



UCL ARTIFICIAL  
INTELLIGENCE SOCIETY

# TUTORIAL #4

Session 4

*Introduction to unsupervised models and data pre-processing*

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# LECTURE OVERVIEW

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01 |

## Data Preprocessing

What is it and how to use it

02 |

## Model Training

Overview of the most important terms in ML

03 |

## Data visualisation

04 |

## Other Supervised Models

Support Vector Machine  
Decision Trees

# SUPERVISED V. UNSUPERVISED LEARNING

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## Supervised L.

- It learns using data X and labels Y
- Learns  $X \rightarrow Y$



## Unspervised L.

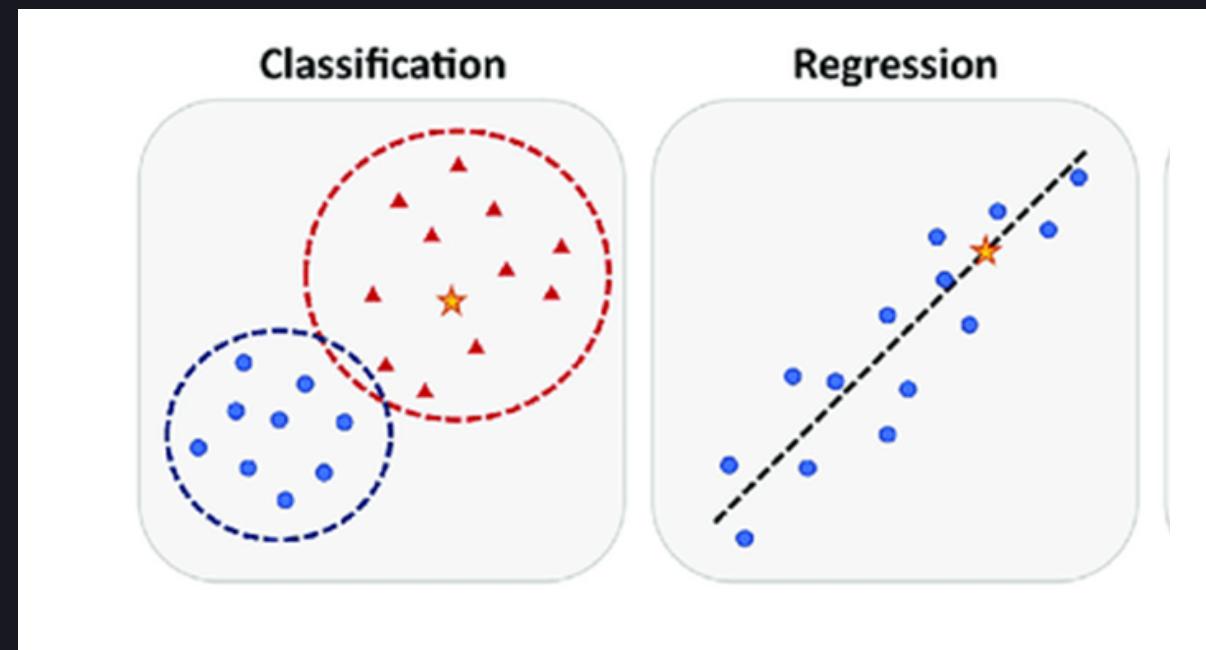
- It learns using just data X
- Observes underlying structures



# SUPERVISED V. UNSUPERVISED LEARNING

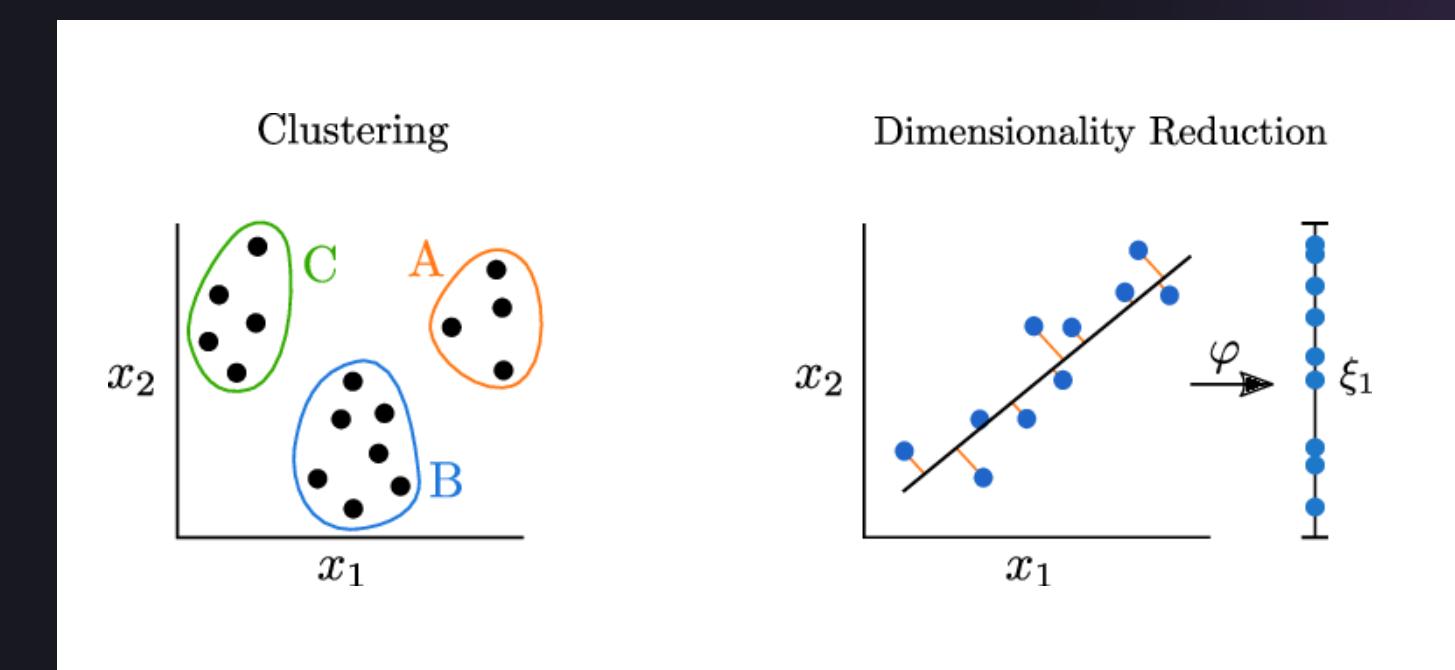
## Supervised L.

- Fits some function
- Regression and Classification



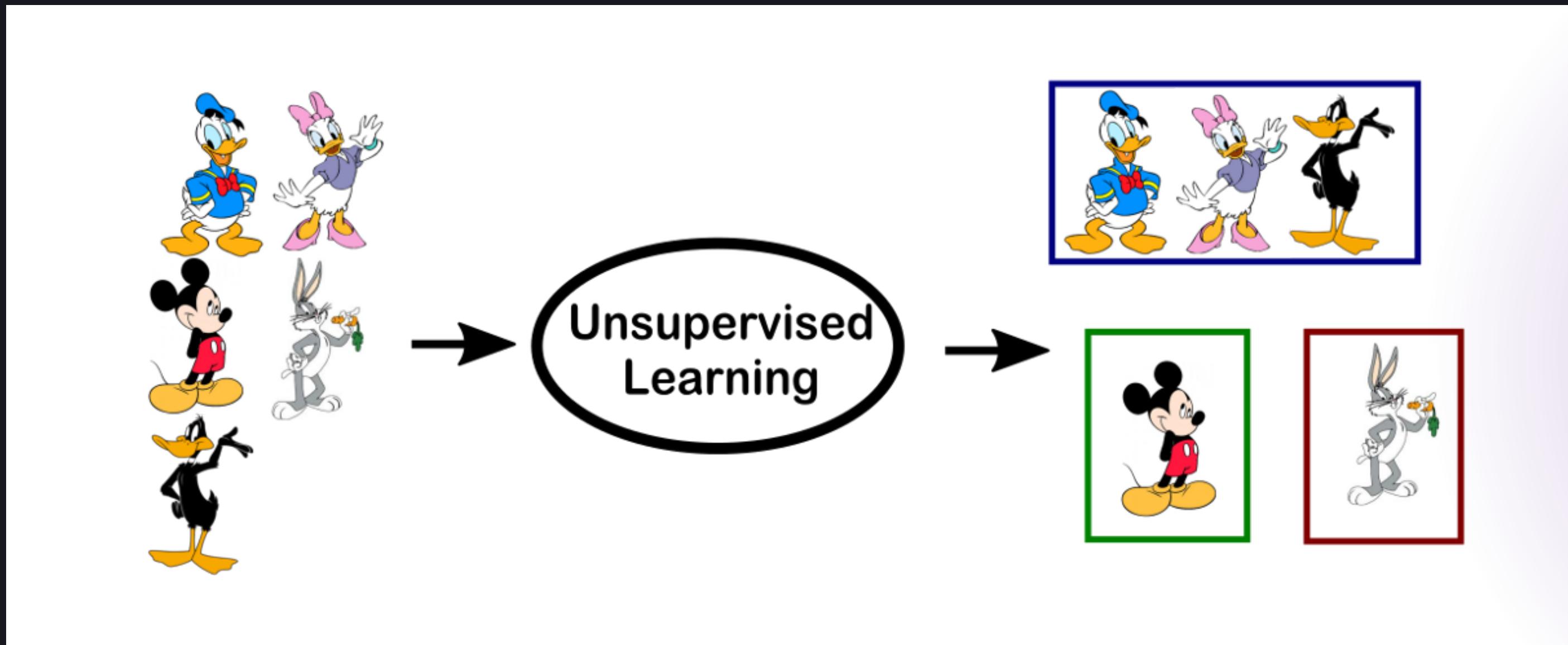
## Unspervised L.

- Works with and transforms data
- Clustering and Dimensional Reduction



Theory

# SUPERVISED V. UNSUPERVISED LEARNING



# SUPERVISED V. UNSUPERVISED LEARNING

	<i>Supervised Learning</i>	<i>Unsupervised Learning</i>
<i>Discrete</i>	classification or categorization	clustering
<i>Continuous</i>	regression	dimensionality reduction

Theory

# DATA PRE-PROCESSING

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Raw Data:

Imagination:

- No inconsistencies
- No noise
- Complete
- No missing values

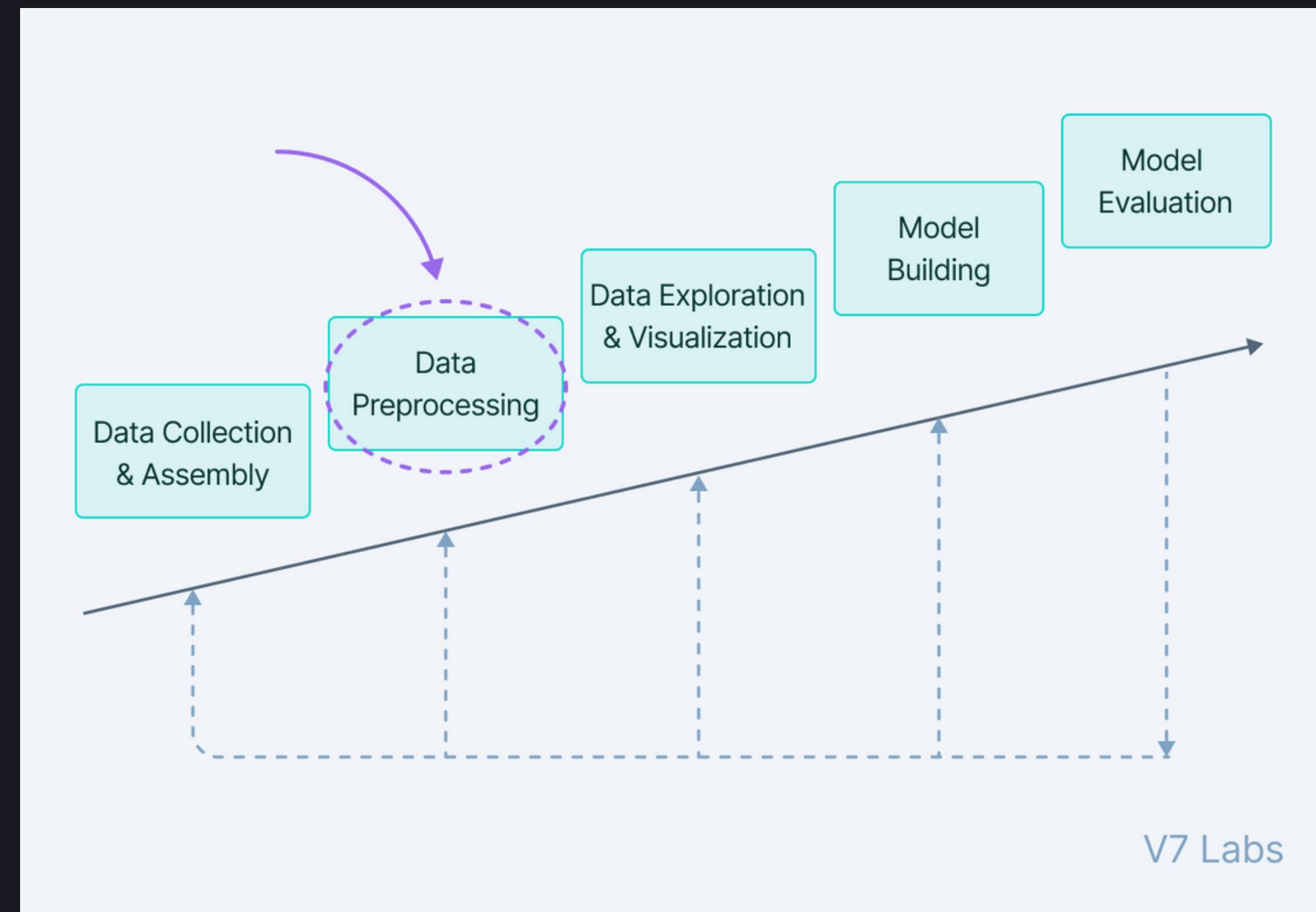
etc

Reality:



Theory

# DATA PRE-PROCESSING

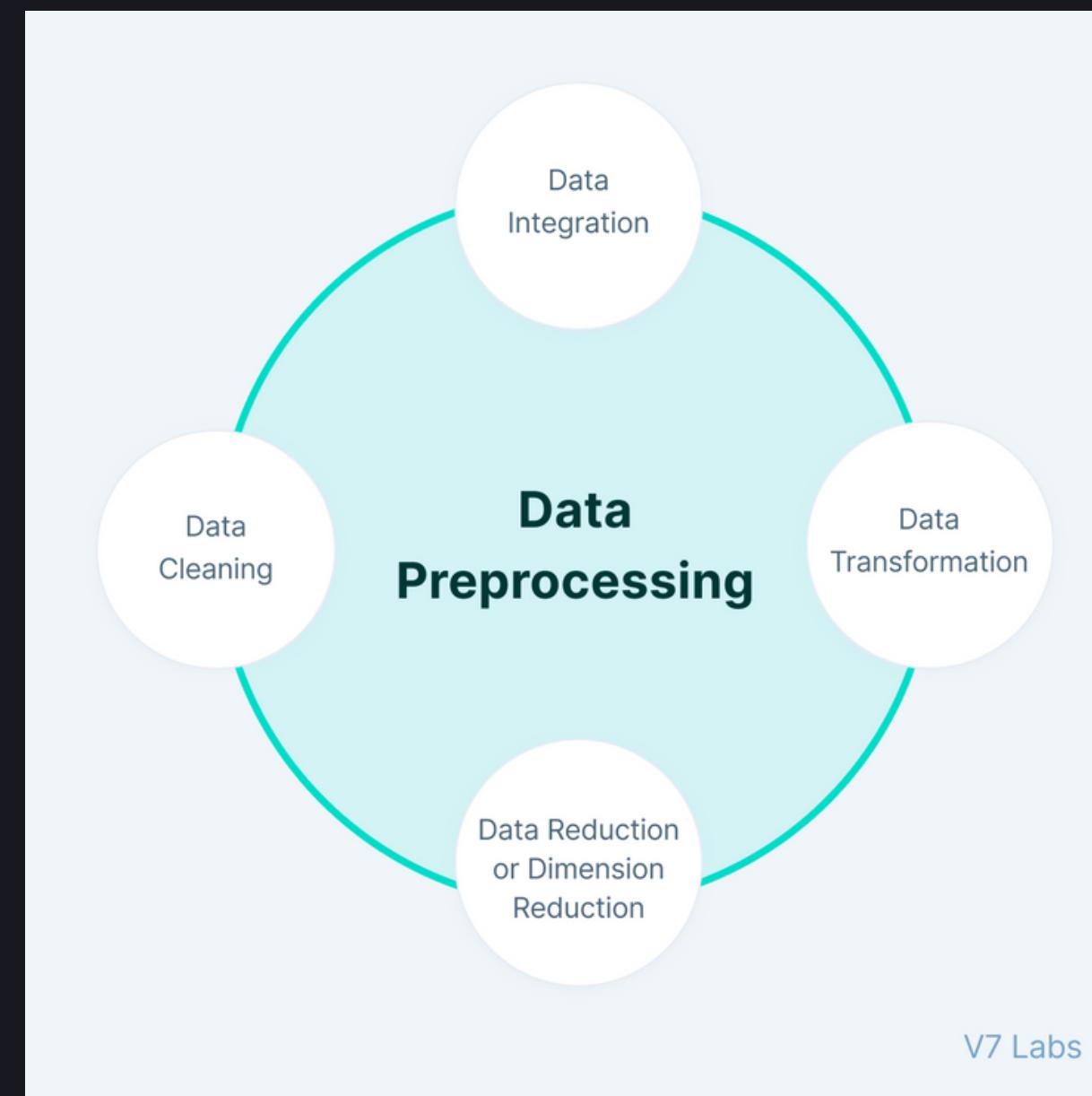


Theory

# DATA PRE-PROCESSING

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## 4 Steps in Data Preprocessing



Theory

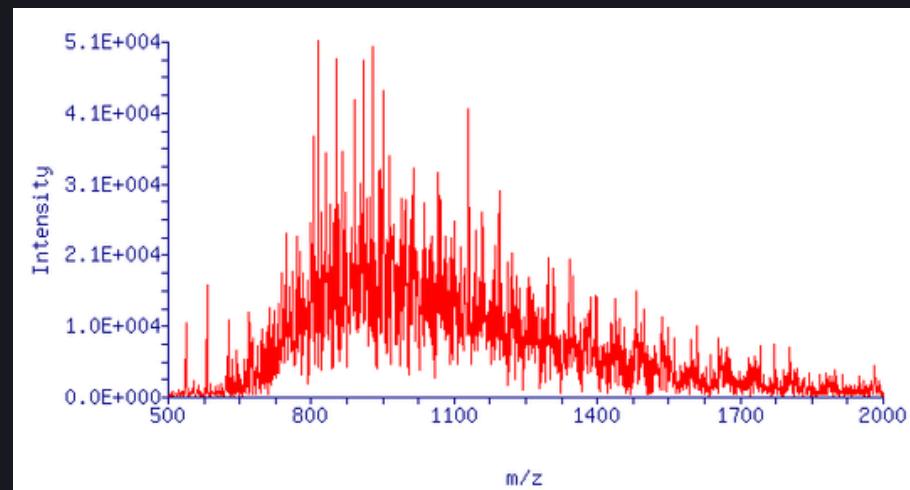
# DATA PRE-PROCESSING

## Data cleaning

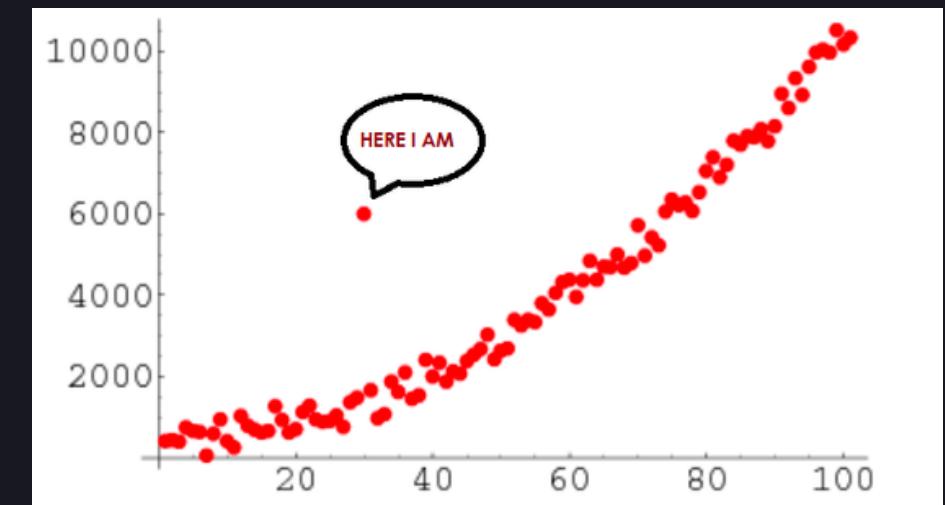
### 1) Missing values

Missing values										
PassengerId	Survived	Pclass	Sex	Age	SibSp	Parch	Ticket	Fare	Cabin	Embarked
1	0	3	male	22	1	0	A/5 21171	7.25		S
2	1	1	female	38	1	0	PC 17599	71.2033	C85	C
3	1	3	female	26	0	0	STON/O2. 3101282	7.925		S
4	1	1	female	35	1	0	113803	53.1	C123	S
5	0	3	male	35	0	0	373450	8.05		S
6	0	3	male	0	0	0	330877	8.4583		Q

### 2) Noisy data



### 3) Removing Outliers



Theory

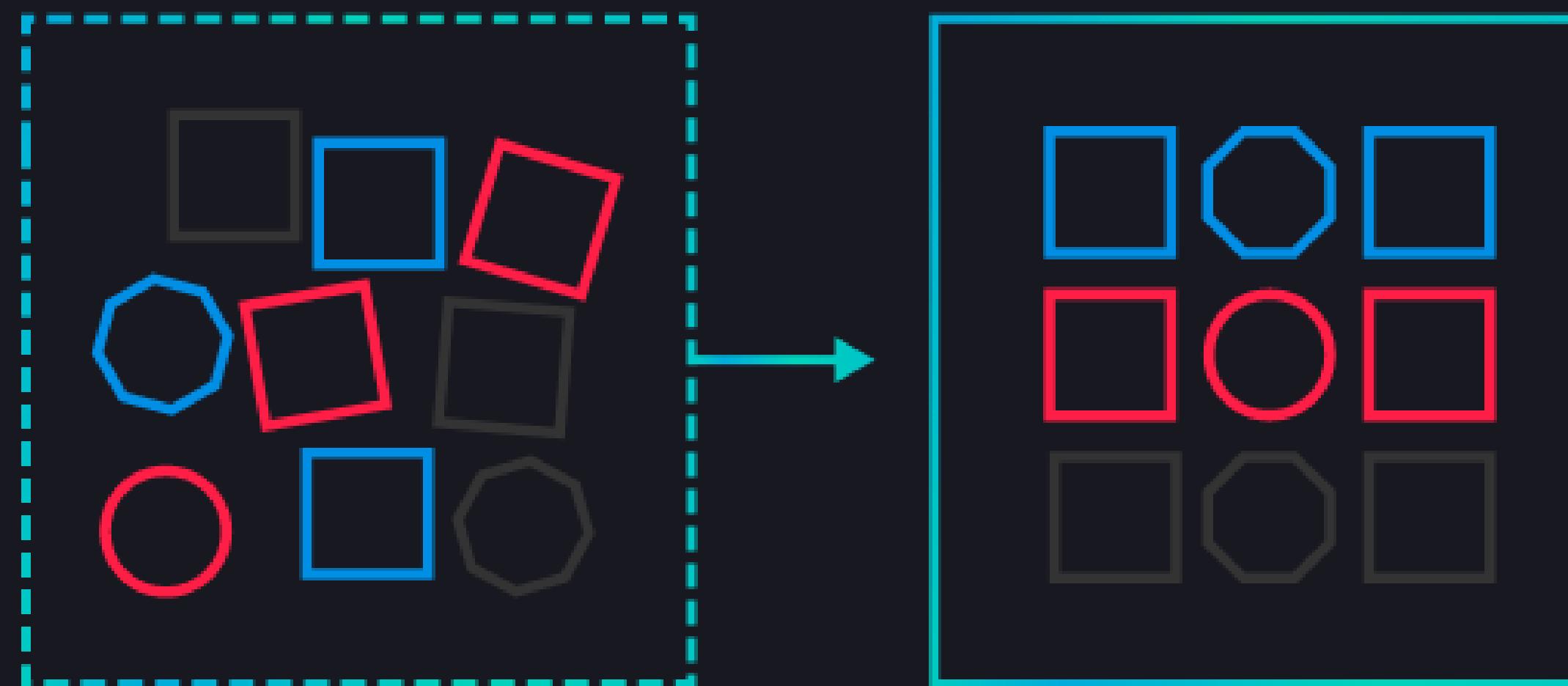
# DATA INTEGRATION

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Theory

# DATA TRANSFORMATION



- Generalisation
- Normalisation
- Attribute Selection
- Aggregation

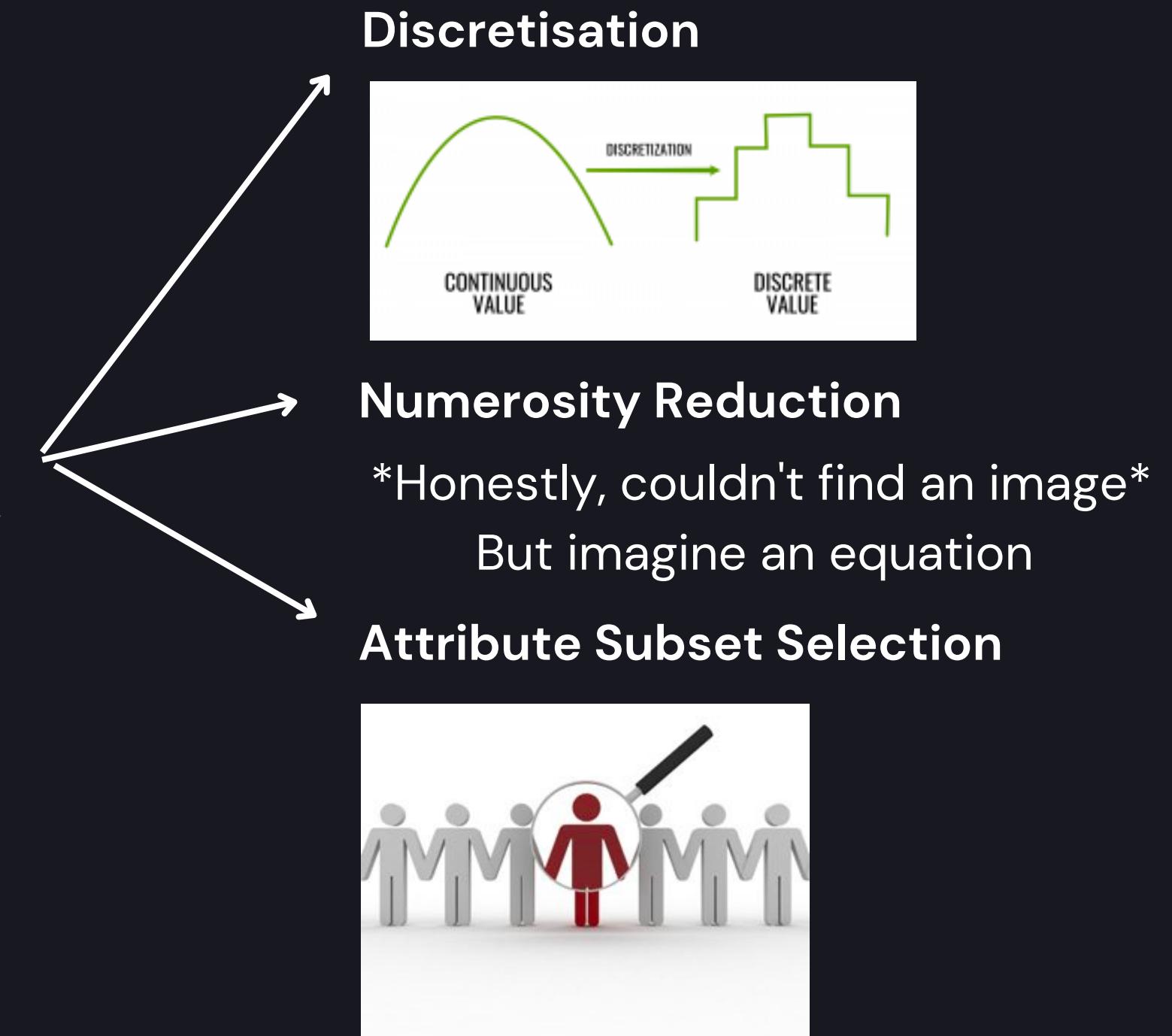
**Basically**, just making the data  
actually usable

Theory

# DATA REDUCTION



How? Lot's of ways.  
Perhaps even too many.  
But here's a couple:



Theory

# VISUALISATION

Why would we need to visualise data?

# VISUALISATION

Why would we need to visualise data?

01

Identify  
patterns

03

Feature selection

02

Identify corrupt  
data/outliers

04

Understanding high  
dimensional data

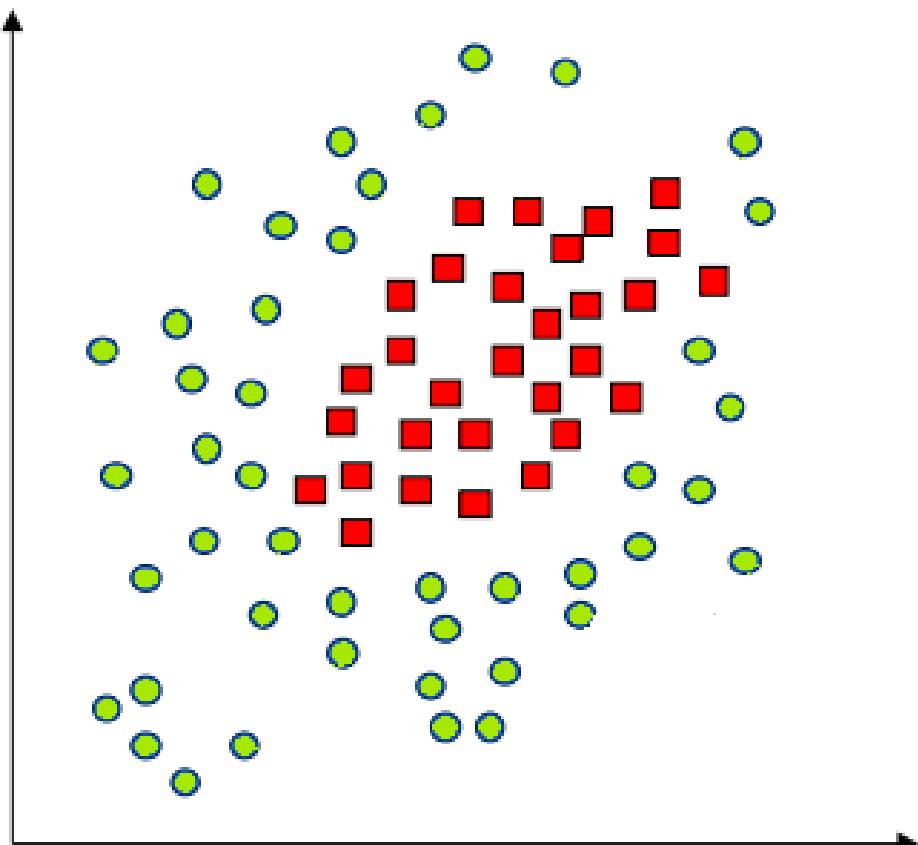
Theory

# VISUALISATION

Why would we need to visualise data?

01

Identify patterns



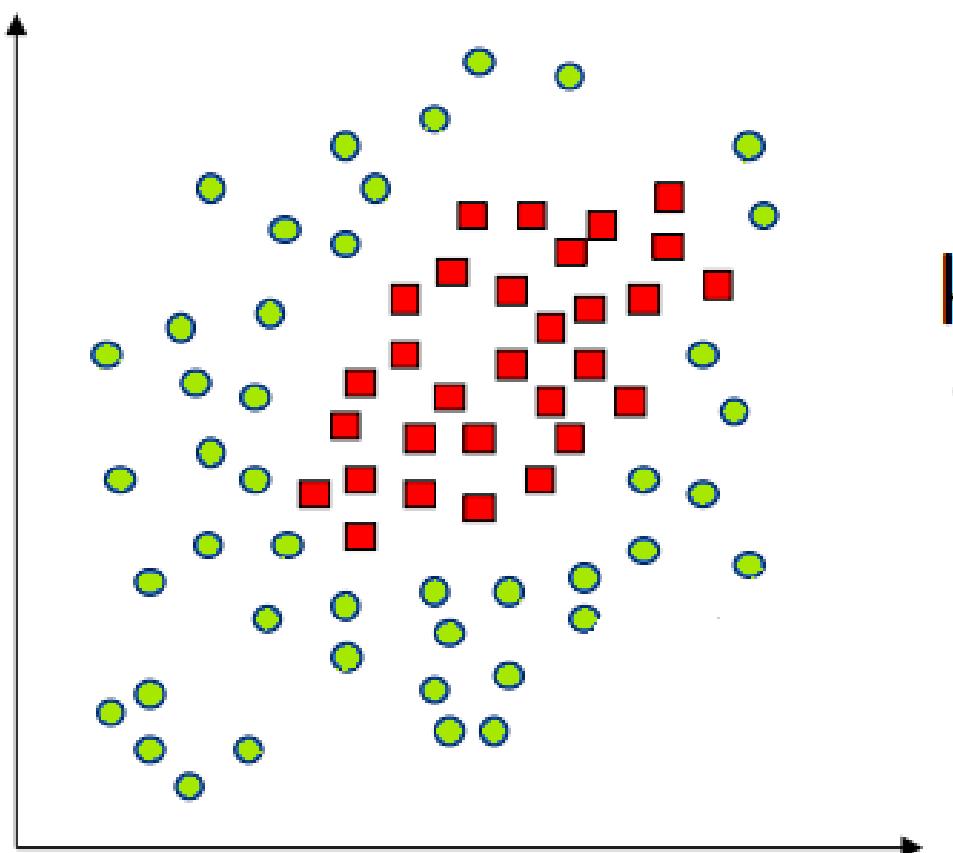
Theory

# VISUALISATION

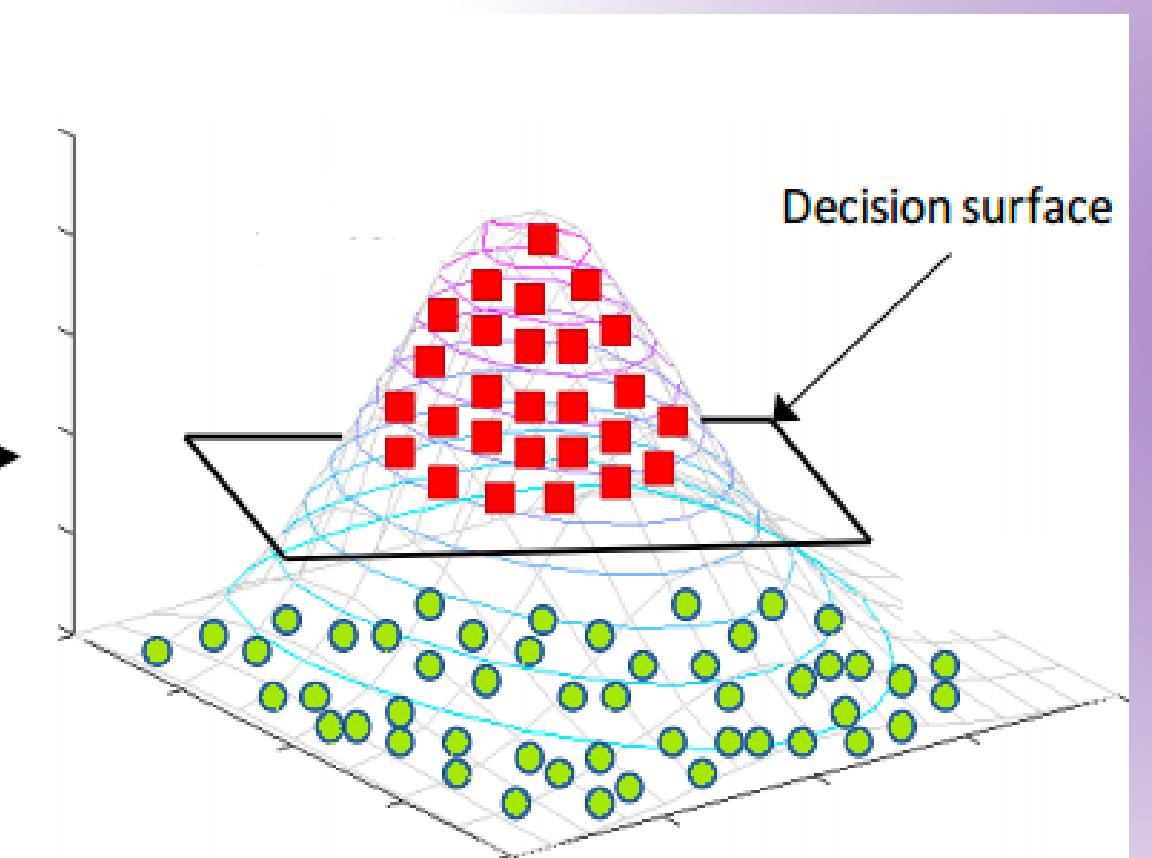
Why would we need to visualise data?

O1

Identify patterns



kernel



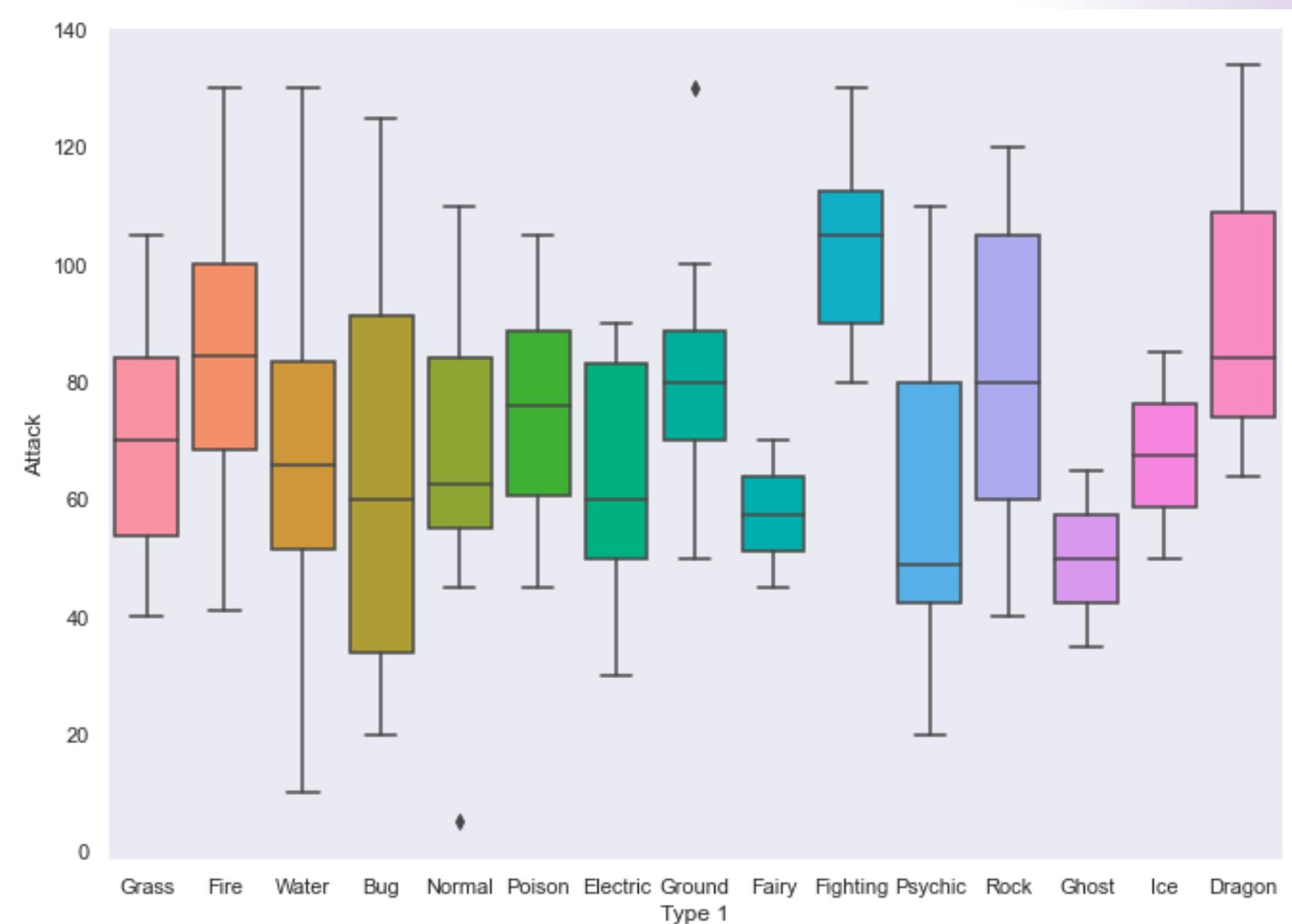
Theory

# VISUALISATION

Why would we need to visualise data?

02

Identify outliers



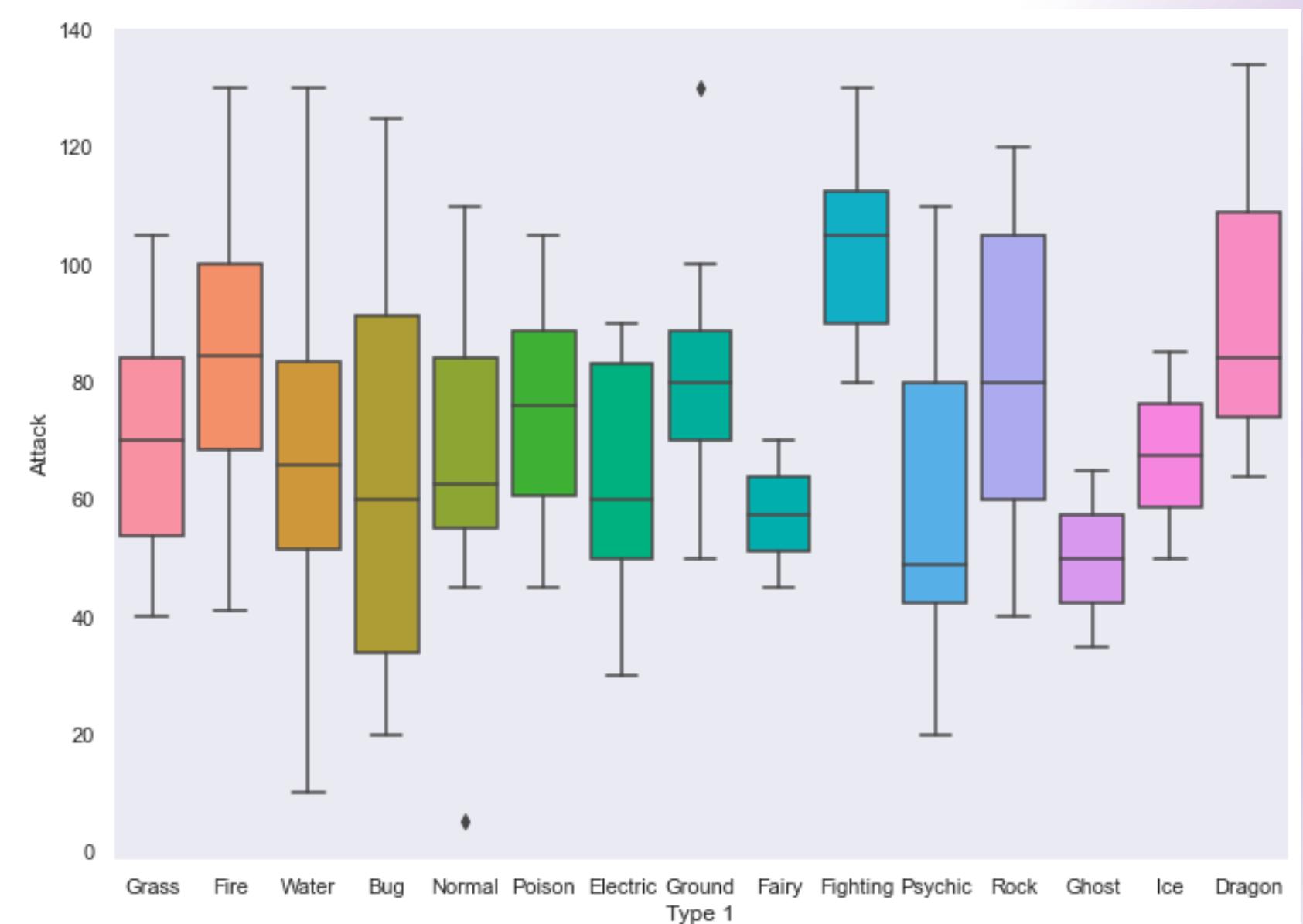
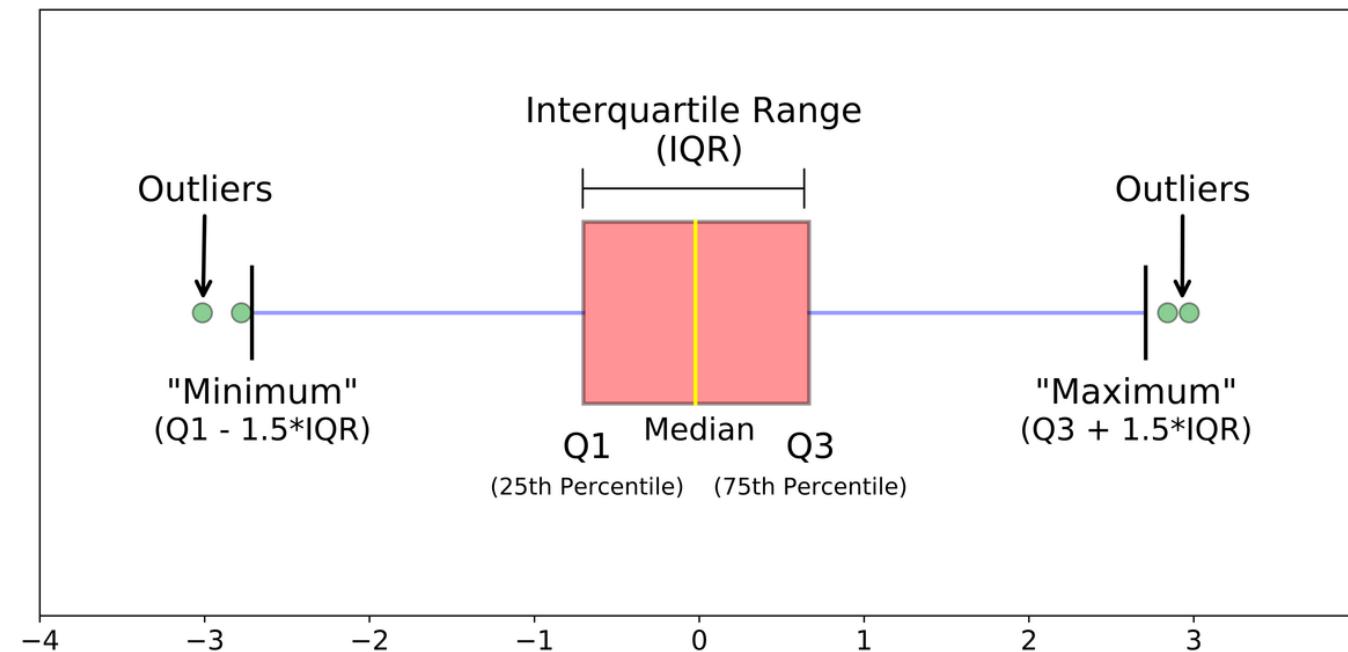
Theory

# VISUALISATION

Why would we need to visualise data?

02

## Identify outliers



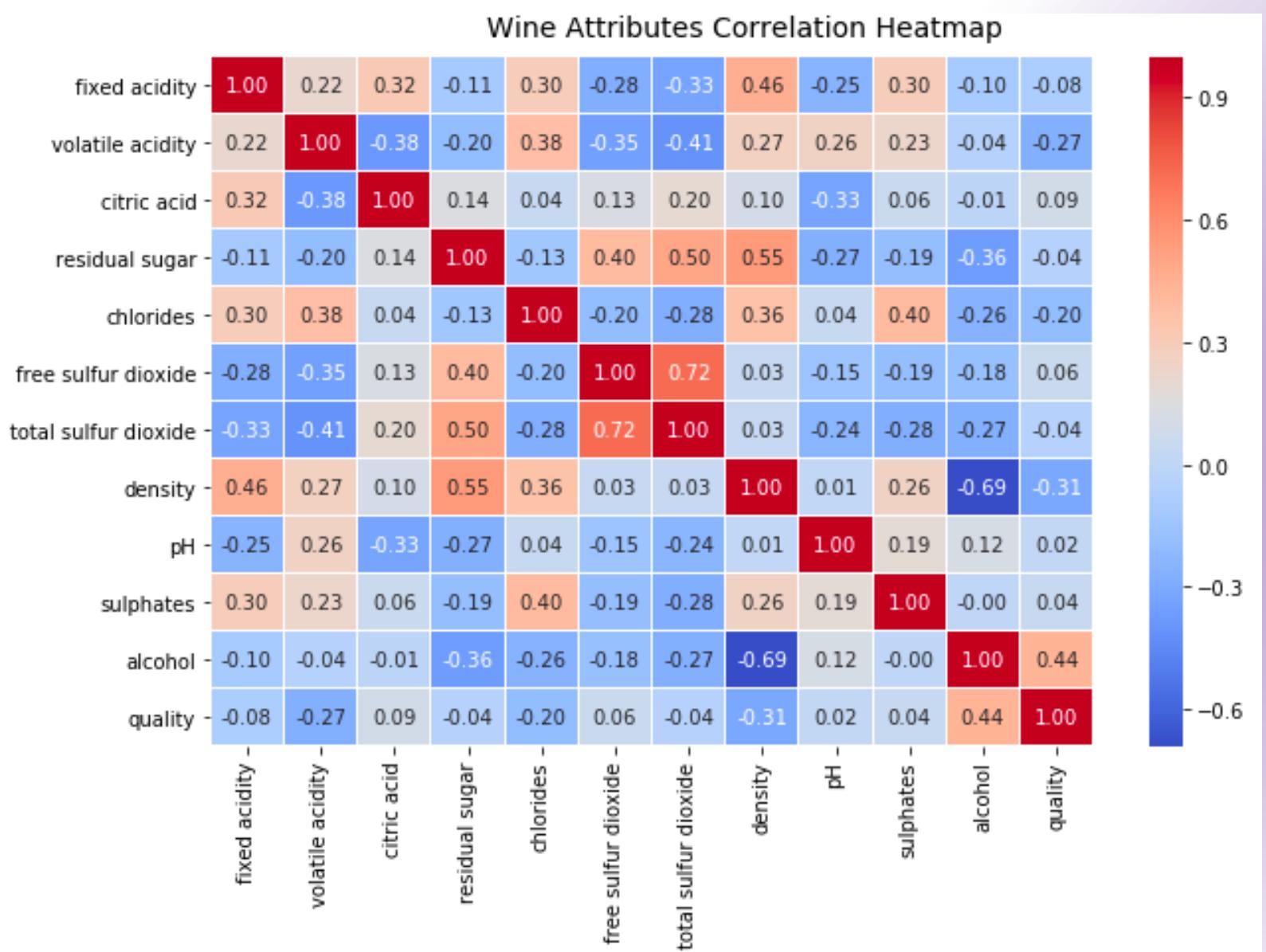
Theory

# VISUALISATION

Why would we need to visualise data?

03

## Feature selection



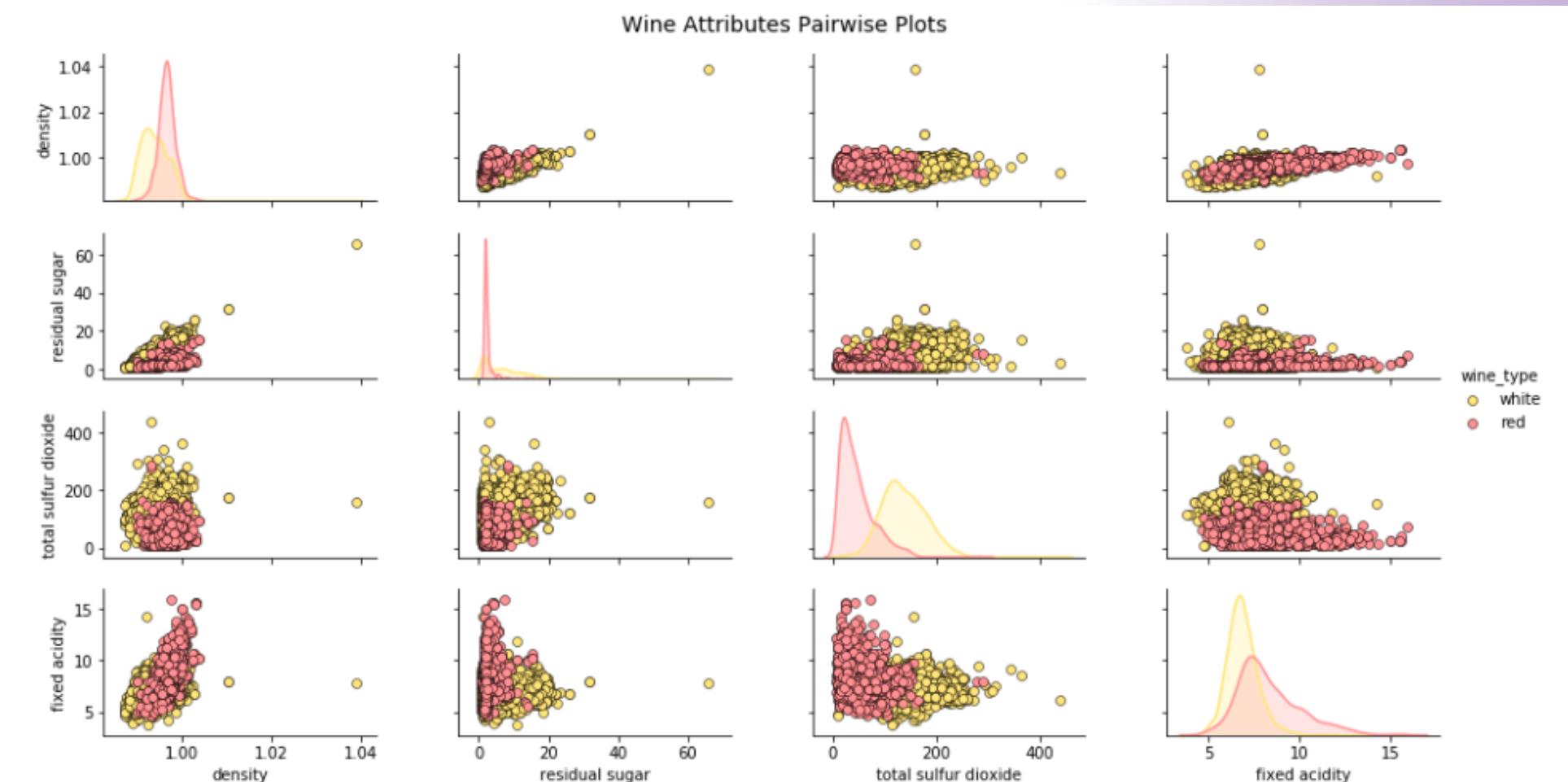
Theory

# VISUALISATION

Why would we need to visualise data?

04

## Understanding high dimensional data



Theory

# PCA

## Dimensionality reduction

- Curse of dimensionality
  - Sparse and dissimilar data

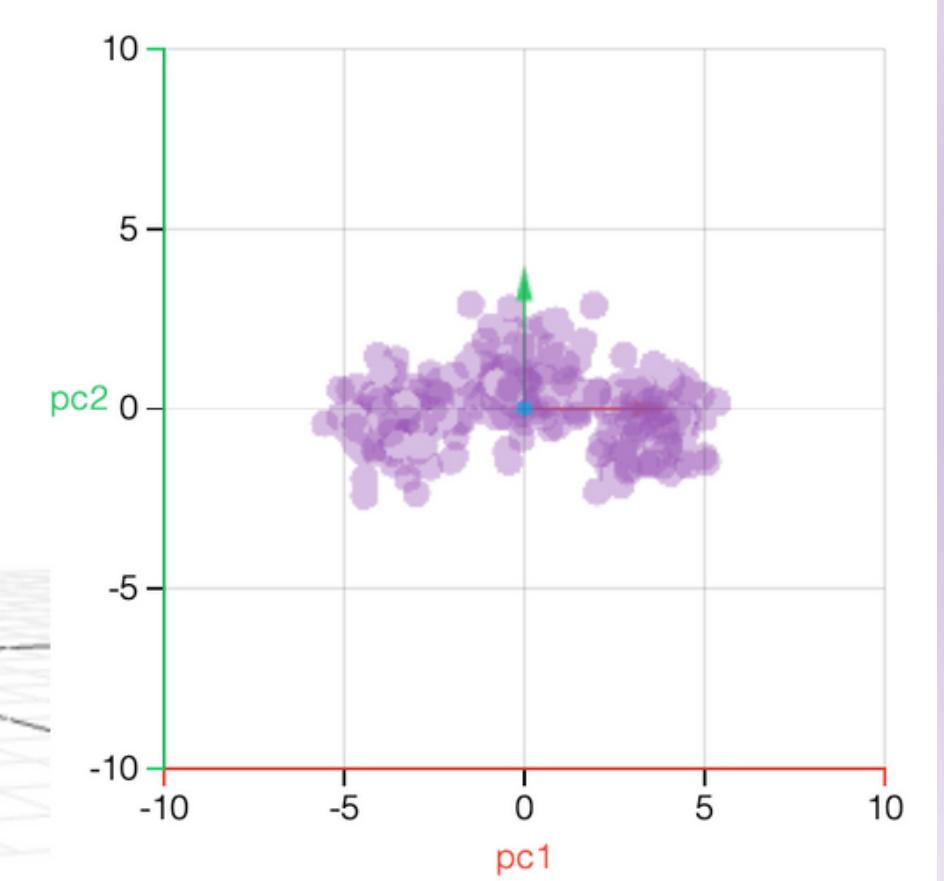
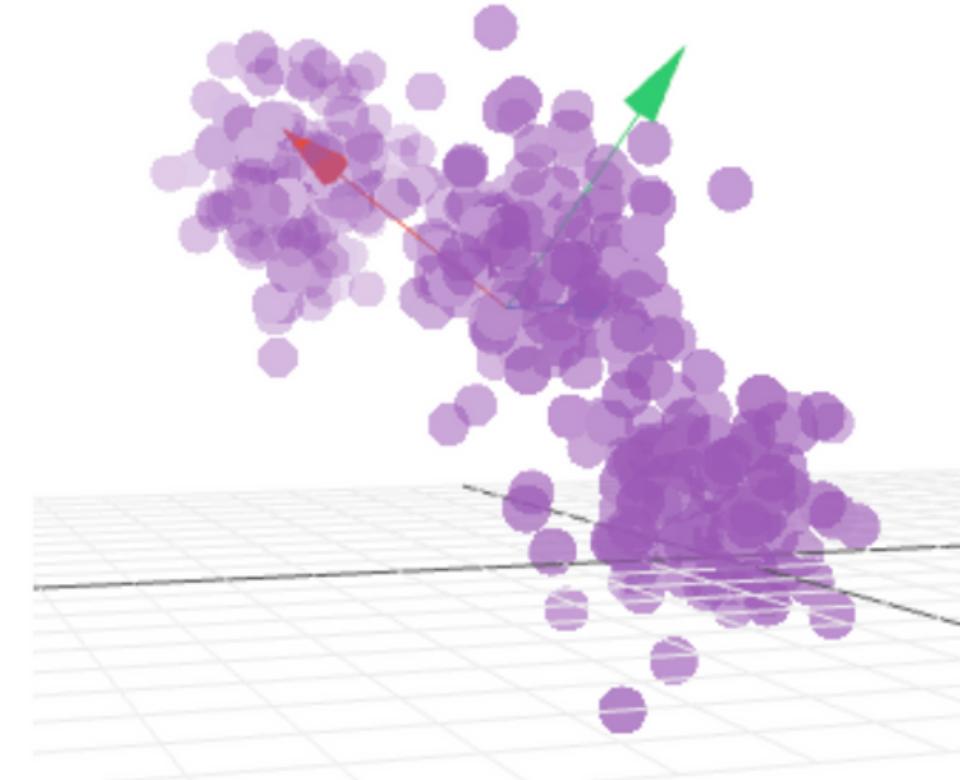
2D

$$d = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

3D

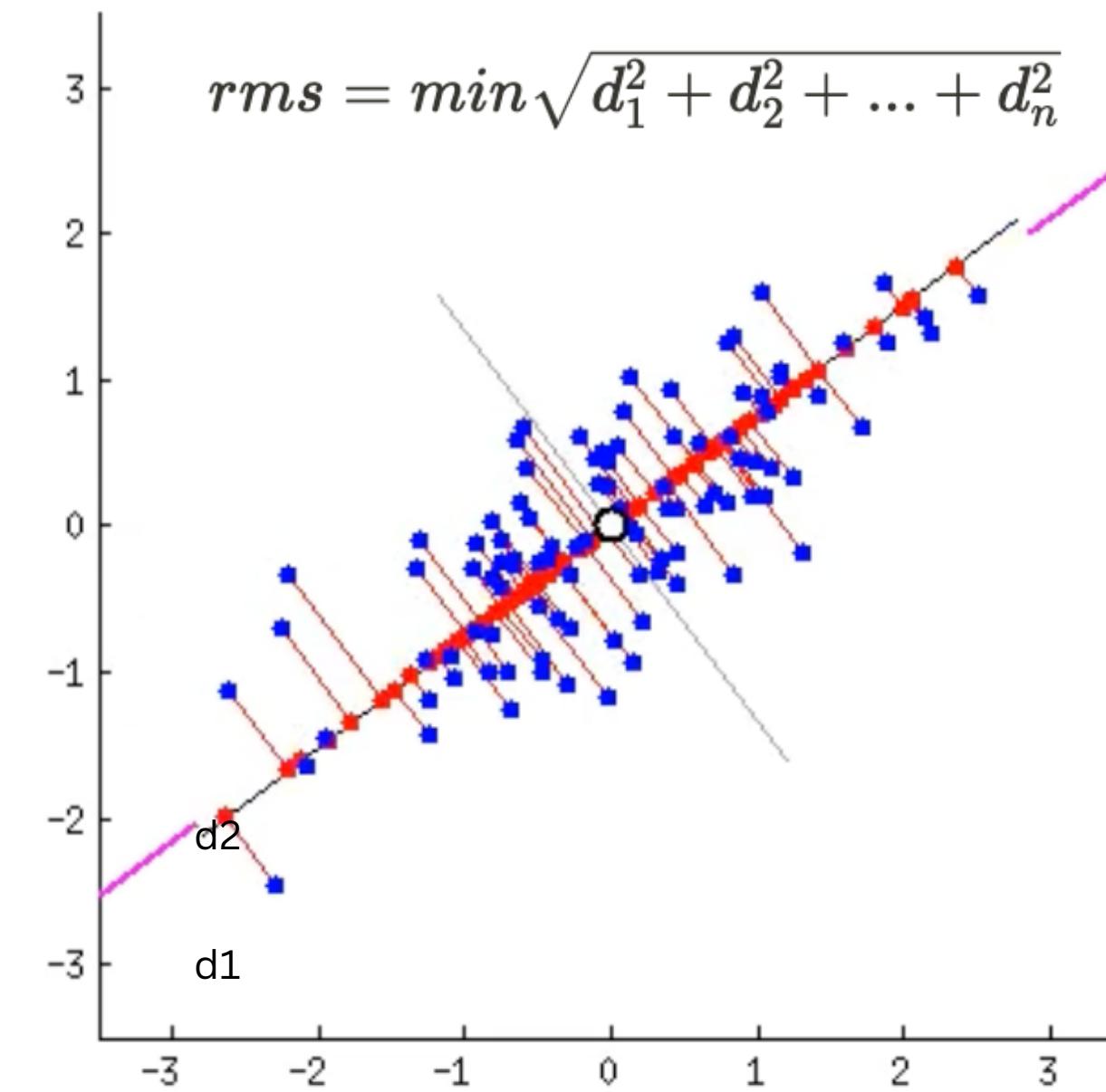
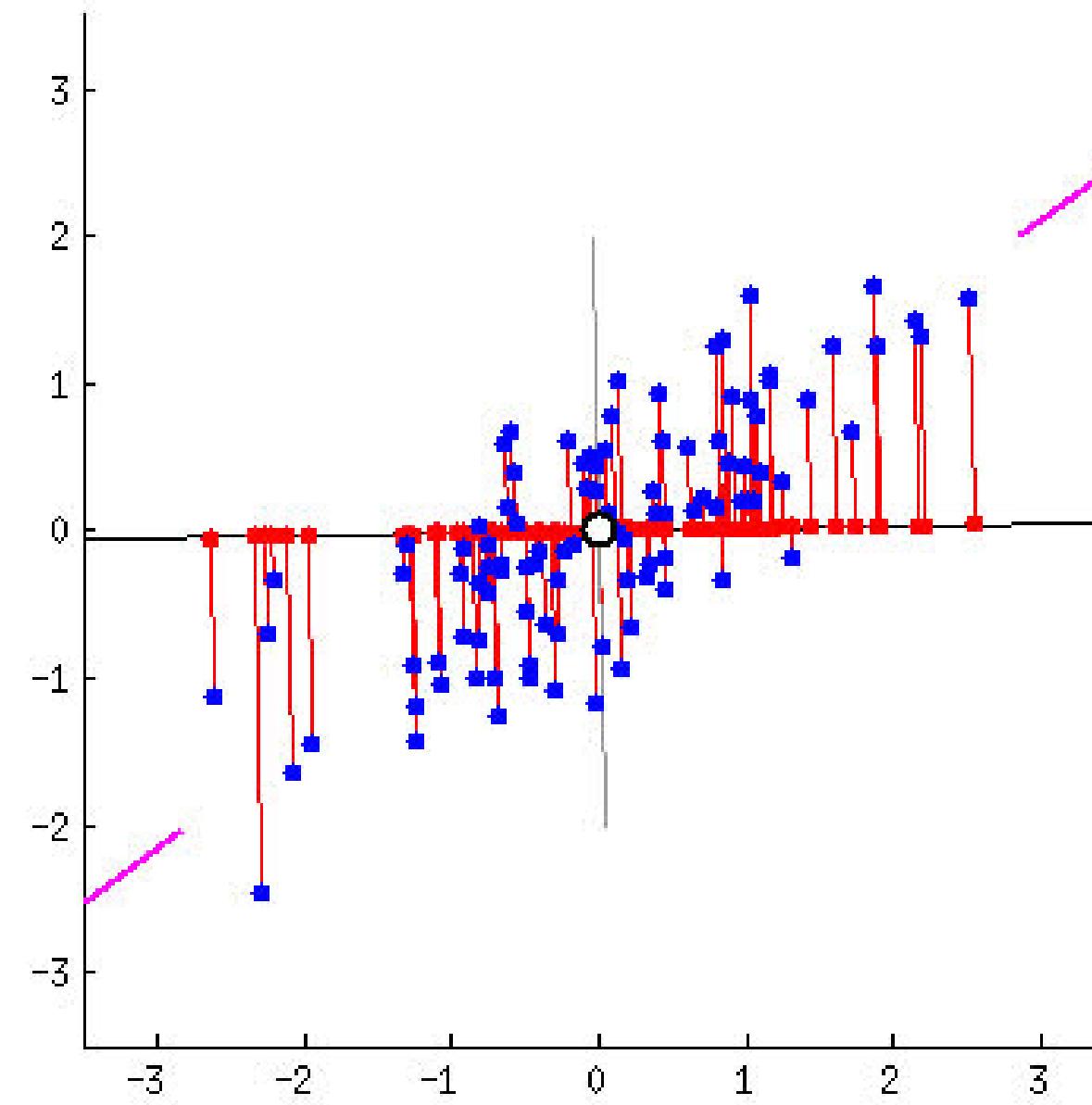
$$d = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}$$

- Reduces multicollinearity



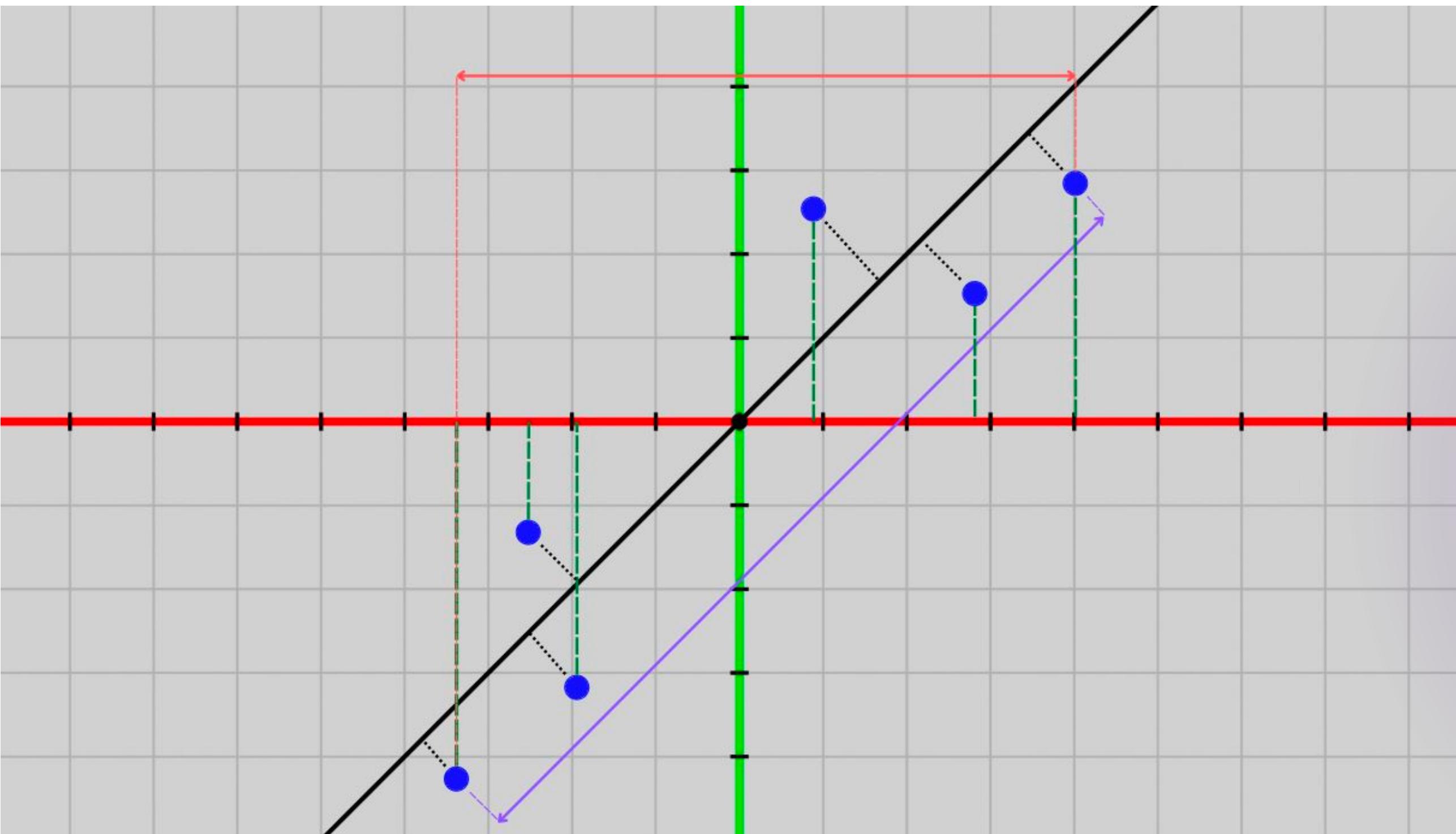
Theory

# PCA



Theory

# PCA



Theory

# PCA

Reducing  
dimensions

Choose n  
best PCs

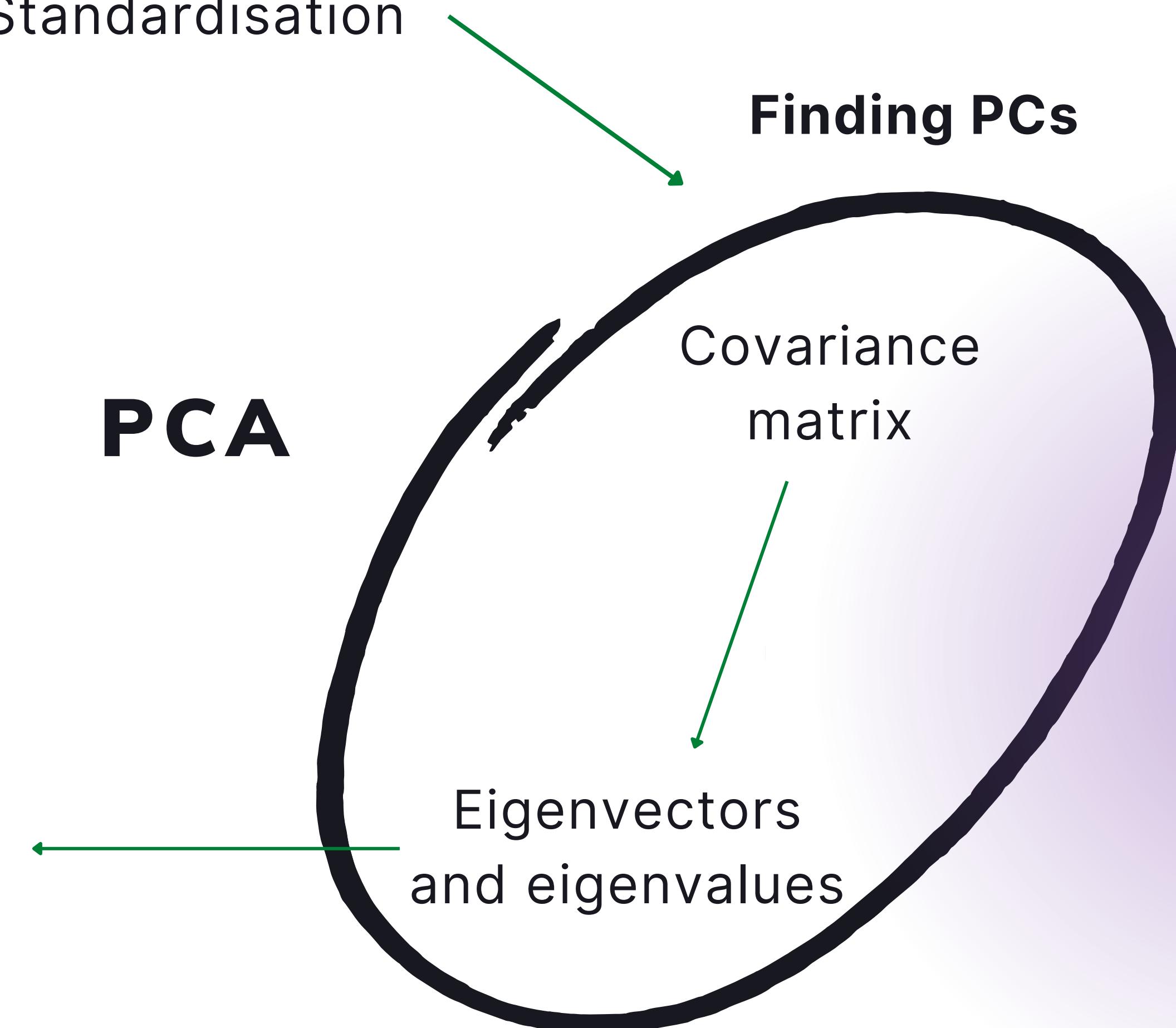
Standardisation

# PCA

**Finding PCs**

Covariance  
matrix

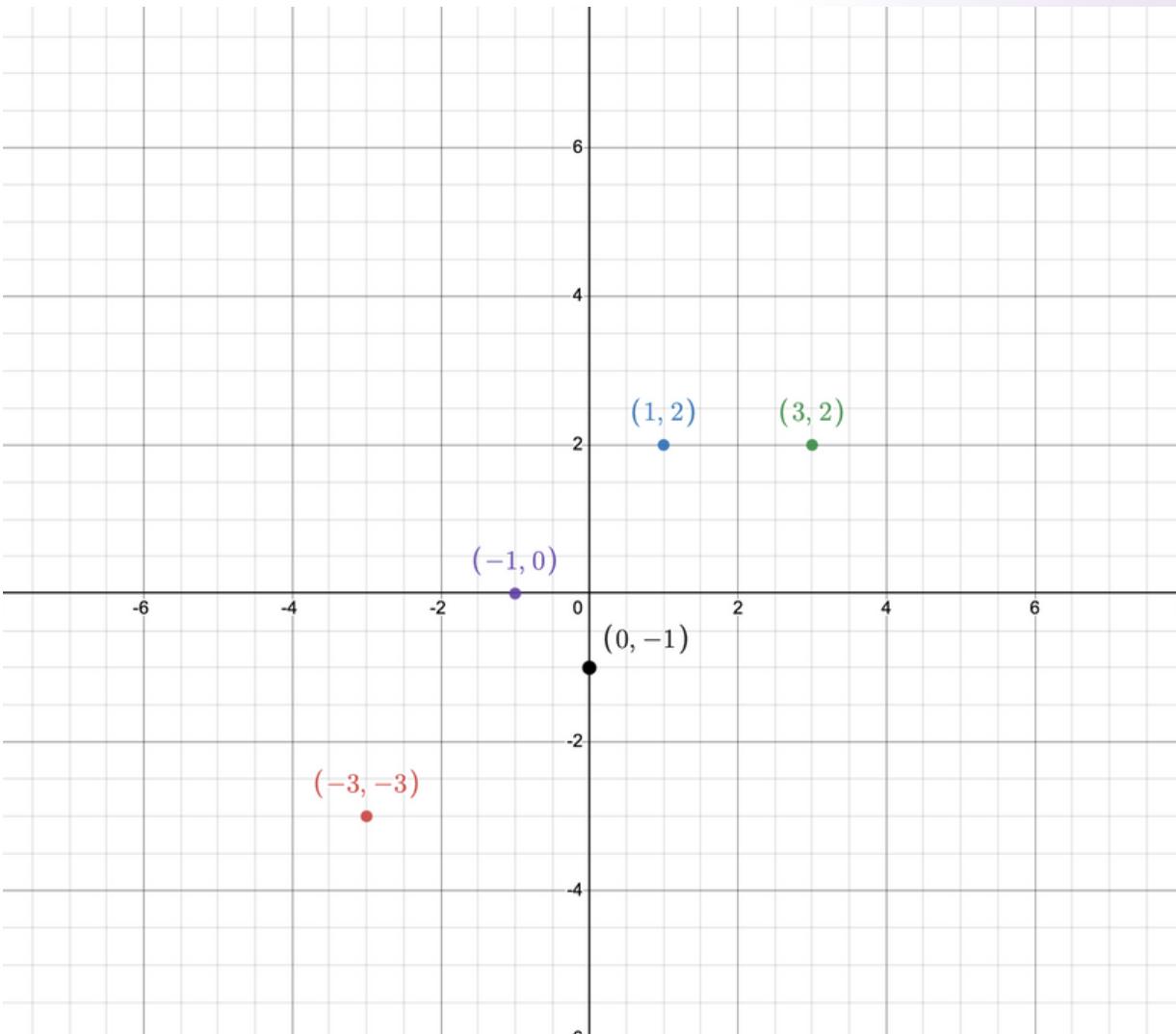
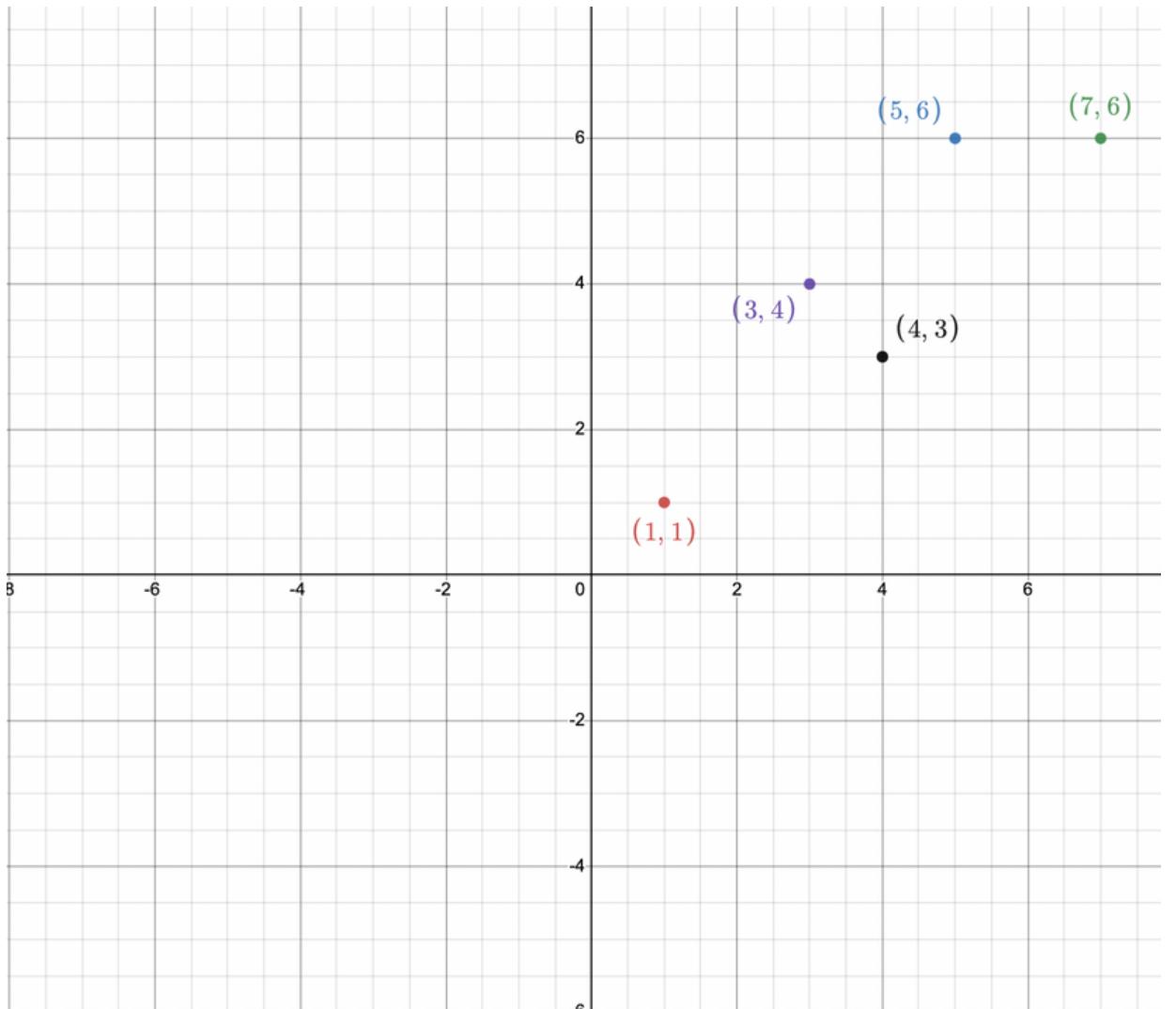
Eigenvectors  
and eigenvalues



Theory

# PCA

## Standardisation



Theory

# PCA

## Covariance matrix

- Measuring the levels by which each pair of variables/attributes vary

$$\text{Cov}(x, y) = \frac{1}{N-1} \sum_{j=1}^N (x_j - \mu_x)(y_j - \mu_y)$$



$$\xrightarrow{\hspace{1cm}} \begin{pmatrix} 2.5 & 3.0 \\ 3.0 & 10.0 \end{pmatrix}$$

Theory

# PCA

Eigenvalues and eigenvectors

$$\mathbf{A}\vec{v}_i = \lambda_i\vec{v}_i.$$

$$\mathbf{A} = \begin{bmatrix} -2 & 2 & 1 \\ -5 & 5 & 1 \\ -4 & 2 & 3 \end{bmatrix}$$



$$\det(\mathbf{A} - \lambda\mathbf{I}) = \begin{vmatrix} -2 - \lambda & 2 & 1 \\ -5 & 5 - \lambda & 1 \\ -4 & 2 & 3 - \lambda \end{vmatrix} = \mathbf{0}$$



$$\lambda = 3, 2, 1.$$



$$\mathbf{A}\vec{v}_i = \lambda_i\vec{v}_i$$

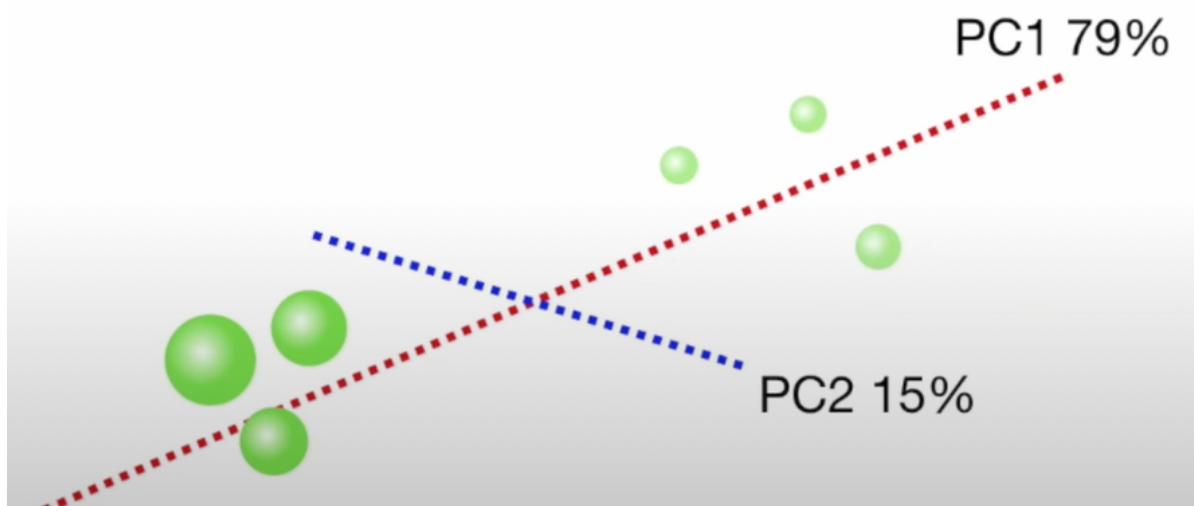
$$\lambda_1 = 3 : \hat{v}_1 = (1/\sqrt{6}, 2/\sqrt{6}, 1/\sqrt{6})^T$$

$$\lambda_2 = 2 : \hat{v}_2 = (1/\sqrt{6}, 1/\sqrt{6}, 2/\sqrt{6})^T$$

$$\lambda_3 = 1 : \hat{v}_3 = (1, 1, 1)^T / \sqrt{3}$$

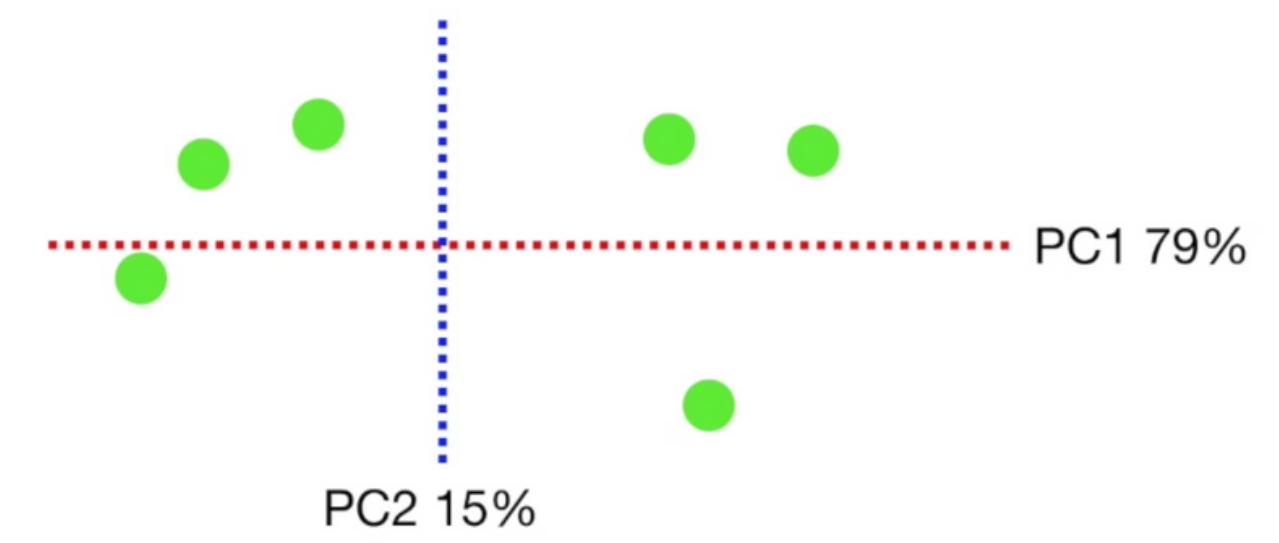
Theory

# PCA

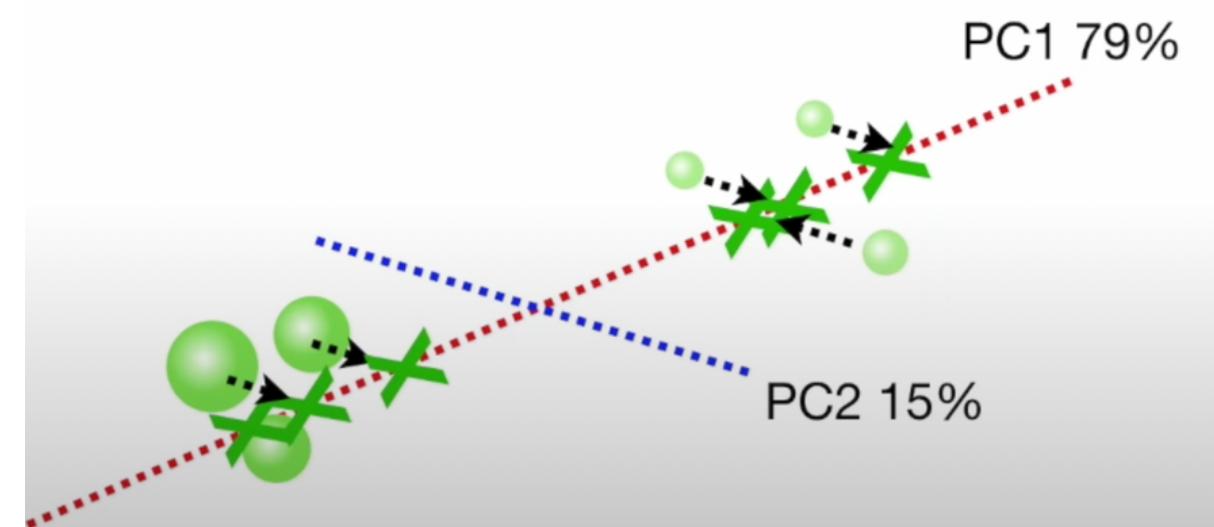


Find principal  
components

Project all the  
datapoints to the  
new PCs



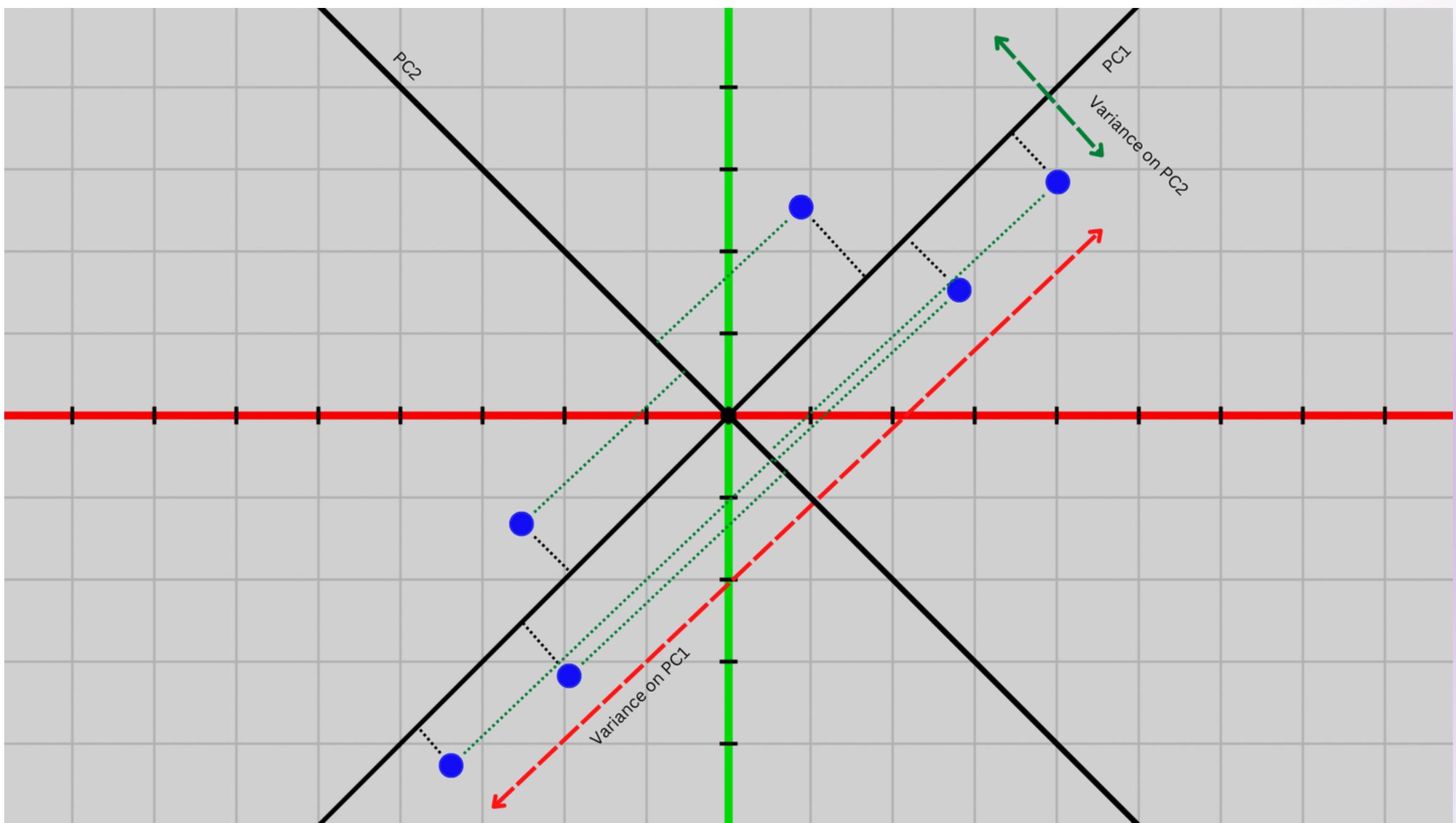
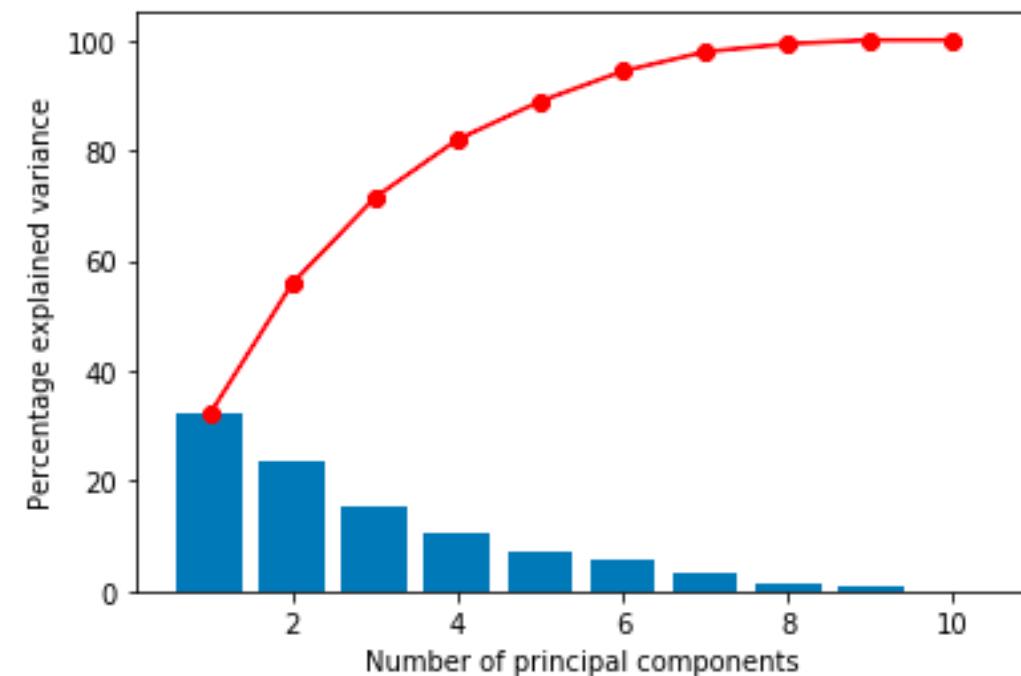
Final dataset



Theory

# PCA

## Explained variance!



Theory

# PCA

PCA from scratch

```
import numpy as np

# Step 1: Standardisation
X_meaned = X - np.mean(X, axis=0)

# Step 2: Computing covariance matrix
cov_mat = np.cov(X_meaned, rowvar=False)

# Step 3: Finding eigenvalues and eigenvectors
eigenvalues, eigenvectors = np.linalg.eigh(cov_mat)
```

Theory

# PCA

## PCA from scratch

```
import numpy as np

# Step 4: Sorting the eigenvectors based on highest eigenvalues
sorted_index = np.argsort(eigenvalues)[::-1]
sorted_eigenvectors = eigenvectors[:, sorted_index]

# Step 5: Choosing n best eigenvectors
eigenvector_subset = sorted_eigenvectors[:, 0:num_components]

# Step 6: Creating the new dataset with n features
X_reduced = np.dot(eigenvector_subset.transpose(), X_meaned.transpose()).transpose()
```

Theory

# PCA

## PCA using libraries

```
from sklearn.preprocessing import StandardScaler  
  
sc = StandardScaler()  
X_train = sc.fit_transform(X_train)  
X_test = sc.transform(X_test)
```

Theory

# PCA

## Drawbacks

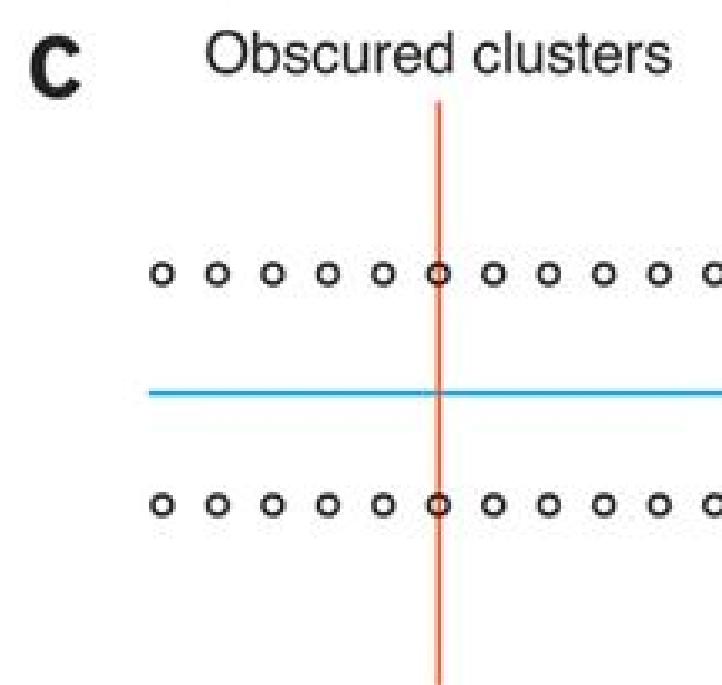
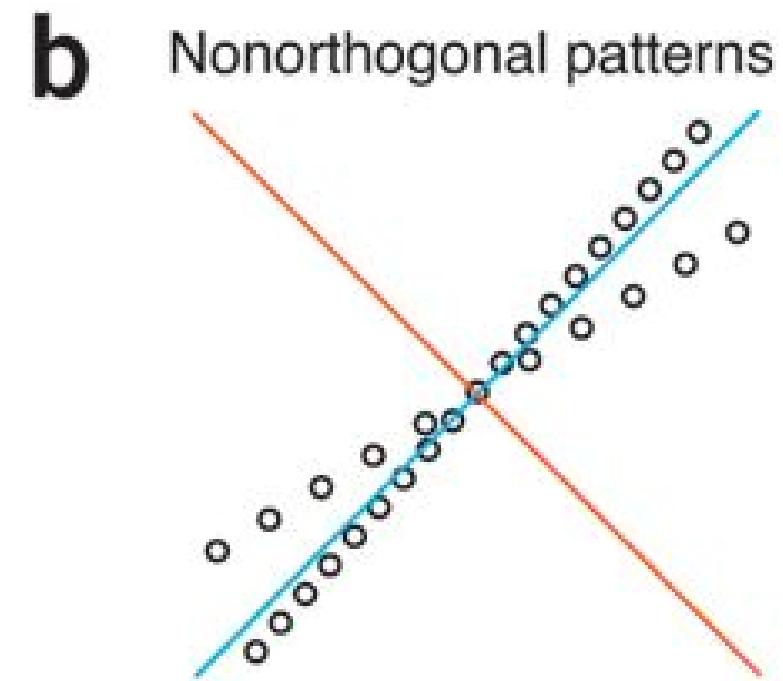
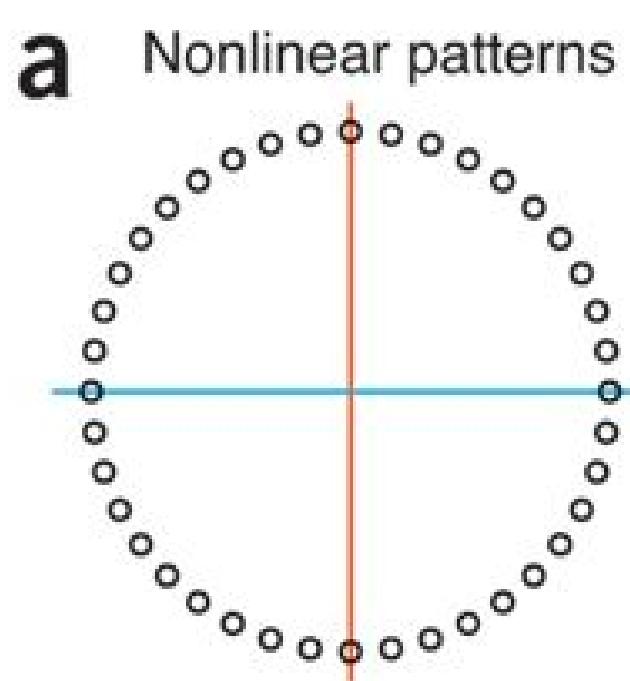
1. Doesn't work on certain data patterns

Theory

# PCA

## Drawbacks

1. Doesn't work on certain data patterns



2. Scaling matters
3. Interpretation of the PCs can be hard!

Theory

# K-MEANS CLUSTERING

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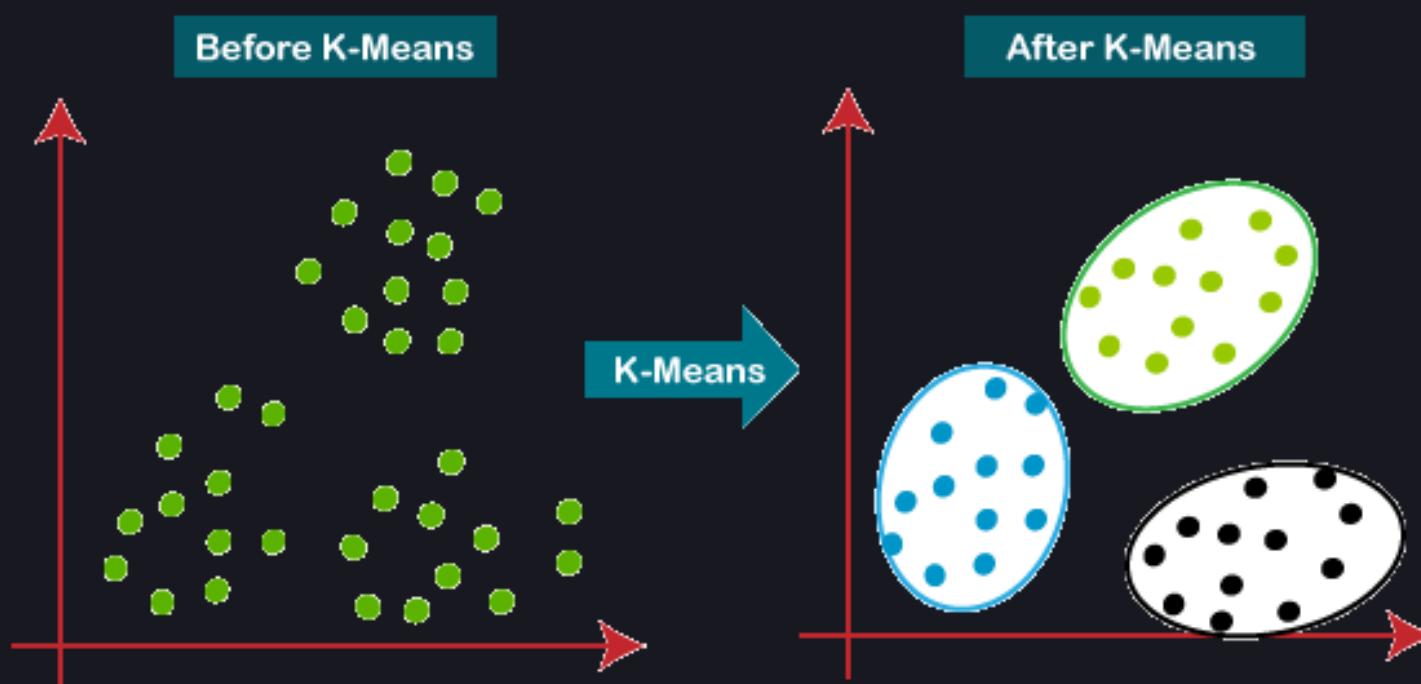
- Vector Quantization (Dividing vectors into groups)
- Can be used for classification
- Not to be confused with KNN!

Theory

# K-MEANS CLUSTERING

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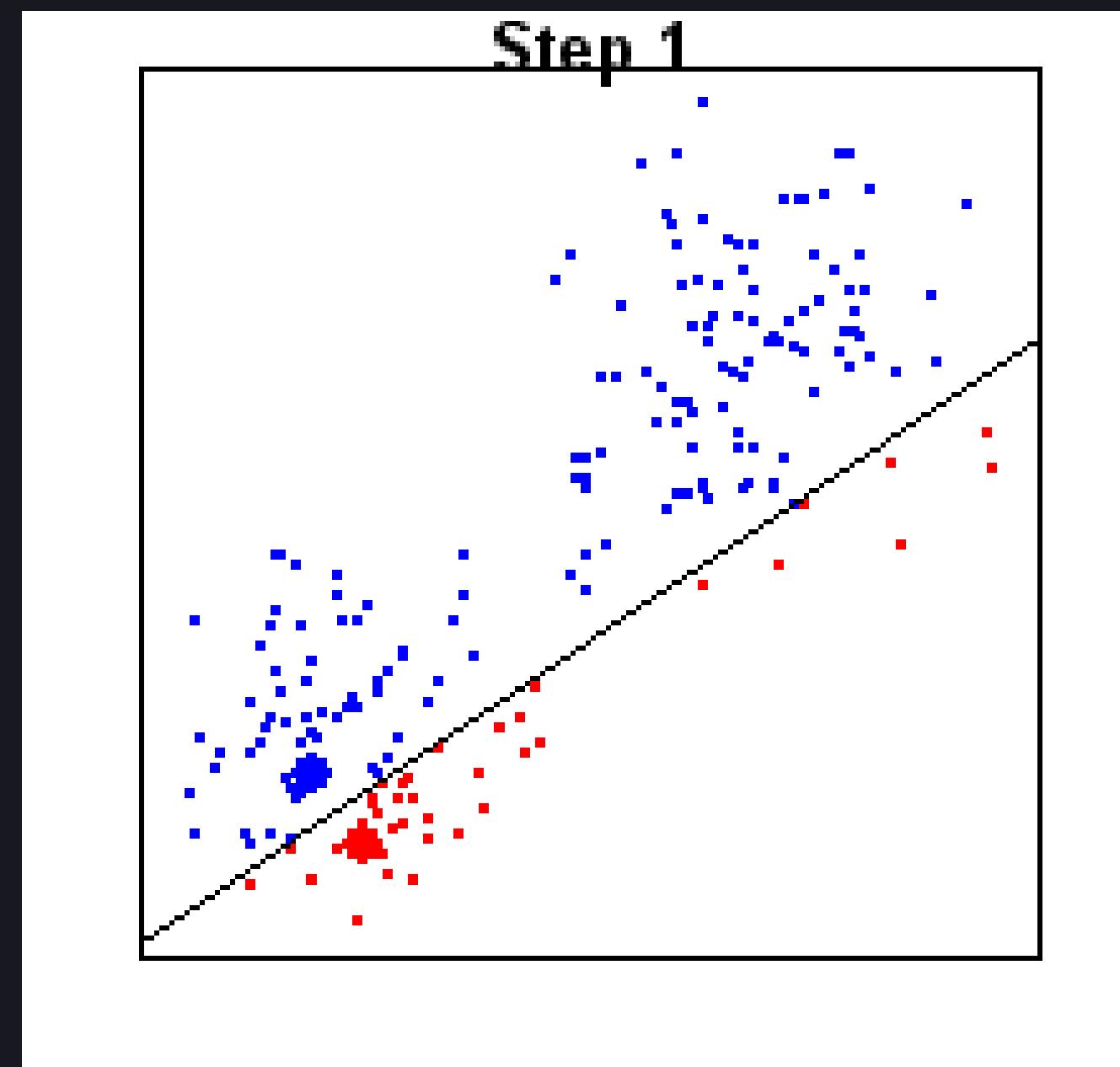
- Iterative process
- Partition points to their nearest mean
- Relatively simple algorithm



Theory

# K-MEANS CLUSTERING

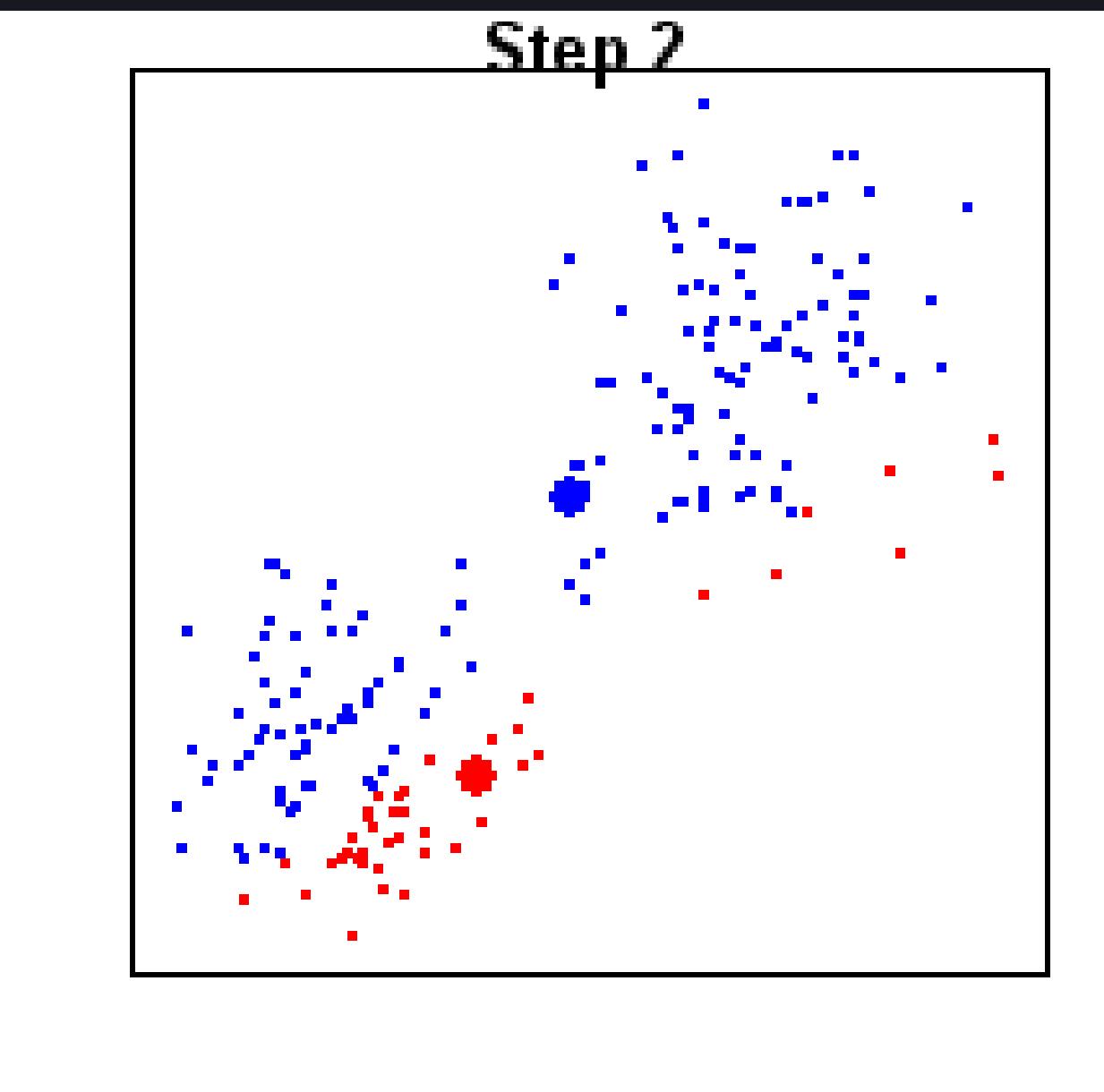
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Theory

# K-MEANS CLUSTERING

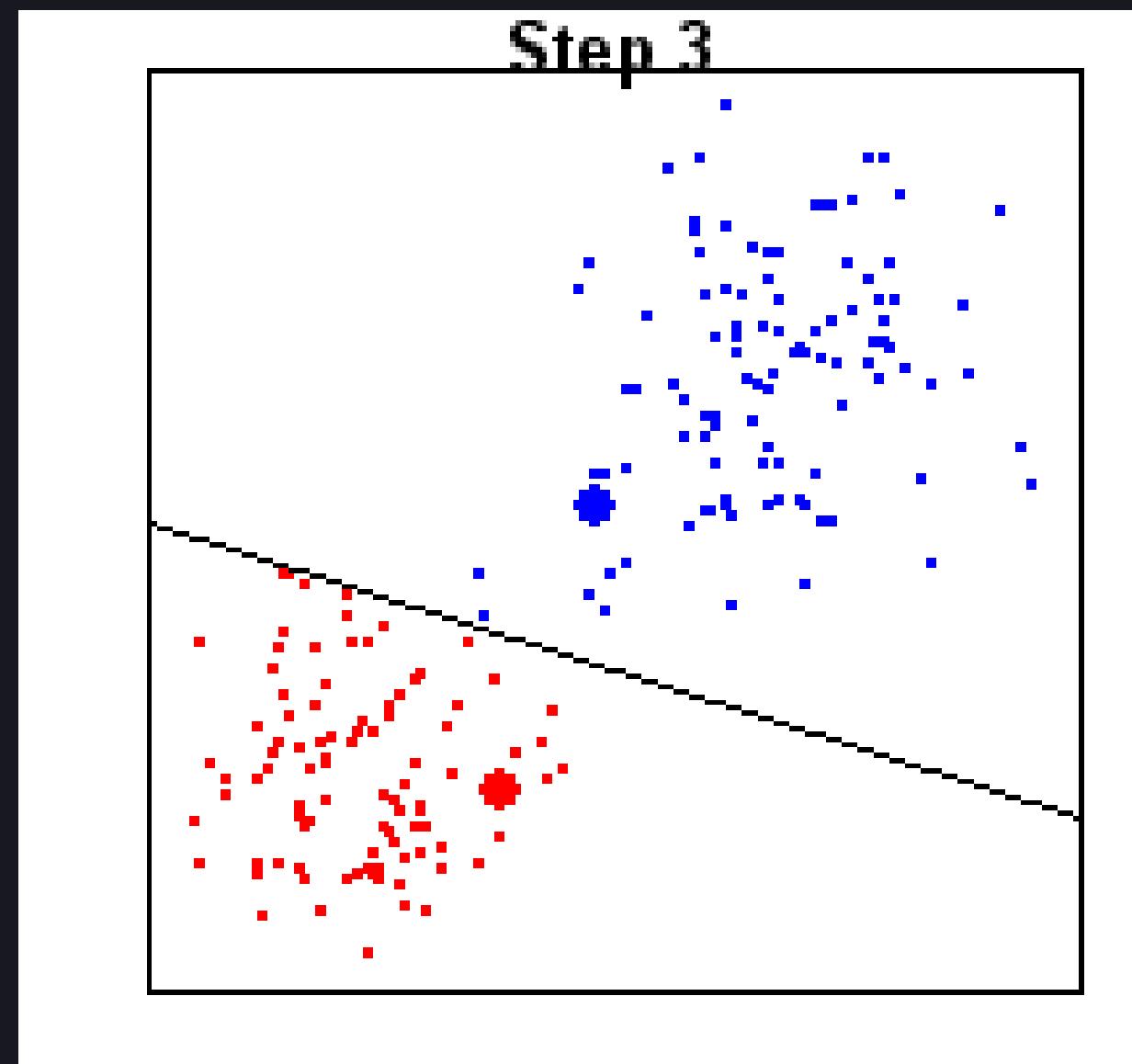
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Theory

# K-MEANS CLUSTERING

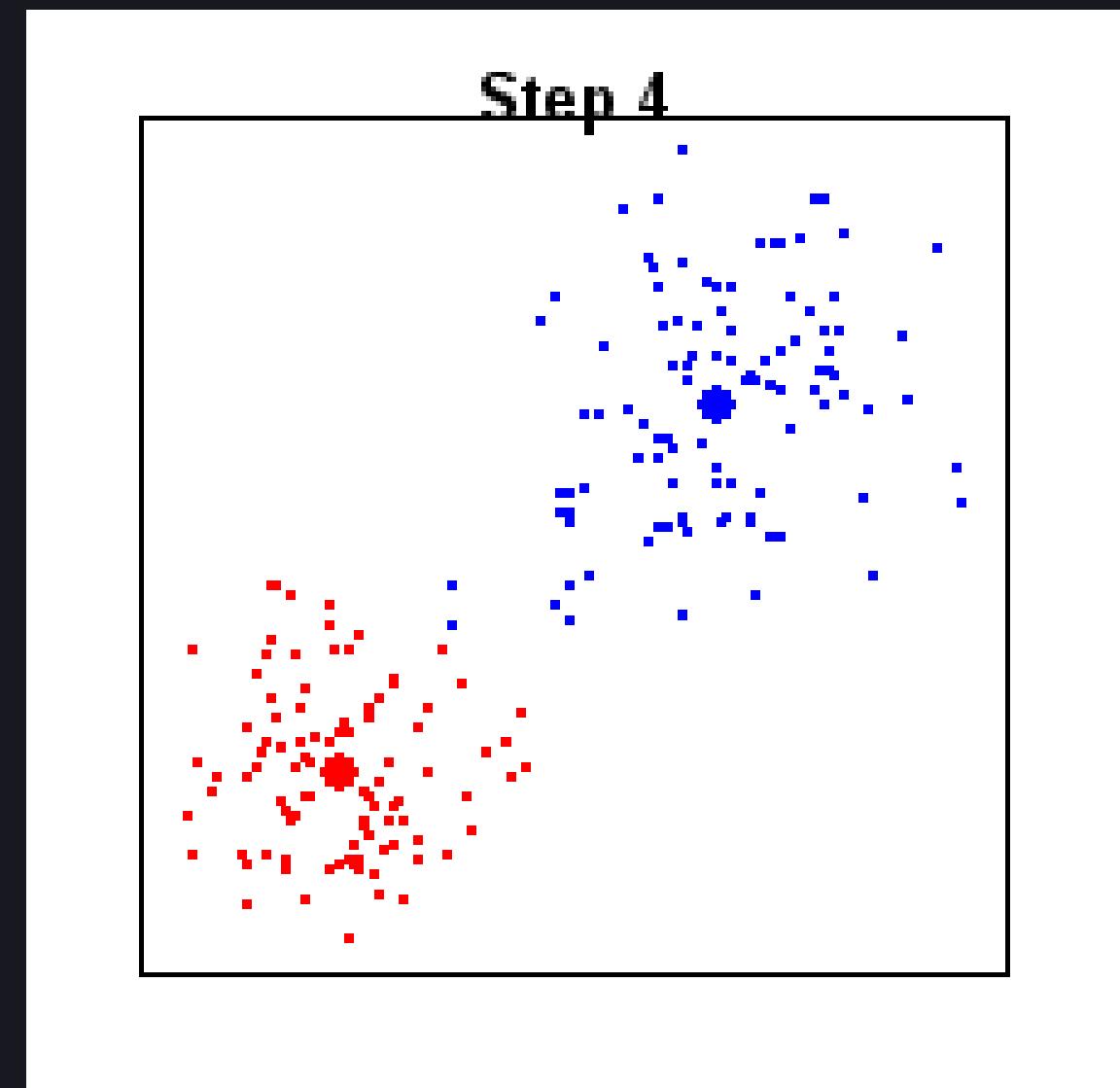
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Theory

# K-MEANS CLUSTERING

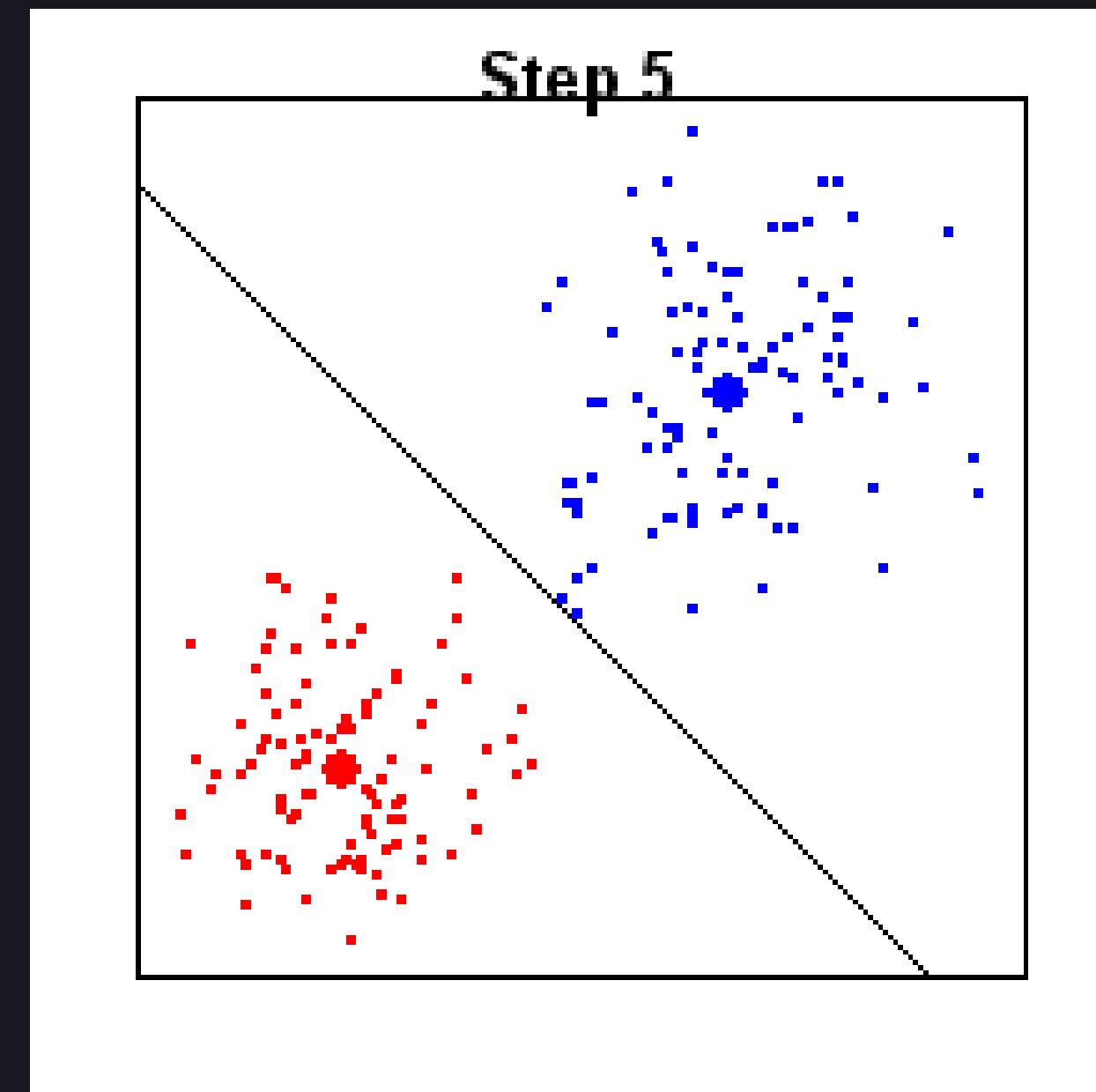
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Theory

# K-MEANS CLUSTERING

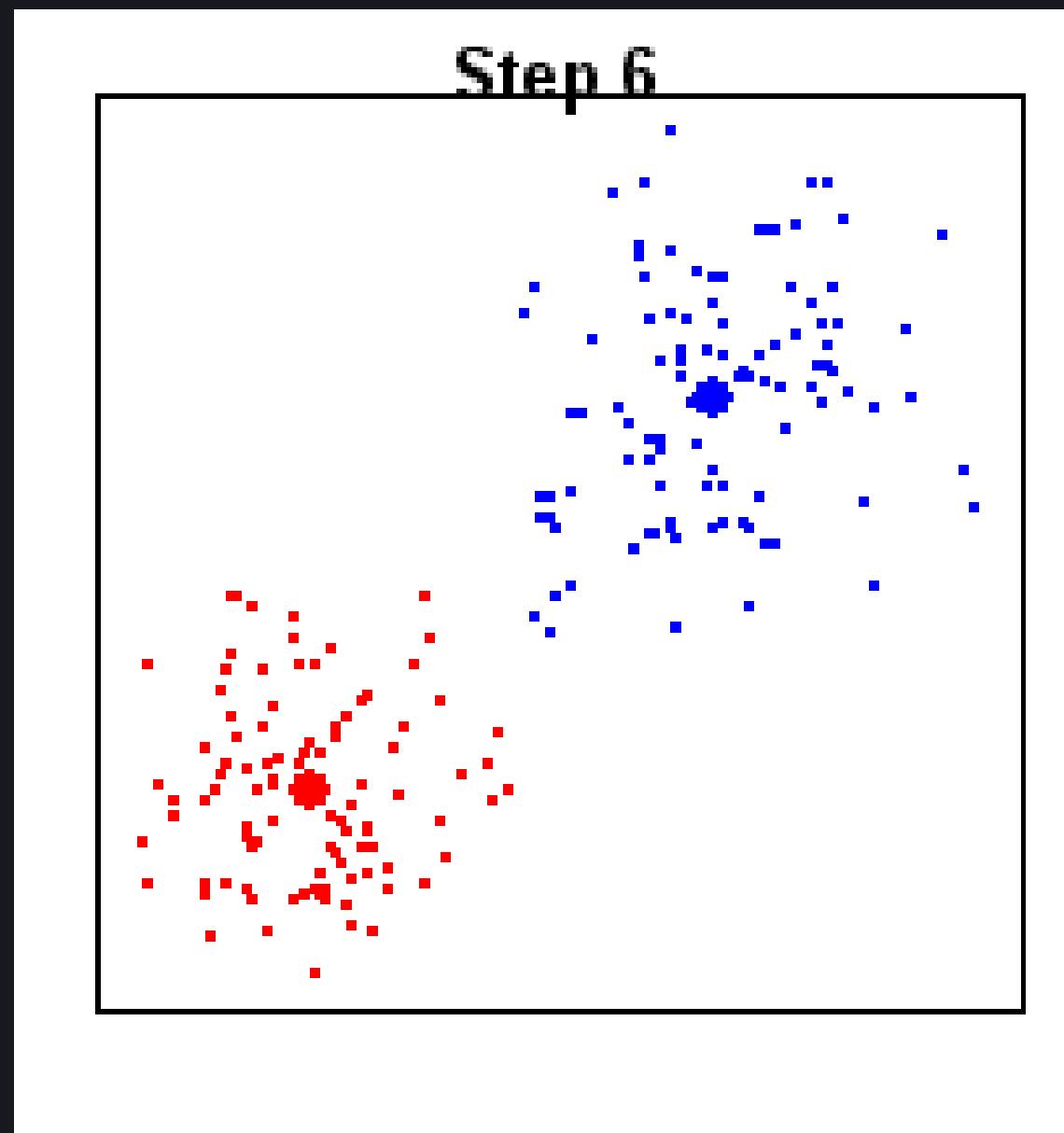
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Theory

# K-MEANS CLUSTERING

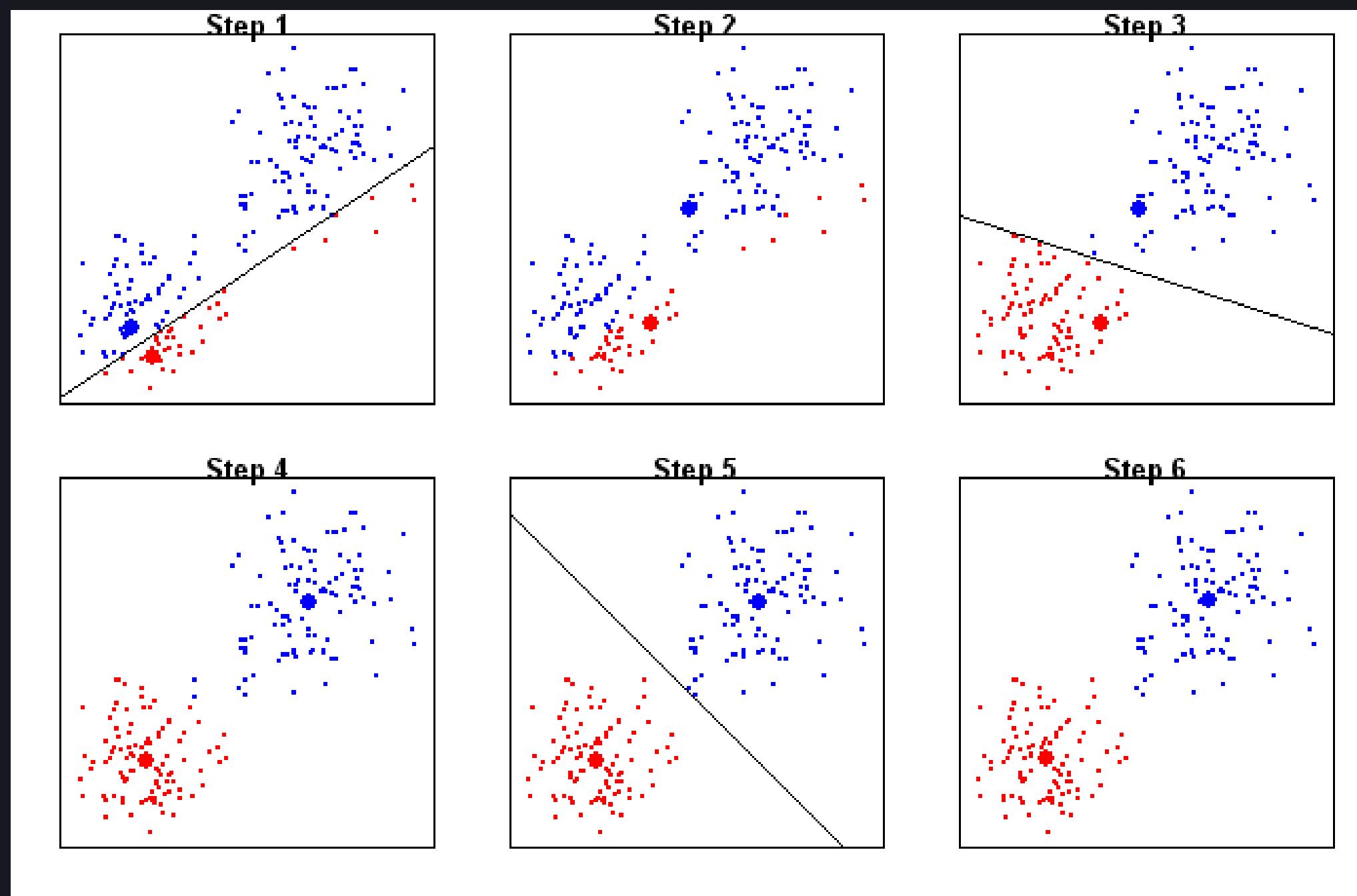
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Theory

# K-MEANS CLUSTERING

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# K-MEANS CLUSTERING

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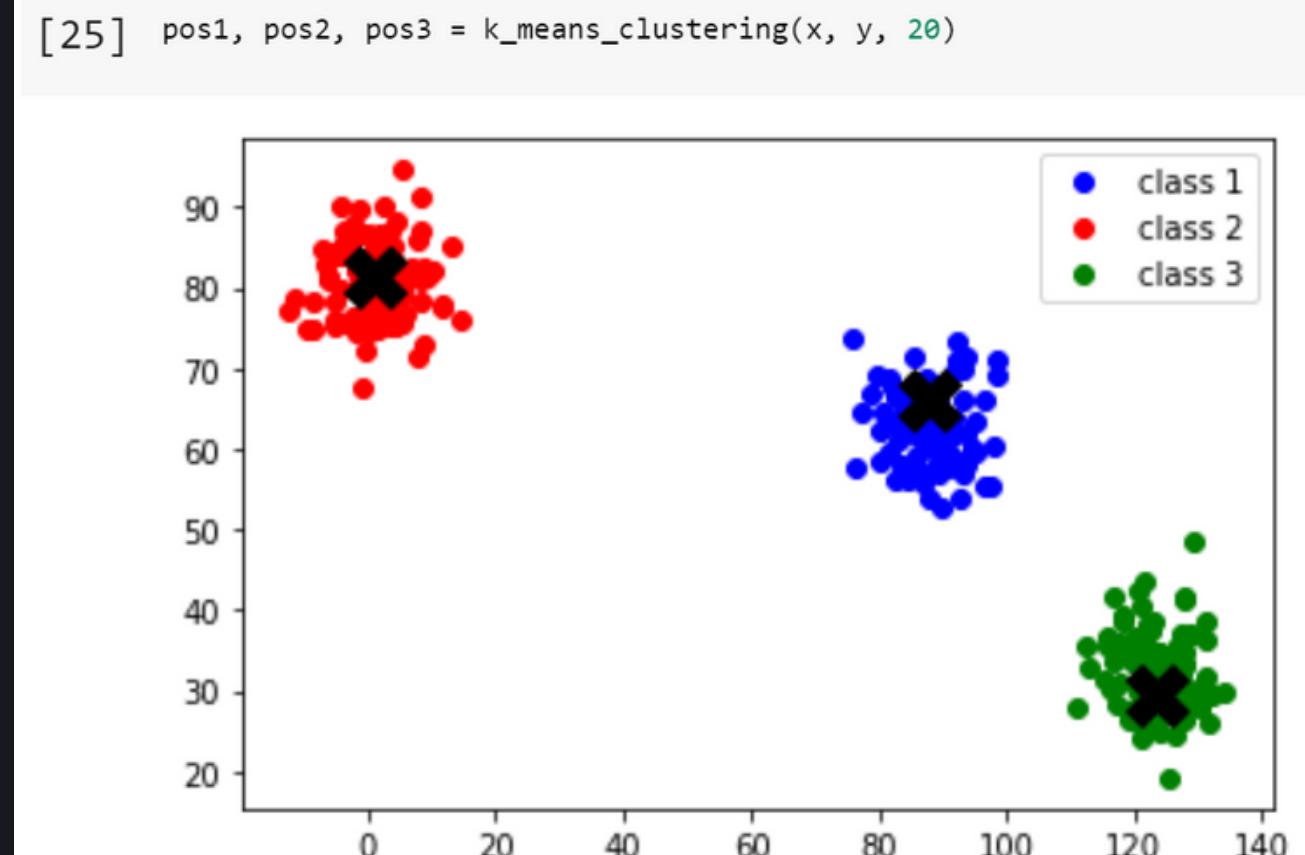
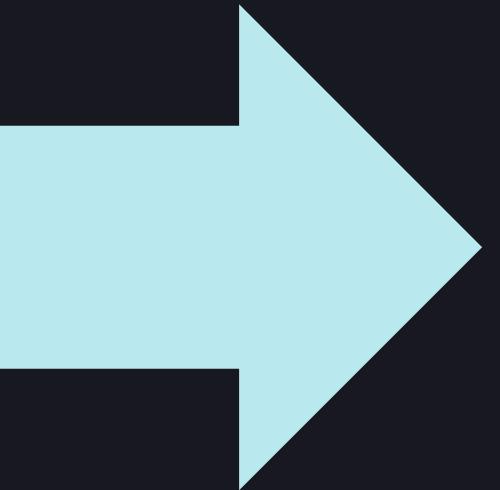
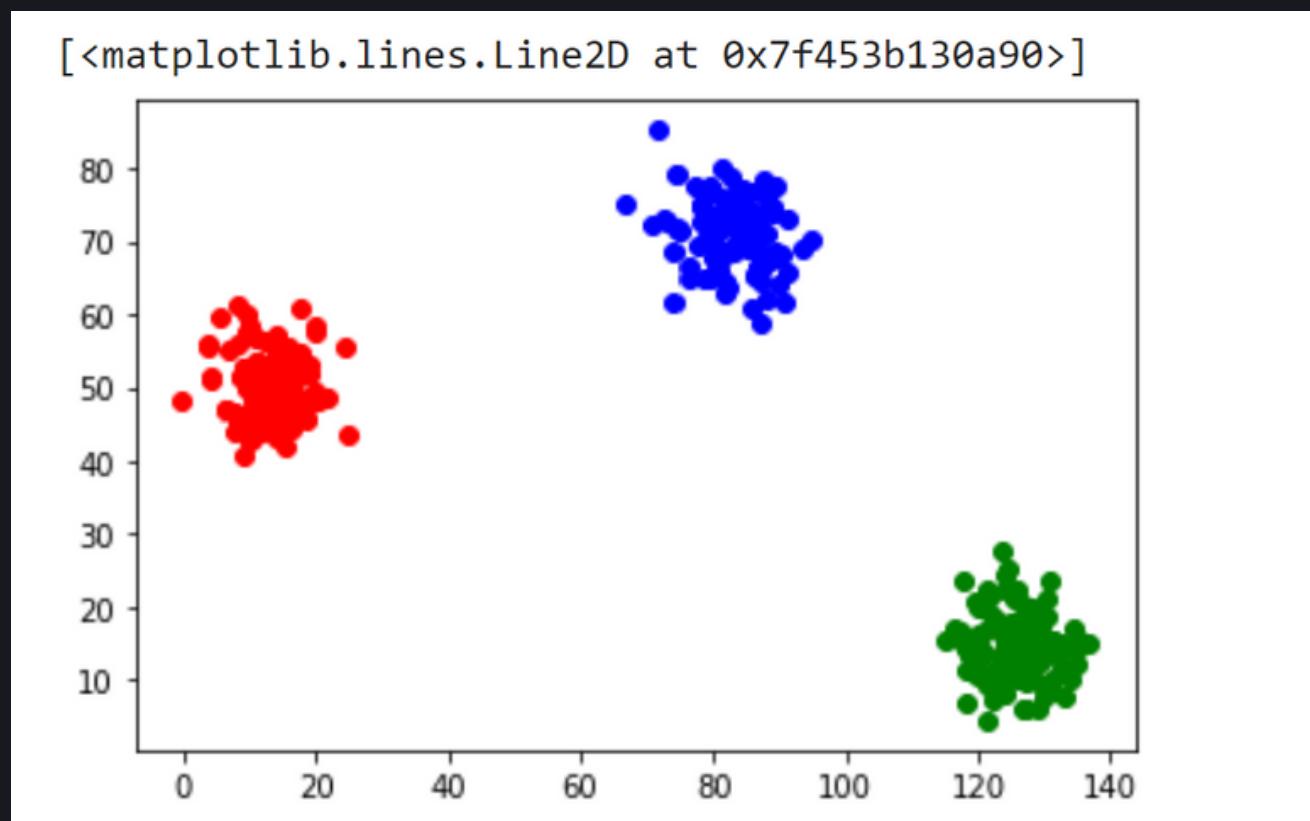
Drawbacks:

- The solution is NP-Hard, so we use heuristic algorithms to converge to local minima
- Does not guarantee global maximum
- The solution highly dependent on initialization and position of clusters
- Very difficult to choose k when number of classes unknown/data hard to visualize

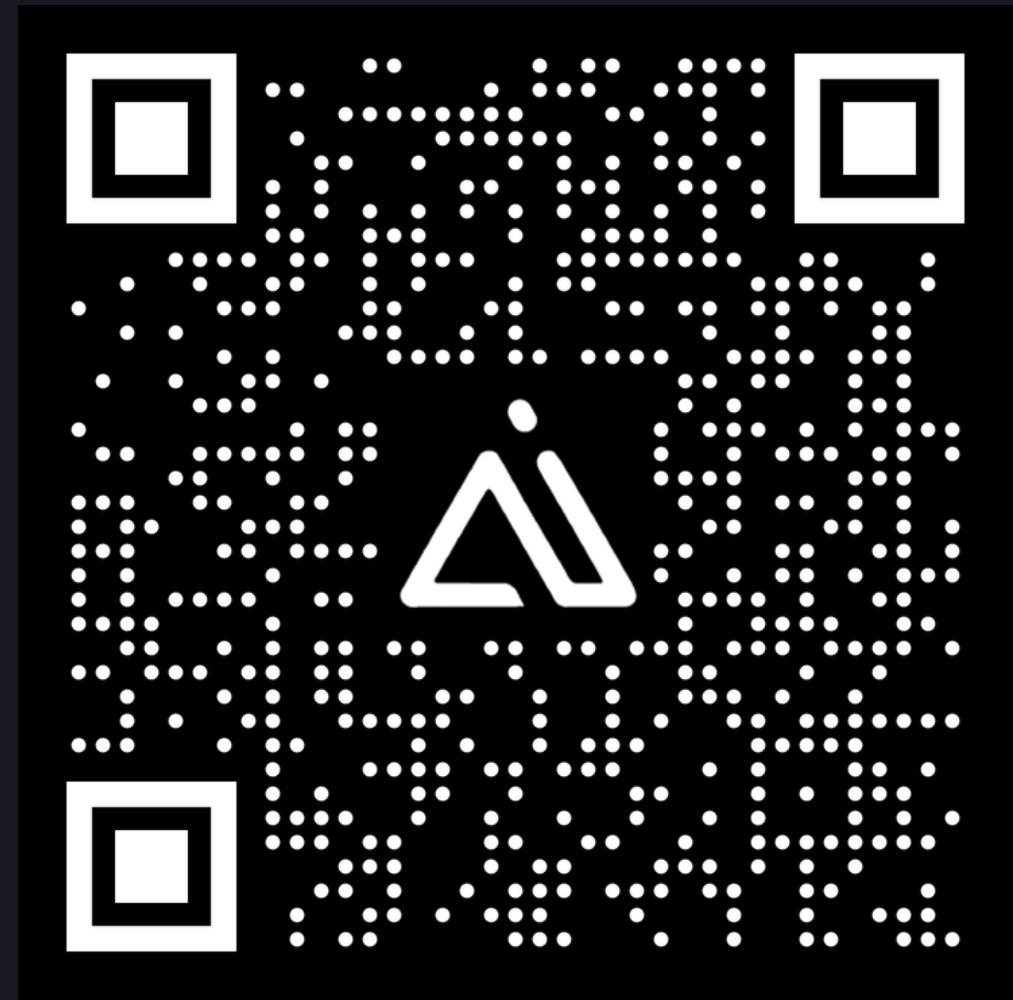
Theory

# K-MEANS CLUSTERING

Implement your own algorithm!



# QUESTIONS?



SEE YOU NEXT TIME