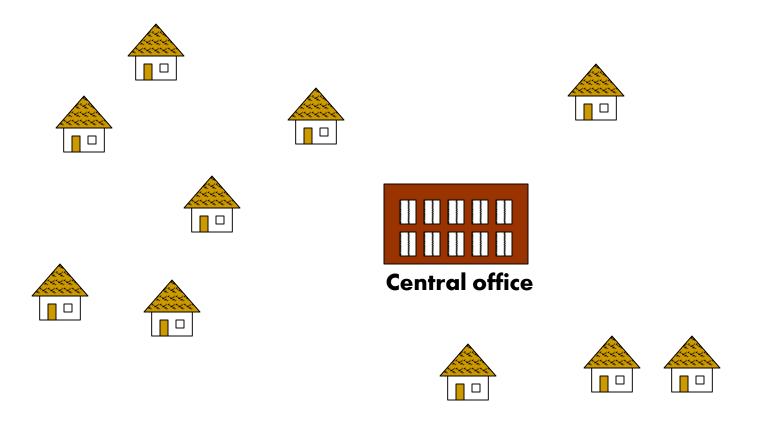
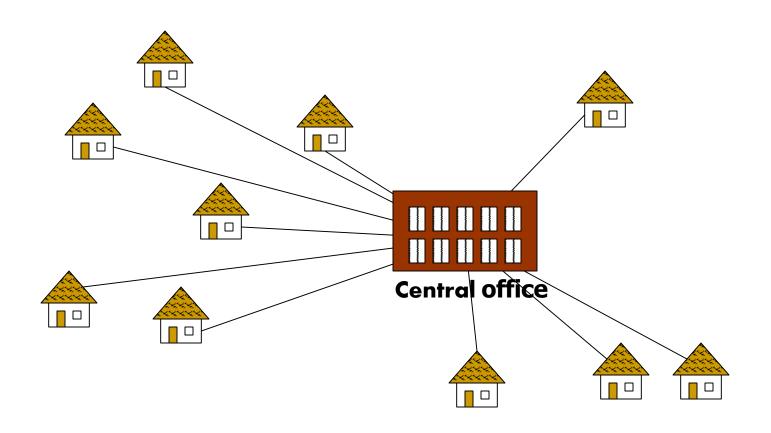
### **Data Structures**

### 25. Minimum Spanning Tree (MST)

# Problem: Laying Telephone Wire

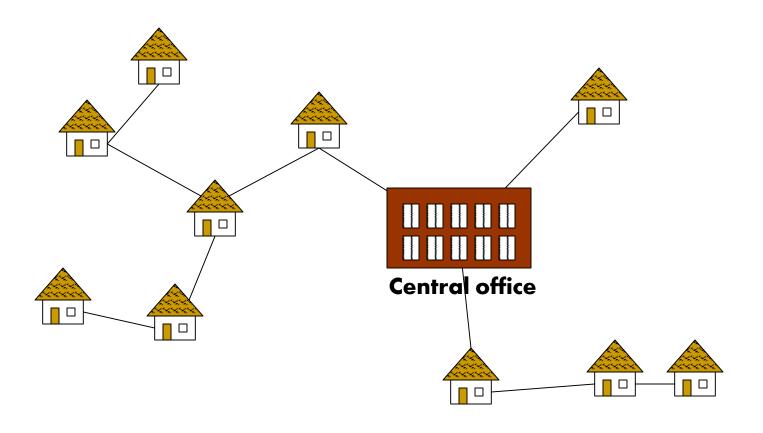


### Wiring: Naïve Approach



# **Expensive!**

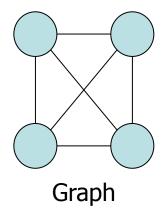
# Wiring: Better Approach

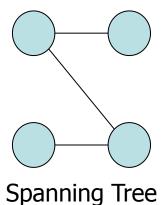


# **Spanning Trees**

 A spanning tree of a graph is just a subgraph that contains all the vertices and is a tree

- Formal definition
  - Given a connected graph with |V| = n vertices
  - A spanning tree is defined a collection of n 1 edges which connect all n vertices
  - The n vertices and n 1 edges define a connected sub-graph



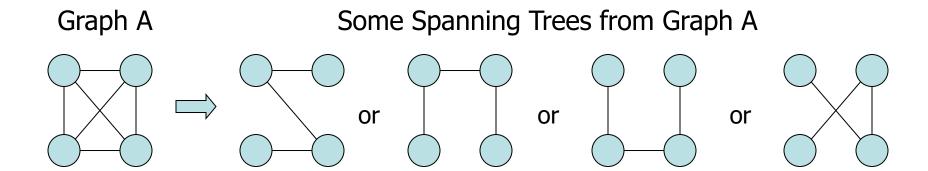


25-MST

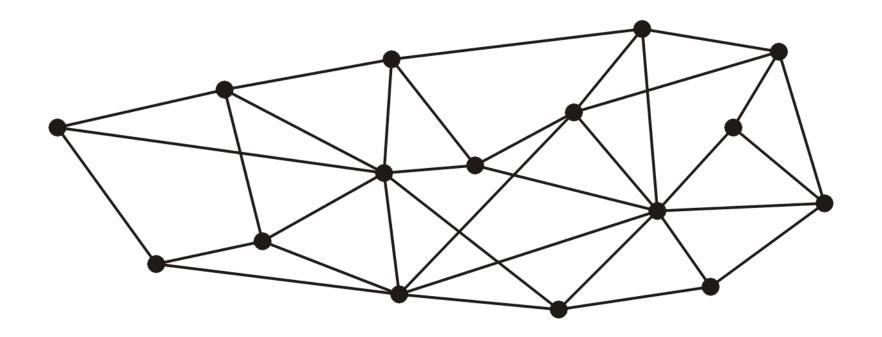
5

# **Spanning Trees**

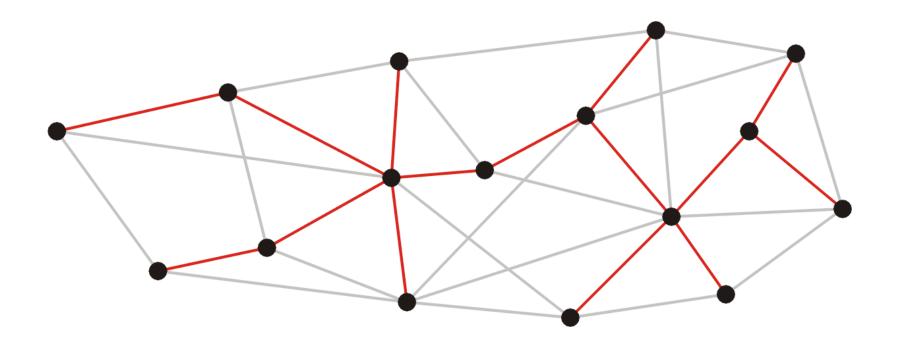
• A spanning tree is not necessarily unique



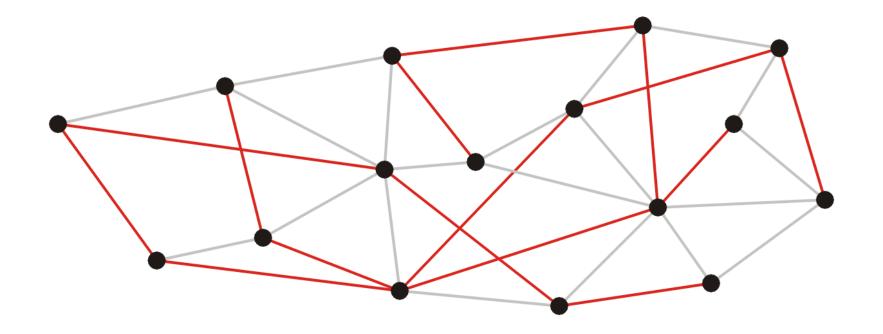
• This graph has 16 vertices and 35 edges

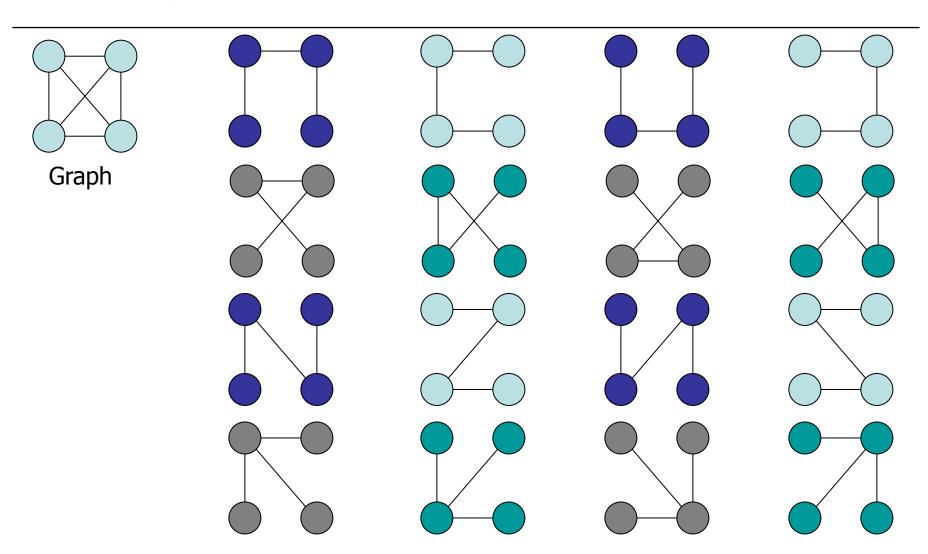


• These 15 edges form a minimum spanning tree



• As do these 15 edges

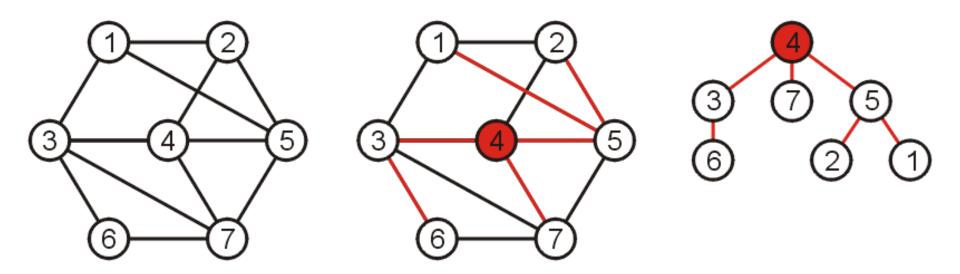




All 16 of its Spanning Trees

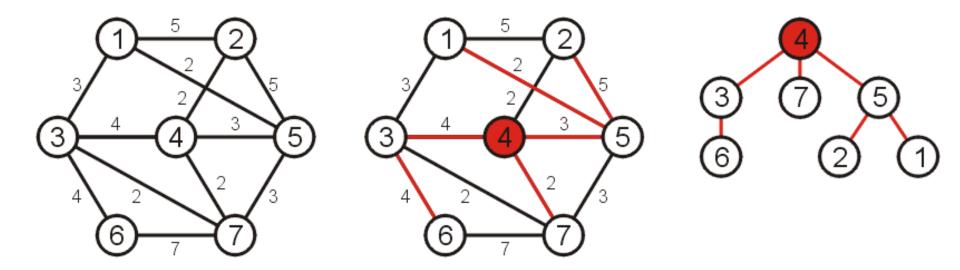
# **Spanning Trees**

- Why such a collection of |V|-1 edges is called a tree?
  - If any vertex is taken to be the root, we form a tree by treating the adjacent vertices as children, and so on...



# Spanning Tree on Weighted Graphs

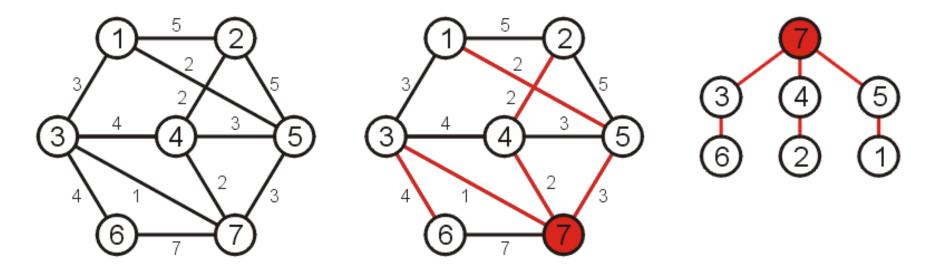
- Weight of a spanning tree
  - Sum of the weights on all the edges which comprise the spanning tree



• The weight of this spanning tree is 20

# Minimum Spanning Tree (MST)

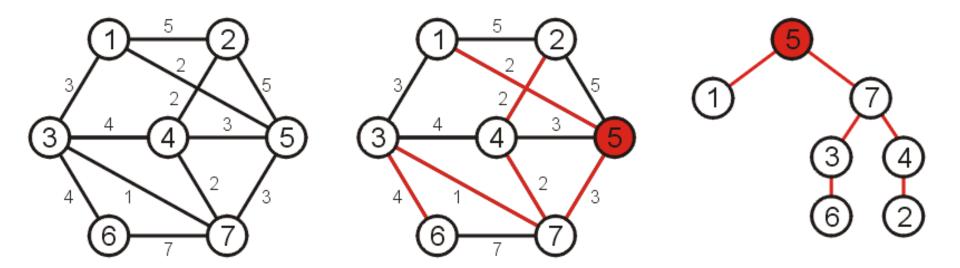
- Spanning tree that minimizes the weight
  - Such a tree is termed a minimum spanning tree



• The weight of this spanning tree is 14

# Minimum Spanning Tree (MST)

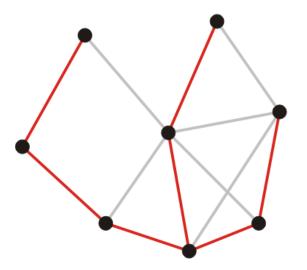
- If a different vertex is used as the root
  - A different tree is obtained
  - However, this is simply the result of one or more rotations

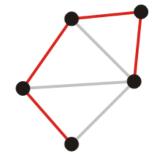


# Spanning Forest

- Suppose that a graph is composed of N connected sub-graphs
- A spanning forest is a collection of N spanning trees
  - One for each connected sub-graph



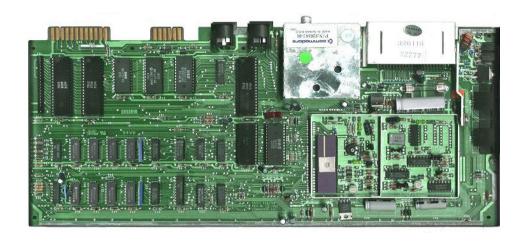




- A minimum spanning forest
  - A collection of N minimum spanning trees
  - One for each connected vertex-induced sub-graph

# **Applications**

- Consider supplying power to
  - All circuit elements on a board
  - A number of loads within a building
- A minimum spanning tree will give the lowest-cost solution





# **Application**

- First application of a minimum spanning tree algorithm was by the Czech mathematician Otakar Borůvka
  - Designed electricity grid in Morovia in 1926



# **Application**

- Consider attempting to find the best means of connecting a number of Local Area Networks (LANs)
  - Minimize the number of bridges
  - Costs not strictly dependent on distances



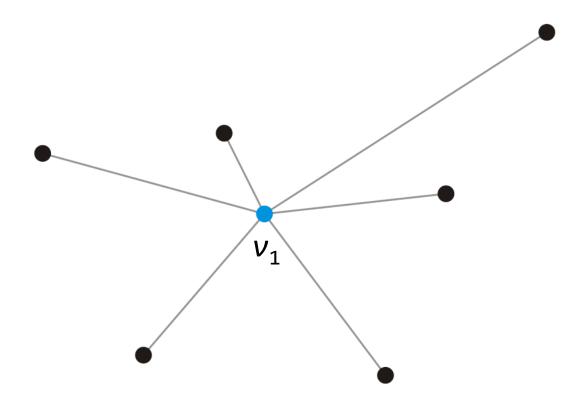
# Algorithms For Obtaining MST

- Kruskal's Algorithm
- Prim's Algorithm
- Boruvka's Algorithm

# Prim's Algorithm

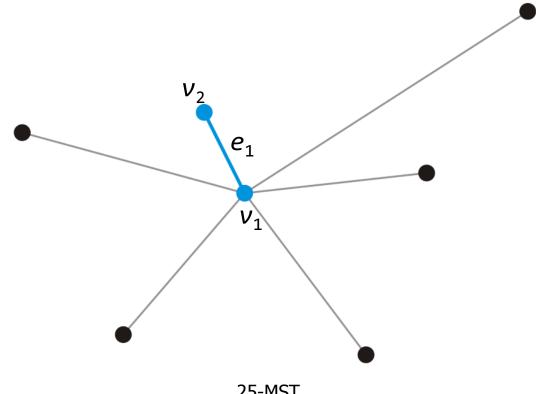
### Idea

- Suppose we take a vertex v<sub>1</sub>
  - It forms a minimum spanning tree on one vertex



#### Idea

- Add that adjacent vertex v<sub>2</sub> that has a connecting edge e<sub>1</sub> of minimum weight
  - This forms a minimum spanning tree on two vertices
  - $e_1$  must be in any minimum spanning tree containing the vertices  $v_1$  and  $v_2$



# Prim's Algorithm

- Start with an arbitrary vertex to form a minimum spanning tree on one vertex
- At each step, add a vertex v not yet in the minimum spanning tree
  - Through an edge with least weight that connects v to the existing minimum spanning sub-tree
- Continue until we have n 1 edges and n vertices

# Prim's Algorithm - Pseudocode

```
MST-Prim(G, w, r) { // w is the weight matrix of edges, r is root
Q = V[G]; // Insert graph vertices to a Priority Queue
for each u \in Q // Set distance of all vertices as \infty
    key[u] = \infty;
key[r] = 0; // Distance of root is set to 0
p[r] = NULL; // Parent of root is NULL
while (Q not empty) {
    u = ExtractMin(Q); // Get the vertex u with min key[u]
    for each v ∈ Adj[u] { // Adj is the adjacency list
         if (v \in Q \text{ and } w(u,v) < \text{key}[v]) 
             p[v] = u;
             \text{key}[v] = w(u,v); // \text{ weight of an edge } (u,v)
```

### Prim's Algorithm – Data Structure

- Associate with each vertex two items of data
  - The minimum distance to the partially constructed tree
    - > For a given vertex v, key[v] represent minimum distance
  - Pointer to the vertex that will form the parent node in resulting tree
    - > For a given vertex v, p[v] represent parent node

#### Initialization

- Set the distance of all vertices as  $\infty$ , e.g., for all u ∈ G, key[u]=  $\infty$
- Set all vertices to being unvisited
  - ➤ Add vertices to the Queue
- Select a root node and set its distance as 0, i.e., key[r] = 0
- Set the parent pointer of root to NULL, i.e., p[r] = NULL

```
MST-Prim(G, w, r)
Q = V[G];
for each u \in Q
                       14
     key[u] = \infty;
key[r] = 0;
p[r] = NULL;
while (Q not empty)
                              Run on example graph
     u = ExtractMin(Q);
     for each v \in Adj[u]
          if (v \in Q \text{ and } w(u,v) < \text{key}[v])
               p[v] = u;
               key[v] = w(u,v);
```

```
MST-Prim(G, w, r)
Q = V[G];
for each u \in Q
                      14
     key[u] = \infty;
                                               15
key[r] = 0;
p[r] = NULL;
while (Q not empty)
                              Run on example graph
     u = ExtractMin(Q);
     for each v \in Adj[u]
          if (v \in Q \text{ and } w(u,v) < \text{key}[v])
               p[v] = u;
               key[v] = w(u,v);
```

```
MST-Prim(G, w, r)
Q = V[G];
for each u \in Q
     key[u] = \infty;
key[r] = 0;
p[r] = NULL;
                                 \infty
while (Q not empty)
                                Pick a start vertex r
     u = ExtractMin(Q);
     for each v \in Adj[u]
          if (v \in Q \text{ and } w(u,v) < \text{key}[v])
               p[v] = u;
               key[v] = w(u,v);
```

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MST-Prim(G, w, r)
Q = V[G];
for each u \in Q
     key[u] = \infty;
key[r] = 0;
p[r] = NULL;
                                 \infty
while (Q not empty)
                               Black vertices have been
     u = ExtractMin(Q);
                                   removed from Q
     for each v \in Adj[u]
          if (v \in Q \text{ and } w(u,v) < \text{key}[v])
               p[v] = u;
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          if (v \in Q \text{ and } w(u,v) < \text{key}[v])
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               key[v] = w(u,v);
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MST-Prim(G, w, r)
Q = V[G];
for each u \in Q
     key[u] = \infty;
key[r] = 0;
p[r] = NULL;
                                3
while (Q not empty)
                             Black arrows indicate parent
     u = ExtractMin(Q);
                                      pointers
     for each v \in Adj[u]
          if (v \in Q \text{ and } w(u,v) < \text{key}[v])
               p[v] = u;
               key[v] = w(u,v);
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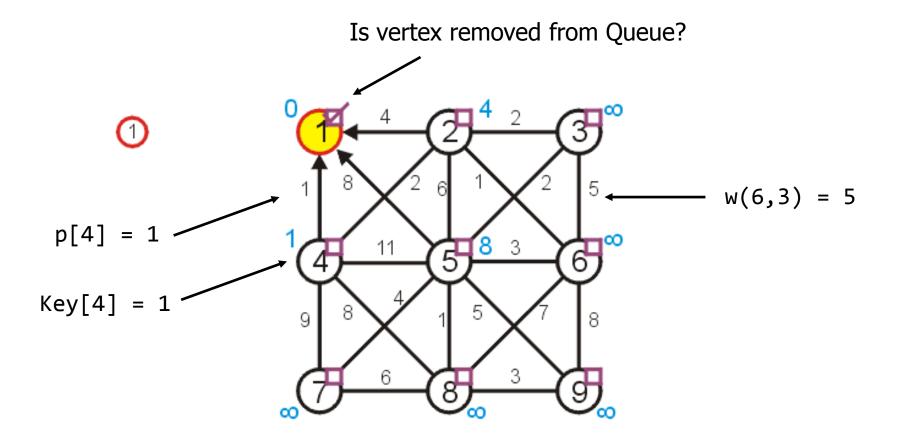
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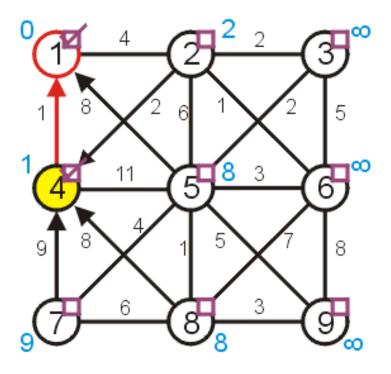
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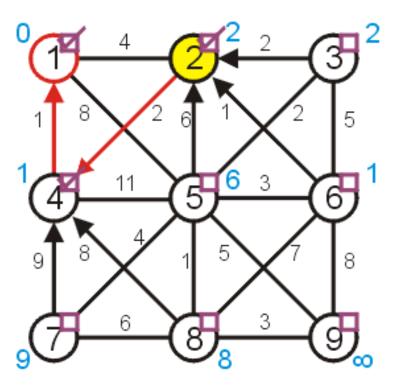
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                      14
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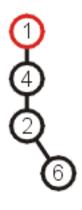


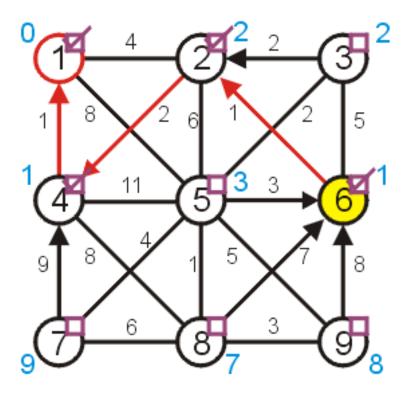


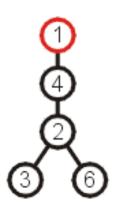


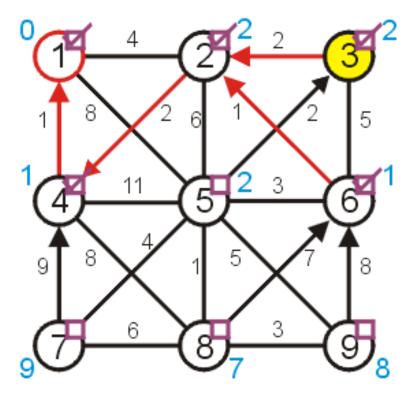


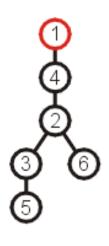


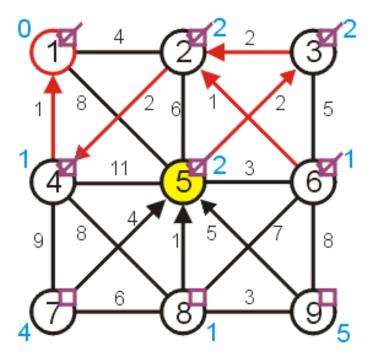


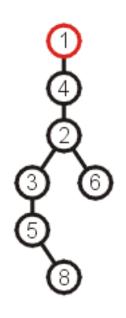


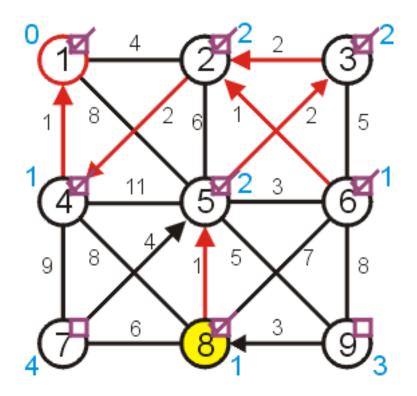


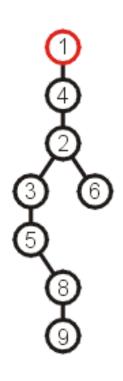


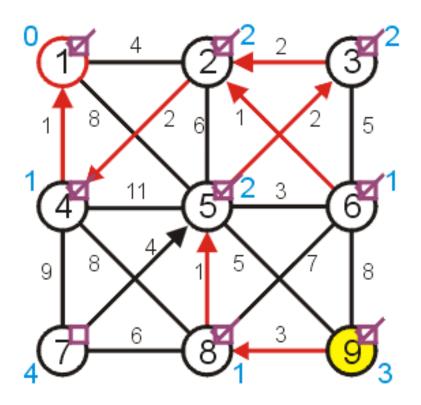


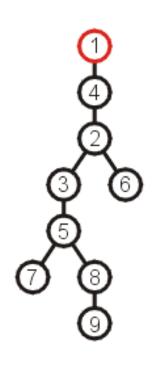


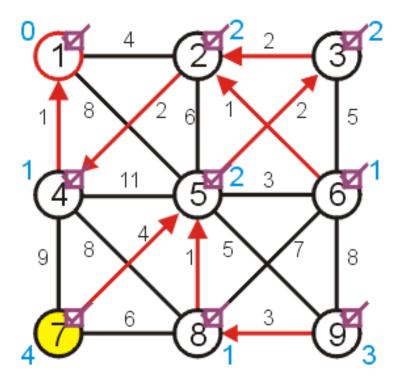


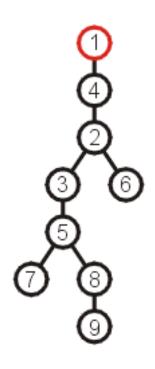


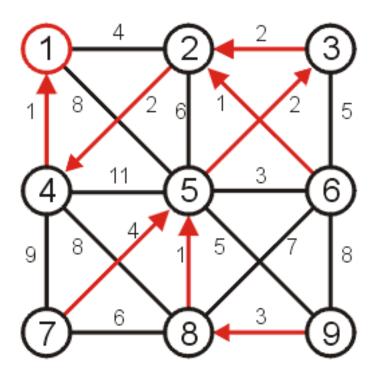












#### Kruskal's Algorithm vs Prim's Algorithm

- In prim's algorithm, graph must be connected
- Kruskal's algorithm can function on disconnected graphs too
- Prim's algorithm is significantly faster for dense graphs with more number of edges than vertices
- Kruskal's algorithm runs faster in the case of sparse graphs

# Any Question So Far?

