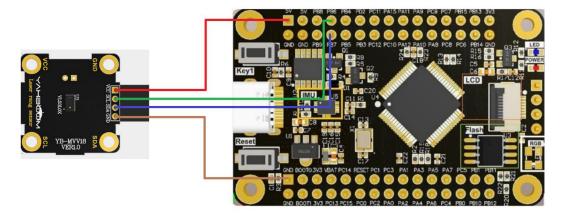
Laser ranging

1. Learning objectives

In this course, we mainly learn to use STM32F103RCT6 and laser ranging module for ranging.

2. Prepare before class

The gesture recognition module adopts I2C communication, and connects the SDA and SCL of the module to the PB7 and PB6 pins of the STM32F103RCT6 board.



3. Program

Initialize the module

```
VL53L0X_Dev_t *pMyDevice = &v15310x_dev;
pMyDevice->I2cDevAddr
                             = 0x52:
pMyDevice->comms_type
pMyDevice->comms speed khz = 400;
VL53L0X i2c init();
Status = VL53L0X_DataInit(pMyDevice); // Data initialization
if (Status != VL53LOX ERROR NONE) {
    print_pal_error(Status);
    return Status;
Status = VL53L0X GetDeviceInfo(pMyDevice, &v15310x dev info);
if (Status != VL53LOX ERROR NONE) (
   print pal error (Status);
    return Status;
printf("VL53L0X GetDeviceInfo:\n");
printf("Device Name : %s\n", v15310x_dev_info.Name);
printf("Device Type : %s\n", v15310x dev info.Type);
printf("Device ID : %s\n", v15310x_dev_info.ProductId);
printf("ProductRevisionMajor : %d\n", v15310x_dev_info.ProductRevisionMajor);
printf("ProductRevisionMinor : %d\n", v15310x_dev_info.ProductRevisionMinor);
if ((v15310x dev info.ProductRevisionMajor != 1) && (v15310x dev info.ProductRevisionMinor != 1)) {
    printf("Error expected cut 1.1 but found cut %d.%d\n",
    v15310x_dev_info.ProductRevisionMajor, v15310x_dev_info.ProductRevisionMinor);
    Status = VL53L0X ERROR NOT SUPPORTED;
    print_pal_error(Status);
    return Status;
Status = v15310x measure init(pMyDevice);
v15310x_status = Status;
if (Status != VL53LOX ERROR NONE) (
   print_pal_error(Status);
    return Status;
```

Microcontroller initialization

```
/* 端口初始化 */
GPIO_Config();
//LED1:紅灯控制; LED2:绿灯控制; LED3:蓝灯控制

/* 配置SysTick 为lus中断一次 */
SysTick Init();
/*初始化USART 配置模式为 115200 8-N-1, 中断接收*/
USART_Config();
v15310x_init();
启动测试。
while(1)
{
    if(v15310x_status == VL53L0X_ERROR_NONE)
    {
        v15310x_start_single_test(&v15310x_dev, &v15310x_data);
    }
}
```

4. Experimental phenomenon

After the program is downloaded, the module is successfully initialized and the module name, ID and other information are printed, please check your own wiring when it fails. The detected distance is then printed in millimeters. The measuring range is 300mm-2000mm.