \pi/2)$



i leads V by $\pi/2$ in a pure cap.

$$I_0 = \frac{V_0}{X_C}$$



$$X_C = \frac{1}{(2\pi f) C}$$

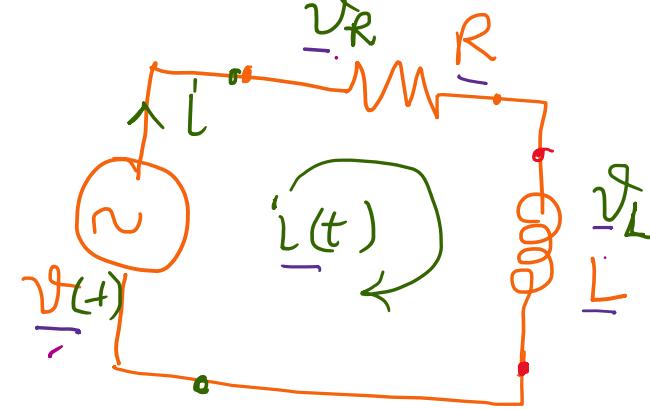
$$X_C \propto \frac{1}{f}$$

$$X_C f = C \cancel{t}$$

$$\boxed{x \cdot y = C}$$

$$\phi = 0 \longleftrightarrow \pi/2$$

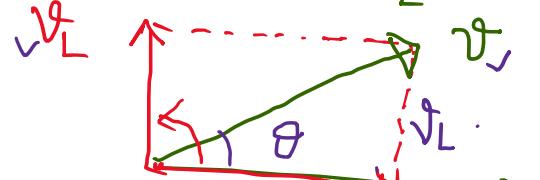
R-L circuit



$$V(t) = V_0 \sin \omega t$$

$$i_R(t) = \frac{V_0}{R} \sin \omega t$$

$$i_L(t) = \frac{V_0}{X_L} \sin(\omega t - \phi) \quad X_L = \omega L$$



$$V_R = i \cdot R$$

$$V_L = i(jX_L)$$

$$i \rightarrow V_R$$

$$i \downarrow V_L$$

$$\bar{V}_R + \bar{V}_L = \bar{V}$$

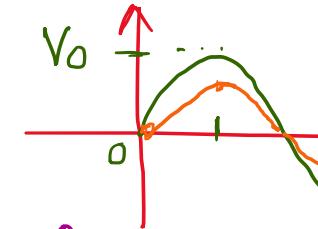
$$V = i_R + i j X_L$$

$$Z = \frac{V}{i} = R + j X_L$$

R

$$V$$

V & i are in phase



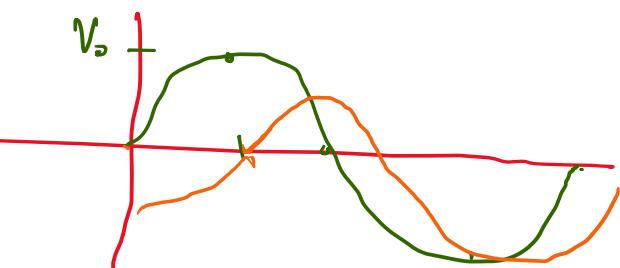
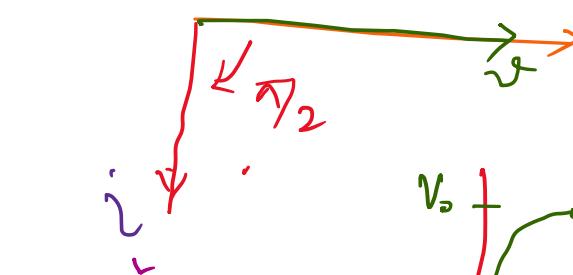
$$\frac{V_0}{R} = I_0$$

$$\theta = \frac{d\theta}{dt} = \omega$$

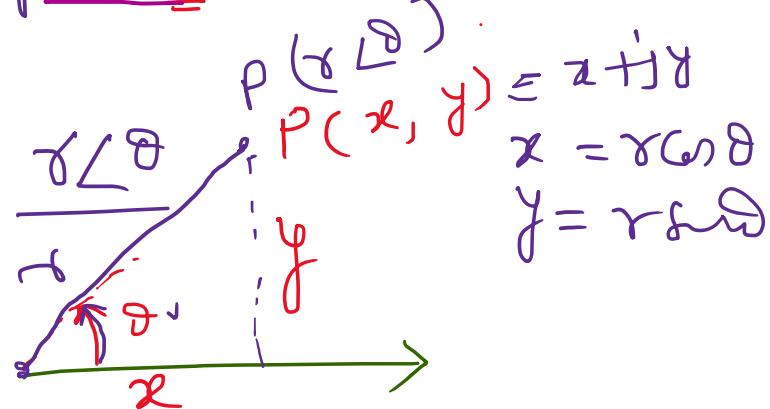
$$\omega \cdot t = \theta$$

$$t = \frac{\theta}{\omega}$$

$$t \rightarrow \theta \rightarrow$$



operator j (Rotation \vec{n}_1)



maths

$$\sqrt{-1} = i$$

||

j

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1}(y/x)$$

$$z_1 P_1(r_1 \angle \theta_1) \cdot P_2(r_2 \angle \theta_2) z_2$$

$$z_1 z_2 = r_1 r_2 \angle (\theta_1 + \theta_2)$$

\vec{n}_2 Rotator in anti clockwise

$$\begin{aligned} j^2 x &= -x \\ jx &= j^2 x \\ jx &= -jx \end{aligned}$$

$$P(x, y), z = x + jy = (x, y), r \angle \theta, r e^{j\theta}, r(\cos \theta + j \sin \theta)$$

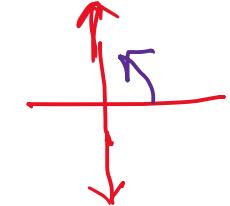
$$z = x + iy$$

$$= r(\cos \theta + j \sin \theta)$$

$$= r(\cos \theta + j \sin \theta)$$

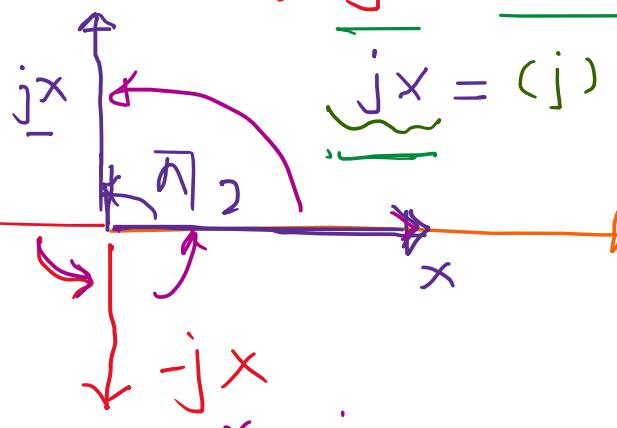
$$= r e^{j\theta}$$

$$= r \angle \theta$$



Real No's

$$\begin{aligned} \sqrt{x} &= x + j \cdot 0 \\ \sqrt{j} &= 0 + j \cdot 1 \end{aligned}$$



$$= \sqrt{x} \angle 0 \cdot \sqrt{(r_1 \angle \theta_1)}$$

$$= 1 \angle \pi/2 \cdot \sqrt{(r_2 \angle \theta_2)}$$

$$\begin{aligned} &= (1 \angle \pi/2) \cdot (x \angle 0) \\ &= x \angle \pi/2 \end{aligned}$$

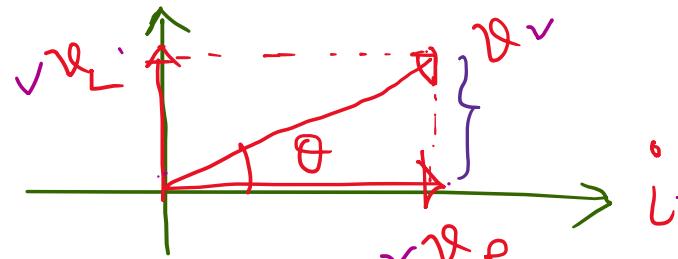
$$\sqrt{j} \cdot (\sqrt{j} x) = j^2 x = -x$$

$$j(-x) = -jx$$

$$\frac{R-L}{\sqrt{R^2 + X_L^2}}$$

$$\checkmark Z = R + jX_L$$

$$\checkmark |Z| = \sqrt{R^2 + X_L^2}$$



$$\bar{V} = \bar{V}_R + \bar{V}_L$$

$$\tan \theta = \frac{V_L}{V_R} = \frac{i X_L}{i R} = \frac{X_L}{R}$$

$$\theta = \tan^{-1}\left(\frac{X_L}{R}\right)$$

$$R = |Z| \cos \theta, \quad X_L = |Z| \sin \theta$$

$$V = V_0 \sin \omega t$$

$$I_0 = \frac{V_0}{|Z|}$$

$$i = I_0 \sin(\omega t - \theta)$$

$$\theta = \tan^{-1}\left(\frac{V_L}{V_R}\right) = \tan^{-1}\left(\frac{X_L}{R}\right)$$

Numerical

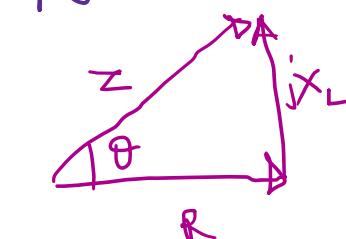
$$R, L, \omega(t) = V_0 \sin \omega t$$

$$\omega = 2\pi f \quad f \downarrow \quad i \text{ will} \\ X_L = \omega L \quad (L) \quad \log b y \theta$$

$$Z = R + jX_L$$

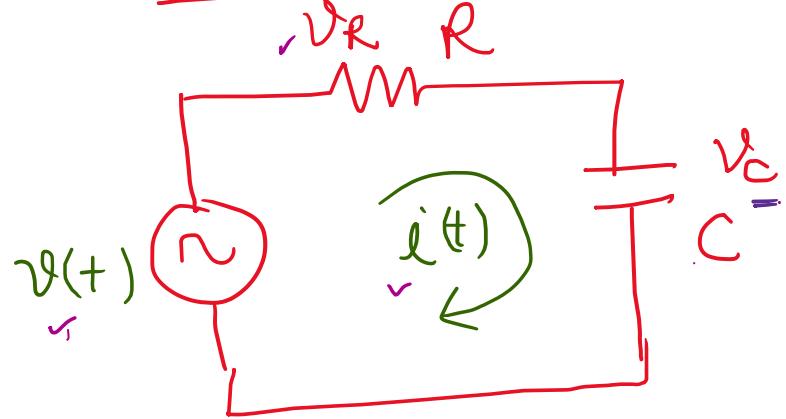
$$|Z| = \sqrt{R^2 + X_L^2}, \quad \theta = \tan^{-1}\left(\frac{V_L}{V_R}\right)$$

$$I_0 = \frac{V_0}{|Z|} = \frac{V_0}{\sqrt{R^2 + X_L^2}} = \tan^{-1}\left(\frac{X_L}{R}\right)$$



$$i(t) = I_0 \sin(\omega t - \theta)$$

R-C circuit



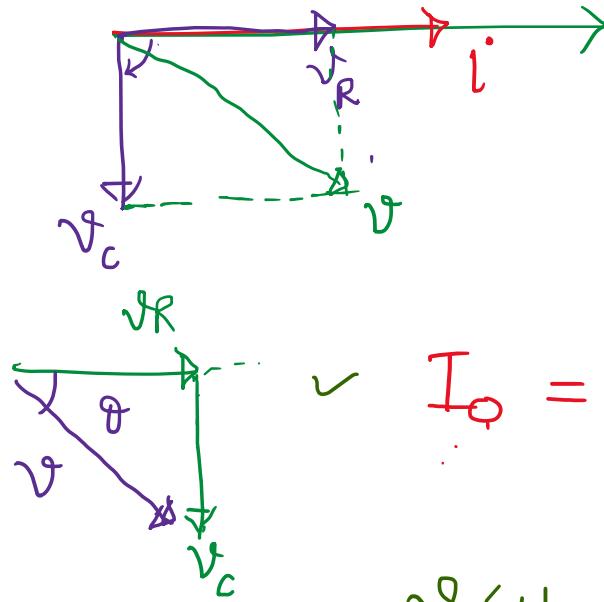
$$\bar{\theta} = \bar{V}_R + \bar{V}_C$$

$$V = iR + i(-jX_C)$$

$$V = i(R - jX_C)$$

$$\frac{V}{i} = Z = R - jX_C$$

$$|Z| = \sqrt{R^2 + X_C^2}$$



i leads v by θ

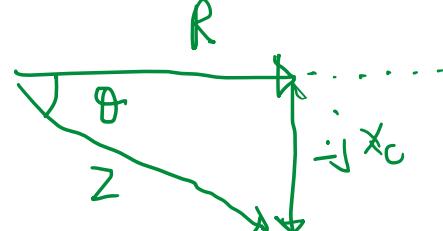
$$\theta = \tan^{-1}\left(\frac{V_c}{V_R}\right) = \tan^{-1}\left(\frac{X_C}{R}\right)$$

$$I_0 = \frac{V_0}{|Z|} = \frac{V_0}{\sqrt{R^2 + X_C^2}}$$

$$V(t) = V_0 \sin \omega t$$

$$X_C = \frac{1}{\omega C}$$

$$i(t) = I_0 \sin(\omega t + \theta)$$



$$\tan \theta = \frac{X_C}{R}$$

Numerical Problems:

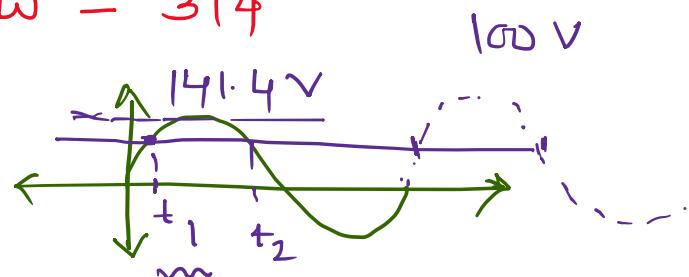
- 1) $v = 141.4 \sin 314t$, Find (i) f. (ii) RMS Voltage (iii) Average Voltage
 (iv) the instantaneous voltage at $t = 3\text{ms}$ (vi) FF. (vii) P.F.
 (v) Time taken to for voltage to reach 100V for the first time
 passing through zero.

$$v = 141.4 \sin 314t \dots \text{No of s.}$$

$$v = V_0 \sin \omega t$$

$$V_0 = 141.4 \text{ Volts}$$

$$\omega = 314$$



$$(i) \omega = 2\pi f = 314$$

$$f = \frac{314}{2\pi} = 50 \text{ Hz.}$$

$$(ii) \text{ RMS Voltage}$$

$$V_{\text{rms}} = \frac{V_0}{\sqrt{2}} = \frac{141.4}{\sqrt{2}} = 100 \text{ V}$$

$$(iii) \text{ Average Value}$$

$$V_{\text{avg}} = \frac{2V_0}{\pi}$$

$$= \frac{2 \times 141.4}{\pi}$$

$$= 90.07 \text{ V}$$

$$v(t) = 141.4 \sin 314t$$

$$v(t) = ? \quad t = 3 \text{ ms}$$

$$= 141.4 \sin \left(314 \times 3 \times 10^{-3} \times \frac{180}{\pi} \right)$$

degree

= - - - .

$$v(t) = 100 \quad t = ?$$

$$v(t) = 141.4 \sin 314t$$

$$100 = 141.4 \sin 31t$$

$$\sin 314t = \left(\frac{100}{141.4} \right) \rightarrow$$

$$314t = \sin^{-1}(\) \Rightarrow t = ?$$

wt

rad \times sec

$$\Rightarrow \underline{\text{rad}} \rightarrow$$

$$\pi^c \rightarrow 180^\circ$$

$$1^c = \frac{180}{\pi}$$

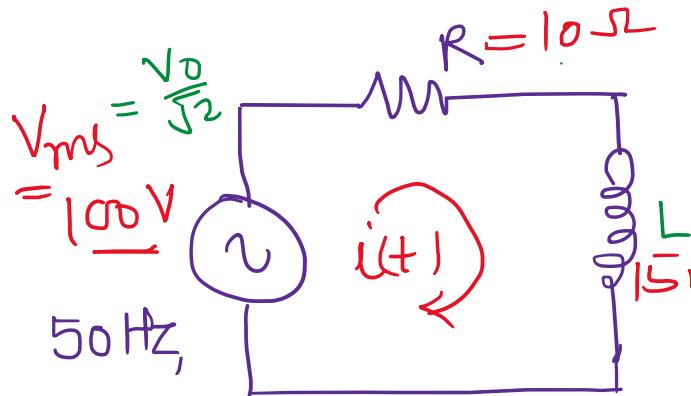
3 ms = rad = degree

$$\sin \theta = \sin \alpha$$

$$\theta = 2n\pi \pm \alpha$$

$$n = 0, 1, \dots$$

2) $R = 10 \Omega$ $L = 15 \text{ mH}$ $f = 50 \text{ Hz.}$, $\frac{100 \text{ V}}{\text{RMS}}$ supply $z = |z| \angle \theta$



$$\underline{v(t)} = \frac{\sqrt{2} \times 100 \sin 314t}{R} \quad \checkmark$$

$$\omega = 2\pi f = 2 \times 3.14 \times 50 = 314 \text{ rad/s}$$

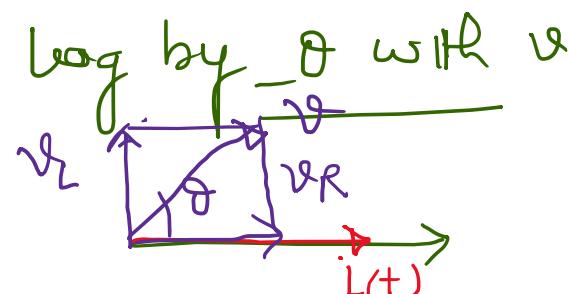
$$X_L = \omega L = 314 \times 15 \times 10^{-3} = 4.7 \Omega$$

$$z = R + j X_L = 10 + j 4.7 \Omega$$

$$|z| = \sqrt{R^2 + X_L^2} = \sqrt{10^2 + 4.7^2} = \dots$$

$$I_{\text{rms}} = \frac{V_{\text{rms}}}{|z|} = \frac{100}{|z|} = \dots$$

$$i(t) = ?$$



$$z \\ I_o, I_{\text{rms}}$$

$$\checkmark I_o = \frac{V_0}{|z|} = \frac{\sqrt{2} \times 100}{|z|} = \dots$$

$$\theta = \tan^{-1} \left(\frac{v_L}{v_R} \right)$$

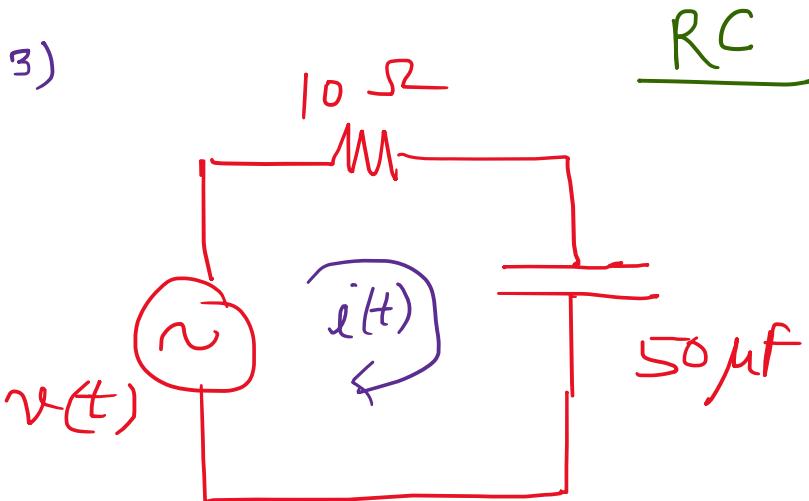
$$\theta = \tan^{-1} \left(\frac{X_L}{R} \right)$$

$$\checkmark \theta = \dots$$

$$i(t) = I_o \sin(\omega t - \theta)$$

$$i(t) = \frac{I_o}{\sqrt{2}} \sin(314t - \theta) \quad \text{Ans}$$

3)



$$i(t) = ?$$

$$v(t) = \underline{100} \sin(\underline{628t + 30^\circ})$$

$$R = 10 \Omega$$

$$\omega = 628 \text{ rad/sec}$$

$$f = 100 \text{ Hz}$$

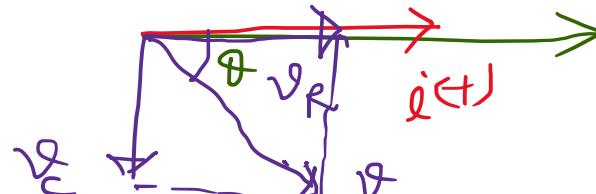
$$X_C = \frac{1}{\omega C} = \frac{1}{628 \times 50 \times 10^{-6}} = -$$

$$Z = R - j X_C$$

$$|Z| = \sqrt{R^2 + X_C^2}$$

$$\theta = \tan^{-1}\left(\frac{X_C}{R}\right) = -$$

$$I_0 = \frac{V_0}{|Z|} = -$$



$i(t)$ leads the voltage $v(t)$ by θ

$$i(t) = \underline{I_0} \sin(\underline{628t + 30^\circ + \theta})$$

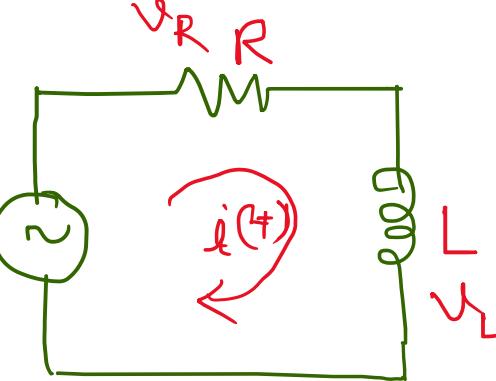
$$4) \quad v = 283 \frac{R-L}{\omega} \sin 314t \equiv 283 \angle 0^\circ$$

$$i(t) = 4 \sin(314t - 45^\circ) \equiv 4 \angle -45^\circ$$

$$(i) \quad R = 70.75 \times 0.767 = \underline{\hspace{2cm}}$$

$$(ii) \quad L = \frac{70.75 \times 0.767}{314} = \underline{\hspace{2cm}}$$

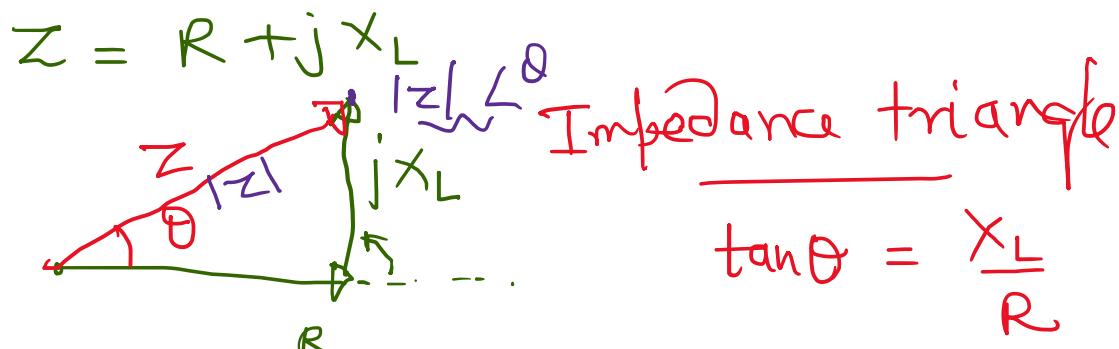
$$(iii) \quad Pf = \cos \theta = \frac{R}{|Z|} = \frac{1}{\sqrt{2}} = 0.707$$



$$\theta = v^\wedge i \\ = 45^\circ$$

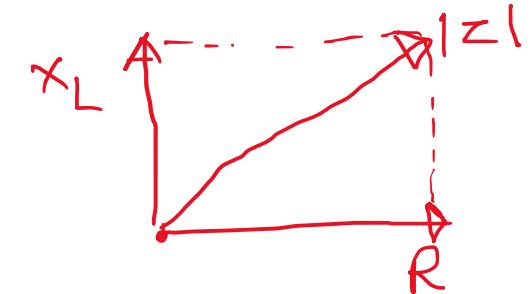
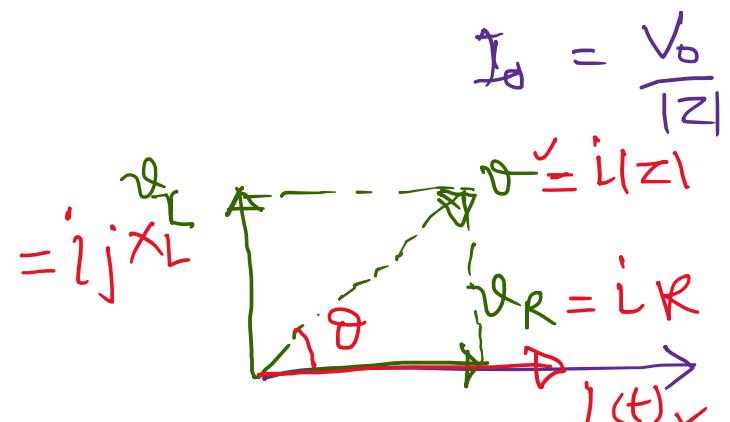
$$\text{freq, } f = \frac{\omega}{2\pi} = \frac{314}{2\pi} = 50 \text{ Hz}$$

$$|Z| = \frac{V_0}{I_0} = \frac{V_{rms}}{I_{rms}} = \frac{283}{4} = 70.75 \Omega$$



$$\tan \theta = \frac{X_L}{R}$$

$$R = |Z| \cos \theta, \quad X_L = |Z| \sin \theta$$



$$\omega L =$$

$$70.75 \times 0.767$$

Power in 1- ϕ AC ckt's :

$$v(t) = V_0 \sin \omega t \equiv V_0 \angle 0^\circ$$

$$i(t) = I_0 \sin(\omega t - \phi) \equiv I_0 \angle \phi$$

$$P(t) = v(t) \cdot i(t)$$

inst. power

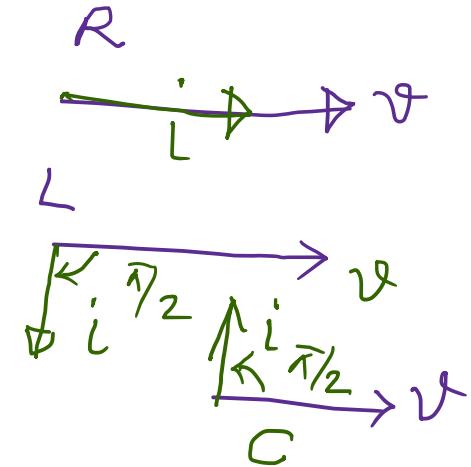
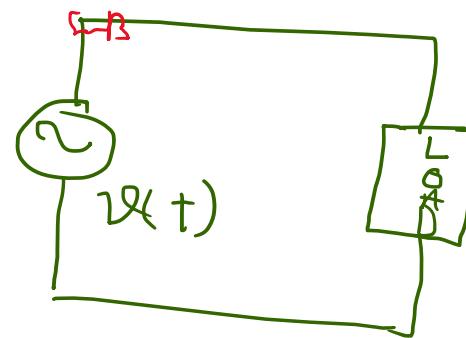
$$= V_0 \sin \omega t \cdot I_0 \sin(\omega t - \phi)$$

$$= \frac{V_0 I_0}{2} \left\{ 2 \underbrace{\sin \omega t}_{A} \underbrace{\sin(\omega t - \phi)}_{B} \right\}$$

$$= \frac{V_0}{\sqrt{2}} \cdot \frac{I_0}{\sqrt{2}} [\cos \phi - \cos(2\omega t - \phi)]$$

$$= V_{rms} I_{rms} \cos \phi - V_{rms} I_{rms} \cos(2\omega t - \phi)$$

$$P(t) = \underline{V \cdot I \cos \phi} - \underline{V I \cos(2\omega t - \phi)}$$



$$\left. \begin{aligned} i_R(t) &= I_0 \sin \omega t \equiv I_0 \angle 0^\circ \\ i_L(t) &= I_0 \sin(\omega t - \pi/2) \equiv I_0 \angle -\pi/2^\circ \end{aligned} \right\}$$

$$\left. \begin{aligned} i_C(t) &= I_0 \sin(\omega t + \pi/2) \\ &\equiv I_0 \angle \pi/2^\circ \end{aligned} \right\}$$

RL

$$i_{RL}(t) = I_0 \sin(\omega t - \theta)$$

RC

$$i_{RC}(t) = I_0 \sin(\omega t + \theta)$$

$$p(t) = VI \cos\phi - VI \sin(2\omega t - \phi)$$

$$\underline{\omega} \rightarrow 2\pi f$$

Instantaneous power in 1-φ AC ckt is pulsating with double the supply frequency.

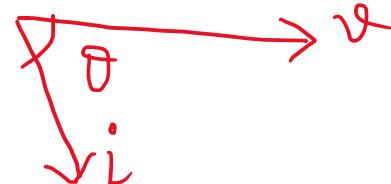
$$2\omega \rightarrow 2\pi(f)$$

$$P = P_{avg} = \frac{1}{T} \int_0^T p(t) dt = \frac{1}{T} \int_0^T VI \cos\phi dt + 0 = VI \cos\phi$$

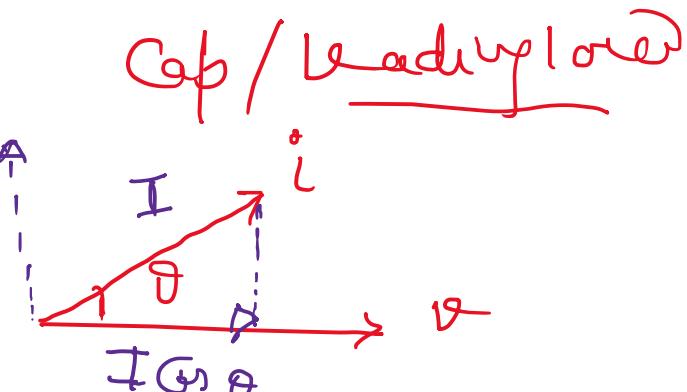
$$\boxed{P = VI \cos\phi}$$

Watts. true power / active power / Real power
Watt power

Lagging load (R-L) i will lag v by θ



(in quadrature to v)
I sinθ



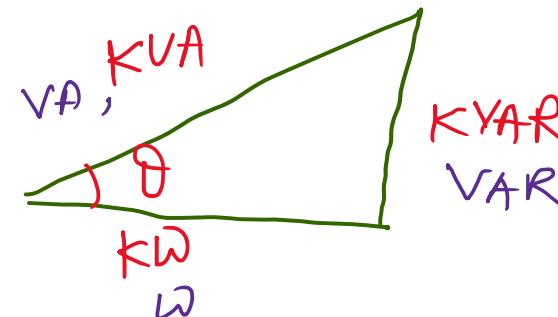
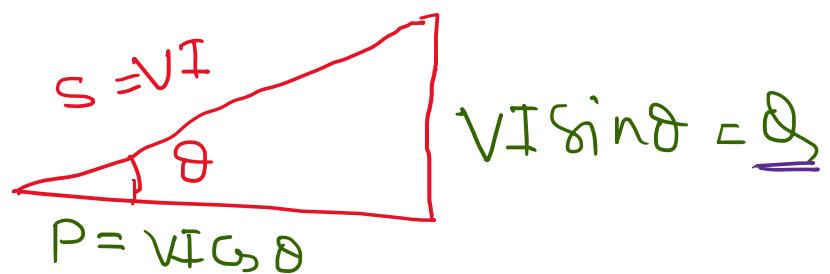
(in phase with v)

- ✓ $P = V \cdot I \cos \theta$ \underline{W} , active/true KW, mW . Real, Actual
- ✓ $Q = V \cdot I \sin \theta$ ✓ $\frac{VAR}{KVAR}$ $\frac{Reactive\ power}{(Volt\ amp\ reactive)}$ Quality of power
 \underline{MVAR}

$$S = \underline{V \cdot I}$$

apparent power - \underline{VA}, KVA, MVA

Power Δ



upto $\theta = 0$
 $\cos \theta = 1$

$$0 \leq \cos \theta \leq 1$$

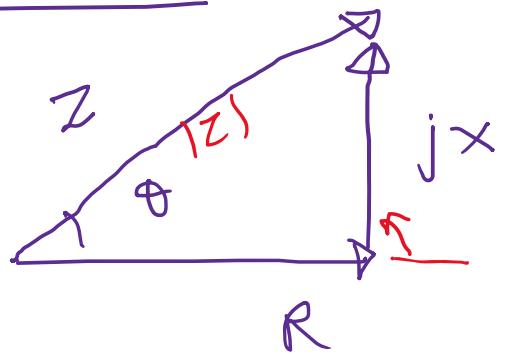
Power factor
1.

$\cos \theta \downarrow \theta \uparrow$

$$P_f = \cos \theta = \frac{P}{VI} = \frac{R}{|z|}$$

$$I = \frac{P}{V \cos \theta}; I \propto \frac{1}{\cos \theta}$$

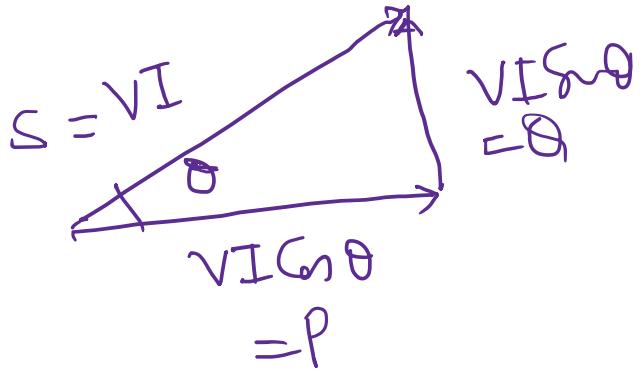
* Impedance Δ



$$\left. \begin{array}{l} R = |Z| \cos \theta \\ X = |Z| \sin \theta \end{array} \right\}$$

$$|Z| = \sqrt{R^2 + X^2}$$

* Power Δ



$$\left. \begin{array}{l} S = V I \\ P = V I \cos \theta \\ Q = V I \sin \theta \end{array} \right\}$$

$$\begin{aligned} \text{Reactive pf} &= \sin \theta \\ &= \frac{Q}{V I} \end{aligned}$$

A factor of a Coil

$$\frac{R}{R+L}$$

Q factor of a coil

$$= \frac{1}{\text{Power factor}}$$

$$= \frac{1}{\cos \theta}$$

$$= \frac{x_L}{R}$$

$$Q = \frac{\omega L}{R}$$



$$Z = R + jx_L$$

$$= R + j\omega L$$

$$\text{pf} = \cos \theta = \frac{R}{|Z|}$$

$$= \frac{R}{\sqrt{R^2 + x_L^2}}$$

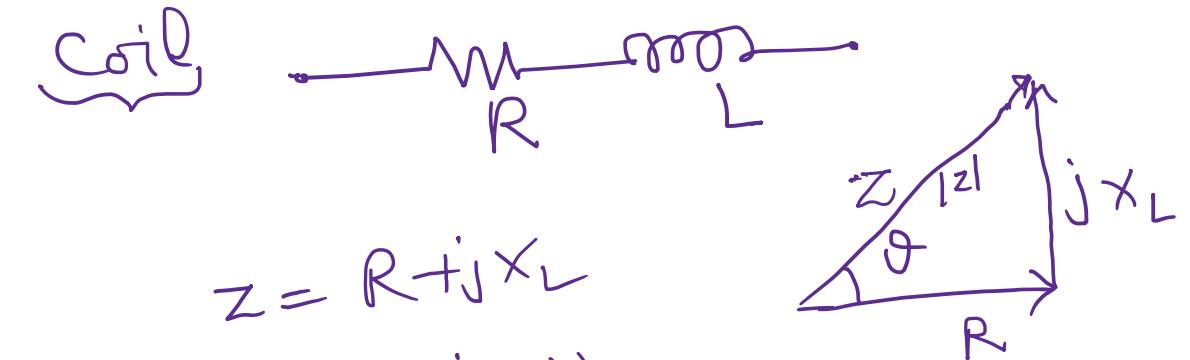
for

R is small compared to x_L

$$R \ll x_L$$

$$R^2 \ll x_L^2$$

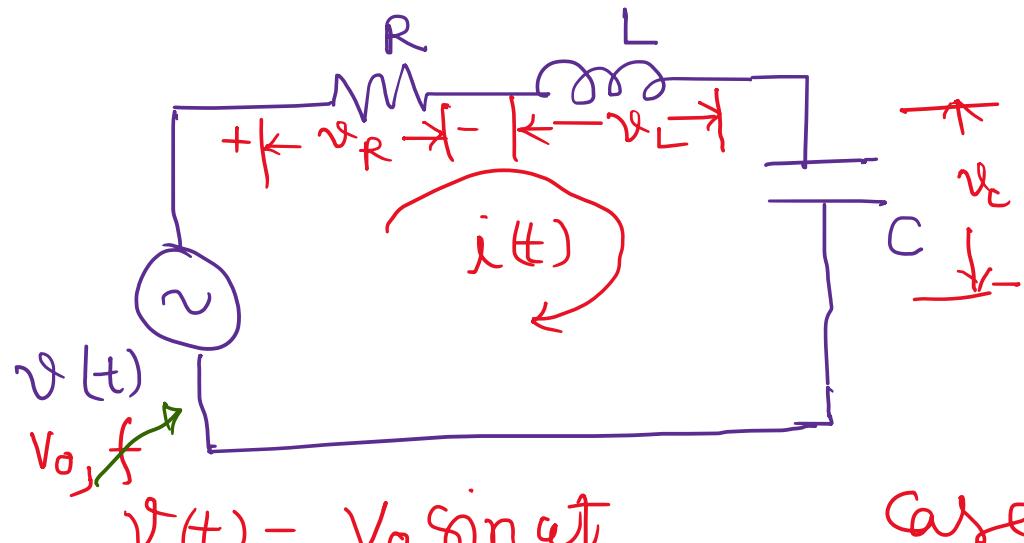
$$|Z| = x_L$$



thus, $\text{pf} = \cos \theta$

$$= \frac{R}{x_L}$$

Series R-L-C circuit :



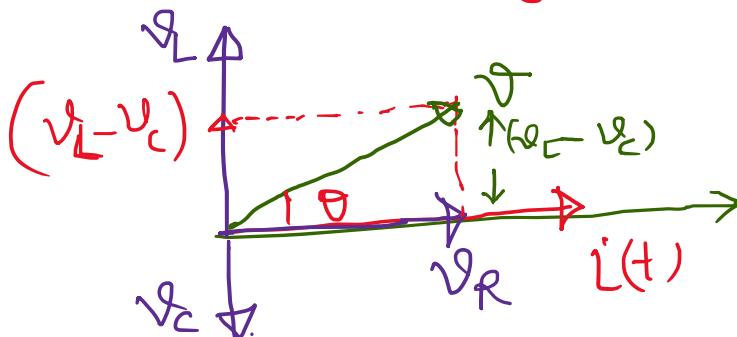
$$\bar{v} = \bar{v}_R + \underbrace{\bar{v}_L + \bar{v}_C}_{\bar{v}}$$

$$x_L \rightarrow \frac{(x_L - x_C)}{RL}$$

$$i(t) = I_0 \sin(\omega t - \theta)$$

$$=$$

Phasor diagram



Case 1)

$$v_L > v_C ; x_L > x_C \quad \text{Inductive RL}$$

$$v = \sqrt{v_R^2 + (v_L - v_C)^2}$$

$$v = \sqrt{(iR)^2 + (ix_L - ix_C)^2}$$

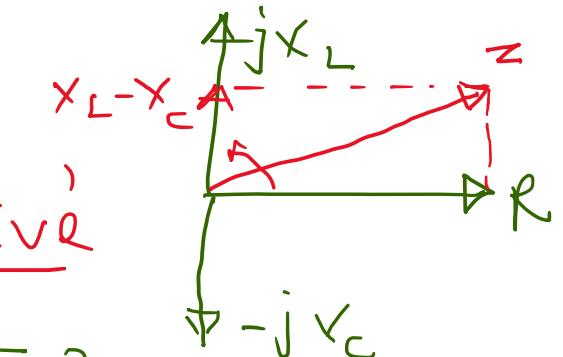
$$v = i \sqrt{R^2 + (x_L - x_C)^2}$$

$$|Z| = v/i = \sqrt{R^2 + (x_L - x_C)^2}$$

$$v_R = iR$$

$$v_L = j i x_L = i(jx)$$

$$v_C = -j i x_C = i(-jx)$$



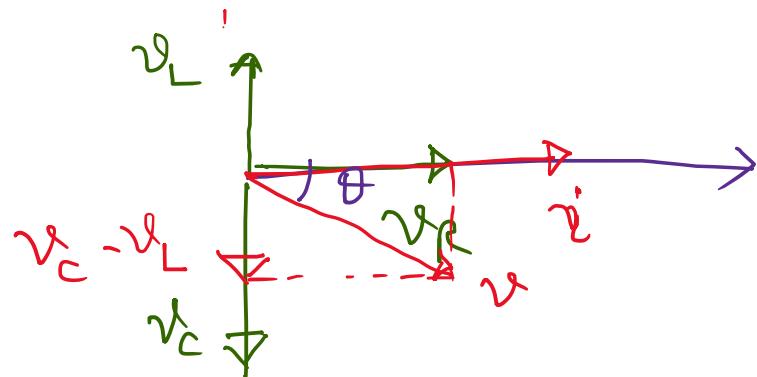
$$z = R + j(x_L - x_C)$$

$$I_0 = \frac{v}{|z|}$$

$$\theta = \tan^{-1} \left(\frac{v_L - v_C}{v_R} \right)$$

$$= \tan^{-1} \left(\frac{x_L - x_C}{R} \right)$$

Case 2 : $v_c > v_L$; $x_c > x_L$; Capacitive, $\frac{RC}{\sqrt{}}$ $x_c \rightarrow (x_c - x_L)$



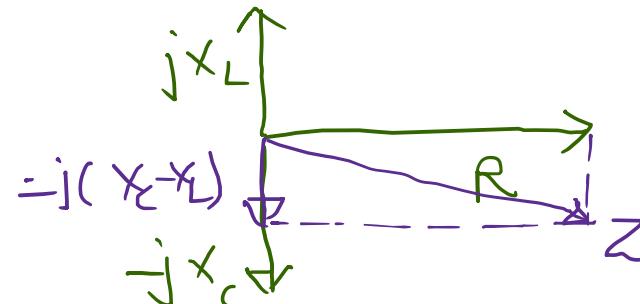
$$\bar{v} = \bar{v}_R + \underbrace{\bar{v}_L}_{-j(x_c - x_L)} + \bar{v}_C$$

$$|v| = \sqrt{v_R^2 + (v_c - v_L)^2}$$

$$= \sqrt{R^2 + (x_c - x_L)^2}$$

$$|Z| = \frac{|v|}{i} = \sqrt{R^2 + (x_c - x_L)^2}$$

$$i(+)=I_0 \sin(\omega t + \theta)$$



$$z = R + jx_L - jx_C$$

$$z = R - j(x_c - x_L)$$

$$z = R - jx$$

$$\sqrt{I_0} = \frac{V_0}{|z|}$$

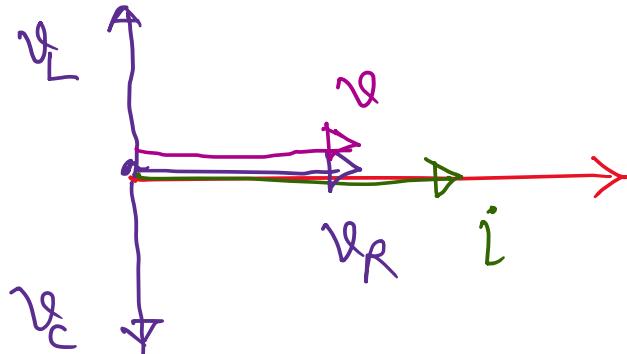
$$v(+) = V_0 \sin \omega t$$

$$\theta = \tan^{-1} \left(\frac{x_c - x_L}{R} \right)$$

$$\cos \theta = \frac{R}{|z|} = \frac{R}{\sqrt{R^2 + (x_c - x_L)^2}}$$

Case III :

$$V_L = V_C ; \quad X_{\text{net}} = X_L - X_C = 0 \quad \text{"Resistive"}$$



$$\Rightarrow \quad \begin{matrix} V \\ i \end{matrix}$$

$$\theta = \vec{V}^\wedge i = 0^\circ$$

$$\cos \theta = \cos 0^\circ = 1 \text{ upf}$$

$$I_0 = \frac{V_0}{|Z|} = \frac{V_0}{R}$$

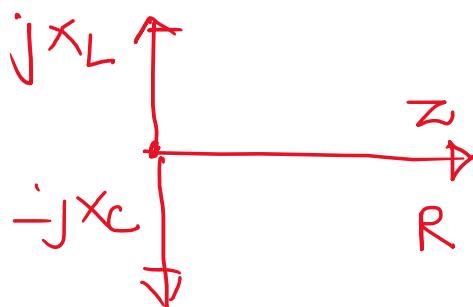
$$I_0 = \frac{V_0}{\sqrt{R^2 + (X_L - X_C)^2}}$$

$$\bar{V} = \bar{V}_R + \underbrace{\bar{V}_L + \bar{V}_C}_{= 0}$$

$$\bar{V} = \bar{V}_R + 0$$

$$\boxed{\bar{V} = \bar{V}_R}$$

$$\begin{aligned} X &= X_L - X_C \\ &= 0 \end{aligned}$$



$$\boxed{Z = R}$$

$$\begin{aligned} Z &\equiv R + jX_L - jX_C \\ &\equiv R + j(X_L - X_C) \\ &\equiv R + j0 \\ &\equiv R \end{aligned}$$

Series ckt "Resonance"
Condition : $X_L = X_C$

General condn

$$X_{\text{net}} = 0$$

Reactive component = 0

$$Z = R + jX \quad X = 0$$

$$X_L = X_C$$

" f_r " Resonance freq.

$$\Rightarrow \omega_L = \frac{1}{\omega_C}$$

$$\omega_r = 2\pi f_r$$

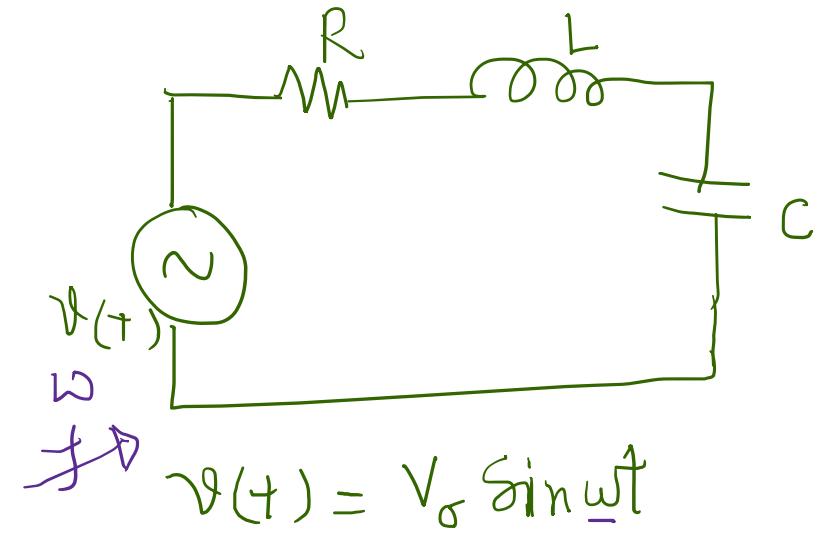
$$\Rightarrow 2\pi f_r L = \frac{1}{2\pi f_r C}$$

$$\Rightarrow f_r^2 = \frac{1}{(2\pi)^2 LC}$$

$$\Rightarrow \boxed{f_r = \frac{1}{2\pi \sqrt{LC}}}$$

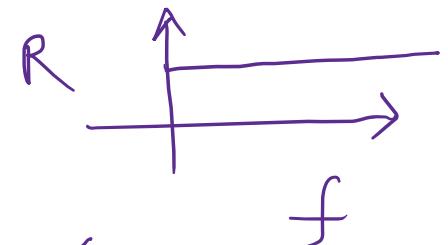
$$Z = R + j X_{\text{net}}$$

$$\begin{aligned} X_{\text{net}} &= 0 \\ Z &= R \end{aligned}$$

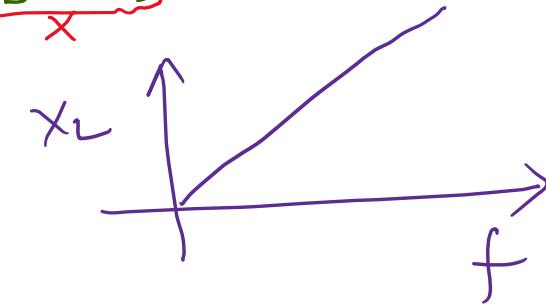


$$z = R + j(x_L - x_C)$$

$$|z| = \sqrt{R^2 + (x_L - x_C)^2}$$

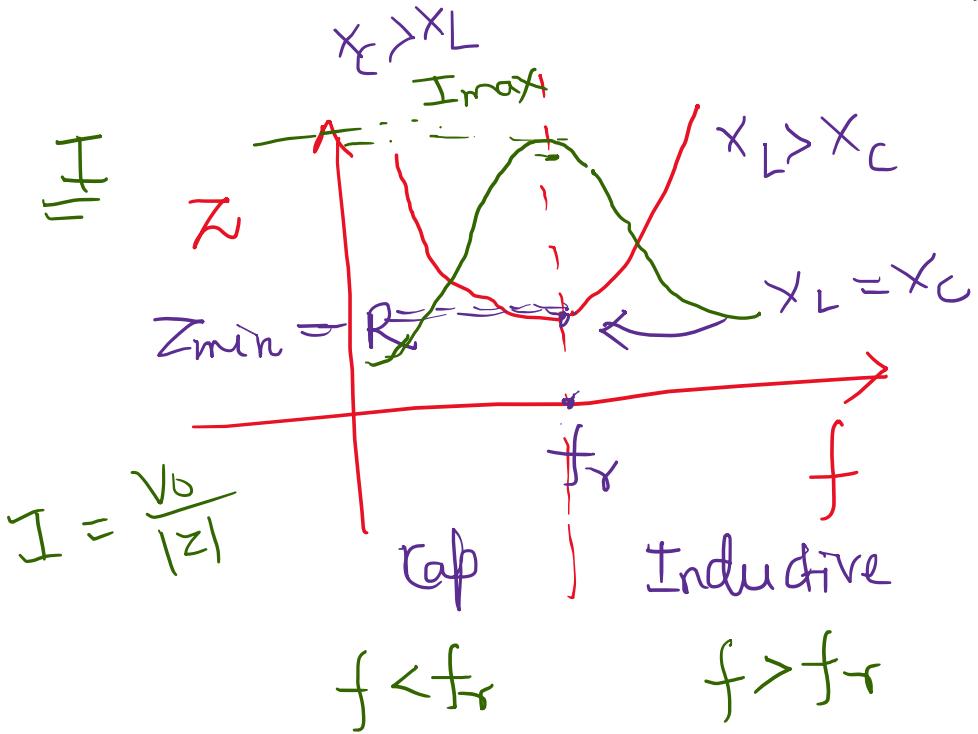
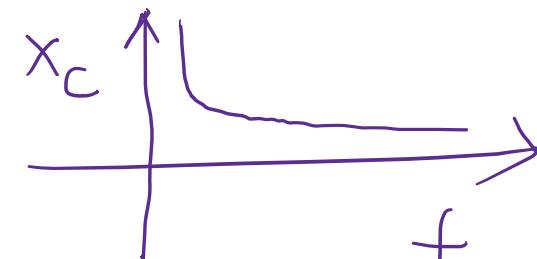


- 1) R const
- 2) $x_L = 2\pi f L$
 $x_L \propto f$

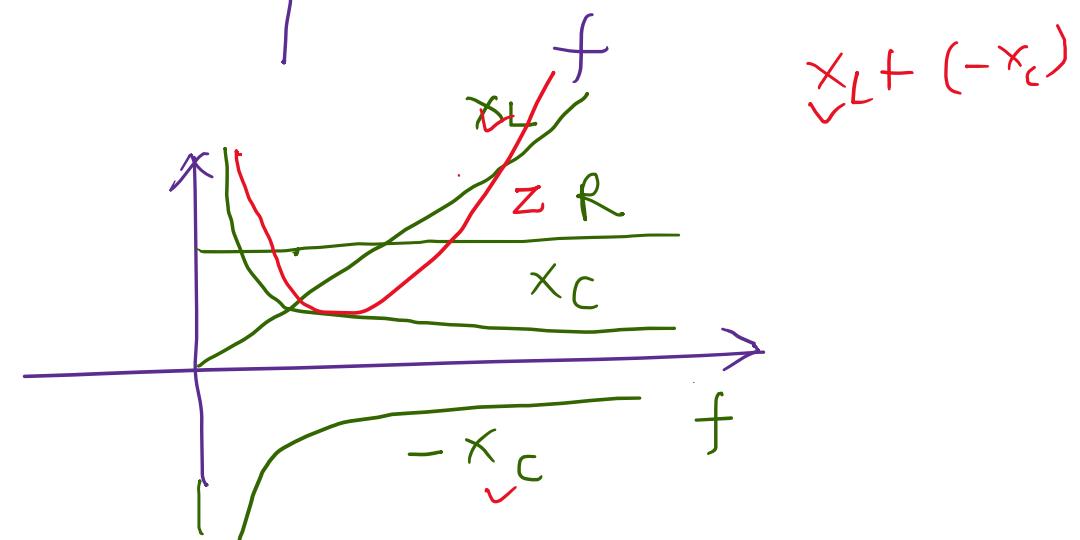


$$3) x_C = \frac{1}{2\pi f C}$$

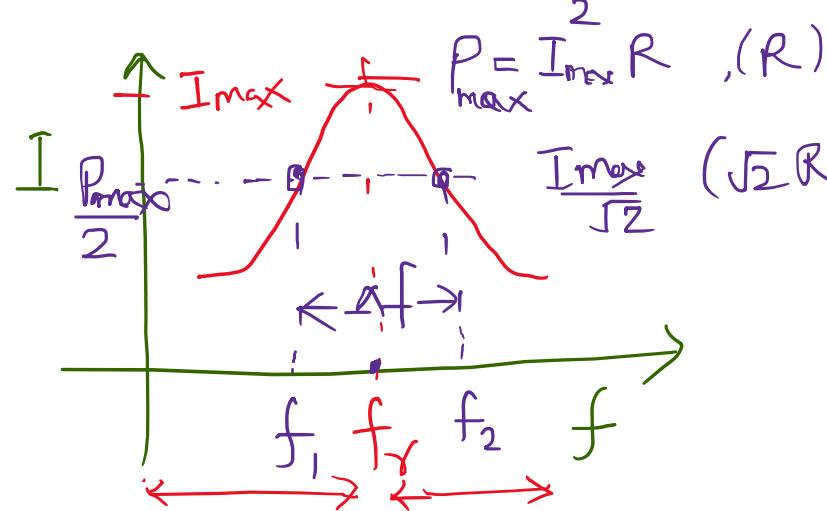
$$x_C \propto \frac{1}{f}$$



Resonance Current
 $I \propto \frac{1}{\sqrt{f}}$



Resonance Curve



half Power freq $\equiv f_1, f_2$

$$\Delta f = f_2 - f_1 \quad (\text{B.W})$$

$$\frac{I_{\max}^2 R}{2} = \left(\frac{I_{\max}}{\sqrt{2}} \right)^2 \cdot R$$

$$X_L = X_C$$

$$Z_{\min} = R$$

$$X_{\text{net}} = 0$$

$$I_{\max}$$

$$f_r$$

$$P = I_{\max}^2 \cdot R$$

$$\cos \phi = 1$$

$$\nu^\uparrow i = \phi = 0^\circ$$

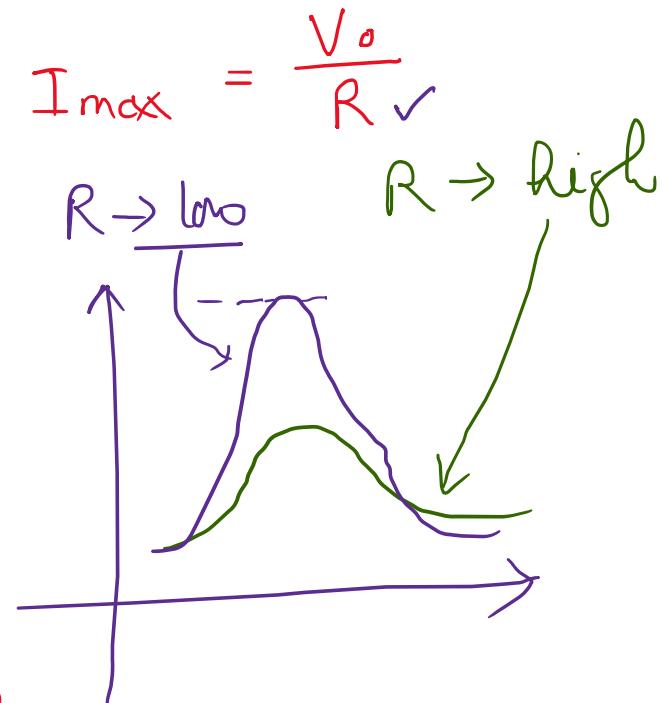
upf \rightarrow Resonance

At f_1, f_2

$$1. \quad P_{\max}/2$$

$$2. \quad I_{\max}/\sqrt{2} = 0.707 I_{\max}$$

$$3. \quad |Z| = \sqrt{2} R$$



selective $R \uparrow$
Bandwidth \downarrow

At f_1, f_2

$$|z| = \sqrt{2} R$$

$$\Rightarrow \sqrt{R^2 + x^2} = \sqrt{2} R$$

$$\Rightarrow R^2 + x^2 = 2R^2$$

$$\Rightarrow x^2 = R^2$$

$$\Rightarrow x = \pm R$$

$$\boxed{\omega_2 - \omega_1 = \frac{R}{L}}$$

$$2\pi(f_2 - f_1) = R/L$$

$$\boxed{BW = \Delta f = \frac{R}{2\pi L}}$$

$$f_1 = f_r - \frac{\Delta f}{2} =$$
$$f_2 = f_r + \frac{\Delta f}{2}$$

$$\xrightarrow{f_1} x_L - x_C = -R \quad \xrightarrow{f_2} x_L - x_C = +R$$
$$\omega_1 = 2\pi f_1 \quad \frac{f_1 < f_r}{\text{cap}} \quad x_C > x_L \quad \omega_2 = 2\pi f_2$$

$$\omega_1 L - \frac{1}{\omega_1 C} = -R \quad \left| \quad \omega_2 L - \frac{1}{\omega_2 C} = R \right.$$

$$\omega_1^2 LC - 1 + R\omega_1 C = 0$$

$$\omega_1^2 + \frac{R}{L}\omega_1 - \frac{1}{LC} = 0$$

$$\omega_2^2 - \frac{R}{L}\omega_2 - \frac{1}{LC} = 0$$

$$\omega_1 = -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}}$$

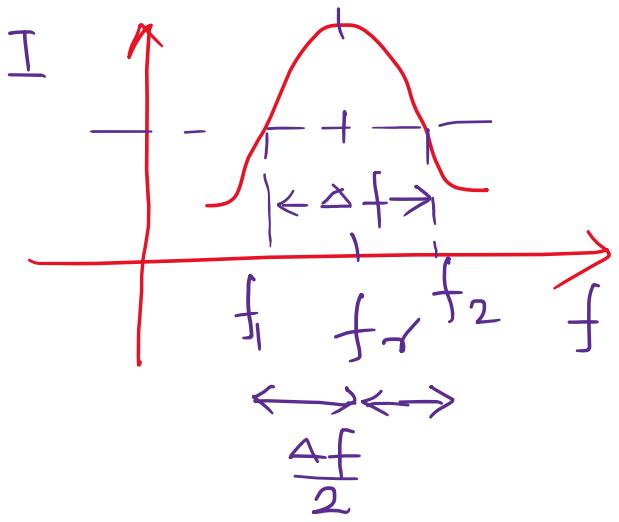
$$\omega_2 = \frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}}$$

$$\omega_1 = -\frac{R}{2L} - \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}} \times$$

$$\omega_2 = \frac{R}{2L} + \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}}$$

$$\checkmark \omega_1 = -\frac{R}{2L} + \sqrt{\left(\frac{R}{2L}\right)^2 + \frac{1}{LC}}$$

$$\omega_2$$



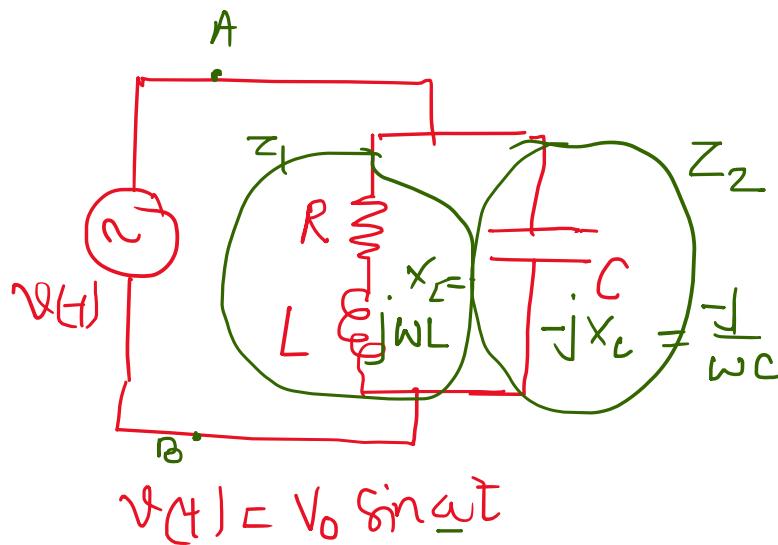
$$f_1 = f_r - \frac{\Delta f}{2} = f_r - \frac{R}{4\pi L}$$

$$f_2 = f_r + \frac{\Delta f}{2} = f_r + \frac{R}{4\pi L}$$

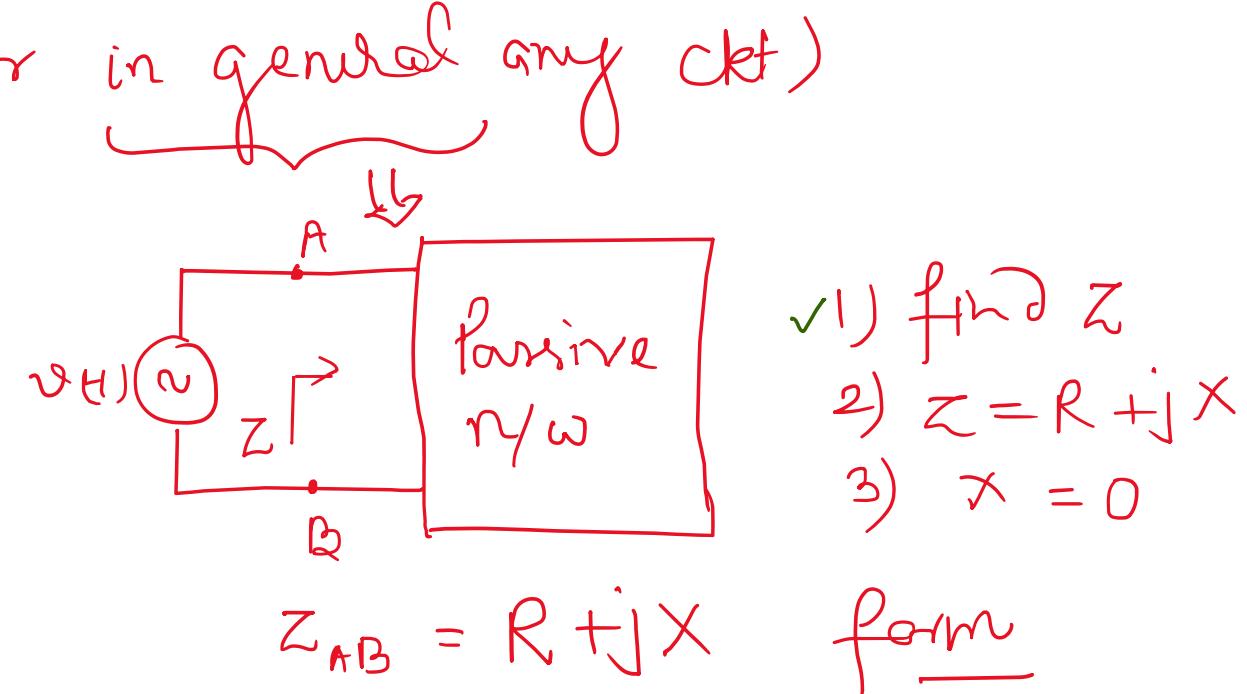
$$f_r = \frac{1}{2\pi\sqrt{LC}}$$

$$\Delta f = \frac{R}{2\pi L}$$

Resonance in 11th ckts. (or in general any ckt)



$$Z_{AB} = \frac{Z_1 Z_2}{Z_1 + Z_2} = \frac{(R + j\omega L)(-j\frac{1}{\omega C})}{R + j\omega L - j\frac{1}{\omega C}}$$



$$X = 0 \rightarrow \underline{\underline{Z_{AB} = R}}$$

Resonance Condⁿ
 ↓
 f_r

$$\begin{aligned}
 Z_{AB} &= \frac{(R+j\omega L)(-\frac{1}{j\omega C})}{R+j(\omega L - \frac{1}{\omega C})} \\
 &= \frac{(R+j\omega L)(-\frac{1}{j\omega C})[R-j(\omega L - \frac{1}{\omega C})]}{\left[R+j\left(\omega L - \frac{1}{\omega C}\right)\right]\left[R-j\left(\omega L - \frac{1}{\omega C}\right)\right]} \\
 &= \frac{-\frac{1}{j\omega C} \left[R^2 + \omega L \left(\omega L - \frac{1}{\omega C} \right) + j \left\{ R\omega L - R \left(\omega L - \frac{1}{\omega C} \right) \right\} \right]}{R^2 + \left(\omega L - \frac{1}{\omega C} \right)^2} \\
 &= \frac{\frac{1}{\omega C} \left\{ R\omega L - R \left(\omega L - \frac{1}{\omega C} \right) \right\}}{R^2 + \left(\omega L - \frac{1}{\omega C} \right)^2} - j \frac{\frac{1}{\omega C} \left[R^2 + \omega L \left(\omega L - \frac{1}{\omega C} \right) \right]}{R^2 + \left(\omega L - \frac{1}{\omega C} \right)^2} \\
 Z_{AB} &= \boxed{R + j \times 0}
 \end{aligned}$$

$$\frac{\frac{1}{\omega_C} [R^2 + \omega L (\omega L - \frac{1}{\omega_C})]}{R^2 + (\omega L - \frac{1}{\omega_C})^2} = 0$$

$$\Rightarrow \boxed{R^2 + \omega^2 L^2 - \frac{L}{C} = 0}$$

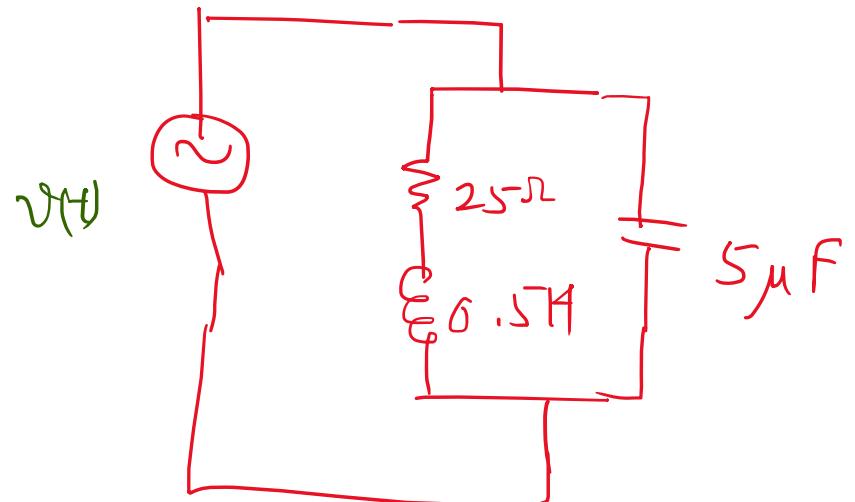
$$\Rightarrow \omega^2 L^2 = \frac{L}{C} - R^2$$

$$\Rightarrow \omega^2 = \frac{1}{LC} - \left(\frac{R}{L}\right)^2$$

$$\boxed{\omega_r = \sqrt{\frac{1}{LC} - \left(\frac{R}{L}\right)^2}}$$

$$\boxed{f_r = \frac{1}{2\pi} \sqrt{\frac{1}{LC} - \left(\frac{R}{L}\right)^2}}$$

Prob: (i) f_r (ii) $\underline{Z_{tot}}$ at resonance (iii) $B\omega$ (iv) Q



$$f_r = \frac{1}{2\pi} \sqrt{\frac{1}{LC} - \left(\frac{R}{L}\right)^2}$$

$$= \frac{1}{2\pi} \sqrt{\frac{1}{0.5 \times 5 \times 10^{-6}} - \left(\frac{25}{0.5}\right)^2}$$

$$= 180.34 \text{ Hz}$$

$$Z = \frac{L}{CR} = \frac{0.5}{5 \times 10^{-6} \times 25} = 4000 \Omega$$

$$B\omega = \frac{R}{2\pi L} = \frac{25}{2\pi \times 0.5} = 7.9 \text{ Hz}$$

$$\alpha = \frac{1}{R} \sqrt{\frac{L}{C}} = \frac{1}{25} \sqrt{\frac{0.5}{5 \times 10^{-6}}} = 12.65$$

Major Exam

Q.1. (10) Unit ① + ② 7 part (a), (b), (c), (d), (e), (f), (g)

$$5 \times 2 = \underline{10} \quad \cancel{\underline{10}}$$

Q.2 (10)] Unit ③ $\begin{cases} (a) \\ (b) \\ (c) \end{cases}$ 2 out of 3 (5×2)

Q.3 (10)

Q.4 (10)] Unit ④

Q.5 (10)

- Unit - ① N ✓
② N.v.P
③ N + T.
④ T.