# Automatic Generation of Context-specific **Fake Reviews**

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#### Introduction

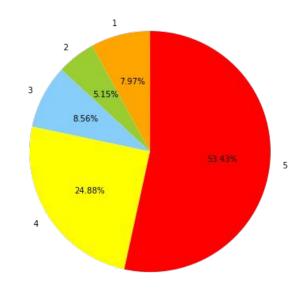
- Fake reviews are a major threat to online review systems by spreading misinformation
- Context-specific reviews are more convincing, thus more threatening
- Malicious crowdsourcing is limited by the cost of human labors
- This project:
  - Explores the possibility of using natural language generation (NLG)
     techniques for automatic generation of context-specific reviews
  - Reveals the potential threat to online review systems in the future

#### **Prior work**

- Yuanshun Yao, et al. (2017) uses a two-stage approach for generating context-specific fake reviews
- Two stages:
  - Initial Review Generation
  - Review Customization with domain-specific keywords replacement
- This project: end-to-end automatic generation

#### **Data**

- Use Yelp Open Dataset
- 5,996,996 reviews,188,593 businesses,280,992 pictures
- Most of the reviews are 4/5-star



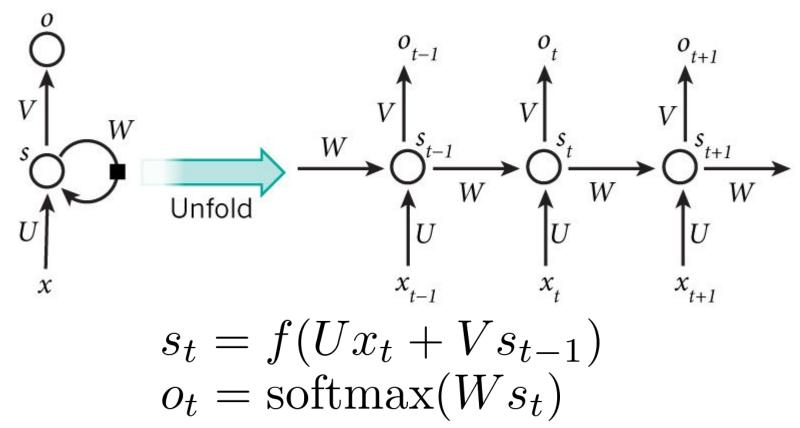
# Methodology

- Adopt the seq2seq architecture for fake review generation, which is originally developed for machine translation by Cho et al.
- The encoder captures the context information of reviews (rating star, categories of reviewed restaurant) and the decoder decodes the context information to generate fake reviews.

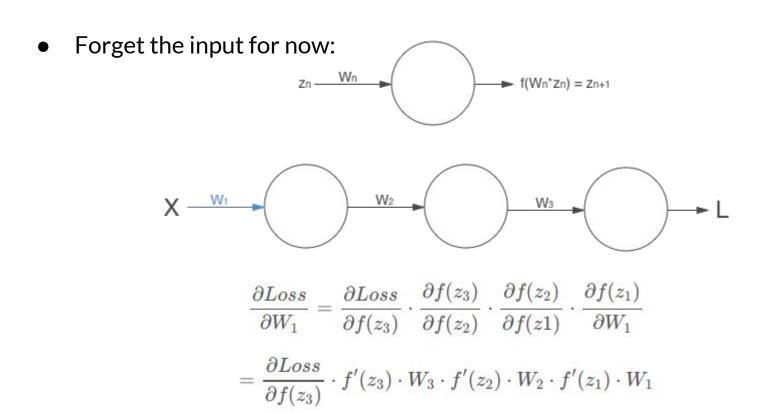
#### Recurrent Neural Networks (RNNs)

- Traditional neural network (like a multi-layer perceptron network): all inputs are assumed to be independent from each other, same for outputs
- Many data are in nature sequential
- How to make use of sequential data?
- Idea: unfold neural network along time, each output is conditioned on previous computations

## Recurrent Neural Networks (RNNs)



#### **Problem with Vanilla RNN**



#### **Problem with Vanilla RNN**

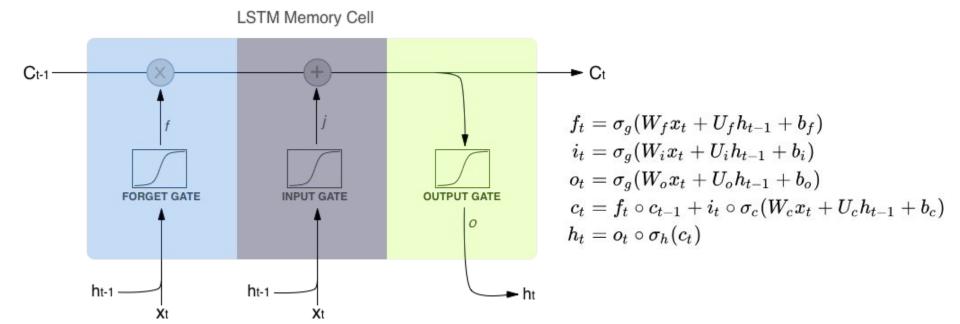
- Matrix W is kept constant along time
- Gradient Explosion/Vanishment can occur!

$$\frac{\partial Loss}{\partial W_1} = \frac{\partial Loss}{\partial f(z_3)} \cdot \frac{\partial f(z_3)}{\partial f(z_2)} \cdot \frac{\partial f(z_2)}{\partial f(z_1)} \cdot \frac{\partial f(z_1)}{\partial W_1}$$

$$= \frac{\partial Loss}{\partial f(z_3)} \cdot f'(z_3) \cdot W_3 \cdot f'(z_2) \cdot W_2 \cdot f'(z_1) \cdot W_1$$

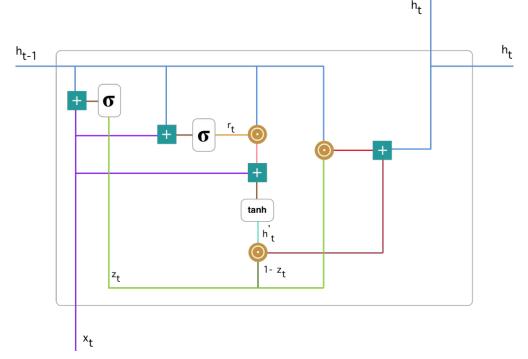
# LSTM (Long Short-Term Memory, 1997)

LSTM: add a cell state with three gates to selectively choose information which is remembered and passed to the next time step



## **GRU (Gated Recurrent Unit, 2014)**

GRU: redundant to keep both the cell state and hidden state in LSTM, why not merge them together? Only has two gates now: update gate and reset gate.

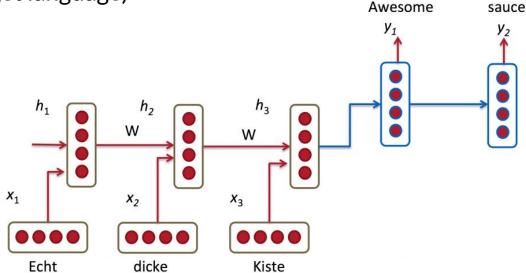


# Seq2Seq Model

Originally developed for machine translation in 2014

Creates a mapping from the context space (source language) to the output

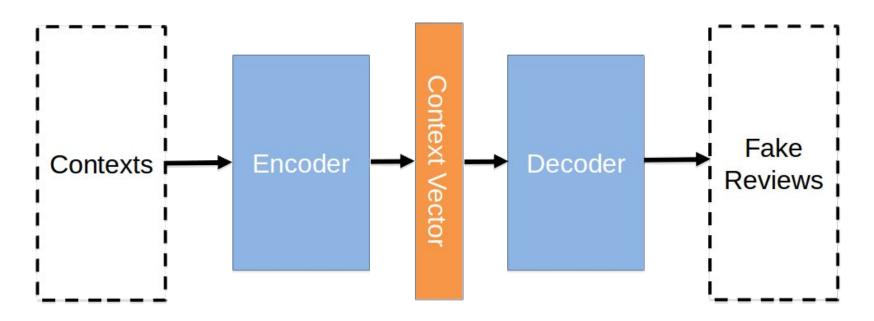
space (target language)



# Seq2Seq for Context-specific Review Generation

- Seq2Seq can be used to generate sentences that are conditioned on the given context information
- Here, the contexts are designed to be
  - Desired rating star
  - Categories of the restaurant (bar? Chinese style? Seafood? e.t.c.)
- Goal: generate reviews that are relevant to the given context

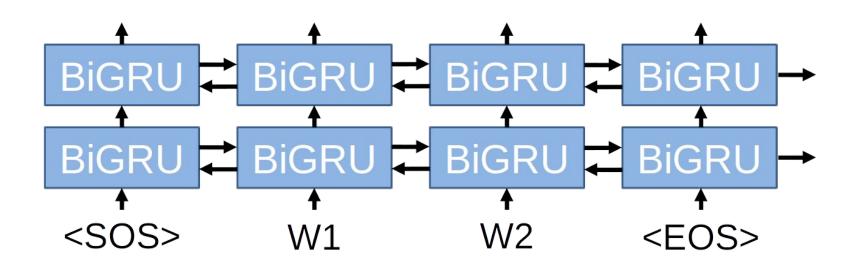
#### Model



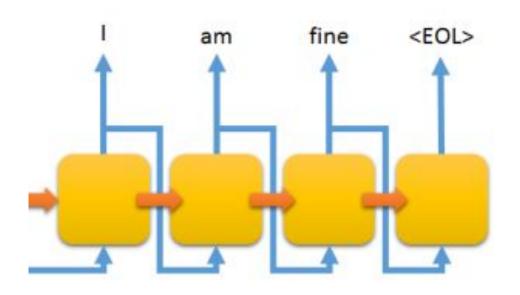
> 5.0 restaurants vietnamese

> its pretty good pho in a nice quiet location, charming.

#### **Encoder — Stacked Bidirectional GRU**



#### **Decoder — Stacked Unidirectional GRU**



# **Data Preprocessing**

- Remove all redundant reviews
- Remove all non-ASCII characters
- Lowercase all letters
- Filter businesses that are non-restaurant or have more than 20 words of categories information
- Filter reviews with more than 30 words
- Filter reviews with characters @#%\*[]+=<>~`^\$&/
- Select 5000 reviews of each rating star, 25000 in all, as training data

# **Training Details**

- Teacher forcing with a probability of 0.5
- Vocabulary size: 15000
- Hidden size: 500
- Dropout probability 0.1 between stacked GRU layers
- Batch size: 64
- Adam optimizer with Ir 0.0001 for both encoder and decoder
- Criterion: NLL loss function
- Trained for 170 epochs, approx 6 hrs on one single Nvidia
   P40 GPU with PyTorch

# **Temperature Control**

- Controls the "novelty" of generated text
- Temperatures lower than 1 amplifies the difference in the sampling probability for each word
- T = 0.5 is used by default

$$\sigma(z)_j = \frac{\exp(z_j/T)}{\sum_{k=1}^K \exp(z_k/T)}, j = 1...K$$

- > 5.0 mexican tacos tapas/small plates restaurants
- =love everything about urban taco! margaritas are well above average with lots of flavors.large wine list.food was unbelievably good! very impressed overall!
- < everything was delicious, happy hour menu rocked! i recommend the short rib taco and cream corn with grilled onions and peppers <EOS>
- < so so so delicious! the will and def be the . and and the the and . the <EOS>
- < so so so good!i will be back..flight the the . the! and! corn the my to very <EOS>
- < so so good! i will rocked be back. the well, happy the
  happy hour prices are. the and and i.again. <EOS>

- > 3.0 korean japanese restaurants
- = everything here is pretty inconsistent. service is terrible when it's crowded. the food is pretty good though, refills on sides cost extra.
- < decent food . portions large small portions . price not good . menu is small bit for . not much < EOS>
- < the food restaurant, the . the not . is . < EOS>
- < ordered pork variety . quality got here in a row like the place and its decent if there are too many other casual dining restaurants . <EOS>
- < decent food , but nothing special the in a bit restaurant .
  service is presentation , crowded and cute little slow . service
  was a bit slow . <EOS>

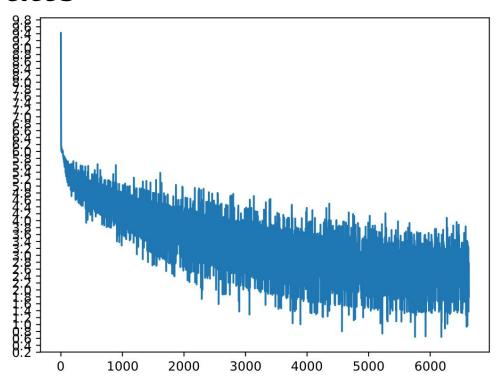
Tested on 2500 hold-out test pairs:

ROUGE1: 0.2396080807469998

ROUGE2: 0.1338730975358988

BLEU: 0.09106170926161619

BLEU\_CLIP: 0.05604014057908484



# Demo

Code is public on: https://github.com/X-czh/fake-review-generation

## **Observations**

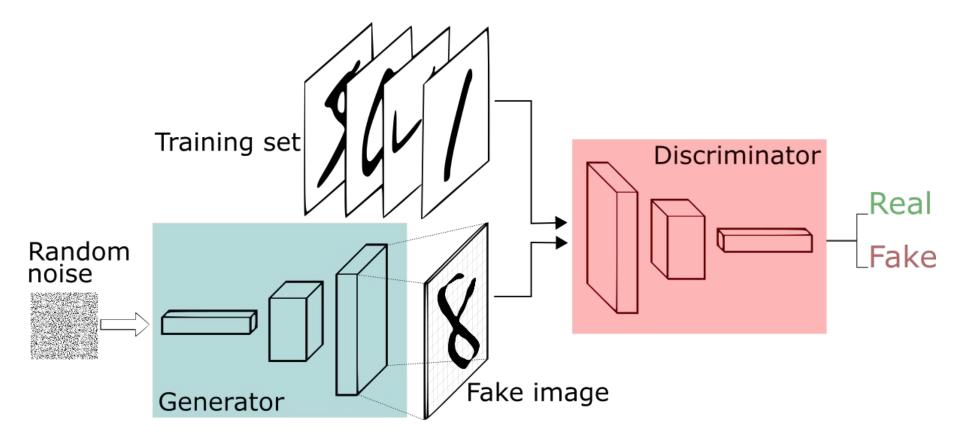
- Data preprocessing is more important than the model itself
- The context information here is "pseudo" sequential, but the model is for "real" sequential data
- Evaluation metric is a big issue
- Discriminating models are much stronger than generating models in this field
- Essential to save every experiment log properly

# SeqGAN GAN for Discrete Data

#### **Generative Models**

- Goal: build a model that generates real-looking samples which are indistinguishable from the real data
- How do we measure the distance between the real data distribution and the generated data distribution?
- What if we build a discriminator to judge whether a data instance is true or fake?
  - Leverage the strong power of deep learning based discriminative models

#### Generative Adversarial Networks (GANs)



#### **Generative Adversarial Networks (GANs)**

- Discriminator tries to distinguish the true data and the fake model-generated data
- Generator tries to fool the discriminator
- Two models are trained simultaneously to find a Nash equilibrium to a two-player non-cooperative game:

$$\min_{G} \max_{D} V(D, G) = \mathbb{E}_{x \sim \mathbb{P}_r} [\log D(x)] + \mathbb{E}_{x \sim \mathbb{P}_G} [1 - \log D(x)]$$
$$= \int_{r} P_r(x) [\log D(x)] + G(x) [1 - \log D(x)]$$

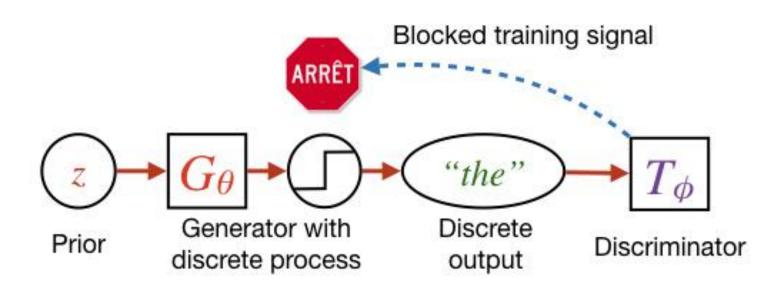
#### Generative Adversarial Networks (GANs)

• In practice, we represent a limited family of  $P_G$  distributions via the function  $G(z; \theta)$ , z is sampled from a prior distribution

$$\begin{split} & \min_{G} \max_{D} V(D,G) \\ &= \mathbb{E}_{x \sim p_{\text{data}}(x)} [\log D(x)] + \mathbb{E}_{z \sim p_{z}(z)} [\log (1 - D(G(z)))] \\ &= \int_{x} p_{\text{data}}(x) \cdot \log(D(x)) dx + \int_{z} p_{z}(z) \cdot \log (1 - D(G(z))) dx \end{split}$$
 Directly entimize the

Directly optimize the differentiable mapping!

#### **Problem with Discrete Data**



#### **Problem with Discrete Data**

- Directly optimize the p.d.f. G(x) with the guidance from discriminator instead of optimizing a non-differentiable transformation
- We could directly build a differentiable parametric distribution for discrete data using softmax function

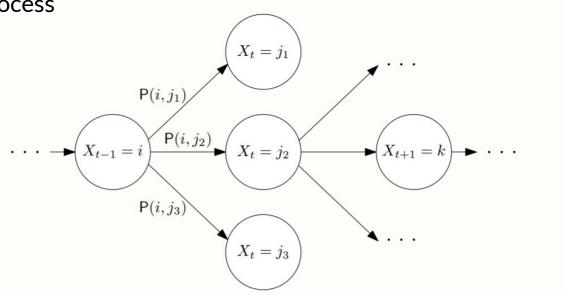
$$\min_{G} \max_{D} V(D, G) = \mathbb{E}_{x \sim \mathbb{P}_r} [\log D(x)] + \mathbb{E}_{x \sim \mathbb{P}_G} [1 - \log D(x)]$$
$$= \int_{x} P_r(x) [\log D(x)] + G(x) [1 - \log D(x)]$$

# **Problem with Sequential Discrete Data**

Discriminator can only work on the whole sequence!

Solution: model the generation of sequential discrete data as a sequential

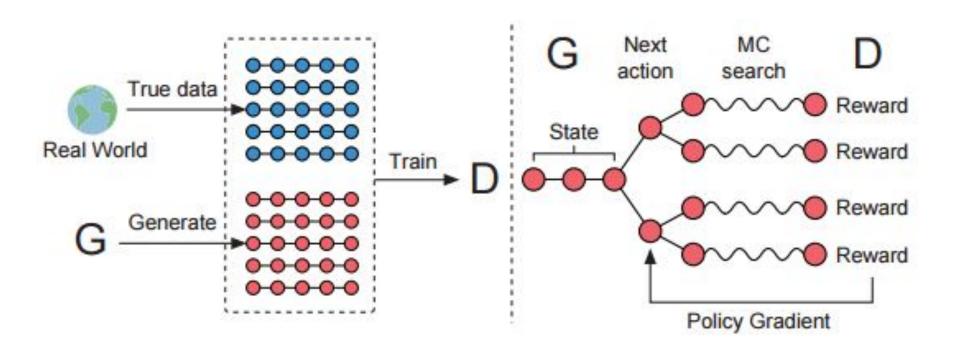
decision process



# **Problem with Sequential Discrete Data**

- Introduce Reinforcement Learning ideas
- Generator is a reinforcement learning policy of generating a sequence
  - decide the next word to generate given the previous ones
- Discriminator provides the reward (i.e. the probability of being true data) for the whole sequence

## Sequence GAN (Yu, Lantao, et al. 2017)



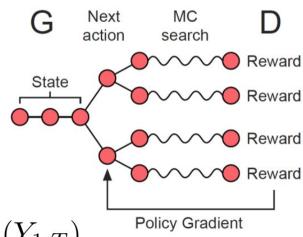
#### For generator:

Objective: to maximize the expected reward

$$J(\theta) = \mathbb{E}[R_T|s_0, \theta] = \sum_{y_1 \in \mathcal{Y}} G_{\theta}(y_1|s_0) \cdot Q_{D_{\phi}}^{G_{\theta}}(s_0, y_1)$$

- State-action value function  $Q_{D_\phi}^{G_\theta}(s,a)$  is the expected accumulative reward that
  - Start from state s
  - Taking action a
  - And following policy G until the end
- Reward is only on completed sequence (no immediate reward)

$$Q_{D_{\phi}}^{G_{\theta}}(s=Y_{1:T-1},a=y_T)=D_{\phi}(Y_{1:T})$$



- Reward is only on completed sequence
  - No immediate reward
  - Then the last-step state-action value

$$Q_{D_{\phi}}^{G_{\theta}}(s=Y_{1:T-1},a=y_T)=D_{\phi}(Y_{1:T})$$

- For intermediate state-action value
  - Use Monte Carlo search to estimate

$$\{Y_{1:T}^1, \dots, Y_{1:T}^N\} = MC^{G_\beta}(Y_{1:t}; N)$$

Following a roll-out policy G

$$Q_{D_{\phi}}^{G_{\theta}}(s = Y_{1:t-1}, a = y_t) =$$

$$\begin{cases} \frac{1}{N} \sum_{n=1}^{N} D_{\phi}(Y_{1:T}^{n}), Y_{1:T}^{n} \in MC^{G_{\beta}}(Y_{1:t}; N) & \text{for } t < T \\ D_{\phi}(Y_{1:t}) & \text{for } t = T. \end{cases}$$

action

**Policy Gradient** 

State

# **Training Sequence Generator**

Using Policy Gradient (REINFORCE):

[Richard Sutton et al. Policy Gradient Methods for Reinforcement Learning with Function Approximation. NIPS 1999.]

$$\nabla_{\theta} J(\theta) = \sum_{t=1}^{T} \mathbb{E}_{y_{t} \sim G_{\theta}(y_{t}|Y_{1:t-1})} [\nabla_{\theta} \log G_{\theta}(y_{t}|Y_{1:t-1}) \cdot Q_{D_{\phi}}^{G_{\theta}}(Y_{1:t-1}, y_{t})]$$

$$\theta \leftarrow \theta + \alpha_h \nabla_{\theta} J(\theta)$$

# **Training Sequence Discriminator**

Objective: standard bi-classification

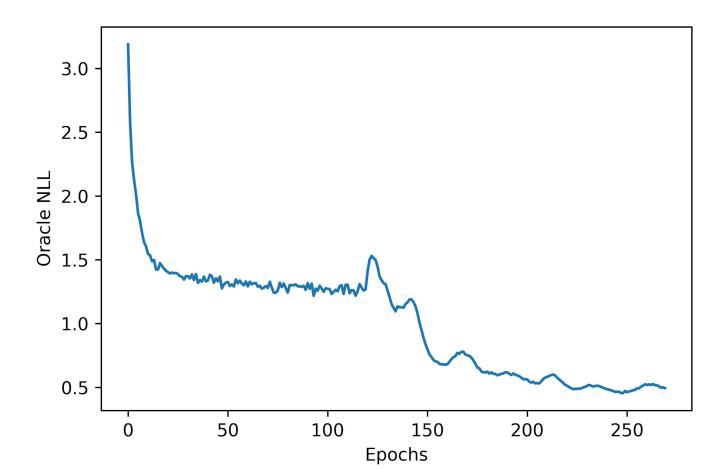
$$\min_{\phi} - \mathbb{E}_{Y \sim p_{\text{data}}}[\log D_{\phi}(Y)] - \mathbb{E}_{Y \sim G_{\theta}}[\log(1 - D_{\phi}(Y))]$$

#### **Algorithm 1** Sequence Generative Adversarial Nets **Require:** generator policy $G_{\theta}$ ; roll-out policy $G_{\beta}$ ; discriminator

 $D_{\phi}$ ; a sequence dataset  $\mathcal{S} = \{X_{1:T}\}$ 1: Initialize  $G_{\theta}$ ,  $D_{\phi}$  with random weights  $\theta$ ,  $\phi$ .

- 2: Pre-train  $G_{\theta}$  using MLE on S
- 3:  $\beta \leftarrow \theta$
- 4: Generate negative samples using  $G_{\theta}$  for training  $D_{\phi}$ 
  - 5: Pre-train  $D_{\phi}$  via minimizing the cross entropy
  - 6: repeat
    - for g-steps do
  - 8:
    - Generate a sequence  $Y_{1:T} = (y_1, \dots, y_T) \sim G_{\theta}$
  - 9: for t in 1:T do Compute  $Q(a = y_t; s = Y_{1:t-1})$  by Eq. (4)
- 10:
- 11: end for Update generator parameters via policy gradient Eq. (8)

- 13: end for 14: for d-steps do
- 15: Use current  $G_{\theta}$  to generate negative examples and com
  - bine with given positive examples S
  - - Train discriminator  $D_{\phi}$  for k epochs by Eq. (5)
- 16: 17:
  - end for
- 18:  $\beta \leftarrow \theta$
- 19: **until** SeqGAN converges



#### Limitations

- Not capable of generating long sequences
  - I also failed to use it to generate relatively short reviews though (may be due to the high diversity of the corpus)
- Hierarchical Reinforcement Learning can be applied (Leaky GAN, 2017)

# Thank you!