12/04/2021 NYU Shanghai Optimization Method · Momentum t=0, set $V_0=0$ t > 0, $Vt \leftarrow V_{t-1} + \eta_t g_t$ $\chi_t \leftarrow \chi_{t-1} - V_t$ hyperparametero< $T \leq 1$, when T = 0 it's normal SGD related to exponentially weighted moving average (EWMA) by writing: $V_t \leftarrow \gamma V_{t-1} + (1-\gamma) \left(\frac{1}{1-\gamma} g_t\right)$ we see V_t is EWMA on the series $\begin{cases} \frac{1}{1-\gamma} g_t \end{cases}$ focus on the steps result. · AdaGrad adjustable learning rates on each dimension for flexibility t=0, set $S_0=0$ t > 0, $St \leftarrow St-1 + g_t \odot g_t$ \odot element-wise multiply $\chi_{t} \leftarrow \chi_{t-1} + \frac{\eta}{\sqrt{S_{t}+\varepsilon}} \odot g_{t}$ Here n is learning rate, & is constant = 10-6 for stability By accumulating the square of gradient in St., if one dimension's gradient is always big, it's learning rate drop quickly. It one dimension's gradient is always small, then its gradient drop slouly. · A the learning rate for Ada Grad is always dropping.

so it might not find optimal solution in later stage due to too small learning rate.

· RMS Prop to solve the "later-too-low-learning-rate" in AdaGrad t=0, $S_0=0$ t > 0, $S_t \leftarrow \delta S_t + (1-\delta) \cdot g_t \odot g_t$ $X_t \leftarrow X_{t-1} - \frac{\eta}{\sqrt{S_t + 9}} \odot g_t$ Hyperparameter 0 < 0 < 1, & stability constant series, so notice RMSProp is EWMA on {gt Ogt | teon. that the learning rate does not always drop. · Ada Delta Similarly to solve the low learning rate problem in Ada Grad t=0: So = 0 $\Delta X_0 = 0$ t > 0: $S_t \leftarrow \nabla S_{t-1} + (1-7).g_t \circ g_t$ $g_t' \leftarrow \int \Delta X_{t-1} + \varepsilon$ g_t g_t g_t $\chi_t \leftarrow \chi_{t} - g_{t}$ $\Delta X_{t} \leftarrow \delta \Delta X_{t-1} + (1-\delta) \cdot g_{t}' \odot g_{t}'$ Hyperparameter 0 < T<1, 2 stability constant The difference between AdaDelta and RMSProp is use DXX+1 to replace learning rate 1/t. · Adam a combination of RMS Prop and Momentum $t=0: V_0=U, S_0=0$ t > 0: $\forall t \leftarrow \forall i \forall t-1 + (i-\forall i) \cdot gt$ $St \leftarrow T_2 \cdot S_{t-1} + (1-T_2) \cdot g_t \odot g_t$