

# VINDULA JAYAWARDANA

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## PERSONAL INFORMATION

Cambridge, United States  
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in [in/vindulajayawardana](https://in.linkedin.com/in/vindulajayawardana)

## RESEARCH INTERESTS

*Learning for autonomy* with the goal of making multi-agent reinforcement learning seamlessly generalize across scenarios. Applications in planning for autonomous vehicles and sustainable cities. Past research on mathematical programming for combinatorial optimizations and natural language processing for information extraction.

## RELEVANT EXPERIENCE

**Massachusetts Institute of Technology**, Cambridge, USA *Sep 2019-May 2025*  
Ph.D. Candidate

- Work with Prof. Cathy Wu at Laboratory for Information and Decision Systems.
- Research on improving robustness and generalization in reinforcement learning, specifically when solving Contextual MDPs [1, R1].
- Model and build large-scale traffic simulations that span over ten major US cities and nearly three million traffic scenarios for impact assessment of cooperative eco-driving [W4, 6].
- Conduct computational studies validating the efficacy of reinforcement learning for eco-driving [2, W4], autonomous vehicle planning [3], and traffic smoothing [5].

**Toyota Motor North America**, Mountain View, USA *June 2023-Aug 2023*  
Research Intern

- Improved generalization in multi-agent reinforcement learning across scenarios by combining nominal-model-based policies with learning-based policies [R1].
- Conducted experiments to validate the effectiveness of the proposed method on eco-driving across 600 signalized intersections [R1].
- Proposed a hierarchical policy architecture aiming for continual learning for eco-driving across signalized intersections [R3].

**University of Moratuwa**, Colombo, Sri Lanka *Jan 2018-July 2019*  
Research Assistant

- Conducted ride-sharing simulations with integer programming for request-driver matching.
- Conducted ride-pooling with meeting points simulations based on integer programming formulations for request-driver-meeting point matching.
- Analyzed the optimality gaps between heuristic methods and optimal methods for ride-pooling with meeting points problem [7].

**Digital Mobility Solutions Lanka**, Colombo, Sri Lanka *Jan 2018-July 2019*  
Consultant Researcher

- Built numerical simulations of ride-sharing in major Sri Lankan cities based on real-world data.
- Evaluated the effectiveness of ride-sharing in select cities with large-scale numerical simulations.

**Cornell University**, Ithaca, USA *June 2018-Aug 2018*  
Research Intern

- Built an open source ride pooling simulator in C++ for large-scale ride pooling with integer programming based driver-passenger matching.
- Formulated Integer programming models for ride pooling with meeting points problem [7].

**WSO2**, Colombo, Sri Lanka *July 2016-Dec 2016*  
Software Engineering Intern

- Developed an open-source library Charon for SCIM 2.0 support following IETF specifications.
- Integrated SCIM 2.0 support for the WSO2 Identity server.

## EDUCATION

**Massachusetts Institute of Technology**, Cambridge, USA *Sep 2019-May 2025*  
Ph.D. Electrical Engineering and Computer Science (GPA: 4.9/5.0)

**Massachusetts Institute of Technology**, Cambridge, USA *Sep 2019-Sep 2022*  
M.S. Electrical Engineering and Computer Science (GPA: 4.9/5.0)

**University of Moratuwa**, Colombo, Sri Lanka *Mar 2014 -Dec 2017*  
B.S. Computer Science and Engineering (GPA: 4.08/4.2)

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|------------------------------|---|--|
| SELECTED PUBLICATIONS        | [1] V. Jayawardana, C. Tang, S. Li, D. Suo, C. Wu. <i>The impact of task underspecification in evaluating deep reinforcement learning</i> , NeurIPS'22.   |  |
|                              | [2] V. Jayawardana, C. Wu. <i>Learning eco-driving strategies at signalized intersections</i> , ECCV'22. <b>MIT News Spotlight, NPR and Tech Crunch featured.</b>   |  |
|                              | [3] S. Jayawardana, V. Jayawardana*, K. Vidanage, C. Wu*. <i>Multi-behavior learning for socially compatible autonomous driving</i> , ITSC'23. <b>* equal supervision</b>   |  |
|                              | [4] V. Jayawardana, A. Landler, C. Wu. <i>Mixed autonomous supervision in traffic signal control</i> , ITSC'21.   |  |
|                              | [5] D. Zhuang, Y. Huang, V. Jayawardana, J. Zhao, D. Suo, and C. Wu, <i>The braess paradox in dynamic traffic</i> , ITSC'22.  |  |
|                              | [6] Qu, A. Valiveru, C. Tang, V. Jayawardana, B. Freydt, and C. Wu, <i>What is a typical signalized intersection in a city?</i> TRB'22.   |  |
|                              | [7] M. Mounesan, V. Jayawardana, Y. Wu, S. Samaranayake, H. T. Vo, <i>Fleet management for ride-pooling with meeting points at scale: A case study in the five boroughs of New York City</i> , '21.   |  |
|                              | * More on <a href="#">Google Scholar</a> .  |  |
| WORK IN REVIEW / PREPARATION | [R1] V. Jayawardana, S. Li, C. Wu, Y. Farid, K. Oguchi. <i>Generalizing eco-lagrangian control via multi-residual task learning</i> , In review ICRA'24.  |  |
|                              | [R2] V. Jayawardana, D. Suo, C. Wu, <i>Learning corridor clearance: A near term deployment perspective</i> , In review T-ITS'23.  |  |
|                              | [R3] V. Jayawardana, Y. Farid, K. Oguchi. <i>Eco-driving at signalized intersections</i> , In review U.S patent.  |  |
|                              | [W4] V. Jayawardana, B. Freydt, A. Qu, C. Hickert, E. Sanchez, C. Tang, S. Chandrasiri, A. Valiveru, J. He, D. Suo, B. Leonard, C. Wu, <i>Assessing no-stop intersections for low carbon transportation using deep reinforcement learning</i> , In preparation (Nature) |  |
|                              | [W5] Y. Kim, V. Jayawardana, S. Samaranayake, <i>Choice modeling in high-capacity ride-pooling with deep reinforcement learning</i> , In preparation (TR-C)   |  |
| SKILLS AND PROJECTS          | <b>Technical Skills:</b> Python (Numpy, PyTorch), C++, Java, C#, JavaScript/CSS/HTML, SQL, Bash, Linux, VSCode, Latex, Gurobi, Mosek, SUMO  |  |
|                              | <b>Research Skills:</b> Reinforcement learning, planning for autonomous vehicles, numerical simulations, intelligent transportation systems, machine learning, control theory, optimizations, traffic engineering, and data analytics.                                  |  |
|                              | <b>Selected Research Projects:</b> <a href="#">Greenwave</a> (AI-driven eco-driving) - Project lead for 14-member team  |  |
|                              | <b>Open Source Projects</b>   |  |
|                              | <a href="#">Open Ridepool Simulator</a> - Co-main contributor   |  |
| AWARDS AND ACHIEVEMENTS      | Harold L. Hazen Teaching Award (MIT) 2022   |  |
|                              | NeurIPS Scholar Award (NeurIPS) 2022, 2023  |  |
|                              | Migara Ranathunga Trust Award (Institute of Engineers Sri Lanka) 2017/2018  |  |
|                              | Digital Mobility Solutions Lanka Fellowship (Digital Mobility Solutions Lanka) 2018   |  |
|                              | Dean's Honor List (University of Moratuwa) 2017   |  |
|                              | Finalists at NASA International Space Apps (NASA) 2017  |  |
|                              | Gold Award at National Best Quality ICT Awards (Sri Lanka Sector of British Computer Society) 2017  |  |
| RESEARCH TALKS               | Silver Medal, Junior Science Olympiad Sri Lanka (Sri Lankan Junior Science Olympiad) 2010   |  |
|                              | Toyota R&D, Mountain View, USA 2023   |  |
|                              | MIT CEE Annual Research Day, Cambridge, USA 2023  |  |
|                              | Neural Information Processing Systems Conference, New Orleans, USA 2022   |  |
|                              | European Control Conference, London, UK 2022  |  |
|                              | Robotics for Climate Change ( <b>Spotlight talk</b> ), Philadelphia, USA 2022   |  |
|                              | MIT CEE Annual Research Day, Cambridge, USA 2022  |  |
|                              | University of Moratuwa, Moratuwa, Sri Lanka 2021  |  |
|                              | MIT-IBM Watson AI Lab Open House, Cambridge, USA 2021   |  |
|                              | Data Drives - Data science applications in technology-based industries, Colombo, Sri Lanka 2019   |  |
| SERVICES                     | Innovative Computing Technology Conference, London, UK 2017   |  |
|                              | Transactions on Robotics (T-RO) - Reviewer 2023   |  |
|                              | Neural Information Processing Systems Conference (NeurIPS) - Reviewer 2023  |  |
|                              | AAAI Conference on Artificial Intelligence (AAAI) - Reviewer 2023   |  |
|                              | Physica A: Statistical Mechanics and its Applications (Physica A) - Reviewer 2023   |  |
|                              | International Conference on Robotics and Automation (ICRA) - Reviewer 2020, 2022  |  |
|                              | Transactions on Intelligent Systems and Technology (T-IST) - Reviewer 2022  |  |
|                              | Transportation Research Board (TRB) - Reviewer 2022   |  |
|                              | Moratuwa Engineering Research Conference (MERCon) - Reviewer 2020, 2021   |  |

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| NeurIPS Tackling Climate Change with Machine Learning - Reviewer                                     | 2023 |
| AAAI When Machine Learning meets Dynamical Systems: Theory and Applications - Reviewer               | 2022 |
| AAAI Representation Learning for Responsible Human-Centric AI - Area Chair ( <b>Top Area Chair</b> ) | 2022 |

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| MIT CEE faculty hiring student committee                             | 2023      |
| President, Sri Lankan Students' Association at MIT                   | 2019-2023 |
| Rotaract Club of Alumni of the University of Moratuwa                | 2017-2019 |
| Old Royalists Engineering Professionals' Association Student Chapter | 2015-2018 |
| Rotaract Club of University of Moratuwa                              | 2014-2016 |

## TEACHING

### Teaching Assistant

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| 1.041/1.200 - Transportation: Foundations and Methods ( <b>MIT EECS Teaching Excellence Award</b> ) <i>MIT Fall 2020, 2021</i> |                        |
| CS2022 - Data Structures and Algorithms  | <i>UoM Spring 2019</i> |
| CS4622 - Machine Learning  | <i>UoM Fall 2018</i>   |
| CS3042 - Database Systems  | <i>UoM Fall 2018</i>   |
| CS2052 - Computer Architecture   | <i>UoM Spring 2018</i> |
| CS2062 - Object Oriented Software Development  | <i>UoM Spring 2018</i> |
| CS3962 - Research and Report Writing   | <i>UoM Fall 2017</i>   |
| CS2963 - Presentation Skills   | <i>UoM Fall 2017</i>   |

## MENTORSHIP

### Graduate Students

*Jessica Ding*: MIT

- Co-authoring a paper on residual transfer learning for traffic control.

*Baptiste Freydt He*: ETH Zurich (Now: software engineer)

- Co-authoring a paper on large-scale eco-driving using deep reinforcement learning [W4].

### Undergraduates

*Anna Landler*: MIT (Now: software engineer at Crusoe)

- Co-authored a paper on autonomous traffic signal supervision [4].

*Catherine Tang*: MIT (Now: sophomore at MIT)

- Co-authored papers on task underspecification in deep reinforcement learning [1] and learning vehicular emission models.

*Anirudh Valiveru*: MIT (Now: sophomore at MIT)

- Co-authored paper on data processing pipeline for open street maps.

*Ammar Fayad*: MIT (Now: junior at MIT)

*Jiixin He*: Vanderbilt University (Now: master student at UC San Diego)

- Co-authoring a paper on large-scale eco-driving using deep reinforcement learning [W4].

*Sunera Chandrasiri*: University of Moratuwa (Now: co-founder of iXD Labs)

- Co-authoring a paper on large-scale eco-driving using deep reinforcement learning [W4].

*Sanjula Jayawardana*: University of Wesminter (Now: software engineer at IFS)

- Co-authoring a paper on socially compatible autonomous driving [3].

## MEDIA

MIT News spotlight: [On the road to cleaner, greener, and faster driving](#)

Techcrunch: [Perceptron: Risky teleoperation, Rocket League simulation, and zoologist multiplication](#)

NPR: [Green Driving](#)

ADAS & Autonomous Vehicle International Magazine: [A greener way to negotiate traffic lights](#)