





Master in Computer Vision Barcelona

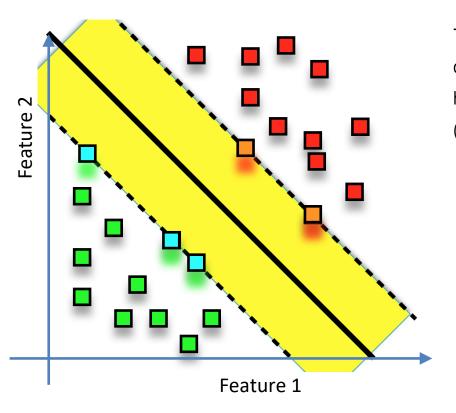
Module: M3. Machine Learning for Computer Vision

Lecture: The Support Vector Machine (SVM):

Mathematical Development

Lecturer: Ramon Baldrich / Fernando Vilariño

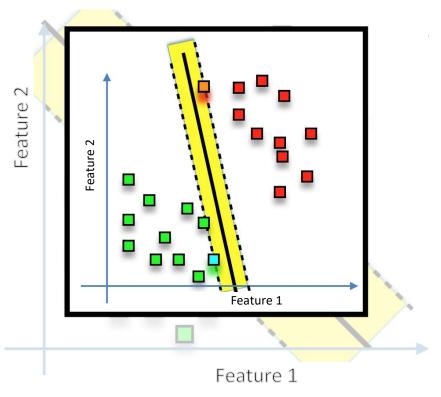




The separating hyperplane is obtained from the solution of an optimization problem: maximal distance between the 2 hyperplanes containing the support vectors of both classes (maximal margin).

- Class 1 vectors
- Class 1 support vectors
- Class 2 vectors
- Class 2 support vectors
- Margin
- Solution hyperplane
- - Support vectors hyperplanes

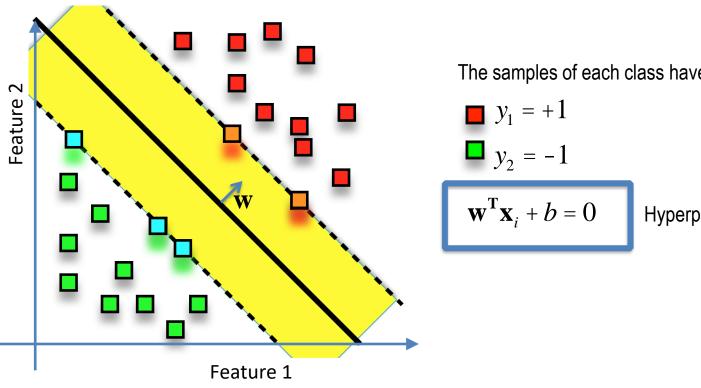




Any other choice of support vectors generate a lower margin.

- Class 1 vectors
- Class 1 support vectors
- Class 2 vectors
- Class 2 support vectors
- Margin
- Solution hyperplane
- - Support vectors hyperplanes

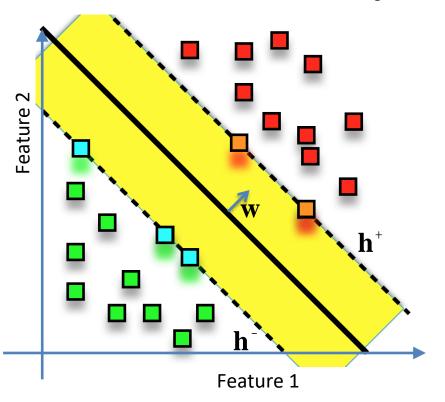




The samples of each class have one label:

Hyperplane solution ${f w}$





The samples of each class have one label:

$$y_1 = +1$$

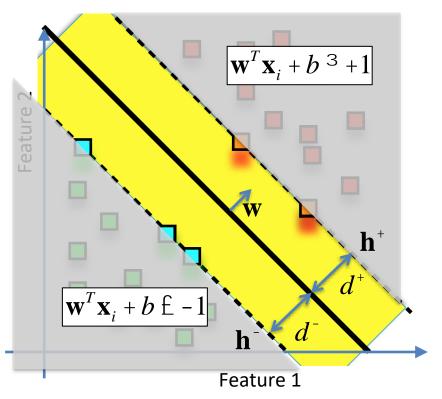
$$y_2 = -1$$

$$\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b = 0$$

$$\mathbf{h}^{+} \rightarrow \mathbf{w}^{T} \mathbf{x}_{i} + b = +1$$
$$\mathbf{h}^{-} \rightarrow \mathbf{w}^{T} \mathbf{x}_{i} + b = -1$$

Support vector hyperplanes





The samples of each class have one label:

$$y_1 = +1$$

$$y_2 = -1$$

$$\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b = 0$$

Classification condition

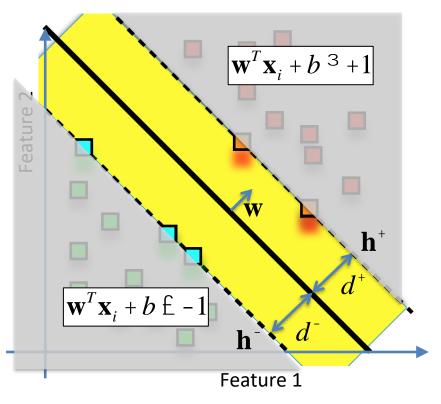
$$\mathbf{h}^{+} \rightarrow \mathbf{w}^{T} \mathbf{x}_{i} + b = +1$$

$$\mathbf{h}^{-} \rightarrow \mathbf{w}^{T} \mathbf{x}_{i} + b = -1$$

$$y_{i} (\mathbf{w}^{T} \mathbf{x}_{i} + b)^{3} 1$$

$$y_i(\mathbf{w}^T\mathbf{x}_i+b)^3 1$$





The samples of each class have one label:

$$y_1 = +1$$

$$y_2 = -1$$

$$\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i}+b=0$$

Classification condition

$$\mathbf{h}^+ \rightarrow \mathbf{w}^T \mathbf{x}_i + b = +1$$

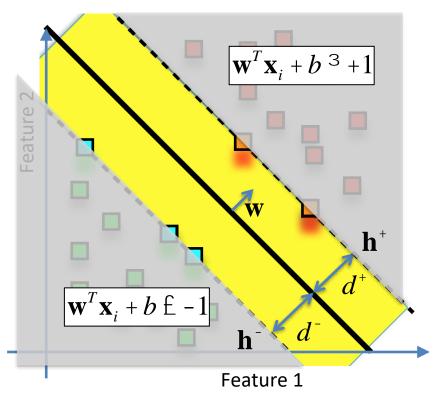
$$\mathbf{h}^- \rightarrow \mathbf{w}^T \mathbf{x}_i + b = -1$$

$$y_i(\mathbf{w}^T\mathbf{x}_i+b)^3 1$$

$$d^{+} = d^{-} = \frac{|\mathbf{w}\mathbf{x} + b|}{\|\mathbf{w}\|} = \frac{1}{\|\mathbf{w}\|}$$
 margin= $d^{+} + d^{-} = 2\frac{1}{\|\mathbf{w}\|}$

Master in Computer Vision Barcelona

SVM: Linear classifier based on maximal margin from the support vectors.



The samples of each class have one label:

$$y_1 = +1$$

$$y_2 = -1$$

$$\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b = 0$$

$$\mathbf{h}^{+} \rightarrow \mathbf{w}^{T} \mathbf{x}_{i} + b = +1$$
$$\mathbf{h}^{-} \rightarrow \mathbf{w}^{T} \mathbf{x}_{i} + b = -1$$

$$\|\mathbf{w}\|^2 = \mathbf{w}^T \mathbf{w}$$

Minimise
$$F(\mathbf{w}) = \frac{1}{2} \|\mathbf{w}\|^2$$

Subject to: $y_i(\mathbf{w}^T\mathbf{x}_i + b)^3 1$

SVM a quadratic optimisation problem



OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

$$\mathbf{w}^{\mathsf{T}}\mathbf{x} + b = 0$$

This is solved as a problem of quadratic optimisation:

$$\underset{\mathbf{w},b}{\text{Minimise}} \, \mathsf{F}(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

Suject to: $y_i(\mathbf{w}^T\mathbf{x}_i + b)^3 1$







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Suject to: $y_i(\mathbf{w}^T \mathbf{x}_i + b)^3 1$

$$L(x,\partial) = f(x) + \mathring{\partial}_i \partial_i g_i(x)$$
 " $\partial_i \partial_i g_i(x)$



OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

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Suject to: $y_i (\mathbf{w}^T \mathbf{x}_i + b)^3 1$

$$L(x,a) = f(x) + \mathring{a}_i a g_i(x) \qquad "a_i = 0$$
Function to optimise Constraints
Lagrange multipliers

$$f(x) \rightarrow F(\mathbf{w})$$

 $g_i(x) \rightarrow y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \ge 0$

OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

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Minimise
$$F(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

Suject to: $y_i(\mathbf{w}^T \mathbf{x}_i + b)^3 1$ $P \max_{a} (\min_{\mathbf{w},b} (L(\mathbf{w}, b, a)))$

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Function to optimise Constraints

Lagrange multipliers

$$f(x) \to F(\mathbf{w})$$

$$g_i(x) \to y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \ge 0$$





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Suject to: $y_i(\mathbf{w}^T \mathbf{x}_i + b)^3 1$ $P \max_{a} (\min_{\mathbf{w}, b} (L(\mathbf{w}, b, a)))$

The Lagrangian of the SVM problem is:

$$L(\mathbf{w}, b, \partial_i) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \mathop{\tilde{o}}_{i} \partial_i [y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1]$$

$$L(x,a) = f(x) + \mathop{a}_{i} a g_{i}(x) \qquad "a_{i} = 0$$
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Lagrange multipliers

$$f(x) \rightarrow F(\mathbf{w})$$

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Construction of the Lagrangian L:

$$L(x,\partial) = f(x) + \mathring{\partial}_i \partial_i g_i(x) \qquad \text{``} \ \partial_i \partial_i 0$$
 Function to optimise Constraints Lagrange multipliers

$$f(x) \to F(\mathbf{w})$$

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$$L(\mathbf{w}, b, a_i) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \underset{i}{\overset{\circ}{\bigcirc}} a_i [y_i (\mathbf{w}^T \mathbf{x}_i + b) - 1]$$

The minimisation of L with respect to \mathbf{w} , b implies:

$$\frac{\P L}{\P \mathbf{w}} = \mathbf{w} - \mathop{\stackrel{\circ}{a}}_{i} \partial_{i} y_{i} \mathbf{x}_{i} = 0 \quad P \quad \mathbf{w} = \mathop{\stackrel{\circ}{a}}_{i} \partial_{i} y_{i} \mathbf{x}_{i}$$

$$\frac{\P L}{\P b} = -\mathop{\stackrel{\circ}{a}}_{i} \partial_{i} y_{i} = 0 \quad P \quad \mathop{\stackrel{\circ}{a}}_{i} \partial_{i} y_{i} = 0 \quad \partial_{i}^{3} 0$$



OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

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Suject to: $y_i(\mathbf{w}^T\mathbf{x}_i + b)^3 1$ \bowtie $\max_{a} (\min_{\mathbf{w},b} (L(\mathbf{w},b,a)))$

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The minimisation of L with respect to \mathbf{w} , b implies:

$$\begin{split} \frac{\P L}{\P \mathbf{w}} &= \mathbf{w} - \mathop{\mathring{a}}_{i} a_{i} y_{i} \mathbf{x}_{i} = 0 \quad P \quad \mathbf{w} = \mathop{\mathring{a}}_{i} a_{i} y_{i} \mathbf{x}_{i} \\ \frac{\P L}{\P b} &= - \mathop{\mathring{a}}_{i} a_{i} y_{i} = 0 \quad P \quad \mathop{\mathring{a}}_{i} a_{i} y_{i} = 0 \quad a_{i} \stackrel{\Im}{=} 0 \\ L(\mathbf{w}, b, a_{i}) &= \frac{1}{2} \mathop{\mathring{c}}_{i} \mathop{\mathring{a}}_{i} a_{i} y_{i} \mathbf{x}_{i} \mathop{\stackrel{\circ}{=}} \mathop{\mathring{c}}_{i} \mathop{\mathring{a}}_{i} a_{j} y_{j} \mathbf{x}_{j} \mathop{\stackrel{\circ}{=}} - \mathop{\mathring{a}}_{i} a_{i} y_{i} \mathop{\mathring{c}}_{i} \mathop{\mathring{c}}_{i} a_{j} y_{j} \mathbf{x}_{j} \mathop{\stackrel{\circ}{=}} \mathop{\mathring{c}}_{i} a_{j} y_{j} \mathbf{x}_{j} \mathop{\stackrel{\circ}{=}} \mathop{\mathring{c}}_{i} a_{i} y_{i} \mathop{\mathring{c}}_{i} \mathop{\mathring{c}}_{i} a_{j} y_{j} \mathbf{x}_{j} \mathop{\stackrel{\circ}{=}} \mathbf{x}_{i} + \mathop{\mathring{a}}_{i} a_{i} \\ &= -\frac{1}{2} \mathop{\mathring{a}}_{i} \mathop{\mathring{a}}_{i} a_{i} a_{j} y_{i} y_{i} \mathbf{x}_{i}^{T} \mathbf{x}_{j} + \mathop{\mathring{a}}_{i} a_{i} \end{split}$$



OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

$$\mathbf{w}^{\mathsf{T}}\mathbf{x} + b = 0$$

This is solved as a problem of quadratic optimisation:

Minimise
$$F(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

Suject to: $y_i(\mathbf{w}^T \mathbf{x}_i + b)^3 1$ \bowtie $\max_{a} (\min_{\mathbf{w}, b} (L(\mathbf{w}, b, a)))$

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The Lagrangian L of the SVM problem is:

$$L(\mathbf{w}, b, a_i) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \underset{i}{\overset{\circ}{\bigcirc}} a_i [y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1]$$

The minimisation of L with respect to \mathbf{w}, b implies:

$$\frac{\P L}{\P \mathbf{w}} = \mathbf{w} - \mathring{\mathbf{a}}_{i} y_{i} \mathbf{x}_{i} = 0 \quad P \quad \mathbf{w} = \mathring{\mathbf{a}}_{i} a_{i} y_{i} \mathbf{x}_{i}$$

$$\frac{\P L}{\P b} = - \mathring{\mathbf{a}}_{i} a_{i} y_{i} = 0 \quad P \quad \mathring{\mathbf{a}}_{i} a_{i} y_{i} = 0 \quad a_{i} \stackrel{?}{=} 0$$

$$L(\mathbf{w}, b, a_{i}) = \frac{1}{2} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{a}}_{i} a_{i} y_{i} \mathbf{x}_{i} + \mathring{\mathbf{c}}_{i} \mathring{\mathbf{a}}_{i} a_{j} y_{j} \mathbf{x}_{j} = 0$$

$$= -\frac{1}{2} \mathring{\mathbf{a}}_{i} \mathring{\mathbf{a}}_{i} a_{i} a_{j} y_{i} y_{i} \mathbf{x}_{i}^{T} \mathbf{x}_{j} + \mathring{\mathbf{a}}_{i} a_{i}$$

Maximize
$$Q(\partial) = -\frac{1}{2} \overset{\circ}{\partial} \overset{\circ}{\partial} \partial_i \partial_j y_i y_i \mathbf{x}_i^T \mathbf{x}_j + \overset{\circ}{\partial} \partial_i$$

Subject to: $\overset{\circ}{\partial} \partial_i y_i = 0 \overset{\circ}{\partial} \partial_i \overset{\circ}{\partial} 0$

SVM DUAL



OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

$$\mathbf{w}^{\mathsf{T}}\mathbf{x} + b = 0$$

This is solved as a problem of quadratic optimisation:

Minimise
$$F(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

Suject to: $y_i(\mathbf{w}^T \mathbf{x}_i + b)^3 1$ \bowtie $\max_{a} (\min_{\mathbf{w}, b} (L(\mathbf{w}, b, a)))$

Maximise
$$Q(a) = -\frac{1}{2} \mathop{a}_{i} \mathop{a}_{j} a_{i} a_{j} y_{i} y_{i} \mathbf{x}_{i}^{T} \mathbf{x}_{j} + \mathop{a}_{i} a_{i}$$

Sujeto a: $\mathop{a}_{i} a_{i} y_{i} = 0$ $a_{i} \stackrel{3}{=} 0$

SVM DUAL

The Lagrangian L of the SVM problem is:

$$L(\mathbf{w}, b, a_i) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \underset{i}{\overset{\circ}{\bigcirc}} a_i [y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1]$$

The minimisation of L with respect to w, b implies:

$$\frac{\P L}{\P \mathbf{w}} = \mathbf{w} - \mathring{\mathbf{a}}_{i} y_{i} \mathbf{x}_{i} = 0 \quad P \quad \mathbf{w} = \mathring{\mathbf{a}}_{i} a_{i} y_{i} \mathbf{x}_{i}$$

$$\frac{\P L}{\P b} = - \mathring{\mathbf{a}}_{i} a_{i} y_{i} = 0 \quad P \quad \mathring{\mathbf{a}}_{i} a_{i} y_{i} = 0 \quad a_{i}^{3} 0$$

$$L(\mathbf{w}, b, a_{i}) = \frac{1}{2} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{a}}_{i} a_{i} y_{i} \mathbf{x}_{i} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{a}}_{i} a_{j} y_{j} \mathbf{x}_{j} \mathring{\mathbf{c}}_{i} - \mathring{\mathbf{a}}_{i} a_{i} y_{i} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{a}}_{i} y_{j} \mathbf{x}_{j} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{c}}_{i} a_{i} y_{j} \mathbf{x}_{j} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{c}}_{i} a_{i} y_{j} \mathbf{x}_{j} \mathring{\mathbf{c}}_{i} \mathring{\mathbf{c}}_{i} a_{i} a_{i} = 0$$

$$= -\frac{1}{2} \mathring{\mathbf{a}}_{i} \mathring{\mathbf{a}}_{i} a_{i} a_{j} y_{i} y_{i} \mathbf{x}_{i}^{T} \mathbf{x}_{j} + \mathring{\mathbf{a}}_{i} a_{i}$$



OBJECTIVE: Obtain \mathbf{w}, b belonging to the solution hyperplane:

$$\mathbf{w}^{\mathsf{T}}\mathbf{x} + b = 0$$

This is solved as a problem of quadratic optimisation:

Minimise
$$F(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w}$$

Suject to: $y_i(\mathbf{w}^T \mathbf{x}_i + b)$ 3 1 $P \max_{a} (\min_{\mathbf{w},b} (L(\mathbf{w},b,a)))$

SVM PRIMAL

Maximise
$$O(\partial) = -\frac{1}{2} \mathop{\stackrel{\circ}{\partial}}_{i} \mathop{\stackrel{\circ}{\partial}}_{j} \partial_{i} \partial_{j} y_{i} y_{i} \mathbf{x}_{i}^{T} \mathbf{x}_{j} + \mathop{\stackrel{\circ}{\partial}}_{i} \partial_{i}$$

Sujeto a: $\mathop{\stackrel{\circ}{\partial}}_{i} \partial_{i} y_{i} = 0$ $\partial_{i} \mathop{\stackrel{\circ}{\partial}}_{0} 0$

SVM DUAL

The Lagrangian L of the SVM problem is:

$$L(\mathbf{w}, b, a_i) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \underset{i}{\overset{\circ}{\bigcirc}} a_i [y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1]$$

The minimisation of L with respect to \mathbf{w} , b implies:

$$\begin{split} \frac{\P L}{\P \mathbf{w}} &= \mathbf{w} - \mathop{\mathring{a}}_{i} \partial_{i} y_{i} \mathbf{x}_{i} = 0 \quad P \quad \mathbf{w} = \mathop{\mathring{a}}_{i} \partial_{i} y_{i} \mathbf{x}_{i} \\ \frac{\P L}{\P b} &= - \mathop{\mathring{a}}_{i} \partial_{i} y_{i} = 0 \qquad P \quad \mathop{\mathring{a}}_{i} \partial_{i} y_{i} = 0 \quad \partial_{i} \stackrel{\Im}{\mathbf{0}} \mathbf{0} \\ L(\mathbf{w}, b, \partial_{i}) &= \frac{1}{2} \mathop{\mathring{c}}_{i} \mathop{\mathring{a}}_{i} \partial_{i} y_{i} \mathbf{x}_{i} \mathop{\overset{\circ}{=}}_{i} \mathop{\mathring{c}}_{i} \mathop{\mathring{a}}_{j} \partial_{j} y_{j} \mathbf{x}_{j} \mathop{\overset{\circ}{=}}_{i} - \mathop{\mathring{a}}_{i} \partial_{i} y_{i} \mathop{\mathring{c}}_{i} \mathop{\mathring{a}}_{j} \partial_{j} y_{j} \mathbf{x}_{j} \mathop{\overset{\circ}{=}}_{i} \mathop{\mathring{a}}_{i} \partial_{i} y_{j} \mathbf{x}_{j} \mathop{\overset{\circ}{=}}_{i} \mathop{\mathring{a}}_{i} \partial_{i} \partial_{j} y_{j} \mathbf{x}_{j} \mathop{\overset{\circ}{=}}_{i} \mathop{\mathring{a}}_{i} \partial_{i} \partial_{i} \partial_{i} \partial_{i} \partial_{j} \partial_{j} \partial_{i} \mathop{\mathring{a}}_{i} \partial_{i} \partial_$$

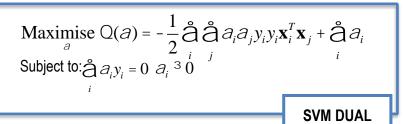


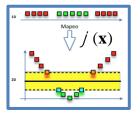
Maximise
$$Q(a) = -\frac{1}{2} \mathop{\stackrel{\circ}{a}}_{i} \mathop{\stackrel{\circ}{a}}_{i} a_{i} a_{j} y_{i} y_{i} \mathbf{x}_{i}^{T} \mathbf{x}_{j} + \mathop{\stackrel{\circ}{a}}_{i} a_{i}$$

Subject to: $\mathop{\stackrel{\circ}{a}}_{i} a_{i} y_{i} = 0$ $a_{i} \stackrel{\circ}{a} \stackrel{\circ}{0}$









Mapping function:

$$\mathbf{x} \mapsto \varphi(\mathbf{x})$$

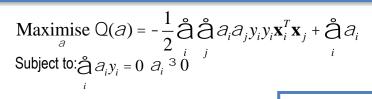
Kernel function:

$$K(\mathbf{x}, \mathbf{z}) = \int (\mathbf{x})^T \int (\mathbf{z})$$

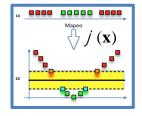




For the case of non linearly separable datasets: The **kernel trick**



SVM DUAL



Mapping function:

$$\mathbf{x} \mapsto \varphi(\mathbf{x})$$

Kernel function:

$$K(\mathbf{x}, \mathbf{z}) = \int (\mathbf{x})^T \int (\mathbf{z})$$

Maximise
$$Q(\partial) = -\frac{1}{2} \mathop{\stackrel{\circ}{a}}_{i} \mathop{\stackrel{\circ}{a}}_{j} \partial_{i} \partial_{j} y_{i} y_{i} K(\mathbf{x}_{i} \mathbf{x}_{j}) + \mathop{\stackrel{\circ}{a}}_{i} \partial_{i}$$

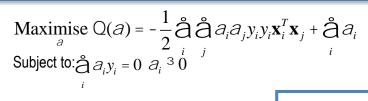
$$b = y_{i} - \mathbf{w}^{T} f(\mathbf{x}_{i}) = y_{i} - \mathop{\stackrel{\circ}{a}}_{j} y_{j} \partial_{i} K(\mathbf{x}_{j}, \mathbf{x}_{i})$$

$$f(\mathbf{x}) = \operatorname{sgn}(\mathop{\stackrel{\circ}{a}}_{i} y_{i} \partial_{i} K(\mathbf{x}, \mathbf{x}_{i}) + b)$$

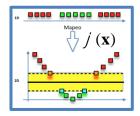
$$i$$
Kernel SVM



For the case of non linearly separable datasets: The kernel trick



SVM DUAL



Mapping function:

$$\mathbf{x} \mapsto \varphi(\mathbf{x})$$

Kernel function:

$$K(\mathbf{x}, \mathbf{z}) = \int (\mathbf{x})^T \int (\mathbf{z})$$

Examples of kernel functions:

Polinomial:
$$K(\mathbf{x}, \mathbf{z}) = \langle \mathbf{x}, \mathbf{z} \rangle^d$$

Radial basis functions:
$$K(\mathbf{x}, \mathbf{z}) = e^{-\|\mathbf{x} - \mathbf{z}\|^2/2S}$$

Sigmoid:
$$K(\mathbf{x}, \mathbf{z}) = \tanh(k\langle \mathbf{x}, \mathbf{z} \rangle - O)$$

Multi-inverse quadratic:
$$K(\mathbf{x}, \mathbf{z}) = (\|\mathbf{x} - \mathbf{z}\|^{1/2} 2S + c^2)^{-1}$$

Intersection kernel:
$$K(\mathbf{x}, \mathbf{z}) = \stackrel{\circ}{\stackrel{\circ}{\bigcirc}} \min(x(i), z(i))$$

Maximise
$$Q(\partial) = -\frac{1}{2} \mathop{\tilde{a}}_{i} \mathop{\tilde{a}}_{j} \partial_{i} \partial_{j} y_{i} y_{i} K(\mathbf{x}_{i} \mathbf{x}_{j}) + \mathop{\tilde{a}}_{i} \partial_{i}$$

$$b = y_{i} - \mathbf{w}^{T} f(\mathbf{x}_{i}) = y_{i} - \mathop{\tilde{a}}_{i} y_{j} \partial_{i} K(\mathbf{x}_{j}, \mathbf{x}_{i})$$

$$f(\mathbf{x}) = \operatorname{sgn}(\mathop{\tilde{a}}_{i} y_{i} \partial_{i} K(\mathbf{x}, \mathbf{x}_{i}) + b)$$

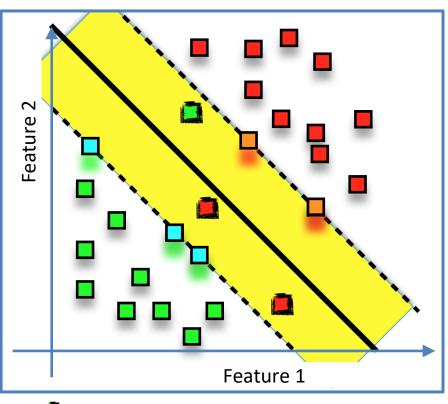
$$Kernel SVM$$

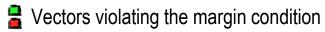
Kernel functions introduce new parameters the value of which must be fixed, generally, through cross-validation.

Support Vector Machines (SVM)

Master in Computer Vision Barcelona

Non linearly separable datasets: **Soft margin**.

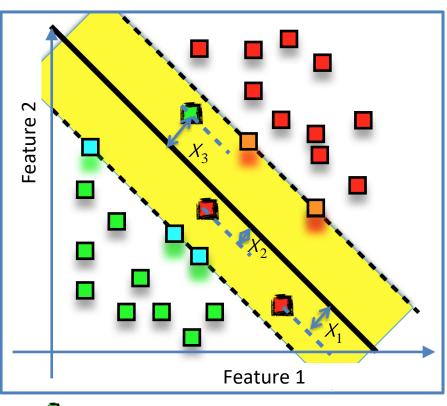




Support Vector Machines (SVM)

Master in Computer Vision Barcelona

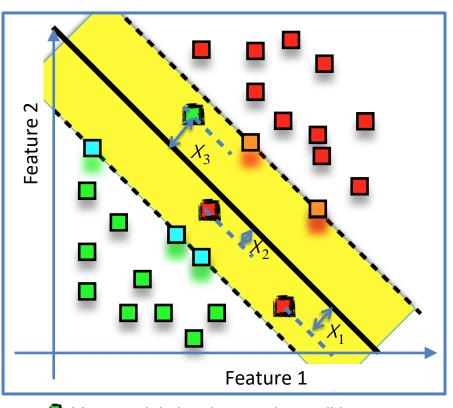
Non linearly separable datasets: **Soft margin**.



Slack variables: $\chi_i \ge 0$



Non linearly separable datasets: **Soft margin**.



 $X_i \stackrel{3}{\cdot} 0$ Slack variables:

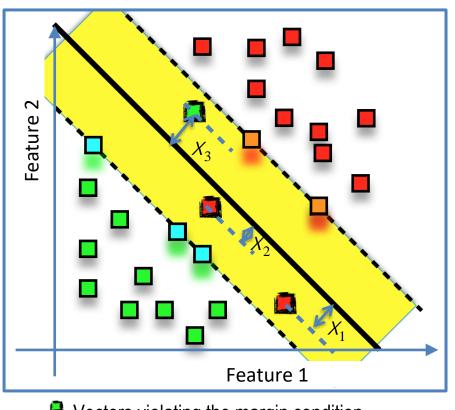
Minimise
$$F(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \underset{i}{\overset{\circ}{\circ}} X_i$$

Subject to: $y_i(\mathbf{w}^T f(\mathbf{x}_i) + b) \stackrel{3}{\circ} 1 - X_i$

SVM PRIMAL



Non linearly separable datasets: **Soft margin**.



Slack variables: $\chi_i = 0$

$$\underset{\mathbf{w},b,X}{\text{Minimise}} \, \mathsf{F}(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \underset{i}{\overset{\circ}{\circ}} X_i$$

Subject to: $y_i(\mathbf{w}^T f(\mathbf{x}_i) + b) \stackrel{!}{\exists} 1 - X_i$

SVM PRIMAL

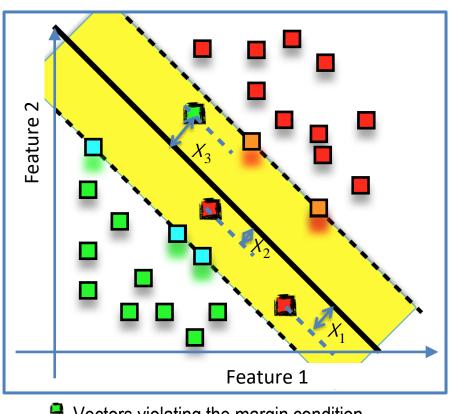
Maximise
$$Q(\partial) = -\frac{1}{2} \mathop{a}_{i} \mathop{a}_{j} \partial_{i} \partial_{j} y_{i} y_{i} K(\mathbf{x}_{i} \mathbf{x}_{j}) + \mathop{a}_{i} \partial_{i}$$

Subject to: $\begin{cases} 0 \notin a_i \notin C \\ \mathring{a}_i a_i y_i = 0 \end{cases}$

SVM DUAL



Non linearly separable datasets: **Soft margin**.



Slack variables: $\chi_i = 0$

Minimise
$$F(\mathbf{w}) = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \mathop{\stackrel{\circ}{o}}_{i} X_i$$

Subject to: $y_i(\mathbf{w}^T f(\mathbf{x}_i) + b) \stackrel{3}{1} - X_i$

SVM PRIMAL

Maximise
$$Q(a) = -\frac{1}{2} \underset{i}{\overset{\circ}{a}} \underset{j}{\overset{\circ}{a}} a_{i} a_{j} y_{i} y_{i} K(\mathbf{x}_{i} \mathbf{x}_{j}) + \underset{i}{\overset{\circ}{a}} a_{i}$$

Subject to:
$$\begin{cases}
0 & \text{f.} a_{i} & \text{f.} C \\ \overset{\circ}{a} a_{i} y_{i} & \text{f.} c \\ \overset{\circ}{a} a_{i} y_{i} & \text{f.} c \\ & \text{i.} & \text{o.} \end{cases}$$

SVM DUAL



Key concepts:

- SVM as a quadratic optimisation problem.
- The SVM solution as a dual problem.
- The dual problem allows the explicit solution from scalar products.
- The solution in form of scalar products allow the introduction of kernels.
- Kernel functions allow to classify non linearly separable datasets.
- The slack variables introduce a regularisation factor that allows tolerance to errors by relaxing the condition of maximal margin.
- Both the kernel parameters and the regularisation factor must be adjusted during the training stage.