Structured Variational Inference in Continuous Cox Process Models

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CONTRIBUTIONS

We propose a scalable *structured* variational inference algorithm for *continuous* sigmoidal Cox processes. Contributions:

- Scalable inference in continuous input spaces via a process superposition.
- Efficient structured posterior estimation giving a posterior capturing the complex variable dependencies in the model
- State-of-the-art performance when compared to alternative inference schemes, link functions, augmentation schemes and representations of the input space.

THE LIKELIHOOD FUNCTION

Discrete likelihood:

$$p(\mathbf{Y}|\mathbf{f}) = \prod_{i=1}^n \mathsf{Poisson}\left(y_n; \lambda(\mathbf{x})\right)$$

Continuous likelihood:

$$\mathcal{L}(N, \{\mathbf{x}_1, ..., \mathbf{x}_n\} | \lambda(\mathbf{x})) = \exp\left(-\int_{\tau} \lambda(\mathbf{x}) d\mathbf{x}\right) \prod_{n=1}^{N} \lambda(\mathbf{x}_n)$$

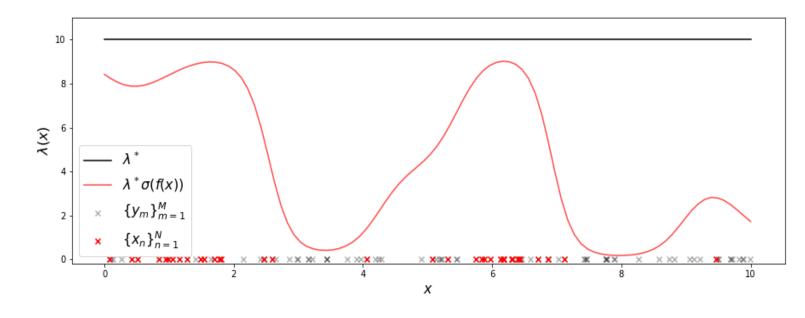


Figure 1: Superposition of two Poisson Point Processes with intensities $\lambda^\star \sigma(f(\mathbf{x}))$ and $\lambda^\star \sigma(-f(\mathbf{x}))$.

	LGCP	SGCP [1]	Gunter et al.(2014)	VBPP [2]	Lian et al. (2015)	MFVB [3]
Inference	MCMC	MCMC	MCMC	VI-MF	VI-MF	VI-MF
\mathcal{O}	N^3	$(N + M)^{3}$	$(N + M)^3$	NK^2	NK^2	NK^2
$\lambda(x)$	$\exp(f(x))$	$\lambda^{\star}\sigma(f(x))$	$\lambda^{\star}\sigma(f(x))$	$(f(x))^{2}$	$(f(x))^{2}$	$\lambda^{\star}\sigma(f(x))$
\mathcal{X}	\sum_{i}	\int	\int	\int_{0}^{∞}	$\sum_{i=1}^{n}$	\int
Tractability		Thinning	Adaptive Thinning	Functional form		Integral approximation

Table 1: Summary of related work. \int is continuous, \sum is discrete. M represents the number of thinned points derived from the thinning algorithm. K are the number of inducing inputs.

Augmentation via superposition

Full joint distribution
$$\mathcal{L}(\{\mathbf{x}_n\}_{n=1}^N, \{\mathbf{y}_m\}_{m=1}^M, M, \mathbf{f}, \lambda^* | \mathcal{X}, \boldsymbol{\theta})$$
:
$$\frac{(\lambda^*)^{N+M} \exp(-\lambda^* \int_{\mathcal{X}} d\mathbf{x})}{N!M!} \prod_{n=1}^N \sigma(f(\mathbf{x}_n)) \prod_{m=1}^M \sigma(-f(\mathbf{y}_m)) p(\mathbf{f}) p(\lambda^*)$$

STRUCTURED VARIATIONAL INFERENCE

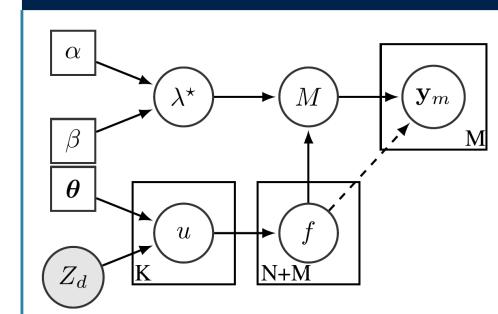


Figure 2: Posterior distribution accounting for all model dependencies. The dashed line represents the assumed factorization.

$$Q(\mathbf{f}, \mathbf{u}, M, {\mathbf{y}_m}_{m=1}^M, \lambda^*) = p(\mathbf{f}|\mathbf{u})q(\mathbf{u})q(\lambda^*)$$
$$\times q({\mathbf{y}_m}_{m=1}^M | M)q(M|\mathbf{f}, \lambda^*)$$

$$q(\mathbf{u}) = \mathcal{N}(\mathbf{m}, \mathbf{S})$$
 $q(\lambda^*) = \mathsf{Gamma}(\alpha, \beta)$

$$q(\{\mathbf{y}_m\}_{m=1}^{M}|M) = \prod_{m=1}^{M} \sum_{s=1}^{S} \pi_s \mathcal{N}_T(\mu_s, \sigma_s^2; \mathcal{X})$$

$$q(M|\mathbf{f},\lambda^{\star}) = \mathsf{Poisson}(\eta) \qquad \eta = \lambda^{\star} \int_{\mathcal{X}} \sigma(-f(\mathbf{x})) d\mathbf{x}$$

THE EVIDENCE LOWER BOUND

$$\mathcal{L}_{\text{elbo}} = T_0 + \underbrace{\mathbb{E}_Q[M \log(\lambda^*)]}_{T_1} - \underbrace{\mathbb{E}_Q[\log(M!)]}_{T_2} + \sum_{n=1}^{N} \mathbb{E}_{q(\mathbf{f})}[\log(\sigma(f(\mathbf{x}_n)))] + \underbrace{\mathbb{E}_Q\left[\sum_{m=1}^{M} \log(\sigma(-f(\mathbf{y}_m)))\right]}_{T_3}$$

$$-\left.\mathcal{L}_{\mathsf{kl}}^{\mathbf{u}}-\mathcal{L}_{\mathsf{kl}}^{\lambda^{\star}}-\underbrace{\mathcal{L}_{\mathsf{ent}}^{M}}_{T_{\mathsf{d}}}-\underbrace{\mathcal{L}_{\mathsf{ent}}^{\{\mathbf{y}_{m}\}_{m=1}^{M}}}_{T_{\mathsf{5}}}$$

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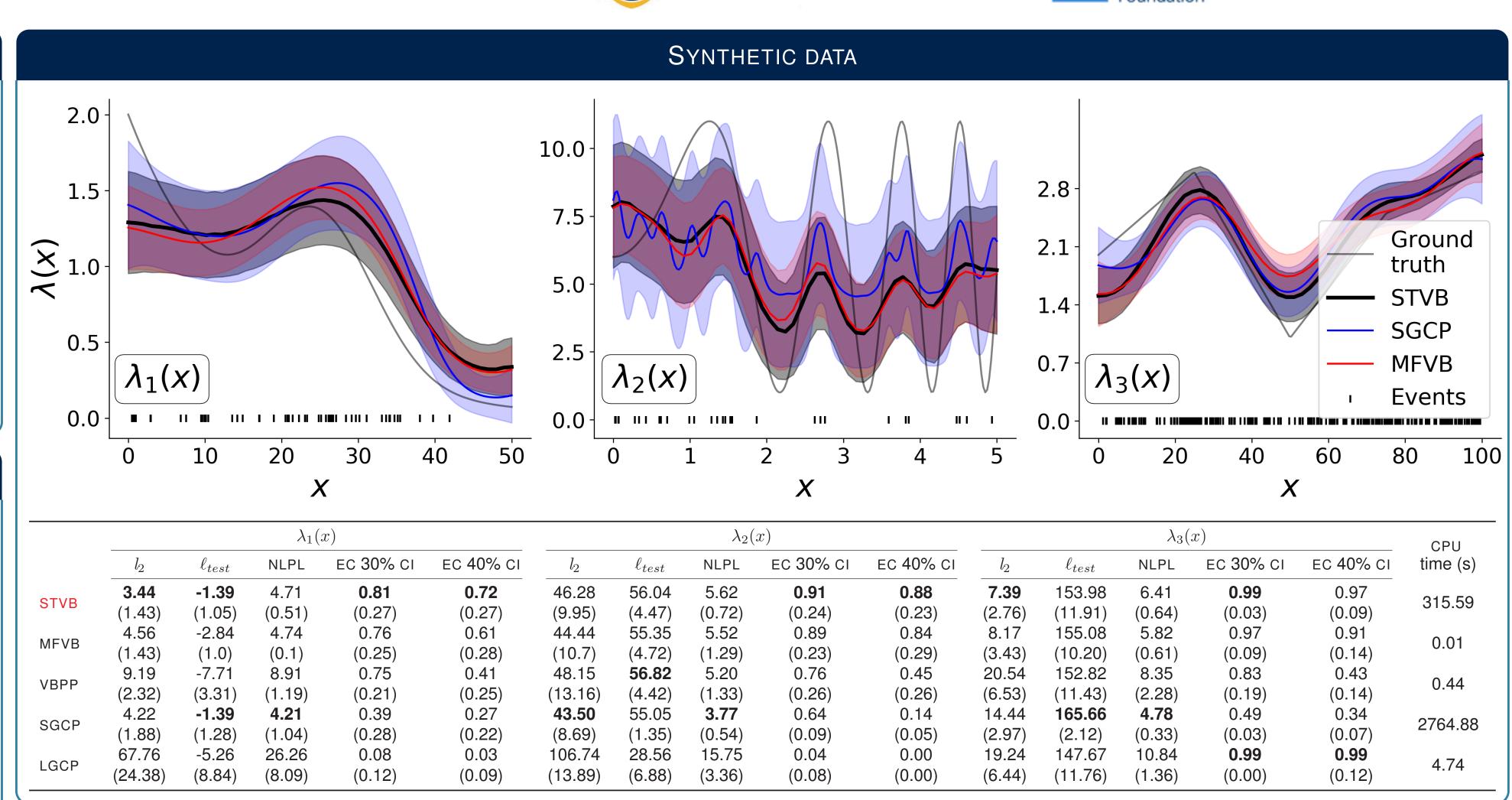
where $T_0 = N(\psi(\alpha) - \log(\beta)) - V\frac{\alpha}{\beta} - \log(N!)$, $V = \int_{\mathcal{X}} d\mathbf{x}$, $\psi(\cdot)$ is the digamma function and $q(\mathbf{f}) = \mathcal{N}(\mathbf{Am}, \mathbf{K}_{xx} - \mathbf{AK}_{zx} + \mathbf{ASA}^T)$.

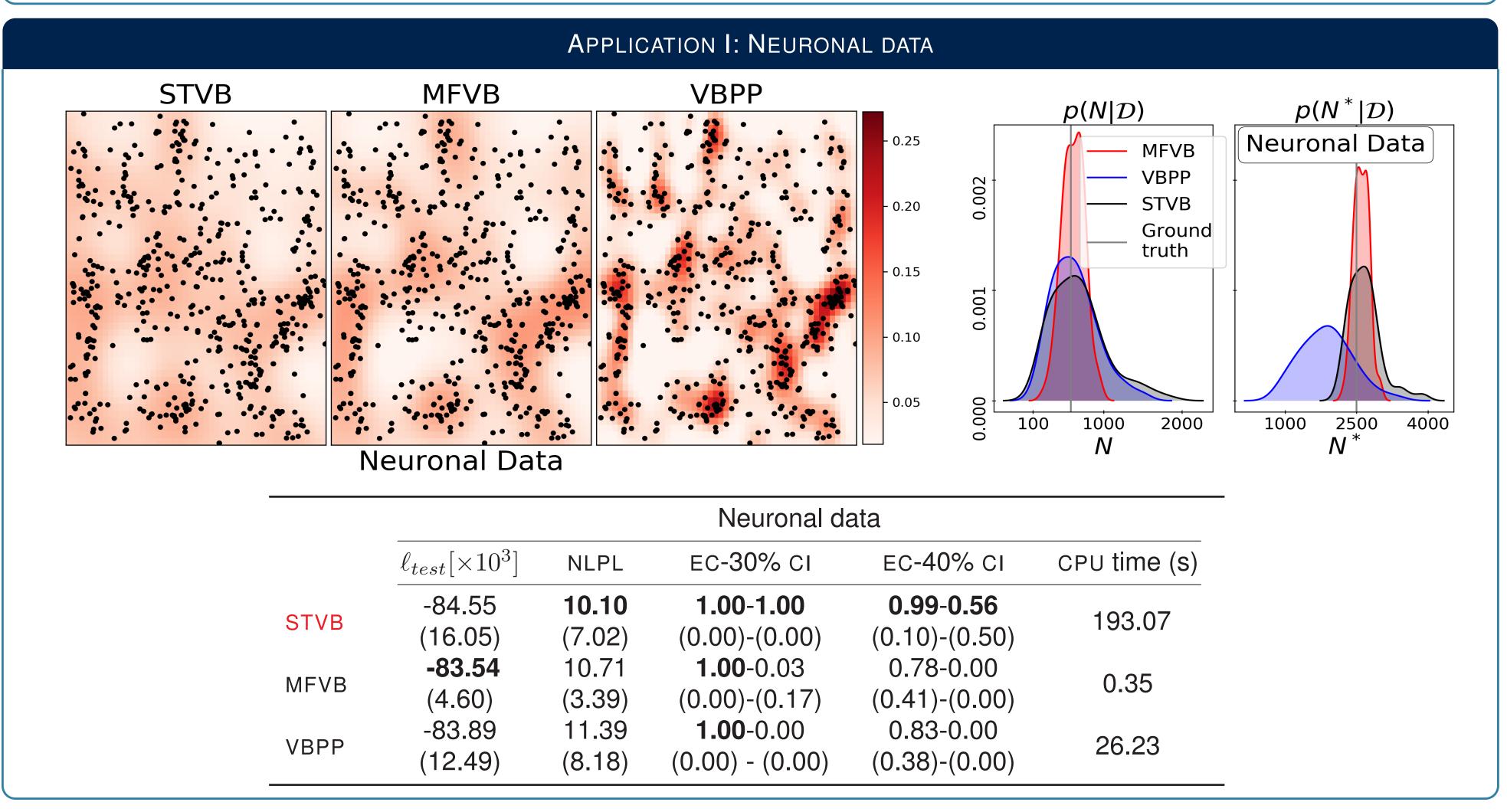
We derive expressions for T_i , i=1,...,5 that avoid sampling from the full joint posterior and computing the GP on the stochastic locations.

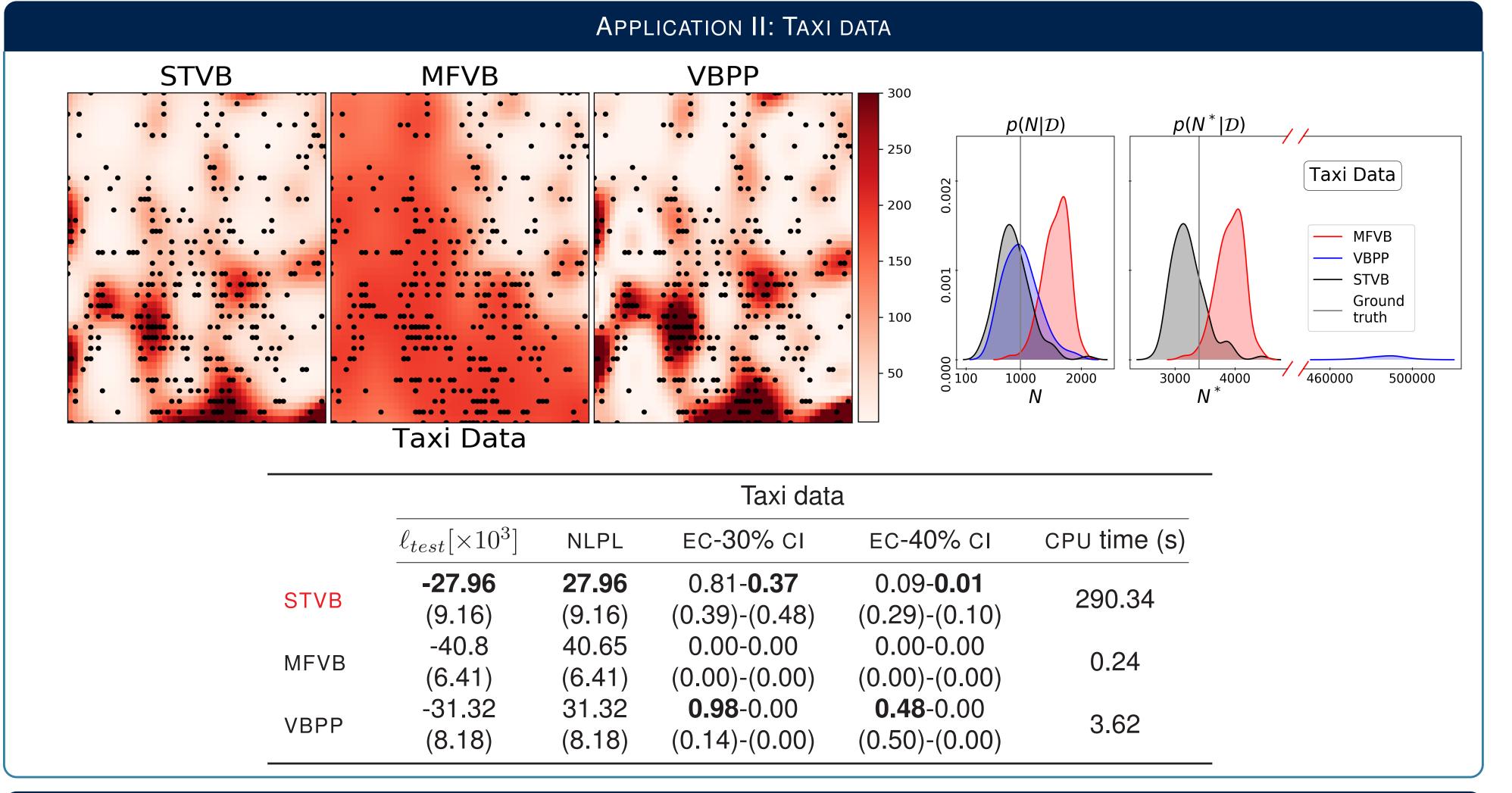
Time complexity: $\mathcal{O}(K^3)$ Space complexity: $\mathcal{O}(K^2)$

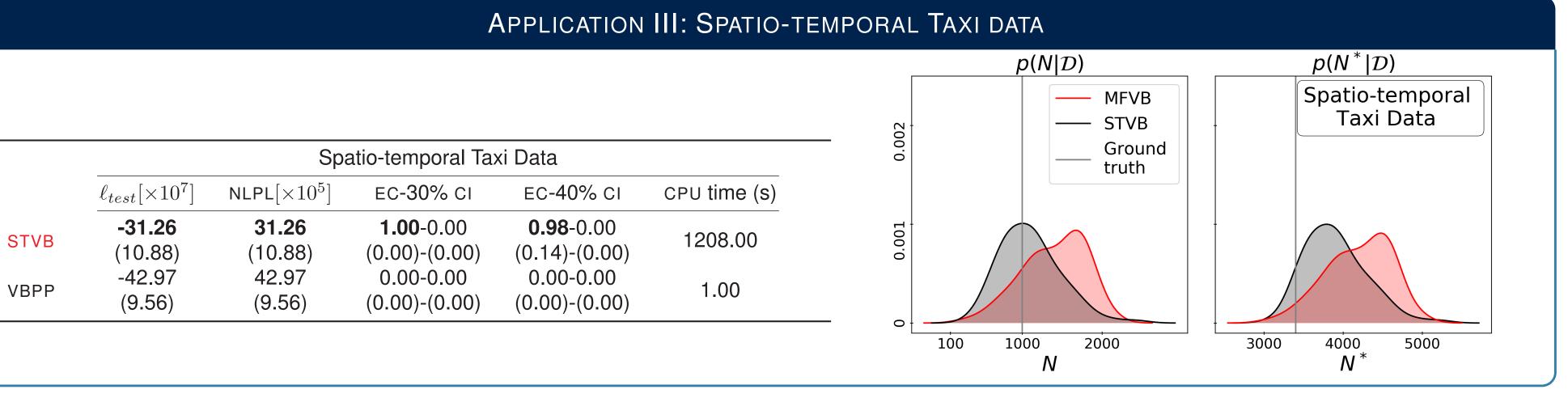
KEY REFERENCES

[1] Adams, R. P., Murray, I., and MacKay, D. J. *Tractable nonparametric bayesian inference in poisson processes with gaussian process intensities* Proceedings of the 26th Annual International Conference on Machine Learning, pages 9–16 (2009).
[2] Lloyd, C., Gunter, T., Osborne, M. A., and Roberts, S. J. *Variational Inference for Gaussian Process Modulated Poisson Processes* International Conference on Machine Learning, pages 1814-1822 (2015).
[3] Donner, C. and Opper, M. *Efficient bayesian inference of sigmoidal gaussian cox processes* The Journal of Machine









FUTURE RESEARCH

- Test the algorithm in higher dimensional settings.
- Develop a scalable fully structured variational inference scheme by relaxing the factorization assumption in the posterior.

MORE INFORMATION