# Independent watchdog

#### **Independent watchdog**

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Demonstration in this tutorial: Combining the serial port (UASRT1) and button functions to demonstrate the **Independent Watchdog (IWDG)** timeout reset function.

### 1. Software-Hardware

- STM32F103CubeIDE
- STM32 Robot Development Board

USART, IWDG: chip internal peripherals

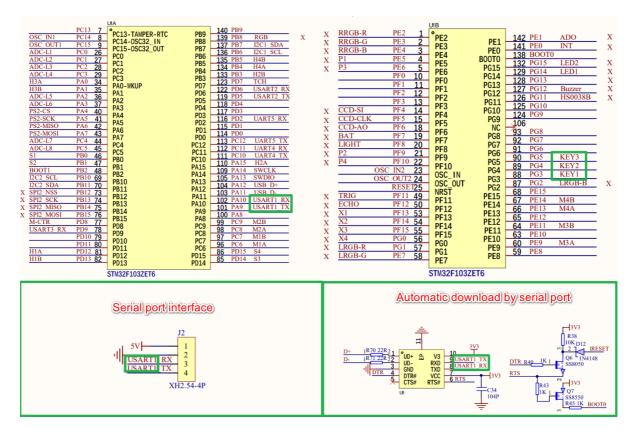
Button: onboard

• Type-C data cable or ST-Link

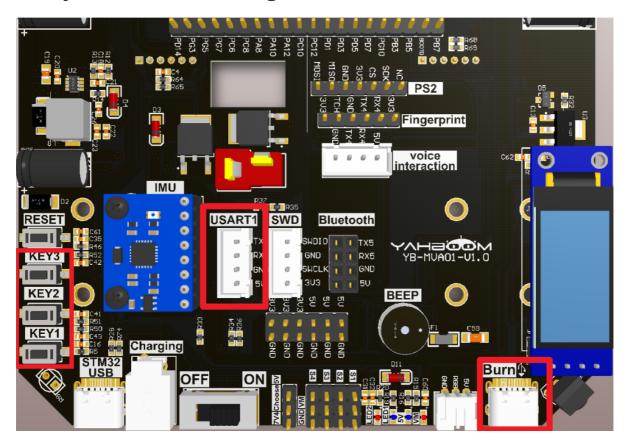
Download programs or simulate the development board

## 2. Brief principle

### 1. Hardware schematic diagram



## 2. Physical connection diagram



## 3. Control principle

By using the button to reset the count value of the independent watchdog (IWDG), the dog feeding function is realized.

#### Watchdog

STM32F103ZET6 has two built-in watchdogs (independent watchdog and window watchdog), which are mainly used for system fault detection and recovery.

Watchdog	Function
Independent Watchdog	Used to detect whether the system is running normally
Window Watchdog	Used to detect system failures

#### Independent watchdog

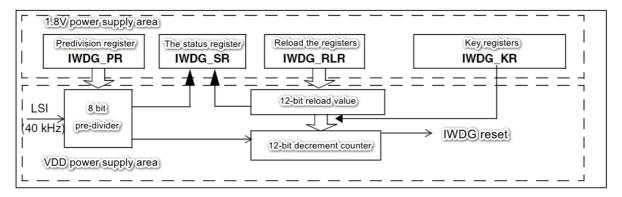
The independent watchdog (IWDG) is driven by a dedicated low-speed clock (LSI) and remains effective even if the main clock fails;

When the system does not feed the dog (reset the count value) within a certain period of time, the independent watchdog will trigger a reset operation to restart the system.

The main function of the independent watchdog is to prevent the system from entering an infinite loop or infinite delay and other fault states during operation, and to prevent the system from being unresponsive or crashing for a long time.

#### Independent watchdog feature

- Free running down counter
- After the watchdog is activated, a reset is generated when the counter counts to 0x000
- Clock is provided by independent RC oscillator (can operate in stop and standby modes)



Watchdog Timeout: 40kHz input clock (LSI)

Prescaler coefficient	PR[2:0]	Minimum time (ms): RL[11:0]=0x000	Maximum time (ms): RL[11:0]=0xFFF
/4	0	0.1	409.6
/8	1	0.2	819.2
/16	2	0.4	1638.4
/34	3	0.8	3276.8
/64	4	1.6	6553.6
/128	5	3.2	13107.2
/256	6 or 7	6.4	26214.4

The prescaler coefficient set in the tutorial is 64, and the reload value is 64

$$T_{\mathit{Timeout}(s)} = rac{4*2^{\mathit{PR}}*\mathit{Reload}}{\mathit{LSI}} = rac{64*625}{40000} = 1s$$

## 3. Project configuration

Project configuration: Prompt configuration options during STM32CubeIDE project configuration

### 1. Description

Omitted project configuration part: **New project, chip selection, project configuration, SYS of pin configuration, RCC configuration, clock configuration and project configuration** content

The project configuration part that is not omitted is the key point that needs to be configured in this tutorial.

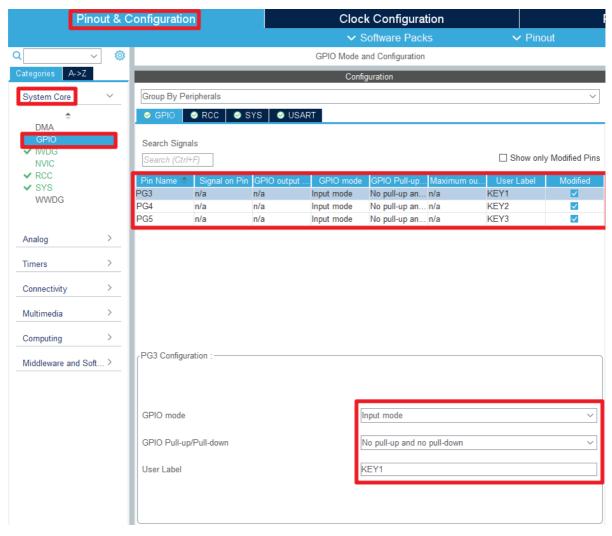
Please refer to [2. Development environment construction and use: STM32CubeIDE installation and use] to understand how to configure the omitted parts of the project.

### 2. Pin configuration

#### • Configure specified pin function

You can directly select the corresponding pin number in the pin view, and the corresponding options will appear when you left-click the mouse.

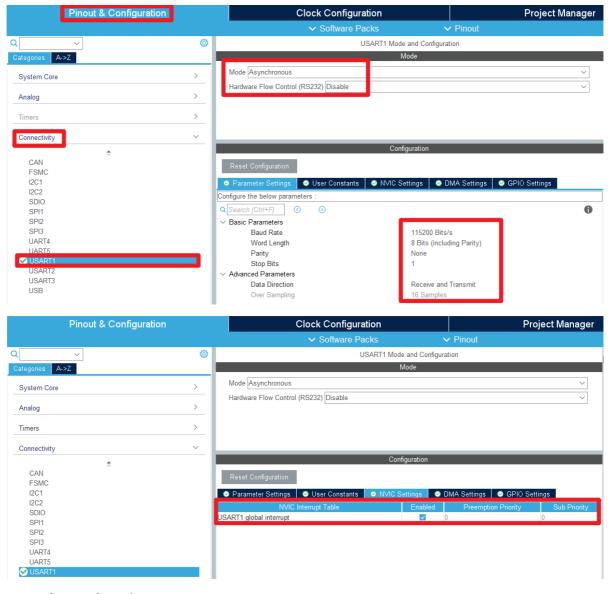
• GPIO



• IWDG



USART



Advanced Settings



• Generate code



### 4. Main functions

It mainly introduces the functional code written by the user. For detailed code, you can open the project file provided by us yourself and enter the Bsp folder to view the source code.

### 1. User function

Function: KeyX\_is\_Press

Function prototype	uint8_t Key1_is_Press(void)
Function description	Detect whether the button is pressed
Input parameters	None
Output parameters	Key status: KEY_PRESS (1), KEY_RELEASE (0)

Key2\_is\_Press and Key3\_is\_Press functions have the same function

Function: KeyX\_Long\_Press

Function prototype	uint8_t Key1_Long_Press(uint16_t timeout)
Function description	Detect button long press status
Input parameters	Long press time
Output parameters	Key status: KEY_PRESS (1), KEY_RELEASE (0)

Key3\_Long\_Press and Key2\_Long\_Press functions have the same function

Function: Key1\_State

Function prototype	uint8_t Key1_State(uint8_t mode)
Function description	Read key status
Input parameters	Mode: 0 means always returning 1, 1 means always returning 0
Output parameters	Key status: KEY_PRESS (1), KEY_RELEASE (0)

Key2\_State and Key3\_State functions have the same function

### 2. HAL library function analysis

The HAL library functions that have been introduced in the previous tutorial will not be introduced again in the tutorial!

If you want to find the HAL library and LL library function analysis involved in the entire tutorial, you can view the documents in the folder [8. STM32 Manual: STM32F1\_HAL Library and LL Library\_User Manual]

Function: HAL\_IWDG\_Init

Function prototype	HAL_StatusTypeDef HAL_IWDG_Init(IWDG_HandleTypeDef *hiwdg)
Function description	Initialize IWDG peripheral parameters
Input parameters	hiwdg: IWDG handle address
Return value	HAL status value: HAL_OK, HAL_ERROR, HAL_BUSY, HAL_TIMEOUT

Function: HAL\_IWDG\_Refresh

Function prototype	HAL_StatusTypeDef HAL_IWDG_Refresh(IWDG_HandleTypeDef *hiwdg)
Function description	Refresh IWDG (feed the dog)
Input parameters	hiwdg: IWDG handle address
Return value	HAL status value: HAL_OK, HAL_ERROR, HAL_BUSY, HAL_TIMEOUT

## 5. Experimental phenomena

After successfully downloading the program, press the RESET button on the development board to open the serial port debugging assistant to observe the phenomenon!

For program download, please refer to [2. Development environment construction and use: program download and simulation]

#### Phenomenon:

When the program is run for the first time, "\*\*\*\* IWDG Test Start \*\*\*\*\*\* will be printed;

If you do not press the KEY1 key, the serial port debugging assistant will print the message "IWDG no no no reload!!!";

If the KEY1 key is pressed, the serial port debugging assistant will print the message "Refreshes the IWDG!!!".

