

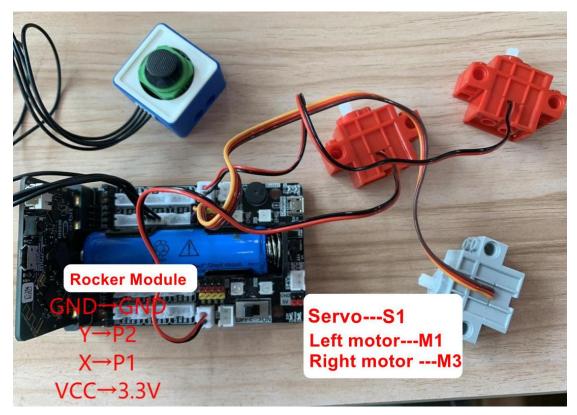
### Rocker carrier car

# 1. Learning target

In this course, we will learn how to use Micro:bit, super:bit expansion board and rocker module to achieve rocker carrier car.

# 2. Preparation

Connect the module to Micro:bit board by expansion board, as shown below.



## 3. Programming method

**Mode 1 online programming:** First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: <a href="http://microbit.org/">http://microbit.org/</a> to enter the programming interface. Add the Yahboom package <a href="https://github.com/YahboomTechnology/SuperBitLibV2">https://github.com/YahboomTechnology/SuperBitLibV2</a> to program.

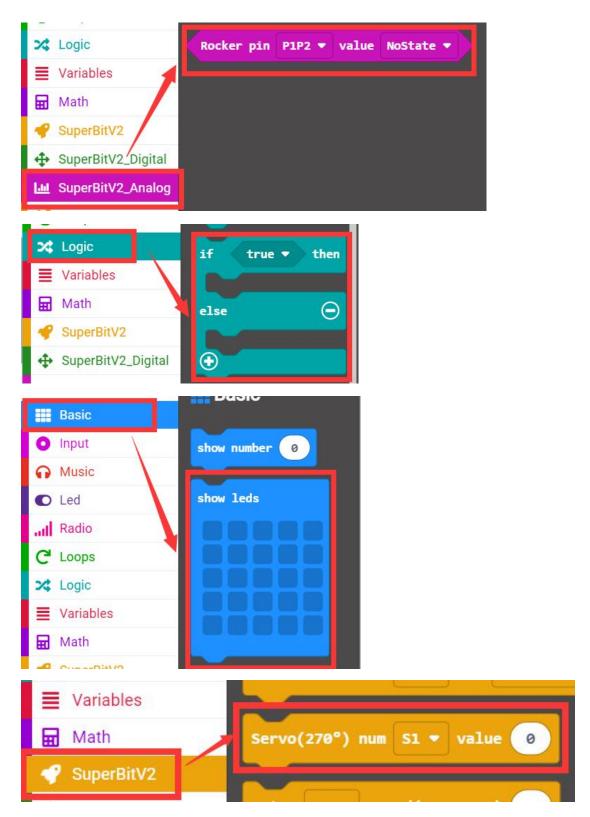
**Mode 2 offline programming:** We need to open the offline programming software. After the installation is complete, enter the programming interface, click 【New Project】, add Yahboom package:

https://github.com/YahboomTechnology/SuperBitLibV2 , you can start programming.

# 4.Looking for blocks

The following is the location of the building blocks required for this programming.





# 5.Combine block

The summary program is shown below.



```
forever
      Rocker pin P1P2 ▼ value Up ▼
                                                         on start
  Servo(270°) num S1 ▼ value 180
 pause (ms) 500 ▼
                                                           show icon
else if Rocker pin P1P2 ▼ value Down ▼
                                                           Servo(270°) num | S1 ♥ value | 120
  Servo(270°) num S1 ▼ value 60
 pause (ms) 500 ▼
else if Rocker pin P1P2 ▼ value Left ▼
  Servo(270°) num | S1 ▼ | value | 120
 pause (ms) 500 ▼
else if Rocker pin P1P2 ▼ value Right ▼
                                            then 🕣
  Servo(270°) num | S1 ▼ | value | 120
 pause (ms) 500 ▼
①
```

### 5. Phenomenon

After the program is downloaded successfully. Micro: bit dot matrix will display a smiling face. Turn on the power switch, and the rudder will initialize. At this time, the forklift is in a flat state.

If the rocker is upward, the shovel will be lifted; if the rocker is downward, the shovel will unload goods; if the rocker is left or right, the shovel will reset.