

# Master in **Computer Vision** Barcelona

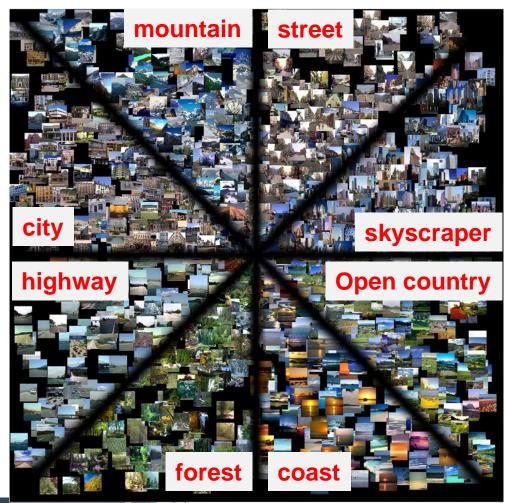
Module 3: Machine Learning for Computer Vision

**Project:** Deep learning classification

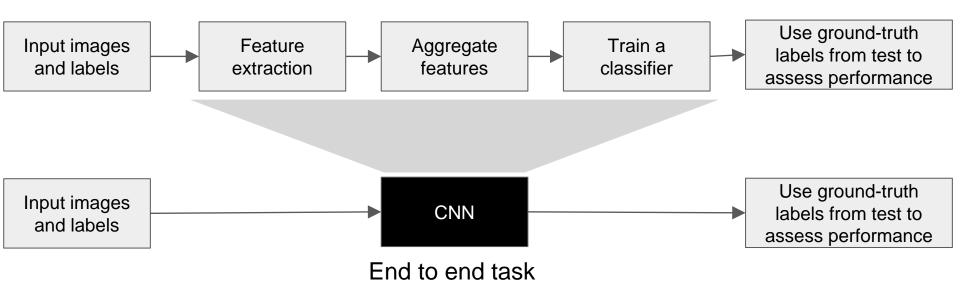
Ramon Baldrich Lecturer:

## Module Goal

The aim of this module is to learn the techniques for category classification: handcrafted and learned.



## Pipeline of the project W5 and W6



Machine learning for image classification:

Data driven methods: Deep Convolutional Networks: 3 sessions

From hand-crafted to learnt features

Fine tuning of pre-trained CNNs

Training a CNN from scratch

## Keras: first example

```
# create model
model = Sequential()
model.add(Dense(12, input dim=8, init='uniform', activation='relu'))
model.add(Dense(8, init='uniform', activation='relu'))
                                                                                           W3-5
inputs = Input(shape=None))
x = Dense(12, init='uniform', activation='relu', name='fc1')(x)
x = Dense(8, init='uniform', activation='sigmoid', name= 'predictions')(x)
model = Model(inputs, x, name='example')
# Compile model
model.compile(loss='categorical crossentropy', optimizer='adam', metrics=['accuracy'])
# Fit the model
                                                                                           W3-4
model.fit(X, Y, nb epoch=150, batch size=10)
# evaluate the model
scores = model.evaluate(X, Y)
print("%s: %.2f%%" % (model.metrics names[1], scores[1]*100))
# predict with the model
                                                                                           W3-4
features = model.predict(X)
```

• UOC

**#UPC** 

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Master in Computer Vision Barcelona

## Week 5: Training a CNN from scratch

#### Return of the Devil in the Details: Delving Deep into Convolutional Nets

Ken Chatfield, Karen Simonyan, Andrea Vedaldi, and Andrew Zisserman Visual Geometry Group, Department of Engineering Science, University of Oxford {ken,karen,vedaldi,az}@robots.ox.ac.uk

Abstract-The latest generation of Convolutional Neural Networks (CNN) have achieved impressive results in challenging benchmarks on image recognition and object detection, significantly raising the interest of the community in these methods. Nevertheless, it is still unclear how different CNN methods compare with each other and with previous state-of-the-art shallow representations such as the Bag-of-Visual-Words and the Improved Fisher Vector. This paper conducts a rigorous evaluation of these new techniques, exploring different deep architectures and comparing them on a common ground, identifying and disclosing important implementation details. We identify several useful properties of CNN-based representations, including the fact that the dimensionality of the CNN output layer can be reduced significantly without having an adverse effect on performance. We also identify aspects of deep and shallow methods that can be successfully shared. In particular, we show that the data augmentation techniques commonly applied to CNN-based methods can also be applied to shallow methods, and result in an analogous performance boost. Source code and models to reproduce the experiments in the paper is made publicly available.

#### INTRODUCTION

**D**ERHAPS the single most important design L choice in current state-of-the-art image classification and object recognition systems is the choice of visual features, or image representation. In fact,

is handcrafted, they contain a very large number of parameters learnt from data. When applied to standard image classification and object detection benchmark datasets such as ImageNet ILSVRC [5] and PASCAL VOC [6] such networks have demonstrated excellent performance [7], [8], [9], [10], [11], most of the quantitative improvements to image significantly better than standard image encod-

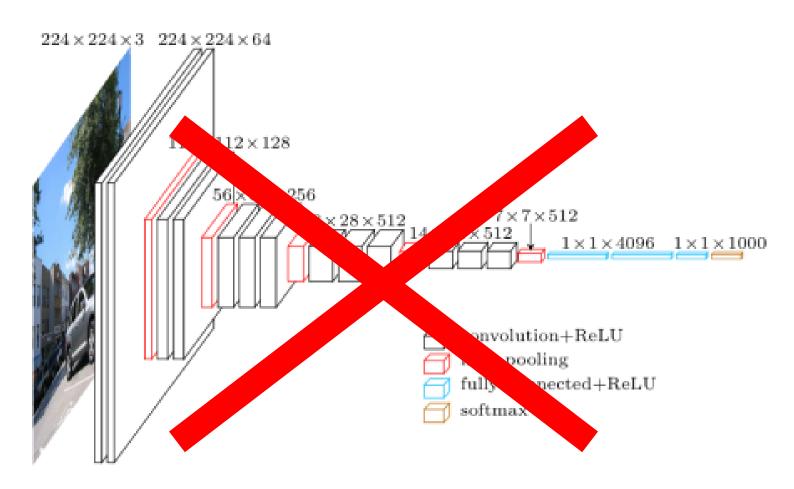
## Goals:

- Putting all together
- **Pipeline Control**
- Taking decisions

Chatfield, Ken, et al. "Return of the devil in the details: Delving deep into convolutional nets." arXiv preprint arXiv:1405.3531 (2014).



# Very deep convolutional networks for large-scale image recognition



Credit Davi Frossard

## layers

```
x = Convolution2D(...)(x)
x = MaxPooling2D((2, 2), strides=(2, 2), name='pool2')(x)
x = Flatten(name='flatten')(x)
x = Dense(..., activation='relu')(x)
x = Dense(..., activation='softmax')(x)
```

## .... more layers

```
x = BatchNormalization()(x)
x = Dropout()(x)
```

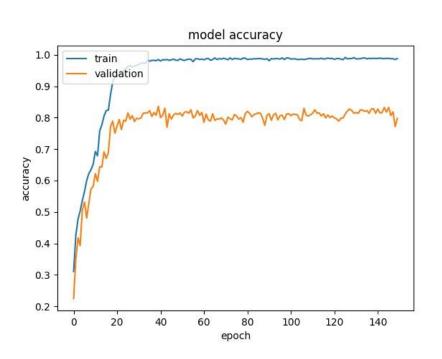
## .... even more layers

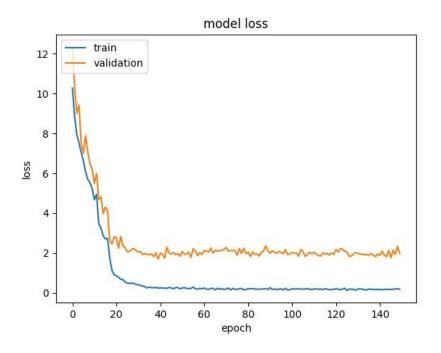
```
x = GaussianNoise (..)(x)
x = Activation()(x)
```



## Baseline

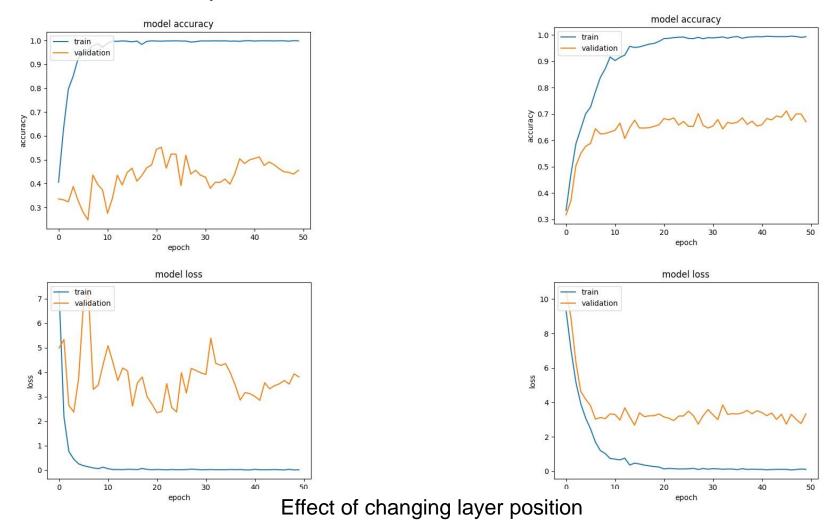
## 2 convolutional layers + ...





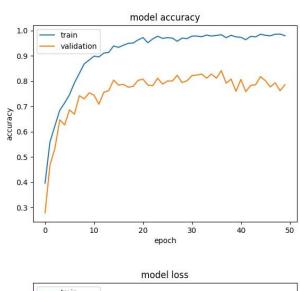
## examples

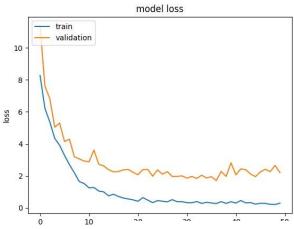
## 2 convolutional layers + batch normalization + ...

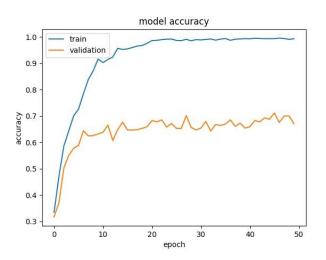


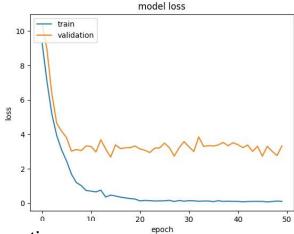
## examples

#### 2 convolutional lavers + dropout + ...









Effect of changing layer position or properties



## Control model size

#### model.summary()

Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	(None, 128, 128, 3)	0	
	(None, 128, 128, 32)	2432	input_1[0][0]
	(None, 64, 64, 32)	0	
	(None, 64, 64, 32)	128	-
	(None, 64, 64, 64)	51264	-
	(None, 32, 32, 64)	0	-
	(None, 32, 32, 64)	256	-
	(None, 16, 16, 64)	0	-
	(None, 16384)	0	-
	(None, 4096)	67112960	-
predictions (Dense)	(None, 8)	32776	-

Total params: 67,199,816 Trainable params: 67,199,624 Non-trainable params: 192



## Modern classification architectures

#### **Network In Network**

Min Lin<sup>1,2</sup>, Qiang Chen<sup>2</sup>, Shuicheng Yan<sup>2</sup>

<sup>1</sup>Graduate School for Integrative Sciences and Engineering

<sup>2</sup>Department of Electronic & Computer Engineering

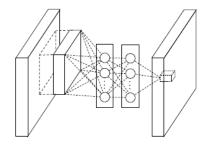
National University of Singapore, Singapore

{linmin, chengiang, eleyans}@nus.edu.sq

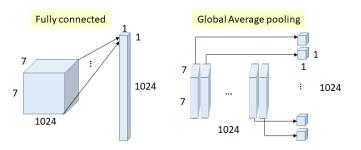
#### Abstract

We propose a novel deep network structure called "Network In Network" (NIN) to enhance model discriminability for local patches within the receptive field. The conventional convolutional layer uses linear filters followed by a nonlinear activation function to scan the input. Instead, we build micro neural networks with more complex structures to abstract the data within the receptive field. We instantiate the micro neural network with a multilayer perceptron, which is a potent function approximator. The feature maps are obtained by sliding the micro networks over the input in a similar manner as CNN; they are then fed into the next layer. Deep NIN can be implemented by stacking mutiple of the above described structure. With enhanced local modeling via the micro network, we are able to utilize global average pooling over feature maps in the classification layer, which is easier to interpret and less prone to overfitting than traditional fully connected layers. We demonstrated the state-of-the-art classification performances with NIN on CIFAR-10 and CIFAR-100, and reasonable performances on SVHN and MNIST datasets.

#### MLPConv



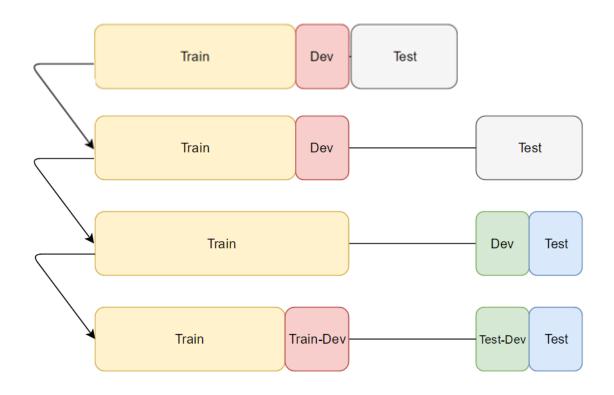
### Global Average Pooling Layer



https://www.coursera.org/lecture/convolutional-neural-networks/networks-in-networks-and-1x1-convolutions-ZTb8x



## **Bias-Variance**



## Nuts and Bolts of Applying Deep Learning (Andrew Ng)

https://www.youtube.com/watch?v=F1ka6a13S9I&t=3044s

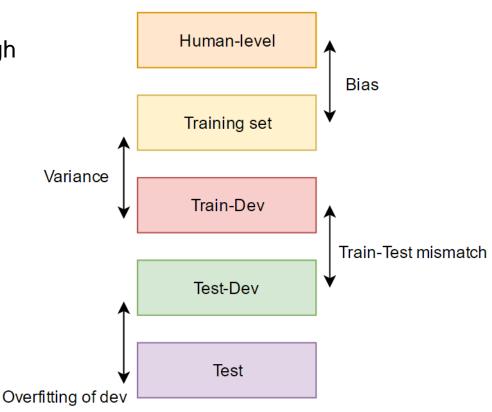
https://kevinzakka.github.io/2016/09/26/applying-deep-learning/



## Bias-Variance

The <u>bias</u> is error from erroneous assumptions in the learning algorithm. High bias can cause an algorithm to miss the relevant relations between features and target outputs (underfitting).

The <u>variance</u> is error from sensitivity to small fluctuations in the training set. High variance can cause overfitting: modeling the random noise in the training data, rather than the intended outputs.

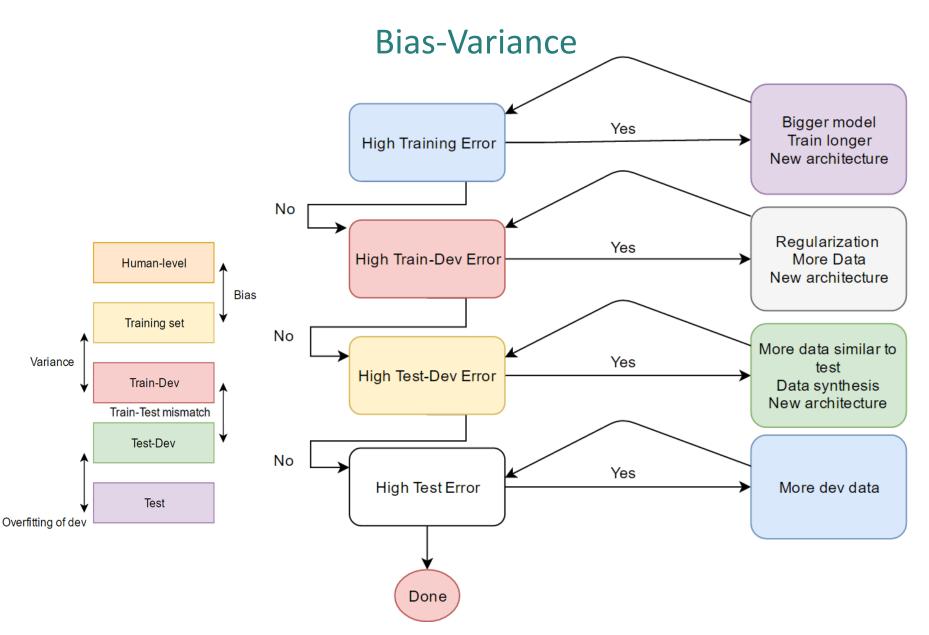


Nuts and Bolts of Applying Deep Learning (Andrew Ng)

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https://kevinzakka.github.io/2016/09/26/applying-deep-learning/





## **Tasks**

# Make it work

What we will look at?

compact model (few parameters)

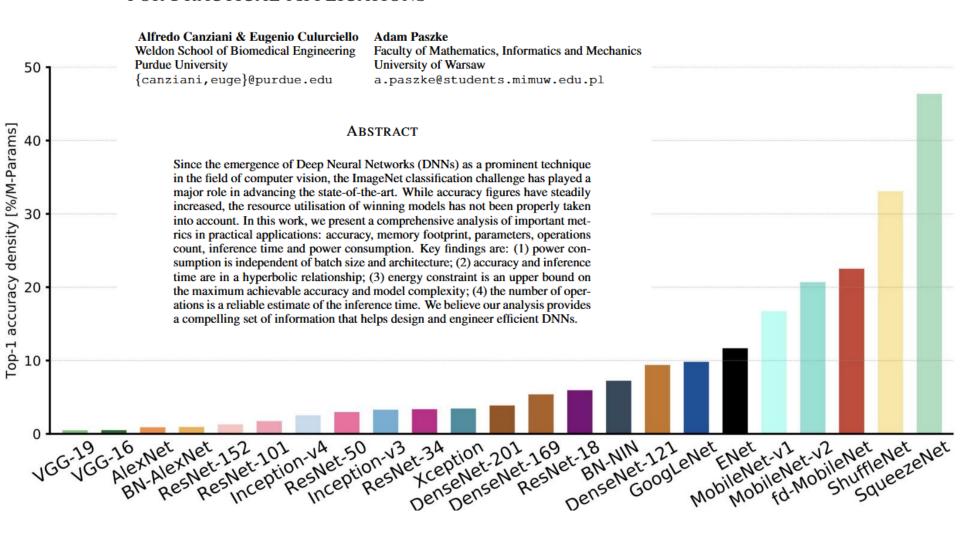
few convolutional layers

different layer types involved

performance

ratio: accuracy/ (number of parameters/ 100K)

## AN ANALYSIS OF DEEP NEURAL NETWORK MODELS FOR PRACTICAL APPLICATIONS



https://medium.com/@culurciello/analysis-of-deep-neural-networks-dcf398e71aae





## deliverables and deadlines

Deliverable: presentation slides Monday 14<sup>th</sup> at 15:00

Final presentation:

groups 1,2,3,4: Monday 14<sup>th</sup> at 16:00

groups 5,6,7,8: Monday 14<sup>th</sup> at 17:30

12 + 3 minutes. Summarizing the whole work. be specific, enhance your approach

Your questions will be graded

FINAL REPORT deadline: Sunday 20<sup>th</sup> at 23:55



