# Instructions for using the 270-degree servo --- Raspberry Pi

## 1. Raspberry Pi pin diagram

| wiringPi 编码 | BCM 编码 | 功能名 | 物理引脚 BOARD编码 | | 功能名 | BCM 编码 | wiringPi 编码 |
|---|---|---|---|---|---|---|---|
| | | 3.3V | 1 | 2 | 5V | | |
| 8 | 2 | SDA.1 | 3 | 4 | 5V | | |
| 9 | 3 | SCL.1 | 5 | 6 | GND | | |
| 7 | 4 | GPIO.7 | 7 | 8 | TXD | 14 | 15 |
| | | GND | 9 | 10 | RXD | 15 | 16 |
| 0 | 17 | GPIO.0 | 11 | 12 | GPIO.1 | 18 | 1 |
| 2 | 27 | GPIO.2 | 13 | 14 | GND | | |
| 3 | 22 | GPIO.3 | 15 | 16 | GPIO.4 | 23 | 4 |
| | | 3.3V | 17 | 18 | GPIO.5 | 24 | 5 |
| 12 | 10 | MOSI | 19 | 20 | GND | | |
| 13 | 9 | MISO | 21 | 22 | GPIO.6 | 25 | 6 |
| 14 | 11 | SCLK | 23 | 24 | CE0 | 8 | 10 |
| | | GND | 25 | 26 | CE1 | 7 | 11 |
| 30 | 0 | SDA.0 | 27 | 28 | SCL.0 | 1 | 31 |
| 21 | 5 | GPIO.21 | 29 | 30 | GND | | |
| 22 | 6 | GPIO.22 | 31 | 32 | GPIO.26 | 12 | 26 |
| 23 | 13 | GPIO.23 | 33 | 34 | GND | | |
| 24 | 19 | GPIO.24 | 35 | 36 | GPIO.27 | 16 | 27 |
| 25 | 26 | GPIO.25 | 37 | 38 | GPIO.28 | 20 | 28 |
| | | GND | 39 | 40 | GPIO.29 | 21 | 29 |



## 2. Hardware wiring

1.Connect the red wire (positive pole) of the servo to the positive pole of the 7.4V battery
2.Connect the brown wire (negative pole) of the servo to the negative pole of the 7.4V battery
3.The yellow wire (signal wire) of the servo is connected to the physical pin of the Raspberry Pi motherboard (pin 33), BCM code (13)
4.The Raspberry Pi motherboard is powered, and any GND interface on the board is connected to the negative pole of the battery.

## 3.Upload and run the program

Upload the servo_270.py file in the folder to the root directory of the Raspberry Pi and enter the following command to run

```
python servo_270.py
```

## 4.Phenomenon

After running the program, the servo will rotate from 0-45-90-135-180-225-270 degrees.