

# 47\_ YASHI SARANG\_ DIAD PHYSICS ASSIGNMENT

Q1. Show that divergence of curl of vector is zero.

To show  $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) = 0$ .

$$\left( \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

$$= \left( \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot \left( \hat{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_y & v_z \end{vmatrix} - \hat{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ v_x & v_z \end{vmatrix} + \hat{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ v_x & v_y \end{vmatrix} \right)$$

$$= \frac{\partial}{\partial x} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_y & v_z \end{vmatrix} - \frac{\partial}{\partial y} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ v_x & v_z \end{vmatrix} + \frac{\partial}{\partial z} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ v_x & v_y \end{vmatrix}$$

$$= \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} = 0.$$

$\therefore$  The value of the determinant is zero because two rows are identical.

Q2. Derive all Maxwell's equations in free space in differential forms.

→ (a) First equation.

$$\oint_a \vec{E} \cdot d\vec{s} = \oint_a \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \oint_v (\rho + \rho_p) dV$$

where  $q = \rho V$  and  $\rho_p = \vec{\nabla} \cdot \vec{p}$

$$\oint_a \vec{E} \cdot \epsilon_0 d\vec{s} = \oint_v \vec{\nabla} \cdot (\epsilon_0 \vec{E}) dV = \oint_v (\rho - \vec{\nabla} \cdot \vec{p}) dV$$

$$\therefore \oint_v \vec{\nabla} \cdot (\epsilon_0 \vec{E} + \vec{p}) dV = \oint_v \rho dV$$

As  $\vec{D} = \epsilon_0 \vec{E} + \vec{p} \quad \therefore \oint_v \vec{\nabla} \cdot \vec{D} dV = \oint_v \rho dV$

$$\therefore \vec{\nabla} \cdot \vec{D} - \rho = 0.$$

$$\vec{\nabla} \cdot \vec{D} = \rho$$

This is the Point form of Maxwell's first equation.

(b) Second equation

$$\oint \vec{B} \cdot d\vec{s} = 0, \quad \oint \vec{B} \cdot d\vec{s} = \oint_v \vec{\nabla} \cdot \vec{B} dV = 0.$$

$$\therefore \vec{\nabla} \cdot \vec{B} = 0.$$

This is the point form of Maxwell's second equation.

c) Third equation.

$$e = -\frac{d\phi}{dt} \quad \phi = \oint_s \bar{B} \cdot d\bar{s}$$

$$e = -\frac{d}{dt} \left( \oint_s \bar{B} \cdot d\bar{s} \right) = - \oint_s \left( \frac{d\bar{B}}{dt} \right) \cdot d\bar{s}$$

$$e = \oint_l \bar{E} \cdot d\bar{l} \quad \oint_l \bar{E} \cdot d\bar{l} = - \oint_s \left( \frac{d\bar{B}}{dt} \right) \cdot d\bar{s}$$

$$\oint_l \bar{E} \cdot d\bar{l} = \oint_s (\bar{V} \times \bar{E}) \cdot d\bar{s}$$

$$\oint_s (\bar{V} \times \bar{E}) \cdot d\bar{s} = - \oint_s \left( \frac{d\bar{B}}{dt} \right) \cdot d\bar{s}$$

$$\therefore \oint_s \left[ (\bar{V} \times \bar{E}) + \frac{d\bar{B}}{dt} \right] \cdot d\bar{s} = 0$$

$$\therefore \bar{V} \times \bar{E} = -\frac{d\bar{B}}{dt}$$

This is Maxwell's third equation.

d) Fourth equation.

$$\oint_l \bar{H} \cdot d\bar{l} = I = \oint_s \bar{J} \cdot d\bar{s}$$

$$\oint_s \bar{J} \cdot d\bar{s} = \oint_s (\bar{V} \times \bar{H}) \cdot d\bar{s}$$

$$\oint_s (\bar{J} - \bar{V} \times \bar{H}) \cdot d\bar{s} = 0$$

$$\therefore \bar{J} = \bar{V} \times \bar{H}$$



$$\text{div } \vec{J} = \text{div} (\vec{V} \times \vec{H}) = 0.$$

$$\text{div } \vec{J} + \frac{\partial \rho}{\partial t} = 0. \quad \text{or} \quad \text{div } \vec{J} = -\frac{\partial \rho}{\partial t} \quad \text{--- (2)}$$

To correct this, Maxwell suggested that the total current density needs an additional component i.e.  $\vec{J}'$ .

$$\vec{V} \times \vec{H} = \vec{J} + \vec{J}'$$

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$$\text{div } \vec{V} \times \vec{H} = \text{div} (\vec{J} + \vec{J}')$$

$$0 = \text{div} (\vec{J} + \vec{J}')$$

$$\therefore \text{div } \vec{J} = -\text{div } \vec{J}'$$

from eqn (2),

$$\text{div } \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$\vec{V} \cdot \vec{D} = \rho \quad \therefore \text{div } \vec{J} = \frac{\partial}{\partial t} (\vec{V} \cdot \vec{D}) = \vec{V} \cdot \frac{\partial \vec{D}}{\partial t}$$

$$\text{Hence, } \vec{J}' = \frac{\partial \vec{D}}{\partial t}$$

$\therefore$  Maxwell's fourth equation is

$$\vec{V} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

The additional term  $\frac{\partial \vec{D}}{\partial t}$  is called Maxwell's correction and is known as displacement current.

Q3. → State Stoke's theorem with expression.

It states that the circulation of a vector field  $\vec{A}$  around a closed path  $\vec{C}$  is equal to the surface integral of the curl of  $\vec{A}$  over the open surface  $\vec{S}$  bounded by  $\vec{C}$  provided that  $\vec{A}$  and  $\nabla \times \vec{A}$  are continuous on  $\vec{S}$ .

$$\oint_C \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) \cdot d\vec{s}.$$

It relates closed line integral of the field with surface integral.

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