# Stamps Solution

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### Stamps - The Problem

#### Given:

- stamps
- lamps
- walls

$$0 \le s, \ell \le 200$$

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Each stamp j has a maximum intensity M<sub>j</sub>.

## Stamps - The Problem

#### · Lamp i:

• power  $p_i$  , illuminates object at distance r with intensity  $\frac{p_i}{r^2}$  .

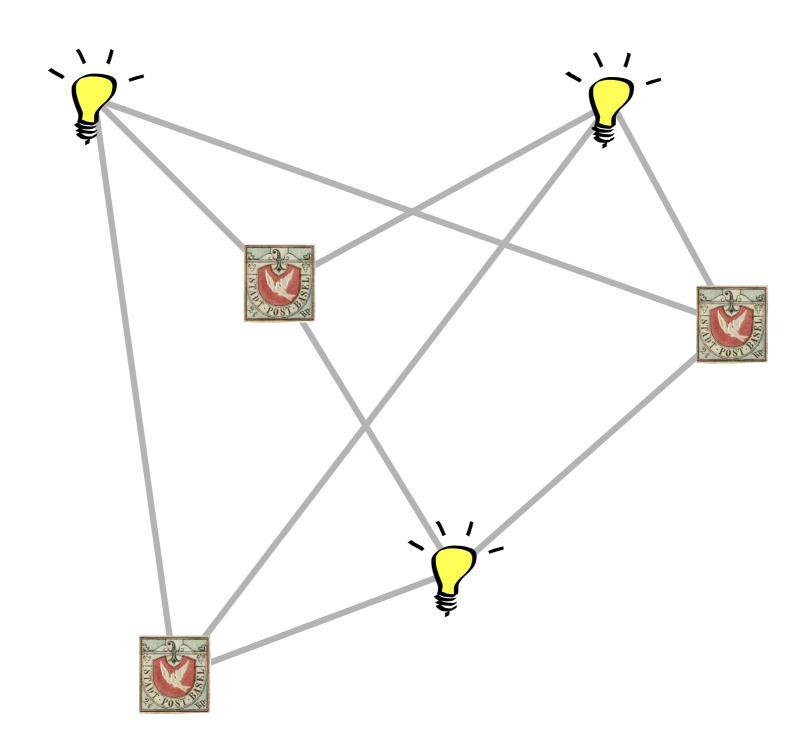
#### · Wall:

blocks light

#### Requirement:

- power  $p_i$  of every lamp:
- total light intensity  $I_j$  for every stamp j:  $1 \le I_j \le M_j$

#### 1st case: No walls!



## At this point...

- You should be able to formulate the LP/QP.
  - decide on correct number types.
  - pick the right solver.

## Number types

• Integral numbers or not?

# Number types

- Integral numbers or not?
- Already for the Input Type ...

• 
$$1 \le I_j \le M_j$$

• where 
$$I_j = \sum_{l \in \{ \text{lamps that can see stamp j} \}} \frac{p_l}{d(j,l)^2}$$

```
std::vector<K::Point_2> lamp(200), stamp(200);
std::vector<K::Segment_2> wall(2000);
int main(){
  std::cin.sync_with_stdio(false);
  int t, l, s, w;
  std::cin >> t;
while(t--){
    std::cin >> l >> s >> w;
    Program lp(CGAL::SMALLER, true, 1, true, (1<<12));</pre>
    for(int i = 0; i < l; i++) std::cin >> lamp[i];
    for(int i = 0; i < s; i++) {
      int I:
      std::cin >> stamp[i] >> I;
      lp.set_b(2*i, -1); lp.set_b(2*i + 1, I);
    for(int i = 0; i < w; i++) std::cin >> wall[i];
    for(int i = 0; i < s; i++)
      for(int j = 0; j < 1; j++){
          double dist2 = CGAL::squared_distance(stamp[i], lamp[j]);
          lp.set_a(j, 2*i, ET(-1)/dist2);
          lp.set_a(j, 2*i+1, ET(1)/dist2);
      }
```

# "Nonnegative"

- solve\_nonnegative\_linear\_program:
  - imposes the lower bound  $x \ge 0$
  - ignores any upper bounds

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  - imposes the lower bound  $x \ge 0$
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...regardless of what upper and lower bounds you might have set.

# "Nonnegative"

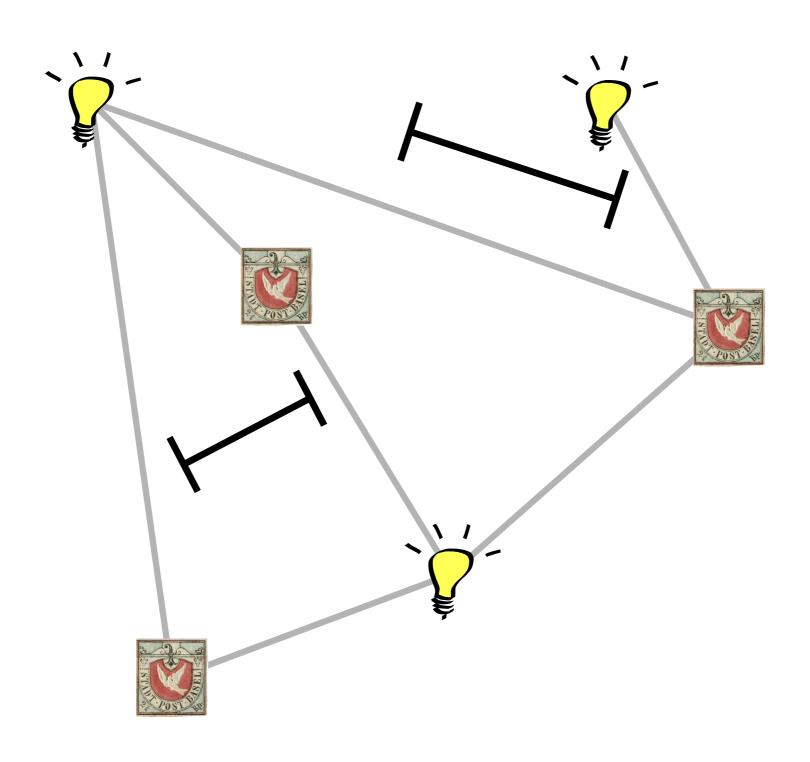
- Suggestion:
  - Always first try to solve without \_nonnegative\_
  - If you get TL and your Program satisifies the conditions mentioned in the previous slide then try also with \_nonnegative\_
  - (Most likely it will not be the case that \_nonnegative\_ will make a difference)

#### \_quadratic\_ vs \_linear\_

- If you have set up a quadratic program (e.g. Portfolios)
- and then use solve\_nonnegative\_linear\_program
- the quadratic part will be ignored...

```
Solution s = CGAL::solve_linear_program(lp, ET());
    std::cout << (s.is_infeasible() ? "no" : "yes") << std::endl;
}
return 0;
}</pre>
```

#### 2nd case: With walls!



#### How to...

- Add the walls to our program?
- Can't be that hard...

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- Add the walls to our program?
- Can't be that hard...
- In this problem, it was enough to just check for every (lamp,stamp) pair if the corresponding segment has an intersection with some wall.

```
bool no_wall_between(const K::Segment_2& seg, const int w){
  for(int i = 0; i < w; i++)
    if(CGAL::do_intersect(seg, wall[i])) return false;
  return true;
}</pre>
```

```
bool no_wall_between(const K::Segment_2& seg, const int w){
  for(int i = 0; i < w; i++)
    if(CGAL::do_intersect(seg, wall[i])) return false;
  return true;
for(int i = 0; i < s; i++)
  for(int j = 0; j < l; j++)
    if(no_wall_between(K::Segment_2(stamp[i], lamp[j]), w)){
        double dist2 = CGAL::squared_distance(stamp[i], lamp[j]);
        lp.set_a(j, 2*i, ET(-1)/dist2);
        lp.set_a(j, 2*i+1, ET(1)/dist2);
```