

1.Program to implement non token based algorithm for Mutual Exclusion

```
#include <iostream>
#include <queue>
#include <vector>
#include <climits>
#include <thread>
#include <mutex>
#include <chrono>
#include <condition_variable>

using namespace std;

// Mutex and condition variable to simulate request queue
std::mutex mtx;
std::condition_variable cv;
int number_of_processes;
bool resource_available = true;
struct Request {
    int timestamp;
    int process_id;
};

// Global variables
std::vector<int> timestamps;
std::vector<bool> waiting;
std::queue<Request> request_queue;

// Function to compare two requests
bool compareRequest(Request a, Request b) {
    if (a.timestamp == b.timestamp)
        return a.process_id < b.process_id;
    return a.timestamp < b.timestamp;
}

// Function for a process to request access to a shared resource
void requestResource(int process_id) {
```

```

std::unique_lock<std::mutex> lock(mtx);

int timestamp = ++timestamps[process_id];

cout << "Process " << process_id << " is requesting the resource with timestamp " << timestamp <<
endl;

request_queue.push({timestamp, process_id});

waiting[process_id] = true;

// Wait until it's this process's turn to access the resource
while (!resource_available || request_queue.front().process_id != process_id) {
    cv.wait(lock);
}

// Now process gets access to the resource
resource_available = false;

waiting[process_id] = false;

cout << "Process " << process_id << " is accessing the resource." << endl;

// Simulate the process holding the resource for some time
std::this_thread::sleep_for(std::chrono::seconds(1));

// Release the resource
cout << "Process " << process_id << " has released the resource." << endl;

resource_available = true;

request_queue.pop();

// Notify other waiting processes
cv.notify_all();
}

// Simulate each process
void process(int process_id) {
    // Simulate some processing work
    std::this_thread::sleep_for(std::chrono::seconds(2 + process_id));

    // Request the shared resource
    requestResource(process_id);
}

int main() {

```

```
number_of_processes = 3; // You can modify this value
timestamps.resize(number_of_processes, 0);
waiting.resize(number_of_processes, false);
std::vector<std::thread> threads;
// Create threads for each process
for (int i = 0; i < number_of_processes; ++i) {
    threads.push_back(std::thread(process, i));
}
// Join all threads
for (auto& th : threads) {
    th.join();
}
return 0;
}
```

Sample Output

Process 0 is requesting the resource with timestamp 1

Process 1 is requesting the resource with timestamp 1

Process 2 is requesting the resource with timestamp 1

Process 0 is accessing the resource.

Process 0 has released the resource.

Process 1 is accessing the resource.

Process 1 has released the resource.

Process 2 is accessing the resource.

Process 2 has released the resource.

2.Program to implement Lamport's Logical Clock.

```
#include <iostream>

#include <vector>

#include <algorithm>

using namespace std;

// Function to simulate the maximum of two numbers
int max(int a, int b) {
    return (a > b) ? a : b;
}

// Class representing a process in the system
class Process {
public:
    int process_id;
    int clock;

    // Constructor
    Process(int id) {
        process_id = id;
        clock = 0; // Initialize the clock to 0
    }

    // Method to simulate an event happening in this process
    void event() {
        clock++;

        cout << "Event in Process " << process_id << " | Logical Clock: " << clock << endl;
    }

    // Method to send a message from this process to another process
    void send_message(Process& receiver) {
        clock++; // Increment the clock for the send event

        cout << "Process " << process_id << " sent a message to Process " << receiver.process_id << " | Clock: " << clock << endl;

        receiver.receive_message(clock);
    }
}
```

```

// Method to receive a message and update the clock
void receive_message(int sender_clock) {
    clock = max(clock, sender_clock) + 1;

    cout << "Process " << process_id << " received a message | Updated Logical Clock: " << clock <<
endl;

}
};

int main() {
    // Create processes
    Process p1(1);
    Process p2(2);
    Process p3(3);

    // Simulate events and message passing
    p1.event();    // Event in Process 1
    p2.event();    // Event in Process 2
    p1.send_message(p2); // Process 1 sends a message to Process 2
    p3.event();    // Event in Process 3
    p2.send_message(p3); // Process 2 sends a message to Process 3
    p1.event();    // Another event in Process 1
    return 0;
}

```

Sample Output

Event in Process 1 | Logical Clock: 1

Event in Process 2 | Logical Clock: 1

Process 1 sent a message to Process 2 | Clock: 2

Process 2 received a message | Updated Logical Clock: 3

Event in Process 3 | Logical Clock: 1

Process 2 sent a message to Process 3 | Clock: 4

Process 3 received a message | Updated Logical Clock: 5

Event in Process 1 | Logical Clock: 3

3.Program to implement edge chasing distributed deadlock detection algorithm.

```
#include <iostream>

#include <vector>

#include <queue>

using namespace std;

class Process {

public:

    int id; // Process ID

    vector<int> waitingFor; // List of processes this process is waiting for

    Process(int id) : id(id) {}

};

// Function to detect deadlock using the Edge Chasing algorithm

bool detectDeadlock(vector<Process>& processes, int initiator) {

    queue<int> probeQueue;

    vector<bool> visited(processes.size(), false);

    // Initiator process starts the deadlock detection by sending probes

    probeQueue.push(initiator);

    visited[initiator] = true;

    cout << "Process " << initiator << " initiates deadlock detection." << endl;

    while (!probeQueue.empty()) {

        int currentProcess = probeQueue.front();

        probeQueue.pop();

        // Check if the current process is waiting for any other process

        for (int waitingFor : processes[currentProcess].waitingFor) {

            // If a probe returns to the initiator, a deadlock is detected

            if (waitingFor == initiator) {

                cout << "Deadlock detected: Process " << initiator << " is involved in a cycle!" << endl;

                return true;

            }

        }

        // If the process has not been visited yet, send a probe to it

        if (!visited[waitingFor]) {
```



```

        visited[waitingFor] = true;

        cout << "Probe sent from Process " << currentProcess << " to Process " << waitingFor << endl;

        probeQueue.push(waitingFor);
    }
}

// No deadlock detected if we exit the loop
cout << "No deadlock detected." << endl;
return false;
}

int main() {
    int numProcesses = 4;

    // Create processes with IDs 0, 1, 2, 3
    vector<Process> processes;

    for (int i = 0; i < numProcesses; i++) {
        processes.push_back(Process(i));
    }

    // Add dependencies (wait-for graph)
    // Example: Process 0 is waiting for Process 1, and Process 1 is waiting for Process 2, etc.
    processes[0].waitingFor = {1}; // Process 0 waits for Process 1
    processes[1].waitingFor = {2}; // Process 1 waits for Process 2
    processes[2].waitingFor = {3}; // Process 2 waits for Process 3
    processes[3].waitingFor = {0}; // Process 3 waits for Process 0, forming a cycle (deadlock)

    // Initiate deadlock detection from Process 0
    int initiator = 0;

    detectDeadlock(processes, initiator);

    return 0;
}

```

Sample Output

Process 0 initiates deadlock detection.

Probe sent from Process 0 to Process 1

Probe sent from Process 1 to Process 2

Probe sent from Process 2 to Process 3

Probe sent from Process 3 to Process 0

Deadlock detected: Process 0 is involved in a cycle!

4.Program to implement locking algorithm.

```
#include <iostream>

#include <thread>

#include <mutex>

#include <chrono> // For sleep_for

using namespace std;

// Global mutex to protect shared resources

mutex mtx;

// Shared resource (a counter)

int shared_counter = 0;

// Function to simulate critical section with locking using lock_guard

void increment_counter(int thread_id) {

    cout << "Thread " << thread_id << " is trying to acquire the lock..." << endl;

    // Lock the critical section using lock_guard (RAII: automatically locks and unlocks)

    lock_guard<mutex> lock(mtx);

    // Critical section starts

    cout << "Thread " << thread_id << " has acquired the lock." << endl;

    shared_counter++;

    cout << "Thread " << thread_id << " incremented the counter to " << shared_counter << endl;

    // Simulate some processing time

    this_thread::sleep_for(chrono::milliseconds(500));

    // lock_guard automatically releases the lock when going out of scope

    cout << "Thread " << thread_id << " has released the lock." << endl;

}

int main() {

    // Create multiple threads to access the shared resource

    thread t1(increment_counter, 1);

    thread t2(increment_counter, 2);

    thread t3(increment_counter, 3);

    // Wait for all threads to complete

    t1.join();
```

```
t2.join();  
t3.join();  
  
// Final value of the shared resource  
cout << "Final value of shared_counter: " << shared_counter << endl;  
return 0;  
}
```

Sample Output

Thread 1 is trying to acquire the lock...

Thread 1 has acquired the lock.

Thread 1 incremented the counter to 1

Thread 2 is trying to acquire the lock...

Thread 1 has released the lock.

Thread 2 has acquired the lock.

Thread 2 incremented the counter to 2

Thread 2 has released the lock.

Final value of shared_counter: 2

5. Program to implement Remote Method Invocation

```
#include <iostream>
#include <string>
#include <netinet/in.h>
#include <unistd.h>
#include <cstring>
using namespace std;
const int PORT = 8080;
void performAddition(int client_socket) {
    int num1, num2, sum;
    // Read numbers from the client
    read(client_socket, &num1, sizeof(num1));
    read(client_socket, &num2, sizeof(num2));
    sum = num1 + num2;
    // Send the result back to the client
    write(client_socket, &sum, sizeof(sum));
}
int main() {
    int server_fd, client_socket;
    struct sockaddr_in address;
    int addrlen = sizeof(address);
    // Create socket file descriptor
    server_fd = socket(AF_INET, SOCK_STREAM, 0);
    if (server_fd == 0) {
        cerr << "Socket creation failed!" << endl;
        return -1;
    }
    // Define the server address
    address.sin_family = AF_INET;
    address.sin_addr.s_addr = INADDR_ANY;
```

```

address.sin_port = htons(PORT);

// Bind the socket to the port
if (bind(server_fd, (struct sockaddr *)&address, sizeof(address)) < 0) {
    cerr << "Binding failed!" << endl;
    return -1;
}

// Start listening for connections
listen(server_fd, 3);

cout << "Server is listening on port " << PORT << endl;

// Accept a client connection
client_socket = accept(server_fd, (struct sockaddr *)&address, (socklen_t *)&addrlen);
if (client_socket < 0) {
    cerr << "Connection failed!" << endl;
    return -1;
}

cout << "Client connected!" << endl;

// Perform addition
performAddition(client_socket);

// Close the socket
close(client_socket);
close(server_fd);

return 0;
}

```

Client Code (client.cpp)

```
#include <iostream>

#include <netinet/in.h>

#include <unistd.h>

#include <cstring>

using namespace std;

const int PORT = 8080;

int main() {

    int sock = 0;

    struct sockaddr_in serv_addr;

    // Create socket

    sock = socket(AF_INET, SOCK_STREAM, 0);

    if (sock < 0) {

        cerr << "Socket creation error!" << endl;

        return -1;

    }

    // Define the server address

    serv_addr.sin_family = AF_INET;

    serv_addr.sin_port = htons(PORT);

    // Convert IPv4 and IPv6 addresses from text to binary form

    if (inet_pton(AF_INET, "127.0.0.1", &serv_addr.sin_addr) <= 0) {

        cerr << "Invalid address/Address not supported!" << endl;

        return -1;

    }

    // Connect to the server

    if (connect(sock, (struct sockaddr *)&serv_addr, sizeof(serv_addr)) < 0) {

        cerr << "Connection failed!" << endl;

        return -1;

    }

    // Input numbers to add

    int num1, num2;
```



```
cout << "Enter two numbers to add: ";  
cin >> num1 >> num2;  
  
// Send numbers to the server  
write(sock, &num1, sizeof(num1));  
write(sock, &num2, sizeof(num2));  
  
// Receive the result from the server  
  
int sum;  
read(sock, &sum, sizeof(sum));  
  
cout << "Result from server: " << sum << endl;  
  
// Close the socket  
close(sock);  
  
return 0;  
}
```

Sample Output

On the server terminal:

arduino

Server is listening on port 8080

Client connected!

On the client terminal:

sql

Enter two numbers to add: 5 7

Result from server: 12

6. Program to implement Remote Procedure Call.

Server Code (server.cpp)

```
#include <iostream>
#include <string>
#include <netinet/in.h>
#include <unistd.h>
#include <cstring>

using namespace std;

const int PORT = 8080;

void performAddition(int client_socket) {
    int num1, num2, sum;

    // Read numbers from the client
    read(client_socket, &num1, sizeof(num1));
    read(client_socket, &num2, sizeof(num2));

    sum = num1 + num2;

    // Send the result back to the client
    write(client_socket, &sum, sizeof(sum));
}

int main() {
    int server_fd, client_socket;
    struct sockaddr_in address;
    int addrlen = sizeof(address);

    // Create socket file descriptor
    server_fd = socket(AF_INET, SOCK_STREAM, 0);

    if (server_fd == 0) {
        cerr << "Socket creation failed!" << endl;
        return -1;
    }

    // Define the server address
    address.sin_family = AF_INET;
```

```

address.sin_addr.s_addr = INADDR_ANY;
address.sin_port = htons(PORT);

// Bind the socket to the port
if (bind(server_fd, (struct sockaddr *)&address, sizeof(address)) < 0) {
    cerr << "Binding failed!" << endl;
    return -1;
}

// Start listening for connections
listen(server_fd, 3);

cout << "Server is listening on port " << PORT << endl;

// Accept a client connection
client_socket = accept(server_fd, (struct sockaddr *)&address, (socklen_t *)&addrlen);
if (client_socket < 0) {
    cerr << "Connection failed!" << endl;
    return -1;
}

cout << "Client connected!" << endl;

// Perform addition
performAddition(client_socket);

// Close the socket
close(client_socket);
close(server_fd);

return 0;
}

```

Client Code (client.cpp)

```
#include <iostream>

#include <netinet/in.h>

#include <unistd.h>

#include <cstring>

using namespace std;

const int PORT = 8080;

int main() {

    int sock = 0;

    struct sockaddr_in serv_addr;

    // Create socket

    sock = socket(AF_INET, SOCK_STREAM, 0);

    if (sock < 0) {

        cerr << "Socket creation error!" << endl;

        return -1;

    }

    // Define the server address

    serv_addr.sin_family = AF_INET;

    serv_addr.sin_port = htons(PORT);

    // Convert IPv4 and IPv6 addresses from text to binary form

    if (inet_pton(AF_INET, "127.0.0.1", &serv_addr.sin_addr) <= 0) {

        cerr << "Invalid address/Address not supported!" << endl;

        return -1;

    }

    // Connect to the server

    if (connect(sock, (struct sockaddr *)&serv_addr, sizeof(serv_addr)) < 0) {

        cerr << "Connection failed!" << endl;

        return -1;

    }

    // Input numbers to add

    int num1, num2;
```

```
cout << "Enter two numbers to add: ";  
cin >> num1 >> num2;  
  
// Send numbers to the server  
write(sock, &num1, sizeof(num1));  
write(sock, &num2, sizeof(num2));  
  
// Receive the result from the server  
int sum;  
read(sock, &sum, sizeof(sum));  
cout << "Result from server: " << sum << endl;  
  
// Close the socket  
close(sock);  
return 0;  
}
```

Sample Output

On the server terminal:

arduino

Server is listening on port 8080

Client connected!

On the client terminal:

sql

Enter two numbers to add: 5 7

Result from server: 12

7.Program to implement Chat Server

Chat Server Implementation (server.cpp)

```
#include <iostream>

#include <string>

#include <vector>

#include <thread>

#include <mutex>

#include <netinet/in.h>

#include <unistd.h>

#include <cstring>

using namespace std;

const int PORT = 8080;

vector<int> clients; // Vector to hold client sockets

mutex clientsMutex; // Mutex to protect access to clients vector

void broadcastMessage(const string& message, int senderSocket) {

    lock_guard<mutex> lock(clientsMutex);

    for (int client : clients) {

        if (client != senderSocket) {

            send(client, message.c_str(), message.size(), 0);

        }

    }

}

void handleClient(int clientSocket) {

    char buffer[1024];

    string welcomeMessage = "Welcome to the chat server!\n";

    send(clientSocket, welcomeMessage.c_str(), welcomeMessage.size(), 0);

    while (true) {
```

```

    memset(buffer, 0, sizeof(buffer));

    int bytesRead = recv(clientSocket, buffer, sizeof(buffer), 0);

    if (bytesRead <= 0) {
        break; // Client disconnected
    }

    string message(buffer);

    cout << "Received: " << message;

    broadcastMessage(message, clientSocket);
}

// Remove client from the list and close the socket
{
    lock_guard<mutex> lock(clientsMutex);

    clients.erase(remove(clients.begin(), clients.end(), clientSocket), clients.end());
}

close(clientSocket);
}

int main() {
    int serverSocket, clientSocket;

    struct sockaddr_in serverAddr, clientAddr;

    socklen_t clientAddrLen = sizeof(clientAddr);

    // Create socket
    serverSocket = socket(AF_INET, SOCK_STREAM, 0);

    if (serverSocket == -1) {
        cerr << "Socket creation failed!" << endl;

        return -1;
    }

    // Define server address
    serverAddr.sin_family = AF_INET;

    serverAddr.sin_addr.s_addr = INADDR_ANY;

```



```

serverAddr.sin_port = htons(PORT);

// Bind the socket to the port
if (bind(serverSocket, (struct sockaddr *)&serverAddr, sizeof(serverAddr)) < 0) {
    cerr << "Binding failed!" << endl;
    return -1;
}

// Start listening for connections
listen(serverSocket, 5);

cout << "Chat server is listening on port " << PORT << endl;

while (true) {
    // Accept a new client connection
    clientSocket = accept(serverSocket, (struct sockaddr *)&clientAddr, &clientAddrLen);
    if (clientSocket < 0) {
        cerr << "Connection failed!" << endl;
        continue;
    }
    {
        lock_guard<mutex> lock(clientsMutex);
        clients.push_back(clientSocket);
    }

    cout << "New client connected!" << endl;

    // Handle client in a new thread
    thread(handleClient, clientSocket).detach();
}

close(serverSocket);

return 0;
}

```

Chat Client Implementation (client.cpp)

```
#include <iostream>
#include <thread>
#include <string>
#include <netinet/in.h>
#include <unistd.h>
#include <cstring>
using namespace std;
const int PORT = 8080;
void receiveMessages(int socket) {
    char buffer[1024];
    while (true) {
        memset(buffer, 0, sizeof(buffer));
        int bytesRead = recv(socket, buffer, sizeof(buffer), 0);
        if (bytesRead <= 0) {
            break; // Server disconnected
        }
        cout << "Message: " << buffer << endl;
    }
}
int main() {
    int socket_fd;
    struct sockaddr_in serverAddr;

    // Create socket
    socket_fd = socket(AF_INET, SOCK_STREAM, 0);
    if (socket_fd < 0) {
```

```

    cerr << "Socket creation error!" << endl;
    return -1;
}

// Define the server address
serverAddr.sin_family = AF_INET;
serverAddr.sin_port = htons(PORT);
if (inet_pton(AF_INET, "127.0.0.1", &serverAddr.sin_addr) <= 0) {
    cerr << "Invalid address/Address not supported!" << endl;
    return -1;
}

// Connect to the server
if (connect(socket_fd, (struct sockaddr *)&serverAddr, sizeof(serverAddr)) < 0) {
    cerr << "Connection to server failed!" << endl;
    return -1;
}

// Start a thread to receive messages
thread(receiveMessages, socket_fd).detach();

// Main loop to send messages
string message;
while (true) {
    cout << "Enter your message: ";
    getline(cin, message);
    send(socket_fd, message.c_str(), message.size(), 0);
}

close(socket_fd);
return 0;
}

```

Sample Output

On the server terminal:

vbnet

Chat server is listening on port 8080

New client connected!

New client connected!

Received: Hello from client 1

Message: Hello from client 1

On the client terminal:

mathematica

Enter your message: Hello from client 1

Message: Hello from client 1

Enter your message: Hi there!

8. Program to implement termination detection

Process Class Definition

```
#include <iostream>

#include <vector>

#include <thread>

#include <mutex>

#include <condition_variable>

#include <chrono>

#include <queue>

using namespace std;

class Process {

public:

    Process(int id) : id(id), state(0), terminationDetected(false) {}

    void run();

    void sendMessage(Process &receiver, const string &message);

    void receiveMessage(const string &message);

    void setPassive();

    void checkTermination();

    int id;

    int state; // 0 for active, 1 for passive

    bool terminationDetected;

private:

    mutex mtx;

    condition_variable cv;

    queue<string> messageQueue;

};
```

```

void Process::sendMessage(Process &receiver, const string &message) {
    unique_lock<mutex> lock(receiver.mtx);
    receiver.messageQueue.push(message);
    cv.notify_all(); // Notify the receiving process
}

void Process::receiveMessage(const string &message) {
    unique_lock<mutex> lock(mtx);
    messageQueue.push(message);
    cout << "Process " << id << " received message: " << message << endl;
}

void Process::setPassive() {
    unique_lock<mutex> lock(mtx);
    state = 1; // Set to passive
    cout << "Process " << id << " is now passive." << endl;
    cv.notify_all(); // Notify termination checking
}

void Process::checkTermination() {
    unique_lock<mutex> lock(mtx);
    if (state == 1 && messageQueue.empty()) {
        terminationDetected = true;
        cout << "Termination detected in process " << id << "!" << endl;
    }
}

```

Main Function to Simulate the System

```
int main() {  
    Process p1(1);  
    Process p2(2);  
    // Simulating sending messages  
    thread t1([&]() {  
        this_thread::sleep_for(chrono::seconds(1));  
        p1.sendMessage(p2, "Hello from Process 1");  
        this_thread::sleep_for(chrono::seconds(1));  
        p1.setPassive();  
    });  
    thread t2([&]() {  
        this_thread::sleep_for(chrono::seconds(2));  
        p2.sendMessage(p1, "Hello from Process 2");  
        this_thread::sleep_for(chrono::seconds(1));  
        p2.setPassive();  
    });  
    // Simulating message receiving and termination checking  
    while (!p1.terminationDetected || !p2.terminationDetected) {  
        this_thread::sleep_for(chrono::milliseconds(500));  
        p1.checkTermination();  
        p2.checkTermination();  
        // Check for incoming messages  
        if (!p1.messageQueue.empty()) {  
            string msg = p1.messageQueue.front();
```

```
    p1.messageQueue.pop();  
    p2.receiveMessage(msg);  
}  
if (!p2.messageQueue.empty()) {  
    string msg = p2.messageQueue.front();  
    p2.messageQueue.pop();  
    p1.receiveMessage(msg);  
}  
}  
t1.join();  
t2.join();  
return 0;  
}
```


Sample Output

Process 1 received message: Hello from Process 2

Process 2 received message: Hello from Process 1

Process 1 is now passive.

Process 2 is now passive.

Termination detected in process 1!

Termination detected in process 2!