## Problem Set 1

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## Hassentein-Reichardt correlator

For a grating stimulus with defined spatial frequency  $(k = 2\pi/\lambda)$  and temporal frequency  $\omega_0$ , the light intensity signal received by two neighboring channels (i.e., two photoreceptors) have the following form:

$$s_1(t) = \Delta I \sin(\omega_0 t) = \operatorname{Im} \left[ \Delta I e^{i\omega_0 t} \right];$$

$$s_2(t) = \Delta I \sin(\omega_0 t - k\Delta x) = \operatorname{Im} \left[ \Delta I e^{i(\omega_0 t - k\Delta x)} \right].$$
(1)

In the simplest model, we can think that the response of a neuron is a low-pass filter of the sensory input with some Kernel  $D_1(t)$  and  $D_2(t)$ . As a result, the response function might be written as

$$r_1(t) = \int_{-\infty}^{\infty} s_1(t - \tau) D_1(\tau) d\tau;$$

$$r_2(t) = \int_{-\infty}^{\infty} s_2(t - \tau) D_2(\tau) d\tau.$$
(2)

Similar responses could be written for  $r_3(t)$  and  $r_4(t)$ . The motion detection output signal is defined as

$$R(t) = r_1(t)r_2(t) - r_3(t)r_4(t)$$
(3)

And the steady state solution is given by averaging over the time period  $2\pi/\omega_0$ .

• Show that the general response has the following functional form\*:

$$\langle R \rangle_t = \sin[\phi_1(\omega_0) - \phi_2(\omega_0)] \sin(k\Delta x) \|\tilde{D}_1(\omega_0)\| \|\tilde{D}_2(\omega_0)\|$$
(4)

where the fourier transform of the kernels are defined as

$$\tilde{D}_1(\omega_0) = \|\tilde{D}_1(\omega_0)\| e^{i\phi_1(\omega_0)},$$

$$\tilde{D}_2(\omega_0) = \|\tilde{D}_2(\omega_0)\|e^{i\phi_2(\omega_0)}$$

• Consider a simple kernel  $D_1(t) = \frac{1}{\tau} \exp(-t/\tau)$ , and  $D_2(t) = \delta(t)$ , we find  $\tilde{D_1}(\omega_0) = \frac{1}{1+i\omega_0\tau}$ , and show that

$$\langle R \rangle = \frac{\omega_0 \tau}{\omega_0^2 \tau^2 + 1} \tag{5}$$

Furthermore, show that this function has a maximum when  $\omega_0 = 1/\tau$ .

• If the filters on both arms are first-order low-pass, so that  $D_1(t) = \frac{1}{\tau} \exp(-t/\tau_1)$ ,  $D_2(t) = \frac{1}{\tau_2} \exp(-t/\tau_2)$ , then the steady state response is given by

$$\langle R \rangle = \frac{\omega(\tau_2 - \tau_1)}{(1 + \omega^2 \tau_1^2)(1 + \omega^2 \tau_2^2)}$$
 (6)

*Hint*: The analytical form of  $r_1(t)$  and  $r_2(t)$  can be computed by taking the fourier transform of the convolution, and then performing an inverse fourier transform. As a first step:

$$\tilde{r}_1(\omega) = \sqrt{2\pi}\delta(\omega - \omega_0)\tilde{D}_1(\omega);$$

$$\tilde{r}_2(\omega) = e^{-ik\Delta x}\sqrt{2\pi}\delta(\omega - \omega_0)\tilde{D}_2(\omega)$$
(7)

Note that problem with  $\ast$  is optional.