

2024 ACC Self-Driving Car

Student Competition Handbook



At their algorithmic core, self-driving cars excel or are held back in their capacity for autonomy by their knowledge and understanding of the state of the environment surrounding the car. This, debatably, makes accurate sensor fusion and state estimation the most crucial element of a self-driving stack.

The state estimation challenge has been approached by various companies using a wide variety of methods, from different sensor suites to the fusion of real-time sensor data with mapping and navigational databases. How that data is gathered, processed, and leveraged represents the grand challenge of self-driving and the motivation for the ACC Self-Driving Competition.

Competition Outline

Welcome to **2024 ACC Self-Driving Car Student Competition**, powered by Quanser!

If you are a returning competition group, welcome back!

You are in the role of an autonomous driving engineer and have been tasked with the following challenge:

Complete the racing line shown in Figure 1.



Figure 1: Top-down view of virtual world

The competition is divided into 3 stages:

➤ **Stage 1: Virtual Design and Submission**

Note: At the end of stage 1, registered teams will be ranked, and a set of finalists will be announced to advance from stage 1 to stages 2 and 3.

➤ **Stage 2: Algorithm Validation on Physical Vehicle**

➤ **Stage 3: On-site Demonstration and Competition**

Stage 1: Virtual Design and Submission

As a registered student team, you automatically participate in Stage 1. This is a qualifying stage, please submit your best result!

In general, teams will be ranked using the following criteria:

1. Successful completion of specified circuit.
2. Accuracy of driving
 - Did the car deviate from the drivable space?
 - How frequently were rules of the road broken?
3. Timely reaction to stop signs and traffic lights.
4. Avoidance of obstacles.

The ranking system is time-based. Your team will obtain a time penalty based on the following constraints:

Time penalty	Description
+5 seconds	Every time car leaves the road
+10 seconds	Consistent departure from the road Every traffic violation committed

Table 1: Time penalty breakdown

Submission Requirements:

1. Please send all required materials to: studentcompetition@quanser.com, and the subject line should contain the school's name and the submission date.
2. Student code **must** be Python based (**Python 3 version 3.6.9**). Should your code not meet this requirement, you will have a failed submission.
3. Maximum 1 minute video demonstration of code successfully completing a lap in a virtual environment.
4. Submission must provide the following:
 - a. Software: **GitHub link** to the repository with your team submission. Code will be run by a Quanser engineer to confirm successful implementation.
 - b. Video: **YouTube link** demonstrating the result of your code.

Available Documentation:

1. Information for interacting with the virtual environment:
<https://qlabs.quanserdocs.com/en/latest/Getting%20Started.html>
2. Current examples released for the Self-Driving Car Studio:
<https://quanserinc.box.com/shared/static/84sb0kqgakrtlt6og39xrbgbaxp7x12z.zip>
3. Competition webpage:
<https://www.quanser.com/community/student-competition/2024-student-self-driving-car-competition/>
4. Additional Software (virtual_world_setup_files.zip) for virtual environment configuration: one of the attachments to this Competition Handbook release email.

Getting Started

Use link #2 from the list of available documentation resources. Your system will download a .zip called research_resources. Follow the instructions provided in the README.txt to configure the required system environment variables.

This setup sequence was designed to be ran on **Windows 11**.

Configuring the Virtual Environment:

Step 1 – Download the .zip file attached to the Handbook release e-mail: virtual_world_setup_files.zip.

Step 2 – Before configuring the virtual environment, a registered team will be asked to create an account to obtain access to Quanser Interactive Labs.

If you have not done so already, please go to <https://portal.quanser.com/Accounts/Login?returnUrl=/> and create an account.

Step 3 – With a valid account, please navigate to the open world. Once inside, please select the warehouse workspace.

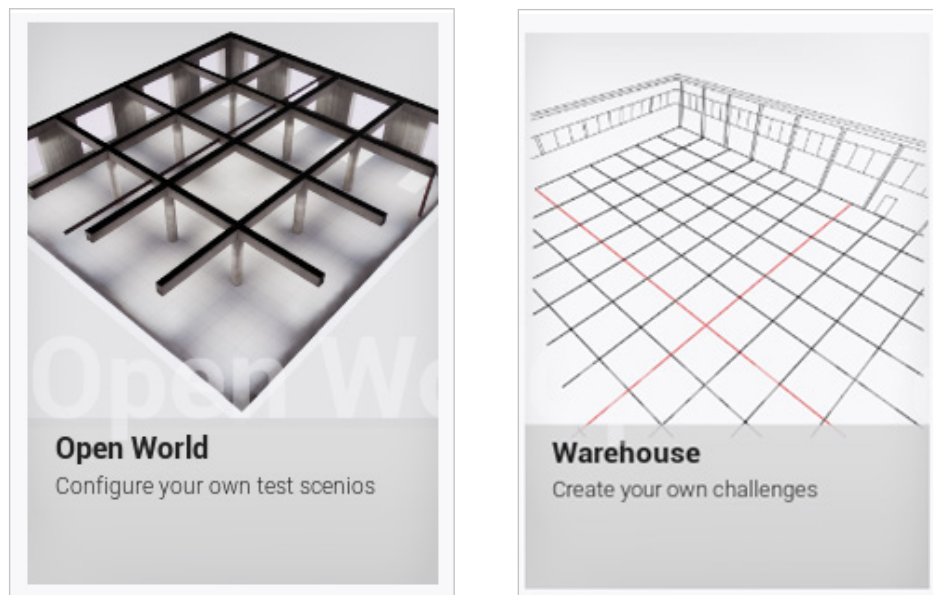


Figure 2: Quanser interactive labs menu item and warehouse workspace icons

Step 4 – In a terminal session run **Setup_Competition.py** to spawn the QCar in the virtual world.

Note: Please **do not** modify the Setup_Competition.py. Quanser will be using the original file to configure the workspace.

Step 5 – When ready, run **Traffic_Lights_Competition.py** to enable control for the traffic lights. The fully configured environment should look as follows:

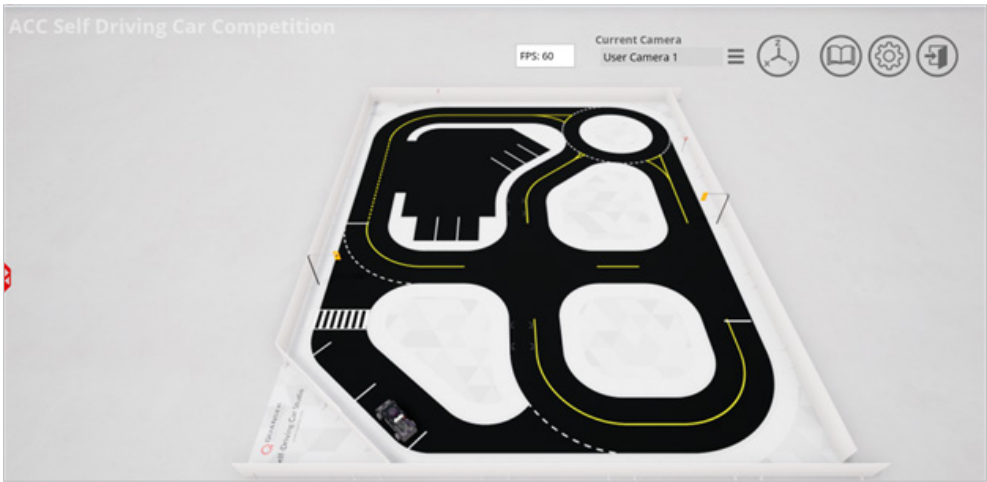


Figure 3: Competition virtual environment.

If your virtual environment looks like Figure 3 you can get started!

Suggested starting points:

- 1. Setting up the research studio resources on your system will create a Quanser folder int the following direc-
tory **C:/users/<User>/Documents/Quanser**
- 2. The folder labeled **SDCS/skills_activities/vehicle_control** contains an example of how to perform speed and
steering control using the QCar.
- 3. Please use the **QCar** class definition found under **pal.productst.qcar** to interface with the QCar.

Good luck!

Competition Schedule

Jan 10 – Feb 29 th	Stage 1 Open Registration
April 30	Stage 1 End Date
June 30	Stage 2 End Date
TBD	Stage 3 Guidance and Information

This document and the software described in it are provided subject to a license agreement. Neither the software nor this document may be used or copied except as specified under the terms of that license agreement.

Quanser Inc. grants the following rights: a) The right to reproduce the work, to incorporate the work into one or more collections, and to reproduce the work as incorporated in the collections, b) to create and reproduce adaptations provided reasonable steps are taken to clearly identify the changes that were made to the original work, c) to distribute and publicly perform the work including as incorporated in collections, and d) to distribute and publicly perform adaptations.

Above rights may be exercised in all media and formats whether now known or hereafter devised. These rights are granted subject to and limited by the following restrictions: a) You may not exercise any of the rights granted to You in above in any manner that is primarily intended for or directed toward commercial advantage or private monetary compensation, and b) You must keep intact all copyright notices for the Work and provide the name Quanser Inc. for attribution. These restrictions may not be waved without express prior written permission of Quanser Inc.



© 2024 Quanser Inc., All rights reserved.