Z-Way Developers Documentation

(c) Z-Wave. Me Team, based on Version $2.2.4\,$

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Chapter 1

Introduction and Overview

1.1 How to use Z-Way

Z-Way offers multiple Application Programmers Interfaces (API) that are partly built on each other. Figure 1.1 shows the general structure of Z-Way with focus on the APIs. The most important part of Z-Way is the Z-Wave core. The Z-Wave core uses the standard Sigma Designs Serial API to communicate with a Z-Wave compatible transceiver hardware but enhanced with some Z-Way specific functions such as Frequency Change. The standard interface is not public but available for owners of the Sigma Designs Development Kit (SDK) ¹ only.

The Z-Wave core services can be accessed directly using the Z-Wave Device API (zDev API). There are two Z-Wave Device API versions available:

- JSON API: All functions are available using a JSON API implemented by an embedded webserver. The "Expert" UI is using this interface and serves both as programmers and installers User Interface to operate the network and as reference implementation to demonstrate the use of this API. The Expert UI is completely written in AJAX Technology.
- C Library API: All functions of the JSON API are available as C library function too. Folder libzway stores all header files with the function prototypes. All function calls and the whole data model are identical. The URL

http://razberry.z-wave.me/fileadmin/z-way-test.tgz provides a sample application written in standard C that makes use of the C level API to demonstrate its application. Makefiles and project files for compilation on Linux and OSX are provided together with the sample code.

The **Z-Wave device API only allows the management of the Z-Wave network** and the control and management of the devices as such. No higher order logic except the so called associations between two Z-Wave devices can be used here.

For all automation and higher order logic a Javascript automation engine is available. This engine is also shipped with Z-Way. There is also a possibility to create your own home automation engine working in addition or instead of the original Z-Way Home Automation engine. The implementation of the Java Script engine is organized in so called modules that

 $^{^{-1}}$ The Sigma Designs SDK is available from Digikey (www.digikey.com). Depending on the hardware options chosen the price varies between 2000 and 4000 USD

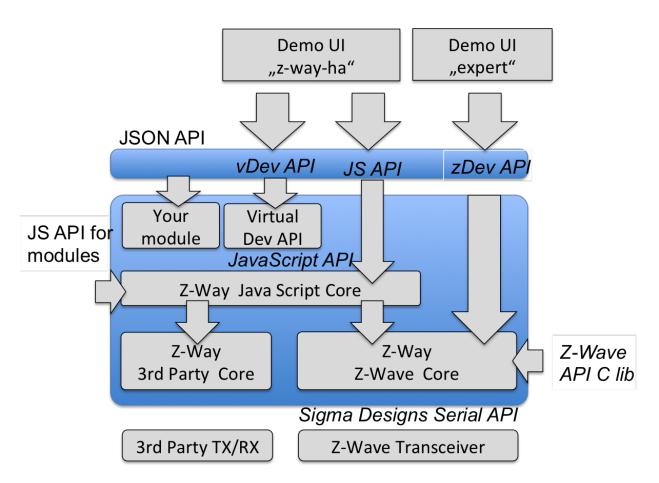


Figure 1.1: Z-Way APIs and their use by GUI demos

implement a broad variety of applications using the underlying Z-Wave devices. The automation logic can also access and use other third party technology stacks such as the EnOcean stack or any technologies based on HTTP.

The Z-Way Home Automation (HA) solution offers multiple prefabricated modules. In addition **Z-Way HA** implements a Virtual Device API (vDev API). The Virtual Devices API uses information from Z-Wave Device API to create virtual devices based in Z-Wave devices and represent them in a unified way to upper level clients using Virtual Device API and provide access to them by JSON based user interfaces. The Demo GUI z-way-ha uses this API and demonstrates the use of the Virtual Device API.

1.2 Quick Start

The best way to learn about Z-Way is to use it. That is why the solutions comes with two reference User Interfaces that can be accesses using a web browser. This allows to built, manage and use a first wireless smart home network with Z-Wave device (and/or with devices using a third party wireless technology such as EnOcean if supported by Z-Way) without writing a single line of code.

Once Z-Way is installed turn your browser to the URL

http://YOURIP:8083/expert

or

http://YOURIP:8083/z-way-ha

to use demonstation UIs available with Z-Way. The port 8083 is predefined (in automation/main.js).

In most cases you will want to control Z-Wave devices with Z-Way. Before a new device can be used, the device needs to be included in the Z-Wave network managed by Z-Way. This management function is accessible in the Expert UI under the Tab 'Network'. Just hit the button "Include new Device" and then confirm the inclusion of the new device by hitting a button on the device or the specific action defined for this device to confirm inclusion.

You may need to refer to the manual of the new device for further information on how to confirm an inclusion by a controller.

The whole Expert UI is described in the Document 'Z-Way Expert User Interface Manual' and therefore no scope of this document.

1.3 API Overview

All communication between the User Interfaces and Z-Way is handled using a web-technology-based JSON interface provided by a built in web server.

There are different Application Programmers Interfaces available for Z-Way that serve different purposes:

- 1. Z-Wave Device API (zDev)
- 2. Third Party Technology APIs

- 3. JavaScript API
- 4. Virtual Device API/Business Logic API (vDev)

1.3.1 Z-Wave Device API

The Z-Wave Device API implements the direct access to the Z-Wave network as such. All Z-Wave devices are referred to by their unique identification in the wireless network - the Node Id. Z-Wave devices may have different instances of the same function, also called channels (for example sockets in a power strip). The Z-Wave Device API refers to them as daughter objects of the physical device object identified by an instance Id. In case there only one instance the instance Id = 0 is used.

All device variables and available commands in a Z-Wave device are grouped in so called command classes. The Z-Wave API allows direct access to all parameters, values and commands of these command class structures.

Beside the devices the Z-Wave Device API also offers access to the management interface of the network. These functions are implemented as so called function classes within the object 'controller' or on the top level 'z-way' object.

The Z-Wave Device API can be accessed on the JSON API using the url path

http://YOURIP:8083/ZWaveAPI/*

Device objects or commands of these objects are accessed by

http://YOURIP:8083/ZWaveAPI/Run/devices[*].*

http://YOURIP:8083/ZWaveAPI/Run/devices[x].instances[y].*

http://YOURIP:8083/ZWave API/Run/devices[x]. instances[y]. command Classes[z]. *

the whole data tree of the Z-Wave network is accessed using

http://YOURIP:8083/ZWaveAPI/Data/*

Attention: The Installer UI is a complete reference of the Z-Wave API. It shows how to use all function it reveals the dynamics of the stack backend and visualizes all internal variables accessible on the API. The chapter 2 describes the Z-Wave Device API in detail.

The section 'Function Classes' in chapter 2.3 explains the different management functions and how they can be used and will use the Expert UI dialogs as application example. The section 'Function Class Reference' in chapter 9 all function classes available.

The control of devices is implemented in Command Classes. The section 'Command Class Implementation' is again using certain dialogs of the Expert UI to explain how to access these functions. The chapter 8 documents all command class functions.

In order to access device and network related data in Z-Way, knowledge of the Z-Way data model is essential. The chapter 7 gives the necessary insight into the data model. All data of Z-Way are exposed on the Expert UI.

1.3. API OVERVIEW 11

1.3.2 Third Party Technology API

Third party Technology APIs implement the same logic as the Z-Wave device API for other wireless technologies such as EnOcean.

For more information please refer to the technology specific descriptions.

1.3.3 JavaScript API (JS API)

The Z-Wave Device API or any other Third Party technology API do not offer any higher order logic support but the pure access to functions and parameters only.

Z-Way offers an automation engine to overcome this restriction. A server-side JavaScript Run time environment allows writing JavaScript modules that are executed within Z-Way (means on the server). The same time all functions of the JS API can also be access on the client side (the web browser). This offers some cool debug and test capabilities. Among others it is possible to write whole JS functions right into the URL or the browser.

The JS API can be accessed from the web browser with the URL

```
http://YOURIP:8083/JS/Run/*
```

Among others the whole Z-Wave Device API is available within the JS API using the object 'zway'. As a result the following three statements refer to the very same function:

- http://YOURIP:8083/ZWaveAPI/Run/devices[3].* Client Side URL access using the Z-Wave Device API.
- 2. http://YOURIP:8083/JS/Run/zway.devices[3].*: Client Side URL access using the JS API
- 3. zway.devices[3].*: Server Side access using the JS and the public zway object

Due to the scripting nature of JavaScript it is possible to 'inject' code at run time using the interface. Here a nice example how to use the Java Script setInterval function:

```
Listing 1.1: Polling of device #2
```

```
^{1} /JS/Run/setInterval(function() { zway.devices[2].Basic.Get(); } , 300*1000);
```

This code will, once 'executed' as URL within a web browser, call the Get() command of the command class Basic of Node Id 2 every 300 seconds.

A very powerful function of the JS API is the ability to bind functions to certain values of the device tree. They get then executed when the value changes. Here is an example for this binding. The device No. 3 has a command class SensorMultilevel that offers the variable level. The following call - both available on the client side and on the server side - will bind a simple alert function to the change of the variable.

```
Listing 1.2: Bind a function
```

2

Chapter 3 and 7 describe the whole JS API in detail. The names and Ids of the different command classes as well as their instance variables can be found in the Annex.

JavaScript modules can and will generate new functions that are accessible using the JSON interface. For simplification function calls on the API (means on the client side) are written in URL style starting with the word 'ZAutomation':

/ZAutomation/JSfunction/JParameter == JSfunction(JParameter)

1.3.4 Virtual Device API

One of the (server side) JavaScript modules already available is a mapping of all physical devices and functions into virtual devices. The purpose of this mapping is to simplify and to unify the implementation of a Graphical User Interface.

All functions and all instances of a physical device - that are represented as daughter objects in the Z-Wave Device API - are enrolled into individual virtual devices.

In case the Z-Wave API shows one single physical device with two channels, while the Virtual Device API will show two devices with similar functionality. In case the Z-Wave API shows a physical device with several different functions (like a binary switch and a analog sensor in one device) the Virtual Device API (vDev API) will show them as several devices with one function each.

The vDev is accessed using the HTTP REST API in a slightly different style than zDev API. All devices, variables and commands are encoded into a URL style for easier handling in AJAX code. A typical client side command in the vDev API looks like

http://YOURIP:8083/ZAutomation/api/v1/devices/ZWayVDev_6:0:37/command/off

'api' points to the vDev API function, 'v1' is just a constant to allow future extensions. The devices are referred by a name that is automatically generated from the Z-Wave Device API. The vDev also unifies the commands 'command' and the parameters, here 'off'.

On the server side the very same command would be encoded in a JavaScript style.

dev = this.controller.devices.get('ZWayVDev_6:0:37'); dev.command('off');

The vDev API also offers support for notifications, locations information, the use of other modules etc. For details please refer to Chapter 5.

1.3.5 Comparison

Table 1.1 summarizes the functions of the different APIs.

For demo and sample code please refer to the following sources:

- 1. **Z-Wave Device API JSON** Expert UI on http://YOURIP:8083/expert
- 2. Z-Wave C Library API Header files in folder /z-way-devel
- 3. JavaScript API Modules in folder /automation
- 4. vDev API z-way-ha UI on http://YOURIP:8083/z-way-ha

²Please note that the Sensor Multilevel Command class data is an array index by the scale Id. Other command classes such as Basic do not have this index but allow direct access using CommandClassName.data.level

1.3. API OVERVIEW 13

| API Type | Core Function | Network | Automation |
|------------------------|------------------------------------|------------|------------|
| | | Management | |
| Z-Wave Dev API (JSON) | Access to physical network and | Yes | No |
| | physical devices via JSON | | |
| Z-Wave Dev API (C lib) | Access to physical network and | Yes | No |
| | physical devices via C style calls | | |
| JavaScript API | Access to physical network and | No | Yes, via |
| | devices plus JS type functions | | zDev |
| vDev API | Unified Access to functions of de- | No | Yes |
| | vices, optimized for AJAX GUI | | |

Table 1.1: Different APIs of the Z-Way system

Chapter 2

The Z-Wave Device API

This chapter describes the Z-Wave Device API and its use in detail All examples will use the HTTP/JSON API notation. Please note that the C library notation offers equal functionality. The Z-Wave Device API is the north bound interface of the Z-Wave Core. This Z-Wave core implement the whole control logic of the the Z-Wave network. The two main functions are

- Management of the network. This includes including and excluding devices, managing the routing and rerouting of the network an executing some housekeeping functions to keep the network clean and stable. In the Z-Wave terminology all these functions are called 'function classes' and they are described in section 2.3. The function classes can be seen as functions offered by the controller itself. Hence the variables and status parameters of the networks are offered by an object called 'controller'.
- Execution of commands offered by the wireless devices as such switching switches and dimming dimmers. Z-Wave groups the command and their corresponding variables into so called command classes. The Z-Wave API offers access to these command classes with their variables and their commands according to the abilities od the respective device.

The next chapters first explain the timings of the communication in a wireless Z-Wave network. Then the data model is presented that reflects the real data and status information in the network.

The description of function Classes and command Classes and their access using the JSON API complete the description of the Z-Wave Device API. For a full reference of function classes and command classes please refer to the Annex.

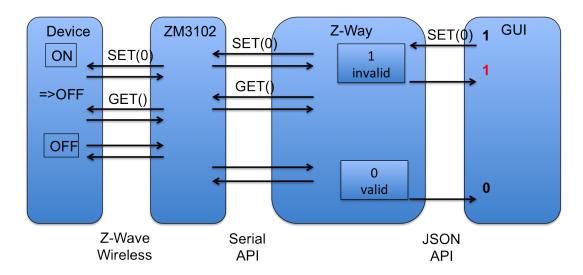


Figure 2.1: Z-Way Timings

2.1 Executing a command from the GUI to the device and back

Please note that all status variables accessible on the Z-Wave Device APIs are only proxy of the real value in the network.

To transport data between the real wireless device and the GUI multiple communication instances are involved. The complexity of this communication chain shall be explained in the following example:

Assuming the GUI shows the status of a remote switch and allows to change the switching state of this device. When the user hits the switching button he expects to see the result of his action as a changing status of the device in the GUI. The first step is to hand over the command (SET) from the GUI to Z-Way using the JSON interface. Z-Way receives the command and will confirm the reception to the GUI. Z-Way recognizes that the execution of the switching command will likely result in a change of the status variable However Z-Way will not immediately change the status variable but invalidate the actual value (mark as outdated). This is the correct action because at the moment when the command was received the status on the remote device has not been changed yet but the status of the switch is now unknown. If the GUI polls the value it will still see the old value but marked as invalid. Z-Way will now hand over the switching command to the Z-Wave transceiver chip. Since it is possible that there are other command waiting for execution (sending) by the Z-Wave transceiver chip the job queue is queuing them and will handle certain priorities if needed. Z-Way has recognized that the command will likely change the status of the remote device and is therefore adding another command to call the actual status after the switching command was issued. The transceiver is confirming the reception of the command and this confirmation is noted in the job queue. This confirmation however only means that the transceiver (Z-Wave chip) has accepted the command and does neither indicate that the remote device has receives it nor even confirming that the remote device has executed accordingly. The transceiver will now try to send the command wirelessly to the remote device. A successful confirmation of the reception from the remote device is the only valid indicator that

the remote device has received the command (again, not that it was executed!). The second command (GET) is now transmitted the very same way and confirmed by the remote device. This device will now sent a REPORT command back to Z-Way reporting the new status of the switching device. Now the transceiver has to confirm the reception. The transceiver will then send the new value to the Z-Way engine by issuing commands via the serial interface. Z-Way receives the report and will update the switching state and validate the value. From now on the GUI will receive a new state when polling.

2.2 The Z-Wave Device API Data model

Z-Way holds all data of the Z-Way network in a data holder structure. The data holder structure is a hierarchical tree of data elements.

Following the object-oriented software paradigm the different commands targeting the network or individual devices are also embedded into the data objects as object methods.

Each data element is handled in a data object that contains the data element and some contextual data.

2.2.1 The Data object

Each Data element such as devices[nodeID].data.nodeId is an object with the following child elements:

- value: the value itself
- name: the name of the data object
- updateTime: timestamp of the last update of this particular value
- invalidateTime: timestamp when the value was invalidated by issuing a Get command to a device and expecting a Report command from the device

Every time a command is issued that will have impact on a certain data holder value the time of the request is stored in "invalidateTime" and the "updated" flag is set to "False". This allows to track when a new data value was requested from the network when this new data value was provided by the network.

This is particularly true if Z-Way is sending a SET command. In this case the data value is invalidated with the "SET" commands and gets validated back when the result of the GET command was finally stored in the data model.

To maintain compatibility with Javascript the data object has the following methods implemented

- valueOf(): this allows to obmit .value in JS code, hence write as an example data.level = 255
- updated(): alias to updateTime
- invalidated(): alias to invalidateTime

These aliases are not enumerated if the dataholder is requested (data.level returns value: 255, name: "level", updatedTime: 12345678, invalidatedTime: 12345678).

2.2.2 The Data and Method Tree

The root of the data tree has two important child objects:

- controller, this is the data object that holds all data and methods (commands, mainly function classes) related to the Z-Way controller as such
- devices array, this is the object array that holds the device specific data and methods (commands, mainly command classes).

Chapter 7 gives a complete overview of the data and method tree.

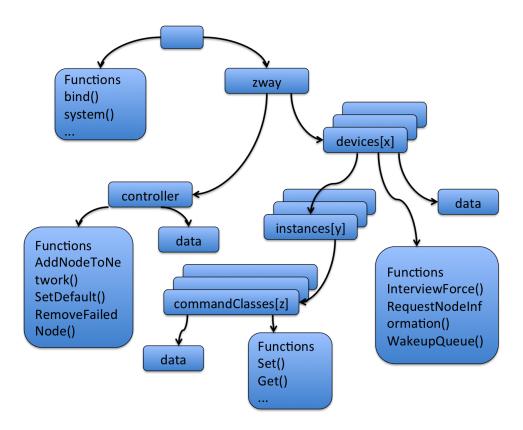


Figure 2.2: Z-Way Object Tree Structure

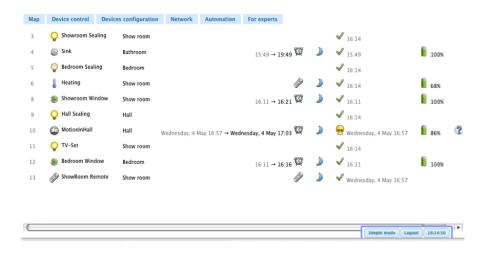


Figure 2.3: Demo UI Dialog for Device Status

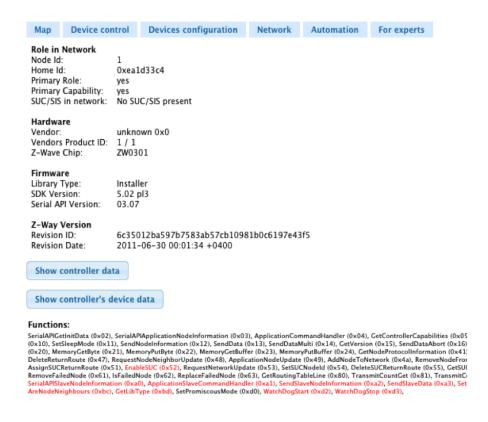


Figure 2.4: Demo UI Dialog for Controller information

2.2.3 Device Data Visualization

One example how to use the Data in the object tree is the device status page provided by the demo user interface in tab "Device Control" of the Expert UI.

This tab gives an overview of the network status and the availability of each device. It shows the time stamp of the last interaction between the controller and the device. For battery powered devices the battery charging status, the time of the last wakeup and the estimated time for the next wakeup is shown. An info icon indicates when the interview of a device was not completed. Clicking on this device opens a window showing the interface status by command class. Please refer to the manual section Interview for more information about the interview process.

The controller information tab shows all controller information. The buttons Show Controller Data shows the internal Z-Way data structure related to the specific controller function of the controller device. The button Show controller device data show the generic device related data of the controller device.

The information given on this page is only relevant for advanced Z-Wave developers and for debugging.

2.2.4 Commands to control Z-Way itself

The last set of commands and values are not related to the Z-Wave network or the Z-Wave devices but to Z-Way itself. Chapter 7 lists all the commands and the values.

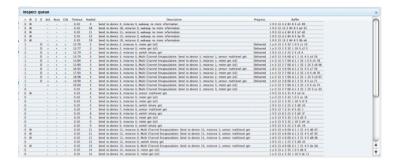


Figure 2.5: Job Queue Vizualization in Demo UI

2.2.5 Job Queue Handling

The Job handling system is the core and heart of Z-Way. It is managing the different Function class and command class calls to the Z-Wave network and dispatches incoming messages. Every communication with the Z-Wave transceiver is scheduled into a job and queued that it can transmitted over the serial hardware interface. The API allows to look into the work of the job queue. The demo UI shows the Job queue under Tab "Network" but in expert mode only.

The table shows the active jobs with their respective status and additional information. Table 2.1 summarizes the different values displayed on the Job Queue visualization. While these infos are certainly not relevant for end users of the system it is a great debug tool.

| n | This column shows the number of sending attempts for a |
|-------------|--|
| | specific job. Z-??Way tries three times to dispatch a job |
| | to the transceiver. |
| W,S,D: | This shows the status of the job. If no indicator is shown |
| | the job is in active state. This means that the controller |
| | just tries to execute the job. 'W' states indicated that |
| | the controller believes that the target device of this job is |
| | in deep sleep state. Jobs in 'W' state will remain in the queue to the moment when the target devices announces |
| | its wakeup state by sending a wakeup notification to the |
| | controller. Jobs in 'S' state remain in the waiting queue to |
| | the moment the security token for this secured information |
| | exchanged was validated. 'D' marks a job as done. The |
| | job will remain in the queue for information purposes until |
| A CITY | a job garbage collection removed it from the queue. |
| ACK: | shows if the Z-Wave transceiver has issued an ACK mes- |
| | sage to confirm that the message was successfully received by the transceiver. This ACK however does not confirm |
| | that the message was delivered successfully. A success- |
| | ful delivery of a message will result in a D state of this |
| | particular job. If the ACK field is blank, then no ACK |
| | is expected. A . indicates that the controller expects an |
| | ACK but the ACK was not received yet. A + indicates |
| | that an ACK was expected and was received. |
| RESP | shows if a certain command was confirmed with a valid |
| | response. Commands are either answered by a response or |
| | a callback. If the RESP field is blank, then no Response is expected. A . indicates that the controller expects a |
| | Response but the Response was not received yet. A + |
| | indicates that a Response was expected and was received. |
| Cbk | If the Cbk field is blank, then no callback is expected. |
| | A . indicates that the controller expects a Callback but |
| | the Callback was not received yet. A + indicates that a |
| - | Callback was expected and was received. |
| Timeout | Shows the time left until the job is de queued |
| Node Id | shows the id of the target node. Communication concerning the protection of the prot |
| | ing the network like inclusion of new nodes will have the controller node id as target node ID. For command classes |
| | command the node ID of the destination Node is shown. |
| | For commands directed to control the network layer of the |
| | protocol, the node id is zero. |
| Description | shows a verbal description of the job |
| Progress | shows a success or error message depending on the delivery |
| | status of the message. Since Z-Way tries three times to |
| | deliver a job up to 3 failure messages may appear. Buffer: |
| | shows the hex values of the command sent within this |
| | job |

Table 2.1: Parameters of the Job Queue Vizualization

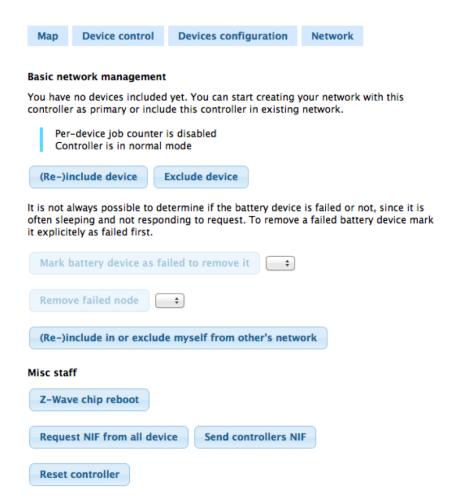


Figure 2.6: Expert UI Dialog for Networking functions

2.3 Function Class Implementation

The commands used to control the controller itself and ot manage the Z-Wave network are called 'function classes'. Most function classes used in the Sigma Designs Serial API are used by the Z-Way lower layer function only but some of them are exposed to the Z-Wave Device API to allow user interactions and network management.

The Expert UI is an excellent reference for the Function Classes. All relevant functions can be monitored 'in action'. Hence the description of the network tab of the Expert UI is more or less a complete reference to the function classes needed in a UI implementation.

2.3.1 Inclusion

You can include devices by pressing the 'Include Device' button. This turns the controller into an inclusion mode that allows including a device. A status information line indicates this status. The inclusion of a device is typically confirmed with a triple press of a button of this particular

device. However, please refer to the manual of this particular device for details how to include them into a Z-Wave network. The inclusion mode will time out after about 20 seconds or is aborted by pressing the 'Stop Include' button.

If the network has a special controller with SIS function (Z-Way will try to activate such as function on default, hence this mode should always be active if the USB hardware used by Z-Way supports it) the inclusion of further devices can also be accomplished by using the include function of any portable remote control which is already included into the network. A short explanation above the include button will inform about the ways devices can be included.

The Inclusion function is implemented using the function class **AddNodeToNetwork(flag)** with flag=1 for starting the inclusion mode and flag=0 for stopping the inclusion mode. Please refer to the chapter 9 for details on how to use this function.

2.3.2 Exclusion

You can exclude devices by pressing the 'Exclude Device' button. This turns the controller into an exclusion mode that allows excluding a device. The exclusion of a device is typically confirmed with a triple press of a button of this particular device as well. However, please refer to the manual of this device for details how to exclude them into a Z-Wave network. The exclusion mode will time out after about 20 seconds or is aborted by pressing the 'Stop Exclude' button. It is possible to exclude all kind of devices regardless if they were included in the particular network of the excluding controller.

If a node is not longer in operation it cant be excluded from the network since exclusion needs some confirmation from the device. Please use the 'Remove Failed Node' function in this case. Please make sure that only failed nodes are moved this way. Removed but still function nodes - called phantom nodes will harm the network stability.

The Exclusion function is implemented using the function class **RemoveNodeToNetwork(flag)** with flag=1 for starting the exclusion mode and flag=0 for stopping the exclusion mode. Please refer to the chapter 9 for details on how to use this function.

2.3.3 Mark Battery powered devices as failed

This function allows marking battery-powered devices as failed. Only devices marked as failed can be excluded from the network without using the exclusion function. Typically multiple failed communications with a device result in this marking. Battery powered devices are recognized as sleeping in the controller and therefore all communication attempts with this device will be queued until a wakeup notification from this device is received. A faulty battery operated device will never send a wakeup notification and hence there is never a communication, which would result in a failed node status. Battery operated devices can therefore be manually marked as faulty. Make sure to only mark and subsequently remove devices that are faulty or have disappeared. A device, which was removed with this operation but is still functioning may create malfunctions in the network.

This function is no Function class but sets the internal 'failed' variable of the device object.

2.3.4 Remove Failed Nodes

Z-Way allows removing a node, if and only if this node was detected as failed by the Z-Wave transceiver. The network will recognize that communication with a device fails multiple times and the device cant be reached using alternating routes either. The controller will then mark the device as 'failed' but will keep it in the current network configuration. Any successful

communication with the device will remove the failed mark. Only devices marked as failed can be removed using the 'Remove Failed Node' function.

If you want to remove a node that is in operation use the 'Exclude' Function.

This function is implemented using the function class **RemoveFailedNode(node id)** with node id as the node id of the device to be removed. Please refer to the chapter 9 for details on how to use this function. It is also possible to replace a failed node by a new node using the function class **RemoveFailedNode(node id)**. Please refer to the chapter 9 for details too.

The function **IsFailedNode(node id)** can be used to detect if a certain node is failed. The Z-Wave transceiver will try to contact the device wirelessly and will then update the failed-status inside the transceiver and also the 'is failed' flag of the device object in Z-Way.

2.3.5 Include into different network

Z-Way can join a Z-Wave network as secondary controller. It will change its own Home ID to the Home ID of the new network and it will learn all network information from the including controller of the new network. To join a different network, the primary controller of this new network need to be in the inclusion mode.

Z-Way needs to be turned into the so called learn mode using the button 'Start Include in others network'. The button Stop Include in others network can be used to turn off the Learn mode, which will time out otherwise or will stop if the learning was successful.

Please be aware that all existing relationships to existing nodes will get lost when the Z-Way controller joins a different network. Hence it is recommended to join a different network only after a reset with no other nodes already included.

The 'Learn' function is implemented using the function class **SetLearnMode(flag)** with flag=1 for starting the learn mode and flag =0 for stopping the learn mode. Please refer to the chapter 9 for details on how to use this function.

2.3.6 Z-Wave chip reboot

This function will perform a soft restart of the firmware of the Z-Wave controller chip without deleting any network information or setting. It may be necessary to recover the chip from a freezing state. A typical situation of a required chip reboot is if the Z-Wave chip fails to come back from the inclusion or exclusion state.

The reboot function is implemented using the function class **SerialAPISoftReset()**. Please refer to the chapter 9 for details on how to use this function.

2.3.7 Request NIF from all devices

This function will call the Node Information Frame from all devices in the network. This may be needed in case of a hardware change or when all devices where included with a portable USB stick such as e.g. Aeon Labs Z-Stick. Mains powered devices will return their NIF immediately, battery operated devices will respond after the next wakeup.

This function controls a Z-Way controller function that will send out a function class **RequestNodeInformation(node)** to all nodes in the network. The function can also be called for one single node only. Please refer to the chapter 9 for details on how to use this function.

2.3.8 Send controllers NIF

In certain network configurations it may be required to send out the Node Information Frame of the Z-Way controller. This is particularly useful for some some remote controls scene activation function. The manual of the remote control will refer to this requirement and give further information when and how to use this function.

This function is implemented with the function class **SerialAPIApplicationNodeInfo** with plenty of parameters. These parameters are partly set by Z-Way but particularly the Command classes supported (parameter 'NIF') can be changed by editing the file defaults.xml. Please refer to the chapter 9 for details on how to use this function the chapter about the translation files on how to change defaults.xml

2.3.9 Reset Controller

The network configuration (assigned node Ids and the routing table and some other network management specific parameters) is stored in the Z-Wave transceiver chip and will therefore even survive a complete reinstallation of the Z-Way software.

The function 'Reset Controller' erases all values stored in the Z-Wave chip and sent the chip back to factory defaults. This means that all network information will be lost without recovery option.

This function is implemented with the function class **SetDefault()**. Please refer to the chapter 9 for details on how to use this function.

2.3.10 Change Controller

The controller change function allows to handover the primary function to a different controller in the network. The function works like a normal inclusion function but will hand over the primary privilege to the new controller after inclusion. Z-Way will become a secondary controller of the network. This function may be needed during installation of larger networks based on remote controls only where Z-Way is solely used to do a convenient network setup and the primary function is finally handed over to one of the remote controls.

This function is implemented with the function class **ControllerChange()**. Please refer to the chapter 9 for details on how to use this function.

2.3.11 SUC/SIS Management

This interface allows controlling the SUC/SIS function for the Z-Wave network. All these functions are almost obsolete and only needed for certain enhanced configurations of the Z-Wave network. Unless you really know what you do - don't use these functions!

The following Function Classes are mapped to the demo user interface functions for SUC/SIS manipulation:

- GetSUCNodeId get the SUC Node ID from the network
- \bullet Enable SUC - enables the SUC function in Z-Way, this is done by default if the transceiver firmware used supports SUC
- SetSUCNodeId assign SUC function to a node in the network that is capable of running there SUC function.
- SendSUCNodeId inform a different node about the node ID of a SUC in the system

| Mark battery device as failed to remove it |
|--|
| Remove failed node ÷ |
| (Re-)include in or exclude myself from other's network |
| Change controller |
| SUC/SIS management |
| No SUC/SIS present |
| Get SUC node Id Request network updates from SUC/SIS |
| Assign SUC Assign SIS Disable SUC/SIS on node 1 ÷ |
| Misc staff |
| Z-Wave chip reboot |
| |
| Request NIF from all device Send controllers NIF |
| Reset controller |

Figure 2.7: Demo UI Dialog for Networking functions - experts functions

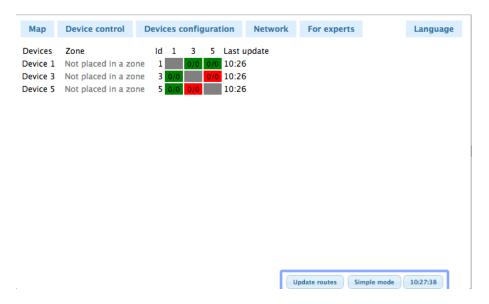


Figure 2.8: Demo UI dialog for Routing Table

2.3.12 Routing Table

The routing table of the Z-Wave network is shown in the tab network as well. It indicates how two devices of the Z-Wave network can communicate with each other. If two devices are in direct range (they can communicate without the help of any other node) the cross point of the two devices in the table is marked as dark green. The color light green indicates that the two nodes are not in direct range but have more than one alternating routes with one node between. This is still considered as a stable connection. The yellow color indicates that there are less than two one-hop routes available between the two nodes. However there may be more routes but with more nodes between and therefore considered as less stable.

A red indicator shows that there are no good short connections between the two nodes. This does not mean that they are unable to communicate with each other but any route with more than 2 routers between Z-Way is considering as not reliable, even taking into account that Z-Wave supports routes with up to four devices between. Grey cells indicate the connection to the own Node ID.

The general rule of thumb is: 'The greener the better'.

The table lists all nodes on the y-axis and the neighborhood information on the x-axis. On the right hand side of the table a timestamp shows when the neighborhood information for a given node was reported.

In theory the table should be totally symmetric, however different times of the neighborhood detection may result in different neighborhood information of the two devices involved.

The neighbor information of the controller works with an exception. The Z-Wave implementation used in current Z-Wave transceiver does not allow requesting an update of the neighbor list for the controller itself. The neighborhood information displayed for the controller is therefore simply wrong.

Battery powered devices will report their neighbors when woken up and report their mains powered neighbor correctly. However mains powered devices will report battery-powered devices as neighbors only when routes are updated twice. This is less critical because battery powered

devices cant be used as routers and are therefore not relevant for calculating route between two nodes anyway.

The context menu command 'Network Reorganization' allows re-detecting all neighborhood information (battery powered devices will report after their next wakeup!) Please refer to the manual section 'Network Stability' for further information about the use of this function.

The routing table is stored in the Z-Wave transceiver and can be read using the function class **GetRoutingTableLine(node id)** for a given node ID. The function **RequestNodeNeighbourUpdate(nodeid)** will cause a certain node Id to redirect its wireless neighbors. It makes sense to call the GetRoutingTable function right after successful callback of the RequestNodeNeighbourUpdate function.

2.4 JSON-API

JSON API allows to execute commands on server side using HTTP POST requests (currently GET requests are also allowed, but this might be deprecated in future). The command to execute is taken from the URL.

All functions are executed in form

http://YOURIP:8083/<URL>

2.4.1 /ZWaveAPI/Run/<command>

This executes zway.<command> in JavaScript engine of the server. As an example to switch ON a device no 2 using the command class BASIC (The ID of the command class BASIC is 0x20, for more information about the IDs of certain command classes please refer to the Annex) its possible to write:

```
/ZWaveAPI/Run/devices[2].instances[0].commandClasses[0x20].Set(255)
```

or

```
/ZWaveAPI/Run/devices[2].instances[0].Basic.Set(255)
```

The Z-Way Expert GUI has a JavaScript command runCmd(<command>) to simplify such operations. This function is accessable in the JavaScript console of your web browser (in Chrome you find the JavaScript console unter View->Debug->JS Console). Using this feature the command in JS console would look like

```
runCmd('devices[2].instances[0].Basic.Set(255)')
```

The usual way to access a command class is using the format 'devices[nodeId].instances[instanceId]. commandClasses[commandclassId]'. There are ways to simplify the syntax:

- 'devices[nodeId].instances[instanceId].Basic' is equivalent to 'devices[nodeId].instances[instanceId].commandClasses[0x20]'
- \bullet the instances [0] can be obmitted: 'devices [nodeId].instances [instanceId].Basic' then turns into 'devices [nodeId].Basic'

Each Instance object has a device property that refers to the parent device it belongs to. Each Command Class Object has a device and an instance property that refers to the instance and the device this command class belongs to.

Data holder object have properties value, updateTime, invalidateTime, name, but for compatibility with JS and previous versions we have valueOf() method (allows to omit .value in JS code, hence write "data.level == 255"), updated (alias to updateTime), invalidated (alias toinvalidateTime). These aliases are not enumerated if the dataholder is requested (data.level returns value: 255, name: "level", updatedTime: 12345678, invalidatedTime: 12345678).

2.4.2 /ZWaveAPI/InspectQueue

This function is used to visualize the Z-Way job queue. This is for debugging only but very useful to understand the current state of Z-Way engine.

2.4. JSON-API 31

2.4.3 /ZWaveAPI/Data/<timestamp>

Returns an associative array of changes in Z-Way data tree since <timestamp>. The array consists of (<path>: <JSON object>) object pairs. The client is supposed to assign the new <JSON object> to the subtree with the <path> discarding previous content of that subtree. Zero (0) can be used instead of <timestamp> to obtain the full Z-Way data tree.

The tree have same structure as the backend tree (Figure 2.2) with one additional root element "updateTime" which contains the time of latest update. This "updateTime" value should be used in the next request for changes. All timestamps (including updateTime) corresponds to server local time.

Each node in the tree contains the following elements:

- \bullet value the value itself
- updateTime timestamp of the last update of this particular value
- invalidateTime timestamp when the value was invalidated by issuing a Get command to a device and expecting a Report command from the device

The object looks like:

Listing 2.1: JSON Data Structure

```
7 {
8 "[path from the root]": [updated subtree],
9 "[path from the root]": [updated subtree],
10 ...
11 updateTime: [current timestamp]
12 }
```

Examples for Commands to update the data tree look like:

```
Get all data: /ZWaveAPI/Data/0
```

Get updates since 134500000 (Unix timestamp): /ZWaveAPI/Data/134500000

Please note that during data updates some values are updated by big subtrees. For example, in Meter Command Class value of a scale is always updated as a scale subtree by [scale].val object (containing scale and type descriptions).

2.4.4 Handling of updates coming from Z-Way

A good design of a UI is linking UI objects (label, textbox, slider, ...) to a certain path in the tree object. Any update of a subtree linked to UI will then update the UI too. This is called bindings.

For web applications Z-Way Web UI contains a library called jQuery.triggerPath (extention of jQuery written by Z-Wave.Me), that allows to make such links between objects in the tree and HTML DOM objects. Use

```
var tree;
```

jQuery.triggerPath.init(tree);

during web application initialization to attach the library to a tree object. Then run

jQuery([objects selector]).bindPath([path with regexp], [updater function], [additional arguments]);

to make binding between path changes and updater function. The updater function would be called upon changes in the desired object with this pointing to the DOM object itself, first argument pointing to the updated object in the tree, second argument is the exact path of this object (fulfilling the regexp) and all other arguments copies additional arguments. RegExp allows only few control characters: * is a wildcard, (1-2-3) - is 1 or 2 or 3.

Please not that the use of the triggerpath extension is one option to handle the incoming data. You can also extract all the interesting values right when the data is received and bind update functions to them.

2.5 Command Class Implementation

Z-Wave device functions are controlled by command classes. A command class can be have one or multiple commands allowing the use of a certain function of the device. Command classes are organized by functions, e.g. the command class "Switch Binary" allows to switch a binary switch. Hence the number of supported command classes defines the functionality and the value of a device

Z-Wave defines quite a few command classes but a lot of them are not implemented in any device. Hence, Z-Way will not implement them either. Command Classes consist of two types of commands:

- commands for users, most of them are either "GET" commands asking for a value or status from a remote device, or they are "SET" commands setting a certain value and therefore causing a certain action.
- commands for configuration

The commands for configuration are used by Z-Way to build the data model used and to manage the device itself but they are not made public for users. The command classes available for users are listed in chapter 8.

Commands to Z-Wave devices take time to be executed. In case the device is awake (mains powered or FLIRS) the delay may be well below one second but for battery powered devices the controller has to wait for the next scheduled wakeup in order to send the command.

In case the command is calling a value update from e.g. a sensor the successful execution of the command only means that the request was accepted by the wireless device. In order to really update a value the device itself needs to send a wireless command back to the controller that needs to be accepted by the controller.

Each data element that is available in a remote wireless device (e.g. a switch) is also stored in Z-Way. First of all there is the assumption that the data value of the remote device and the corresponding data value in Z-Way are identical.

Most commands of command classes are eighter a "GET" asking for an update of an value or they are a "SET" - setting a new value. Setting a new value may also cause an action on the remote side. As an example switching a binary switch means in Z-Wave command classes changing the switching state value wirelessly.

Z-Way will never "just" update the local corresponding value of the real remote value but always ask the remote device after a successful "SET" command for an update of the remote value using a "GET" command. This means that the local - displayable - value of a certain remote device will only update after some delay.

The process can be examined using the "Device Control" dialog in the Expert User Interface.

2.5.1 Switch Overview

This page gives a table style overview of all actuators of the Z-Wave network. Actuators are devices with some kind of switching function such as

- Digital (on/off) switches,
- Light Dimmer,
- Motor Controls for Venetian blinds, window bind,
- Motor Control to open/close doors and windows.



Figure 2.9: Demo UI Dialog for Switches



Figure 2.10: Demo UI Dialog for Sensors

Beside the name of the device, the location and the type of device the actual status and the timestamp of this status are shown.

Of course it is possible to switch the devices and to update the status of the device.

A little icon indicates how the device will react to a switch all devices command (will switch, will not switch, will react to off command only or to on command only).

The commands to control the different actors apply the command classes "Switch Multilevel" and "Switch Binary". Please refer to Chapter 8 for details how to use these command classes.

2.5.2 Sensor Overview

This page gives a table style overview of all sensors of the Z-Wave network. Sensors are devices able to report measured values. Sensors can report binary or analog values. Beside the name of the device, the location and the type of sensor the actual sensor value and the timestamp of this value are shown. It is possible to ask for an update of the sensor value.

The update command of the sensor interface and the values shown are using the command classes "Sensor Multilevel" and "SensorBinary". Please refer to Chapter 8 for details how to use these command classes.

2.5.3 Meter Overview

This page gives a table style overview of all meters of the Z-Wave network. Meters are devices able to report accumulated values. Beside the name of the device, the location and the type of meter the actual meter value and the timestamp of this value are shown. It is possible to ask for an update of the meter value.

The update command of the meter interface and the values shown are using the command class "Meter". Please refer to Chapter 8 for details how to use the meter command class.

2.5.4 Thermostat Overview

This page gives a table style overview of all thermostats of the Z-Wave network. Depending on the thermostat capabilities reported, the dialog will allow to change the thermostat mode and/or change the setpoint temperature for the thermostat mode selected.

Please refer to Chapter 8 for details how to use the thermostat setpoint and thermostat mode command classes.

2.5.5 Door Lock Overview

This page gives a table style overview of all door locks of the Z-Wave network. Depending on the door lock reported, the dialog will allow to open/close the door and differentiate on door handles.

Please refer to Chapter 8 for details how to use the door lock, user code and door lock logging command classes.

2.5.6 Device Configuration

Beside the command class to directly control devices and update device values there are more commands that are used to built the data model of the device and to get configuration values.

The device also allow certain configurations itself. The demo UI shows the use of these command classes in the Tab "Device Configuration". The device configuration fulfills three basic tasks:

- The interview process after inclusion of the device
- The configuration of the device according to user requirements and needs.
- Setting Cause/effect relationships. This means that certain devices can directly control other devices.

2.5.7 Interview Process

After the inclusion of a new device Z-Way will interview this very device. The interview is a series of commands Z-Way is sending to the device in order to learn the capabilities and functions of this device.

Depending on the capabilities announced in the Node Information Frame that was received during the inclusion, Z-Way will ask further questions to get more detailed information. The interview process may take some seconds since more questions may be required to ask depending in certain answers given. Since all functions of a device are grouped in so called Command Classes each command class announced in the Node Information frame will typically cause its part of the interview. The interview will be executed in three different steps:

- 1. In case there is a Version Command Class ask for the Version of the device and the versions of all Command Classes announced in the Node Information frame. Otherwise Version 1 is assumed.
- 2. In case there is a Multi Channel Command class announced, ask for the number of the capabilities of the different channels and repeat Step 3 for each channel.
- 3. Ask for all capabilities of all command classes.

4. Do some auto configurations if needed.

The Device Status tab will indicate if the interview was successfully completed. The blue information icon shows if the interview was not complete. Clicking on this icon opens a dialog with all command classes and the status of their respective interviews. A complete interview is important in order to have access to all functions of the device included. Incomplete interviews may also be a reason for malfunctions of the network. There are several reasons why an interview may not be completed.

- 1. A battery-operated device may be gone into sleep mode too early. In this case it is possible to wake up the device manually to complete the interview. Sometimes manual wakeup is needed several times.
- 2. The device does not fully comply with the Z-Wave protocol. This is particularly possible for devices that were brought to market before 2008. The current more sophisticated certification process makes sure that devices are 100% compatible to the Z-Wave product when they hit the market. Please check online ressources on wikis and forums for further details and possible ways to fix these kinds of problems.
- 3. The device does not have a reliable communication route to the controller. Interview communication typically use longer packets than normal polling communication. This makes the interview communication more vulnerable against weak and instable communication links. Its possible that the controller is able to include a device and even receive confirmation of a polling request but still not being able to complete the interview. However this is a rare case.
- 4. The device may be simply broken.

Most of the command exchange during interview is using commands dedicated for the interview process. They are not exposed on the API.

2.5.8 Device Configuration

Each Z-Wave device is designed to work out of the box after inclusion without further configuration. However, it may be suitable and in certain contexts even required to do a device specific configurations.

The device configuration page allows to further configure the device and to access certain additional information about the device. The tab is grouped into several sections. The sections can be toggled from invisible to visible and back by clicking on the headlines:

- Select Z-Wave Device Description Record
- Device Description
- Configurations
- Actions with configurations
- Advanced Actions

Select Z-Wave Device Description Record After a successful inclusion Z-Way will interview the device to gather further information.

Certain information such as names of association groups, the brand name of the device and the parameters of further configuration values can not be detected during interview. Z-Way uses a device database with product description files to obtain this information. In order to identify the right device description record, certain parameters of the interview are used. If these parameters match exactly one device description record, this very record is loaded and its content is shown on the device configuration page automatically.

If the information from the device is sufficient to select one specific record from the database this section of the tab is hidden. If it is not possible to identify the correct device description record the user can manually choose the correct record. It is also possible to manually change the selection of the device description by unhiding this section and clicking on the Select Device Description Record button.

Device Description The upper part of the dialog shows some descriptive values of the device. The Z-Wave device type is the only value generated solely from the interview data. All other data are taken from the device description record.

- Zone: ... the zone/room the device is assigned to. Will be manually defined in Zone-tab.
- Brand: the product code or brand name of the device. This will be taken from the device description record.
- Device Type: ... the type of Z-Wave device as reported by the device during inclusion.
- Description: a verbal description of the function. This will be taken from the device description record.
- Interview Stage: shows the progress of the interview process. This information is generated by Z-Way.
- Inclusion Note: how to (re-) include the device. This will be taken from the device description record.
- Wakeup Note: this will be taken from the device description record.
- Documents: If the device description record offers links to manuals or other online documents there are shown here. This will be taken from the device description record.
- Device State: Status of the device plus number of packets queued for this device

There are a couple of reasons why no device description record was found:

- There is no record for the device available. Since there are always new devices on the market Z-Way needs to catch up and update its device database. If your device is not found, updating to the most recent version of Z-Way may help.
- 2. The interview was not finished to the point where enough parameters were detected to identify the correct device description record. You may manually choose the correct device description record using the button Select Device Description Record. A dialog box will be opened for manual selection of the product (if available). The manual selection of a device description record is only needed if no record was found on default.

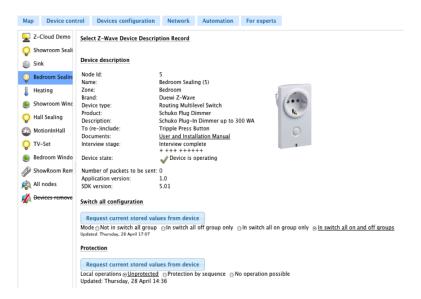


Figure 2.11: Demo UI Dialog for Sensors

- 3. The interview of the device was completed but the device does not offer enough information to identify the correct device. You may manually choose the correct device description record using the button Select Device Description Record. A dialog box will be opened for manual selection of the product (if available). The manual selection of a device description record is only needed if no record was found on default.
- 4. There is more than one device description record matching the information gathered during interview. This is particularly possible if a vendor sells devices with different firmware and functions without properly updating the firmware version information. You may manually choose the correct device description record using the button Select Device Description Record. A dialog box will be opened for manual selection of the product (if available). The manual selection of a device description record is only needed if no record was found on default.

Device Configuration This section will, if device description record is loaded, show device specific configuration values including their possible parameters and a short description of the configuration value. You may change these values according to your needs.

Actions with configurations The most important action in regard to the configuration is to apply the configuration to the device. This is only done when the button Apply configuration for this device is hit. This button is therefore even shown, when the rest of the tab part is hidden.

- Mains Powered Devices: The settings will become effective immediately after hitting the button.
- Battery Powered Devices: The settings will become effective after the next wakeup of the device, as shown in the Device Status tab.

• Battery Powered Controllers (remote controls or wall controllers): The settings will only become effective if the devices are woken up manually. Refer to the controller manual for more information on how to wake up the device. Appendix B may also give further advice.

If there are many similar devices in a network, it is desirable to just apply one working configuration to all these devices. This can be done using the function 'Copy from other Device'.

The set of defined configuration values is stored for every device. Therefore its possible to pick a different device and reuse its configuration values for the device to be configured. The Save function of the bottom context menu allows saving the configuration for further use and reuse

Actions with configurations This function requests the selected device to send its Node Information frame (NIF) to the controller. It can be used instead of triple pressing a button on the device itself that would also instruct the device to send it NIF. The NIF is needed to know device capabilities.

Delete Configuration of this device in section Actions with configuration This function deletes the stored configuration for this device. This function is for debugging purposes only.

Force Interview in section Advanced This functions forces to redo the whole interview. All previous interview data will be deleted. This function is for debugging purposes only.

Show Interview Results in section Advanced This function shows the result of the interview. This function is for debugging purposes only. For information about reasons for incomplete interview please refer to the manual section Device Status.

The bottom context menu function Reset Configuration deletes all configurations stored in Z-Way, but does not affect devices!

The configuration dialog documents the use of the command classes "Association", "Protection", "Configuration" and "Switch All".

2.5.9 Associations

If there was no previous device of the same type installed, the interface will show the values as read from the device. If there was already a device of the same kind installed, there may exist a stored default configuration for this particular device. Then the setup in the device may differ from the default configuration stored in Z-Way.

- Gray Icon: This Node ID is stored in the device but its not stored in the default configuration of the Z-Way. You can double click this device to store this setting in the Z-Way default configuration of this device type.
- Red Icon: This Node ID is stored locally but not in the association group of the device yet. Apply the settings to transmit the setting into the device. In case of a battery operated device you need to wakeup the device in order to store the configuration.
- Black Icon: This Node ID is stored both in the device and in the local configuration of Z-Way.

Hint: The auto configuration function of Z-Way will place the node ID of the Z-Way controller in all association groups if possible. This allows the activation of scenes from these devices.

All management of Associations is handled by the command class "Association", In case the target device is a multi channel device the command class "Multi Channel Association" is used. Please refer to chapter 8 for details how to use these command classes.

Chapter 3

JavaScript API

The JavaScript API mirrors all functions of the Z-Wave device API and combines them with the ability to run JavaScript code on top of the Z-Wave Device functions and variables.

There are two ways to run JavaScript functions in Z-Way.

- They can be executed in the web browser URL string (using /JS/Run/ prefix)
- They can be implemented as module running in the backend or be stored in a file on the server side.

Both options have their pros and cons. Running JS code in the browser is a very nice and convenient way to test things but the function is not persistent.

Writing a module requires some more knowledge and debugging is more complicated. On the other hand the possibilities of JavaScript in the module are almost infinite and goes far beyond just accessing Z-Wave device. JavaScript as any other language can make use of services available in the Internet and combine them in any possible way with information from the Z-Wave network and can execute functions within the Z-Wave network but the same time on any place accessible via Internet based services. In theory there is not even a need to have Z-Wave device in order to make use of the powerful JavaScript engine. As an example you can write a JavaScript module polling weather data from the internet and depending on certain well defined conditions the same module can send you a short message on your mobile. Both functions are by the way already implemented as open source modules and can be accessed and studied for further modification or use.

3.1 The JavaScript Engine

Z-Way uses the JavaScript engine provided by Google referred to as V8. You find more information about this JavaScript implementation on https://code.google.com/p/v8/. V8 implements JavaScript according to the specification ECMA 5^{-1} .

Z-Way extends the basic functionality provided by V8 with plenty of application specific functions.

3.2 Accessing the JS API

The JS API can be accessed from any web browser with the URL

¹http://www.ecma-international.org/publications/standards/Ecma-262.htm

http://YOURIP:8083/JS/Run/* All functions of the Z-Wave Device API can be used by JavaScript. They are encapsulated in the 'zway' object. This object has the same structure as defined in chapter ??. The client side access to the device data is done like

http://YOURIP:8083/JS/Run/zway.devices[x].* Due to the scripting nature of JavaScript its possible to 'inject' code at run time using the interface. Here a nice example how to use the Java Script setInterval function:

This code will, once 'executed' as URL within a web browser, call the Get() command of the command class Basic of Node ID 2 every 300 seconds.

A very powerful function of the JS API is the ability to bind functions to certain values of the device tree. they get then executed when the value changes. Here an example for this binding. The device No. 3 has a command class SensorMultilevel that offers the variable level. The following call - both available on the client side and on the server side - will bind a simple alert function to the change of the variable.

```
Listing 3.2: Bind a function
```

3.3 HTTP Access

The JavaScript implementation of Z-Way allows to directly accessing HTTP objects. The http request is much like jQuery.ajax(): r = http.request(options); Here's the list of options:

- url required. Url you want to request (might be http, https, or maybe even ftp);
- method optional. HTTP method to use (currently one of GET, POST, HEAD). If not specified, GET is used;
- headers optional. Object containing additional headers to pass to server:

```
1 headers: {
2     "Content-Type": "text/xml",
3     "X-Requested-With": "RaZberry/1.5.0"
4 }
```

- data used only for POST requests. Data to post to the server. May be either a string (to post raw data) or an object with keys and values (will be serialized as 'key1=value1&key2=value2&');
- auth optional. Provides credentials for basic authentication. It is an object containing login and password:

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```
1 auth: {
2     login: 'username',
3     password: 'secret'
4 }
```

• contentType optional. Allows to override content type returned by server for parsing data (see below);

- async optional. Specifies whether request should be sent asynchronously. Default is false. In case of synchronous request result is returned immediately (as function return value), otherwise function exits immediately, and response is delivered later thru callbacks.
- success, error and complete optional, valid only for async requests. Success callback is called after successful request, error is called on failure, complete is called nevertheless (even if success/error callback produces exception, so it is like 'finally' statement);

Response (as stated above) is delivered either as function return value, or as callback parameter. Is is always an object containing following members:

- status HTTP status code (or -1 if some non-HTTP error occurred). Status codes from 200 to 299 are considered success;
- statusText status string;
- URL response URL (might differ from url requested in case of server redirects);
- headers object containing all the headers returned by server;
- contentType content type returned by server;
- data response data.

Response data is handled differently depending on content type (if contentType on request is set, it takes priority over server content type):

- application/json and text/x-json are returned as JSON object;
- application/xml and text/xml are returned as XML object;
- application/octet-stream is returned as binary ArrayBuffer;
- string is returned otherwise.

In case data cannot be parsed as valid JSON/XML, it is still returned as string, and additional parseError member is present.

```
http.request({
    url: "http://server.com" (string, required),
    method: "GET" (GET/POST/HEAD, optional, default "GET"),

headers: (object, optional)

name": "value",

name": "value",

name": "value",

name": "value",
```

```
10
          auth: (object, optional)
11
12
                   "login": "xxx" (string, required),
13
                   "password": "***" (string, required)
          },
15
16
          data: (object, optional, for POST only)
17
                   "name": "value",
19
20
           -- OR. --
          data: "name=value &..." (string, optional, for POST only),
23
24
          async: true (boolean, optional, default false),
           success: function(rsp) {} (function, optional, for async only),
27
           error: function(rsp) {} (function, optional, for async only),
28
          complete: function(rsp) {} (function, optional, for async only)
30
  });
31
32
зз response:
34 {
           status: 200 (integer, -1 for non-http errors),
35
          statusText: "OK" (string),
36
          url: "http://server.com" (string),
          contentType: "text/html" (string),
38
          headers: (object)
39
40
          {
                   "name": "value"
           },
42
          data: result (object or string, depending on content type)
43
44 }
```

3.4 XML parser

ZXmlDocument object allows to convert any valid XML document into a JSON object and vice versa.

3.4.1 var x = new ZXmlDocument()

Create new empty XML document

$3.4.2 ext{ x = new ZXmlDocument("xml content")}$

Create new XML document from a string

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3.4.3 $\mathbf{x}.\mathbf{root}$

33

```
Get/set document root element. Elements are got/set in form of JS objects:
1 {
       name: "node_name",
                                  mandatory
2
       text: "value",
                             optional, for text nodes
3
       attributes: {
                            optional
4
           name: "value",
5
6
       },
7
                         optional, should contain a valid object of same type
       children: [
            { ... }
9
10
11 }
     For example:
1 (new ZXmlDocument('<weather><city id="1"><name>Zwickau</name><temp>2.6</temp></city><city
  {
2
     "children":[
3
         {
4
             "children":[
5
6
                    "text": "Zwickau",
                    "name": "name"
10
                    "text":"2.6",
11
                    "name": "temp"
13
14
             "attributes":{
15
                " id" : " 1"
17
             "name": "city"
18
19
             "children":[
21
22
                    " text": "Moscow",
23
                    "name": "name"
24
25
26
                    " {\rm text}": " -23.4",
27
                    "name":"temp"
29
30
             "attributes":{
                "id":"2"
             },
```

```
"name":"city"
"name":"city"
"name":"weather"
"name":"weather"
```

3.4.4 x.isXML

This hidden readonly property allows to detect if object is XML object or not (it is always true).

3.4.5 x.toString()

Converts XML object into a string with valid XML content.

3.4.6 x.findOne(XPathString)

Returns first matching to XPathString element or null if not found.

```
1 x.findOne('/weather/city[@id="2"]') // returns only city tag for Moscow
2 x.findOne('/weather/city[name="Moscow"]/temp/text()') // returns temperature in M
```

3.4.7 x.findAll(XPathString)

Returns array of all matching to XPathString elements or empty array if not found.

```
1 x.findAll('/weather/city') // returns all city tags
2 x.findAll('/weather/city/name/text()') // returns all city names
```

3.4.8 XML elements

Each XML element (tag) in addition to properties described above (text, attributes, children) have hidden readonly property parent pointing to parent object and the following methods:

- insertChild(element) Insert new child eleemnt
- removeChild(element) Remove child element
- findOne(XPathString) Same as on root object, but relative (no leading / needed in XPathString
- findAll(XPathString) Same as on root object, but relative (no leading / needed in XPathString

ZXmlDocument is returned from http.request() when content type is "application/xml", "text/xml" or any other ending with "+xml". Namespaces are not yet supported.

3.5 Cryptographic functions

crypto object provides access to some popular cryptographic functions such as SHA1, SHA256, SHA512, MD5, HMAC, and provides good random numbers.

3.5.1 var guid = crypto.guid()

Provides standard GUID in string format.

3.5.2 var rnd = crypto.random(n)

Generates n random bytes. Returned values is of type ArrayBuffer. To convert it into array use this trick:

```
rnd = (new Uint8Array(crypto.random(10)));
```

3.5.3 var dgst = crypto.digest(hash, data, ...)

Returns digest calculated using selected hash algorithm. It supports virtually all the algorithms available in OpenSSL (md4, md5, mdc2, sha, sha1, sha224, sha256, sha384, sha512, ripemd160). If no data parameters specified, it returns a digest of an empty value. If more than one data parameters are specified, they're all used to calculate the result. Data parameters may be of different types (strings, arrays, ArrayBuffers). Return value is of type ArrayBuffer.

There are also a few shortcut functions for popular algorithms: "md5", "sha1", "sha256", "sha512". For example, these calls are equivalent:

```
dgst = crypto.digest("sha256", data);
dgst = crypto.sha256(data);
```

3.5.4 var hmac = crypto.hmac(cipher, key, data, ...)

Returns hmac calculated using selected hash algorithm. Hash algorithms are the same as for digest() function. Key parameter is required. If no data parameters specified, it returns a HMAC of an empty value. If more than one data parameters are specified, they're all used to calculate the result. Key and data parameters may be of different types (strings, arrays, ArrayBuffers). Return value is of type ArrayBuffer.

There are also a few shortcut functions for popular algorithms: "hmac256", "hmac512". For example, these calls are equivalent:

```
dgst = crypto.hmac("sha256", key, data);
dgst = crypto.hmac256(key, data);
```

3.6 Sockets functions

Socket module allows easy access to TCP and UDP sockets from JavaScript. Both connection to distant ports and listening on local are available. This API fully mirrors into JavaScript POSIX TCP/IP sockets. This can be used to control third party devices like Global Cache or Sonos as well as emulating third party services.

To start communications one need to create socket and either **connect** it or **listen** it. **onrecv** method is called on data receive from remote, while **send** is used to send data to remote side.

The example below dumps to log file response to http://ya.ru:80/ (raw HTTP protocol is used as an example).

```
var sock = new sockets.tcp();
3 sock.onrecv = function(data) {
      debugPrint(data.byteLength);
7 sock.connect("ya.ru", 80);
9 sock.send("GET / HTTP/1.0\r\n\r\n");
    Here is an example of TCP echo server on port 8888:
var sock = new sockets.tcp();
3 sock.bind(8888);
5 sock.onrecv = function(data) {
      this.send(data);
7 };
9 sock.listen();
    And echo server for UDP:
var sock = new sockets.udp();
3 sock.bind(8888);
5 sock.onrecv = function(data, host, port) {
      this.sendto(data, host, port);
7 };
9 sock.listen();
```

Detailed description of Socket API:

- bind(ip, port) or bind(port) binds socket to port (integer number). ip should be a string like "192.168.0.1". If omited "0.0.0.0" is used (bind on all IP addresses of all interfaces). Returns false on error.
- connect(ip, port) connects to remote side ip:port. TCP sockets requires this call before sending data. For UDP sockets it is optional, but once used allows to use send call instead of sendto call. Returns false on error.
- listen() starts listening port (this is required not only for TCP, but for UDP too). Returns false on error.
- close() initiate close of socket.
- send(data) sends data to connected or accepted socket.
- sendto(data, host, port) sends data to a non-connected UDP socket.

- onrecv(data, host, port) called on new data receiption from remote side. For UDP sockets and connected TCP sockets "this" object reffers to the socket itself, while for accepted TCP sockets "this" reffers to the client's individual objects.
- onconnect(remoteHost, remotePort, localHost, localPort) called only for TCP sockets on new connection accept. "this" reffers to the client individual socket object.
- onclose(remoteHost, remotePort, localHost, localPort) called on socket close by remote or due to close() call. Note that for TCP sockets this callback is called for client sockets on connection close and for binded listening socket if close() is called. "this" object will be defined like in onrecy.
- reusable() sets SO_REUSEADDR socket option to allow multiple bind() on the same port.
- broadcast() sets SO_BROADCAST socket option to allow sending broadcast UDP messages.
- multicastAddMembership(multicastGroup) subscribe socket to multicast group
- multicastDropMembership(multicastGroup) unsubscribe socket from multicast group

3.6.1 WebSockets functions

Socket module also implements WebSockets (RFC 6455). WebSocket API is made to be compatible with browser implementations (some rarely used functions are not implemented - see below).

The example below implemnts basic application using WebSockets client:

```
var sock = new sockets.websocket("ws://echo.websocket.org");
  sock.onopen = function () {
      debugPrint('connected, sending ping');
4
      sock.send('ping');
5
  }
6
  sock.onmessage = function(ev) {
      debugPrint('recv', ev.data);
9
  }
10
11
 sock.onclose = function() {
      debugPrint('closed');
13
14
  sock.onerror = function(ev) {
      debugPrint('error', ev.data);
17
  }
18
    Next example shows basic application using WebSockets server:
var sock = new sockets.websocket(9009);
_3 sock.onconnect = function () {
      debugPrint('client connected, sending ping');
```

```
5 }
  sock.onmessage = function(ev) {
      debugPrint('recv', ev.data);
      sock.send('pong');
10
11
12 sock.onclose = function() {
      if (this = sock) 
           debugPrint('server websocket closed');
14
      } else {
15
           debugPrint('client disconnected');
17
18
19
  sock.onerror = function(ev) {
20
      debugPrint('error', ev.data);
22 }
```

Detailed description of WebSocket API:

- socket.websocket(url, [protocol]) creates new client WebSocket and connects to the specified URL (should be a string like "ws://host:port" or "wss://host:port" for SSL channel). Optional protocol parameter can be used to specify protocol from server capabilities (comma separated string), default is "default".
- socket.websocket(port) creates new WebSocket server on port.
- close() initiate close of WebSocket.
- send(data) sends data to WebSocket. data can be array, ArrayBuffer (sent as binary) or string (sent as text).
- onmessage(event) called on new data receiption from remote side. Object event contains only data property. Other properties mentioned in RFC 6455 are not supported.
- onopen() or onconnect() called on connection establish. Compared RFC 6455 event parameter is not passed.
- onclose() called on WebSocket close by remote or due to close() call. For server side will be called on client instance and on listening instance (use this to differenciate). Note that if close() is called before connection was established, onclose() is not executed. Compared RFC 6455 event parameter is not passed.
- onerror(event) called on error. For example host or port unreachable. Note that new sockets.websocket(..) can throw an exception on DNS resolution error or on network unreachable. Other errors will be reported via onerror. Parameter event contains only propery data. Other properties from RFC 6455 are not implemented.

3.7 Other JavaScript Extensions

fs.list(folder)

This returns list of items in the folder or undefined if not folder is not existing.

fs.stat(file)

This returns one of the following values:

- 1) undefined if object does not exist or not readable
- 2) object { type: 'file', size: <size>} if it is a file
- 3) object { type: 'dir' } if it is a folder

fs.loadJSON(filename)

This function reads a file from the file system and loads it into the memory. The file must contain a valid JSON object. The only argument is the name of the file including relative pathname to the automation folder. The functions returns the full JSON object or null in case of error.

fs.load(filename)

This function reads a file from the file system and returns it's content as a string. The only argument is the name of the file including relative pathname to the automation folder. The functions returns null in case of error.

executeFile(filename) and executeJS(string)

Loads and executes a particular JavaScript file from the local filesystem or executes JavaScript code represented in string (like eval in browsers).

The script is executed withing the global namespace.

Remark: If an error occurred during the execution it won't stop from further execution, but erroneous script will not be executed completely. It will stop on the first error. Exceptions in the callee can be trapped in the caller using standard try-catch mechanism.

system(command)

The command system() allows to execute any shell level command available on the operating system. It will return the shell output of the command. On default the execution of system commands is forbidden. Each command executed need to be permitted by putting one line with the starting commands in the file automation/.syscommands or in an different automation folder as specified in config.xml.

Timers

Timers are implemented exactly as they are used in browsers. They are very helpfull for periodical and delayed operations. Timeout/period is defined in milliseconds.

- timerId = setTimeout(function() , timeout)
- timerId = setInterval(function() , period)
- clearTimeout(timerId)
- clearInterval(timerId)

loadObject(object_name) and saveObject(object_name, object)

Loads and saves JSON object from/to storage. These functions implements flat storage for application with access to the object by it's name. No folders are available.

Data is saved in automation/storage folder. Filenames are made from object names by stripping characters but [a-ZA-Z0-9] and adding checksum from original name (to avoid name conflicts).

exit()

Stops JavaScript engine and shuts down Z-Way server

allowExternalAccess(handlerName) and listExternalAccess()

allowExternalAccess allows to register HTTP handler. handlerName can contain strings like aaa.bbb.ccc.ddd - in that case any HTTP request starting by /aaa/bbb/ccc/ddd will be handled by a function aaa.bbb.ccc.ddd() if present, otherwise aaa.bbb.ccc(), ... up to aaa(). Handler should return object with at least properties status and body (one can also specify headers like it was in http.request module).

listExternalAccess returns array with names of all registered HTTP handlers. Here is an example how to attach handlers for /what/timeisit and /what:

```
what = function() {
   return { status: 500, body: 'What do you want to know' };
};
what.timeisit = function() {
   return { status: 200, body: (new Date()).toString() }
};
allowExternalAccess("what");
allowExternalAccess("what.timeisit");
```

debugPrint(object, object, ...)

Prints arguments converted to string to Z-Way console. Very usefull for debuggin. For convenience one can map 'console.log()' to debugPrint().

This is how it was done in automation/main.js in Z-Way Home Automation engine:

3.7.1 Debugging JavaScript code

Change in config.xml debug-port to 8183 (or some other) turn on V8 debugger capability on Z-Way start.

node-inspector debugger tool is required. It provides web-based UI for debugging similar to Google Chrome debug console.

You might want to run debugger tool on another machine (for example if it is not possible to install it on the same box as Z-Way is running on).

Use the following command to forward debugger port defined in config.xml to your local machine:

```
ssh -N USER@IP_OF_Z-WAY_MACHINE -L 8183:127.0.0.1:8183

(for RaZberry USER is pi)
    Install node-inspector debugger tool and run it:

npm install -g node-inspector
node-inspector --debug-port 8183
```

Then you can connect to http://IP_OF_MACHINE_WITH_NODE_INSPECTOR:8080/debug?port=8183 If debugging is turned on, Z-Way gives you 5 seconds during startup to reconnect debugger to Z-Way (refresh the page of debugger Web UI withing these 5 seconds). This allows you to debug startup code of Z-Way JavaScript engine from the very first line of code.

Chapter 4

The Automation Subsystem

The automation subsystem allows writing automation scripts using Javascript. It uses the ECMA compatible Javascript Engine described in chapter 3. All the code realizing the automation engine is written in Javascript itself and is available as open source for further study and modification.

The automation engine performs different actions based on events. The actions are either signal commands or scripts that can add additional logic and conditions. Events are either generated from the Z-Wave network or from an outside sources such as the Internet or even from a user interaction is causing certain actions, either within the Z-Wave network (e.g. switching a light) or outside Z-Wave (e.g. sending a email). In Z-Way all automation is organized in so called modules. The subsequent manual will explain how these modules work and how to create own modules.

Attention: There is no Graphical User Interface for the automation engine at this moment in time. You will need a text editor such as joe, textwrangler or vi to edit certain files.

4.1 How to get to the automation engine

The starting point for automation in Z-Way is called config.xml and is located in the main folder of Z-Way. The statement for the automation engine looks like

```
< automation - dir > pathToAutomationCodeBase < / automation - dir >
```

Assuming the automation is like on default in the subdirectory /automation the statement should look like

```
< automation - dir > automation < /automation - dir >
```

The automation folder consists of several files and subdirectories. The most important file of the automation is called config.json. This file contains the information about all automation modules and their instances. This file is automatically generated and should be changed without proper knowledge.

4.2 The Event Bus

All communication from and to the automation modules is handled by events. An event is a structure containing certain information that is exchanged using a central distribution place, **the**

event bus. This means that all modules can send events to the event bus and can listen to event in order to execute commands on them. All modules can 'see' all events but need to filter out their events of relevance. The core objects of the automation are written in JS and they are available as source code in the sub folder 'classes':

- AutomationController.js: This is the main engine of the automation function
- AutomationModule.js: the basic object for the module

The file main.js is the startup file for the automation system and it is loading the three classes just mentioned. The subfolder /lib contains the key JS script for the Event handling: eventemitter.js.

4.2.1 Emitting events

The 'Event emitter' emits events into the central event bus. The event emitter can be called from all modules and scripts of the automation system. The syntax is:

```
controller.emit(eventName, args1, arg2, ...argn)
```

The event name 'eventName' has to be noted in the form of 'XXX.YYY' where 'XXX' is the name of the event source (e.g. the name of the module issuing the event or the name of the module using the event) and 'YYY' is the name of the event itself. To allow a scalable system it makes sense to name the events by the name of the module that is supposed to receive and to manage events. This simplifies the filtering of these events by the receiver module(s).

Certain event names are forbidden for general use because they are already used in the existing modules. One example are events with the name cron.XXXX that are used by the cron module handling all timer related events.

Every event can have a list of arguments developers can decide on. For the events used by preloaded modules (first and foremost the cron module) this argument structure is predefined. For all other modules the developer is free to decide on structure and content. It is also possible to have list fields and or any other structure as argument for the event

One example of an issued event can be

emit(mymodule.testevent, Test, [event1, event2])

4.2.2 Catching (binding to) events

The controller object, part of every module, offers a function called 'on()' to catch events. The 'on(name, function())' function subscribes to events of a certain name type. If not all events of a certain name tag shall be processed a further filtering needs to be implemented processing the further arguments of the event. The function argument contains a reference to the implementation using the event to perform certain actions. The argument list of the event is handed over to this function in its order but need to be declared in the function call statement.

```
this.controller.on(mymodule.testevent, function (name, eventarray) )
```

The same way objects can unbind from events:

```
this.controller.off(mymodule.testevent, function (name, eventarray));
```

4.3 Module-Syntax

Each module is located in a sub directory of the module-subfolder defined in the config.json file. The name of the sub folder equals to the module name (not the instance of the module name!) and has at least two files:

4.3.1 Module.json

This file contains the module meta-definition used by the AutomationController. It must be a valid JSON object with the following fields (all of them are required):

- autoload Boolean, defines will this module automatically instantiated during Home Automation startup.
- singleton Boolean, defines this module can be instantiated more than one time or not.
- defaults Object, default module instance settings. This object will be patched with the particular config object from the controller's configuration and resulting object will be passed to the initializer.
- actions Object, defines exported module instance actions. Object keys are the names of actions and values are meta-definitions of exported actions used by AutomationController and API webserver.
- metrics Object, defines exported module metrics.

All configuration fields are required. Types of the object must be equal in every definition in every case. For instance, if module doesn't export any metric corresponding key value should be and empty object .

4.3.2 index.js

This script defines an automation module class which is descendant of AutomationModule base class. During initialization the module script must define the variable '_module' containing the particular module class.

Example of a minimal automation module:

Listing 4.1: Minimal Module

```
function SampleModule (id, controller) {
   SampleModule.super_.call.init(this, id, controller);

   this.greeting = "Hello, World!";
   this.greeting = "Hello, World!";
   inherits(SampleModule, AutomationModule);
   _module = SampleModule;

SampleModule.prototype.init = function () {
        this.sayHello();
   }
}
```

```
15 SampleModule.prototype.sayHello = function () {
16          debugPrint(this.greeting);
17 }
18
19 SampleModule.prototype.stop = function () {
20          this.sayByeBye();
21 }
```

The first part of the code illustrates how to define a class function named SampleModule that calls the superclass' constructor. Its highly recommended not to do further instantiations in the constructur. Initializations should be implemented within the 'init' function.

The second part of the code is almost immutable for any module. It calls prototypal inheritance support routine and it fills in _module variable.

The third part of the sample code defines module's init() method which is an instance initializer. This initializer must call the superclass's initializer prior to all other tasks. In the initializer module can setup it's private environment, subscribe to the events and do any other stuff. Sometimes, whole module code can be placed withing the initializer without creation of any other class's methods. As the reference of such approach you can examine AutoOff module source code.

After the init function a module may contain other functions. The 'sayHello' function of the Sample Module shows this as example.

4.4 Available Core Modules

The automation engine already contains certain modules essential for the work of the whole system. Do now exclude these modules from the config.json and alter them only if you know exactly what you do.

4.4.1 Cron, the timer module

All time driven actions need a timer. The Z-Way automation engine implement a cron-type timer system as a module as well. The basic function of the cron module is

- It accepts registration of events that are triggered periodically
- It allows to de-register such events.

The registration and deregistration of events is also handled using the event mechanism. The cron module is listening for events with the tags 'cron.addTask' and 'cron.removeTask'. The first argument of these events are the name of the event fired by the cron module. The second argument of the 'addTask' event is an array desricing the times when this event shall be issued. It has the format:

- Minute [start, stop, step] or 0-59 or null
- Hour [start,stop, step] or 0-23 or null
- weekDay [start,stop, step] or 0-6 or null
- dayOfMonth [start,stop, step] or 1-31 or null
- Month [start, stop, step] or 1-12 or null

The argument for the different time parameters has one of three formats

- null: the event will be fired on every minute or hour etc.
- single value: the event will be fired when the value reaches the given value
- array [start, stop, step]: The event will be fired between start and stop in steps.

The object

```
\{minute: null, hour: null, weekDay: null, day: null, month: null\}
```

will fire every minute within every hour within every weekday on every day of the month every month. Another example of an event emitted towards the cron module for registering an timer event can be found in the Battery Polling Module:

Listing 4.2: Registering a Battery Polling Command

```
this.controller.emit("cron.addTask", "batteryPolling.poll", {
    minute: 0,
    hour: 0,
    weekDay: this.config.launchWeekDay,
    day: null,
    month: null
});
```

This call will cause the cron module to emit an event at night (00:00) on a day that is defined in the configuration variable this.config.launchWeekDay, e.g. 0 = Sunday.

The 'cron.removeTask' only needs the name of the registered event to deregister.

4.4.2 The Virtual Device Module

This module generates virtual devices and manages them. For more information about virtual devices and the use in a Graphical User Interface please refer to chapter 6 and 5.

4.4.3 DeviceCollection module

The Device Collection Module manages devices and shall not be changed.

Chapter 5

The Z-Way HA User Manual

You can access the User Interface 'z-way-ha' using the URL

http://YOURIP:8083/z-way-ha

The following sections describes the 'Z-Way-HA' from the users point of view

The Z-Way-HA User Interface is a AJAX based user interface available for web browsers. At the moment it supports Google Chrome, Firefox and Apple Safari only but no Microsoft Internet Explorer.

The functions of the Z-Way-HA UI are:

- show all device functions of the Z-Way based Smart Home systems as widgets
- allow to activate and manage automation modules that make use of the widgets and may generate new widgets

The User Interface offers four function groups:

- **Dashboard**: Important widgets are shown in the dashboard. The section 'widgets' in the 'Preferences' allow to define what widget is shown in the Dashboard.
- Widgets: The widget section allows to access all widgets of the Home Automation System. They are grouped by 'Rooms', 'Type', and 'Tags' The 'Preferences' allow to manage rooms, types and widgets and to assign certain widgets to these groups.
- Notifications: Clocking om the notifications button opens a dialog showing all notification generated by the system and the modules. Notifications will stay in this list until these are individually confirmed.
- Preferences: The preferences tab opens a dialog with different setup options.
 - General: This allows to setup and manage profiles
 - Rooms: This allows to setup and manage rooms
 - Widgets: This allows managing widgets
 - Automation: This allow managing the modules of the Javascript based automation engine

5.1 Widgets

The widget section allows managing all widgets that are automatically created from the device included into the Z-Wave or Third party Wireless Control System plus the widgets generated from Automation Modules.¹

A widget does not necessarily represent a physical device but a function of a device. This means that one single device can create multiple widgets. For Z-Wave devices every function (switch, battery, sensor value) and every channel in a multichannel environment generated a widget. The widget is not technology dependent but the initial name and the unique id of the generated widget is referring to the attributes of the physical device. The pattern for the id is

ZWayVDev_[Node ID]:[Instance ID]:[Command Class ID]:[Scale ID]

The Node ID referred to the node ID of the physical device corresponding to thie widget, the instance is the instance or zero in case there are no multiple instances. The command class ID refers to the command class generated the function of the widget. Some command classes offer multiple sensor values differentiated by their scale id (e.g. Celsius or Fahrenheit). For command classes without multiple scales (e.g. battery value) this value is always zero.

The line below the main menu offers three options grouping the widgets:

- by Room: The Ui can define rooms and in the room definitions widgets can be assigned to rooms. Each widget can be assigned only to one room. The line below shows all rooms currently defined. Clicking on the room shows all widgets assigned to this room. To manage rooms please refer to the section Preferences.
- by Type: All Widgets belong to one specific type. At the moment the following types are defined and supported by the Z-Way-HA UI:
 - **sensorBinary**: A binary sensor, only showing on or off
 - sensorMultilevel: The type, the value and the scale of the sensor are shown
 - switchBinary: The device can be switched on and off
 - switchMultilevel: The device can be switched on and off plus set to any percentage level between 0 % and 100 %.
 - **switchRGBW**: This device allows setting RGB colors
 - switchControl:
 - toggleButton: The device can only be turned on. This is for scene activation.
 - thermostat: The thermostat shows the setpoint temperature plus a drop down list of thermostat modes if available
 - battery: The battery widget just shows the percentage of charging capacity left
 - camera: A camera will show the image and can be operated
 - fan: A fan can be turned on and off

The line below shows all types where devices exist. Device types can not be managed on the UI but will be shown automatically when new widgets are generated.

¹Technically also te widgets from the wireless control systems are generated by modules but this happens automatically when they registered resp. included in the wireless system.

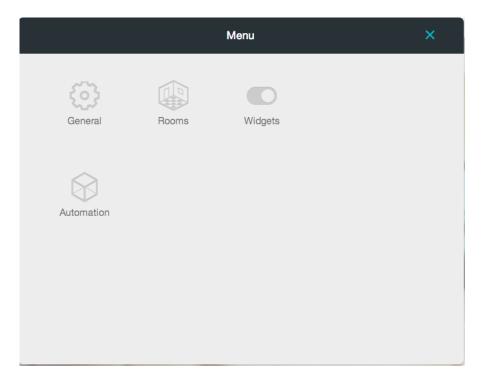


Figure 5.1: Preferences Submenu

• By Tag: The system allows to generate user defined tags and assign these tags to defines. The only predefined tag is the 'dashboard'. This tag is used to select all widgets that are shown in the dashboard. The line below shows all tags currently defined. Clicking on the tags shows all widgets assigned where this tag is assigned to. Tags can be freely defined when managing a certain widget.

5.2 Notifications

Left beside the Notification button the number of notifications are shown. Clicking on the String 'Notification' opens a dialog box with the notification string. Notifications are generated by the system (error message) or by application modules. 'Hide' deletes the message.

5.3 Preferences

Clicking on 'Preferences' opens a dialog with four sub menus as shown in Figure 5.1. One the upper side there is a 'X' to close the dialog. Once a sub menu is opened on the upper left side the ' < ' returns to the sub menu overview.

5.3.1 General

The dialog shows different profiles. At the moment there are no further options and actions available except naming the profiles and giving a Name.

On the lower left corner there is a '-' and a '+'. Clicking on the '+' adds a new profile, '-' deletes the profile highlighted on the left hand side. A filter can be applied to find certain profiles.

On factory default only the 'default' profile is available.

5.3.2 Rooms

The dialog 'Rooms' offers four submenus. On the lower left corner there is a '-' and a '+'. Clicking on the '+' adds a new room, '-' deletes the room highlighted on the left hand side. A filter can be applied to find certain rooms.

General Clicking on the 'Edit'-Button allows editing the Room setup.

The name can be chosen by the user. Clicking on the icon image opens a file chooser dialog to pick a new icon. Clicking on the device button opens a new dialog where devices can be assigned to this room. The left hand side shows the device available (not assigned of any room). Picking the device is done by 'drag and drop'. Devices on the right hand side are assigned to the room.

Temperature Preference This dialog is not used at the moment.

Auto Mode This dialog is not used at the moment.

Devices This is a short cut to the device assignment dialog also accessible in the 'General' sub menu.

5.3.3 Widgets

The widgets menu allows managing the widgets generated by the Home Automation system. All widget are listed with their names on the left hand side. A filter can be applied to find certain widgets.

The name of the widget is auto-generated by the system but can be changed. The id of the widget is unique and shown below the name entry. The device type is shown.

The tag section allows to add new tags defined by the user. Defined tags are listed and can be deleted clicking on the 'x' symbol.

A checkbox defined if the widget is shown on the dash board.

5.3.4 Automation

This section allows managing the automation modules of the Automation system. On the left hand side there is a list of all defined module instances. Please refer to the automation section 4 for the relationship between module definitions and instances of modules.

On the lower left corner there is a '-' and a '+'. Clicking on the '+' adds a new module instance, '-' deletes the module instance highlighted on the left hand side. A filter can be applied to find certain module instances.

Clicking on the module instances name or the '+' button opens a dialog menu on the right hand side. When a new module instance is created the first option is to pick one of the modules available.

The list of modules consist of a set of modules that are scope of delivery of the system. Additionally the list will show all modules defined by the users.

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All setups of modules consist of a module specific part (upper part) and a generic part (lower part), that allows to

- define a name
- define a description of the instance
- enable or disable the module

Important predefined modules are:

Bind Devices: This modules implements the association function known from Z-Wave. Compared to the Associations in Z-Wave that are stored in the devices the bind function settings are stored in the gateway but can bind devices of different wireless technologies or widgets created.

Load custom JS Code: This allows to activate an own piece of Javascript.

Load custom JS File: This allows to activate an own piece of Javascript loaded from a file.

Group devices: Groups several devices together and adds a new widget.

Sensor Polling Z-Way itself will not poll devices but rely on unsolicited status updates to keep the UI information updated. Certain sensor values should be updated periodically. If different sensors shall be polled in different intervals (e.g. meter less frequently than actual power draw) multiple instances of the modules need to be defined.

Sensors Values Logging: This modules allows to report sensor values to a cloud service. The values are either written into a JSON file or sent over the Internet. In this case a receiving URL can be defined.

Trap events from Remote And Sensors: Generates new widgets on the fly for Remote Switch Controls and other devices sending control commands to controller.

Other modules are

- Always On: keeps a device on regardless of switching command
- Auto Off: turns off a device after defined time
- BatteryPolling: polls all battery devices for charging level
- Camera: controls a IP camera
- LightScene: defines light scenes
- NotificationSMSru: allows to sen SMS notifications
- OpenRemoteHelpers: Adapts to the solution from openremote.org
- OpenWeather: polls weather data from Internet
- RGB: Creates RGB device based on three different dimmers
- RoundRobinScenes: Activates scene in Round Robin

- SecurityNotifications: Notify on changes of sensors and switches state
- SwitchControlGenerator: Generates new widgets on the fly for Remote Switch Controls and other devices sending control commands to controller
- ZWaveGate: creates virtual devices from Z-Wave Devices

5.4 Dashboard

The dashboard shows all widgets selected as 'in dashboard in the widget dialog of the Preferences section.

Chapter 6

Virtual Device API (vDev)

The functions of the 'Z-Way HA' User Interface are described in the chapter 5. It is based on so called virtual devices plus some other supporting functions like rooms, notifications, tagging etc. The interface providing all these functions is called Virtual Device API (vDev).

The intention of this vDev API is to further simplify the use of Z-Way by AJAX based User interface implementations and to unify the user experience across different wireless technologies. The vDev API has the following objectives and functions.

- Provide a list of devices that are independent of the physical devices of a given wireless network With this devices of different networks appear similarly.
- Show all functions of a physical device as one virtual device each. This simplifies the use of the data and functions provides. The Z-Wave Device API still required a lot of domain knowledge about the different devices, their instances, command classes, scales. In the vDev API every function is represented by one virtual device only allowing simple loops for display.
- Provide end user related context information. This allows e.g. to define profiles, rooms, application etc.
- Handle events in an user friendly way to that they can be used a notifications on a UI.

There is an online manual for syntax of the various functions that can be accessed on

http://docs.zwayhomeautomation.apiary.io/

6.1 Authentication

In order to access API one need to authenticate itself. Z-Way uses sessions to authenticate users. Session can be obtained by sending login and password in JSON format using POST to URL /ZAutomation/api/v1/login. User credentials should look like {"login":"admin", "password":"admin"}

In return the session will be sent in two forms:

- as data.sid field in JSON structure,
- as a cookie called **ZWAYSession**.

Example of successful login will look like:

Listing 6.1: Successful login reply

```
1 {
       "data": {
           "sid": "ba69cb5b-b2fd-5ce0-5b75-9bae3e8bc369",
3
           "id": 1,
           "role": 1,
           "name": "Administrator",
6
           "lang": "en",
"color": "#dddddd",
           "dashboard": [],
           "interval": 2000,
10
           "rooms":
11
               0
12
13
           "hide_all_device_events": false,
14
           "hide_system_events": false,
15
           "hide_single_device_events": []
       "code": 200,
18
      "message": "200 OK",
19
       "error": null
20
21 }
                         Listing 6.2: Wrong login/password reply
       "data": null,
       "code": 401,
3
       "message": "401 Unauthorized",
4
      "error": "User login/password is wrong."
```

One obtained, the session can be sent to the server via cookie (as set by Z-Way) or via HTTP header.

6.2 The virtual device

The virtual device in the vDev API is an object that had properties and offers functions. Both properties, variables and functions are unified and their syntax is independent of the physical nature of the device they are are referred to (If there is any).

6.2.1 Types and Ids

Every Virtual device is identified by a simple string type id. For all virtual devices that are related to physical Z-Wave devices the device name is auto-generated by the ZWaveGate module following this logic:

6.2.2 Virtual Device Ids

Auto-generated devices are named after their IDs in the physical network. For Z-Wave devices the naming is generated using the following logic.

ZWayVDev_[Node ID]:[Instance ID]:[Command Class ID]:[Scale ID] The Node Id is the node id of the physical device, the Instance ID is the instance id of the device or '0' if there is only one instance. The command class ID refers to the command class the function is embedded in. The scale id is usually '0' unless the virtual device is generated from a Z-Wave device that supports multiple sensors with different scales in one single command class.

6.2.3 Virtual Device Type

Virtual devices can have a certain types. The type of the device can be chosen. For a list of the device types current supported in the Z-Way-HA API please refer to chapter 5.

6.2.4 Access to Virtual Devices

Virtual devices can be access both on the server side using JS modules and on the client side using the JSON API. On the client they are encoded into a URL style for easier handling in AJAX code. A typical client side command in the vDev API looks like

http://YOURIP:8083/ZAutomation/api/v1/devices/ZWayVDev_6:0:37/command/off 'api' points to the vDev API function, 'v1' is just a constant to allow future extensions. The devices are referred by a name that is automatically generated from the Z-Wave Device API. The vDev also unifies the commands 'command' and the parameters, here 'off'.

On the server side the very same command would be encoded in a JavaScript style.

Listing 6.3: Access vDevs

```
vdevId = vdev.id;
vDev = this.controller.devices.get(vdevId);
vDevList = this.controller.devices.filter(function(x) {
    return x.get("deviceType") === "switchBinary"; });
vDevTypes = this.controller.devices.map(function(x) {
    return x.get("deviceType"); });
```

6.2.5 Virtual Device Usage / Commands

In case the virtual device is an actor it will accept and execute a command using the syntax:

Vdev.performCommand(name of the command) The name of the accepted command should depend on the device type and can again be defined free of restrictions when implementing the virtual device. For auto-generated devices derived from Z-Wave the following commands are typically implemented.

- 1. 'update': updates a sensor value
- 2. 'on': turns a device on. Only valid for binary commands
- 3. 'off': turns a device off. Only valid for binary commands
- 4. 'exact': sets the device to an exact value. This will be a temperature for thermostats or a percentage value of motor controls or dimmers

6.2.6 Virtual Device Usage / Values

Virtual devices have inner values. They are called metrics. A metric can be set and get. Each virtual device can define its own metrics. Metrics can be level, title icon and other device specific values like scale (

```
vDev.set("metrics:...", ...);
vDev.get("metrics:...");
```

6.2.7 How to create your own virtual devices

Virtual devices can be created using modules or Javascript code in the browser itself. The following code sample demonstarte how to create and delete a virtual device. For more information about the module concept and the creating of modules and virtual device within modules please refer to chapter ??.

Register device

Listing 6.4: Register Device

```
vDev = this.controller.devices.create(vDevId, {
               deviceType: "deviceType",
20
               metrics: {
21
                   level: "level",
                   icon: "icon from lib or url"
23
                    title: "Default title"
24
25
           }, function (command, ...) {
                   // handles actions with the widget
27
           });
28
```

Unregister device

Devices can be deleted or unregistered using the following command:

this.controller.devices.remove(vDevId)

Binding to metric changes

The metric - the inner variables of the vDev a changed by the system automatically. In order to perform certain functions on these changes the function needs to be bound to the change to the vdev. The syntax for this is

vDev.on('change:metrics:...", function (vDev) ...); Unbinding then works as one can expect:

vDev.off(change:metrics:..., function (vDev) ...)

6.3 Notifications and events

Notifications are a special kind of event to inform the user on the GUI. This means that normale events are typically describes with numbers or ids while notifications contain a human readable message. The creating of events and the reaction on events is describes in chapter 4

The UI can be notified on the certain events.

this.controller.addNotification("....severity....", "....message....", "....origin...."); The parameters define

- severity is error, info, debug;
- origin describes which part of the system it is about: core, module, device, battery.

The controller can act on notifications or disable them.

this.controller.on('notifications.push', this.handler);

this.controller.off('notifications.push', this.handler);

Chapter 7

Z-Way Data Model Reference

7.1 zway

- Description: zway is the Z-Way part of the object tree
- Syntax: zway.X with X as child object
- Child objects
 - controller: controller object, see below for details
 - devices: devices list, see below for details
 - version: Z-Way.JS version
 - isRunning(): Check if Z-Way is running
 - isIdle(): Check if Z-Way is idle (no pending packets to send)
 - discover(): Start Z-Way discovery process
 - stop(): Stop Z-Way
 - InspectQueue(): Returns list of pending jobs in the queue.
 - * item: [timeout, flags, nodeId, description, progress, payload]
 - * flags: [send count, wait wakeup, wait security, done, wait ACK, got ACK, wait response, got response, wait callback, got callback]
 - ProcessPendingCallbacks(): Process pending callbacks (result of setTimeout/setInterval or functions called via HTTP JSON API)
 - bind(function, bitmask): Bind function to be called on change of devices list/instances list/command classes list
 - unbind(function) : Unbind function previously bind with bind()
 - all function classes in 9 are also methods of this data object

7.2 controller

You can access the data elements of "controller" in the demo user interface in menu "for experts + Controller Info"

- Description: Controller object
- Syntax: controller.X with X as child object
- Child objects
 - data: Data tree of the controller
 - * homeId: Home ID of the controller
 - * nodeId: Node ID of the controller
 - * SISPresent: is SIS available (if TRUE, SUCNodeId is a SIS, otherwise it is SUC)
 - * SUCNodeId: Node ID of SUC or SIS or 0 if no SUC/SIS present
 - * isInOtherNetworks: is controller the original Primary or it is in other's network
 - * isPrimary: can controller include devices (Primary or Inclusion controller)
 - * isRealPrimary: is controller Primary Controller or SIS in the network
 - * isSUC: is SUC present
 - * libType: Z-Wave library type
 - * frequency: current frequency of the transceiver
 - * controllerState: current network management state of the controller
 - * lastExcludedDevice: Node ID of last excluded device
 - * lastIncludedDevice: Node ID of last included device
 - * secureInclusion: shall inclusion be done using Security
 - * caps: Z-Way license information
 - * softwareRevisionVersion: version of Z-Way build
 - * softwareRevisonDate: date of Z-Way build
 - * softwareRevisionId: git commit of Z-Way build
 - * manufacturerId / manufacturerProductId / manufacturerProductTypeId: IDs to identify the transceiver hardware
 - * vendor: name of hardware vendor
 - * APIVersion: Version of the Serial API of the transceiver firmware
 - * SDK: Z-Wave SDK version of the transceiver firmware
 - * ZWVersion: ZWave Version (firmware)
 - * ZWaveChip: Serie of the transceiver Z-Wave chip
 - * ZWlibMajor / ZWlibMinor: library version
 - * capabilities: array of Function Class IDs supported by the transceiver firmware
 - * functionClasses: ordered array of IDs of Function Classes
 - * functionClassesNames: ordered array of Names of Function Classes
 - * uuid: Z-Way transceiver firmware unique ID
 - \ast memory GetAddress: address of last data stored in memory GetData read by one of memory read function
 - * memoryGetData: last data read by one of memory read function
 - * countJobs: shall job be counted (nonManagementJobs and devices[x].data.queueLength)
 - * nonManagementJobs: number of non-management jobs in the queue
 - * deviceRelaxDelay: time in 10ms to wait before sending next command to same device (configurable in Defaults.xml)
 - * incomingPacket: last incoming packet from Z-Wave network

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- * curSerialAPIAckTimeout10ms: timing parameter of Serial API
- * curSerialAPIBytetimeout10ms: timing parameter of Serial API
- * oldSerialAPIAckTimeout10ms: previous timing parameter of Serial API
- * oldSerialAPIBytetimeout10ms: previous timing parameter of Serial API
- AddNodeToNetwork(mode): Reference to zway.AddNodeToNetwork()
- RemoveNodeFromNetwork(mode): Reference to zway.RemoveNodeFromNetwork()
- ControllerChange(mode): Reference to zway.ControllerChange()
- GetSUCNodeId(mode): Reference to zway.GetSUCNodeId()
- SetSUCNodeId(nodeId): Assign SUC role to a device
- SetSISNodeId(nodeId): Assign SIS role to a device
- DisableSUCNodeId(nodeId): Revoke SUC/SIS role from a device
- SendNodeInformation(nodeId): Reference to zway.SendNodeInformation()

7.3 Devices

The devices object contains the array of the device objects. Each device in the network - including the controller itself - has a device object in Z-Way.

- Description: list of devices
- Syntax: X with X as child object
- Child objects
 - m: Device object
 - length: Length of the list
 - SaveData(): Save Z-Way Z-Wave data for hot start on next run (in config/zddx/HOMEID-DevicesData.xml)

7.4 Device

The data object can be accesses in the demo UI in advanced mode of "Configuration"

- Description: the device object
- Syntax: device[n].X with X as child object
- Child objects
 - id: (node) Id of the device
 - Data: Data tree of the device
 - * SDK: SDK used in the device firmware
 - * ZDDXMLFile: file of the Devcie Description Record
 - * ZWLib: Z-Wave library used in the device firmware
 - * ZWProtocolMajor / ZWProtocolMinor: Z-Wave protocol version
 - * applicationMajor / ApplicationMinor: Application Version of devices firmware

- * manufacturerId / manufacturerProductId / manufacturerProductTypeId: ids used to identify the device
- * basicType: Z-Wave Basic Type
- * genericType: Z-Wave Generic Type
- * specificType: Z-Wave Specific Type
- * deviceTypeString: verbal Z-Wave Device Class
- * vendorString: verbal vendor name
- * nodeInfoFrame: Node Information Frame (NIF) array
- * isListening: is always listening
- * isAwake: is currently awake
- * keepAwake: shall the device be kept awake even if there is nothing to send to it
- * isRouting: is abale to send routed unsolicited packets
- * sensor1000: device is a FLiRS with 1000 ms wakeup
- * sensor250: device is a FLiRS with 250 ms wakeup
- * isVirtual: is virtual device from a bridge controller
- * option: are optional Command Classes present in addition to mandatory for this Device Class
- * infoProtocolSpecific: internal information about the device
- * neighbours: list of neighbour nodes
- * givenName: name for Expert UI
- * isFailed: is failed
- * failureCount: number of tries since last device failed
- * lastRecevied: timestamp of last packet received
- * lastSend: timestamp of last sent operation
- * lastPacketInfo: structure with deliveryTime, delivered and packetLength information about last packet sent
- * queueLength: length of device specific send queue (if countJobs is enabled)
- * lastNonceGet: internal
- instances: iInstances list of the device
- RequestNodeInformation(): Request NIF
- RequestNodeNeighbourUpdate(): Request routes update
- InterviewForce(): Purge all command classes and start interview based on device's NIF
- RemoveFailedNode(): Remove this node as failed. Device should be marked as failed to remove it with this function.
- SendNoOperation(successCallback = NULL, failureCallback = NULL): Ping the device with empty packet (even if device is not reachable successCallback is called use isFailed to check device availability)
- LoadXMLFile(file): Load new Z-Wave Device Description XML file. See http://pepper1.net/zwavedb/
- GuestXML(): Return the list of all known Z-Wave Device Description XML files with match score. [score, file name, brand name, product name, photo]
- WakeupQueue(): Pretend the device is awake and try to send packets
- AssignReturnRoute(target): Send device new routes to target node
- DeleteReturnRoute(): Clear routes in device
- AssignSUCReturnRoute(): Inform device about SUC and route to reach it

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7.5 Instances

Each device may have multiple instances (similar functions like switches, same type sensors, ...) If only one instance is present the id of this instance is 0. Command classes are located in instances only-

- Description: list of instances
- Syntax: device[n].instance[m].X with X as child object
- Child objects
 - m: instance object
 - length: Length of the list
 - commandClasses: list of command classes of this instance. In case there is only one
 instance, this is equivalent to the list of command classes of the device. For details
 see below.
 - Data: data object of instance
 - * dynamic: flag if instance is dynamic
 - * genericType: generic Z-Wave device class of instance
 - * specificType: specific Z-Wave device class of instance

7.5.1 CommandClass

This is the Command Class object. It contains public methods and public data elements that are described in chapter 8

- Description: Command Class Implementation
- Syntax: device[n].instance[m].commandclass[id].X with X as child object
- Child objects
 - id: Id of the Command Class of the instance of the device
 - data: Data tree of the Command Class
 - * interviewCounter: number of attempts left until interview is terminate even if not successful
 - * interviewDone: flag if interview of the command class is finished
 - * security: flag if Command Class is operated under Security Command Class
 - * version: version of the Command Class implemented in the device
 - * supported: flag if Command Class is supported or only controlled
 - * commandclass data: Command Class specific data see chapter 8 for details.
 - name: Command Class name
 - Method: Command Class method see chapter 8 for details.

7.6 Data

This is the description of the data object (called Data Holder or DH).

General note: Z-Way objects and it's decendents are NOT simple JS objects, but native JS objects, that does not allow object modification.

- name: Name of data tree element
- updated: Update time
- invalidated: Invalidate time
- valueOf(): Returns value of the object (can be omitted to get object value)
- invalidate(): Invalidate data value (mark is as not valid anymore)
- bind(function (type[, arg]) ..., [arg, [watchChildren=false]]): Bind function to a change of data tree element of its descendants
- unbind(function): Unbind function bind previously with bind()

Chapter 8

Command Class Reference

Command Classes are groups of wireless commands that allow using certain functions of a Z-Wave device. In Z-Wave each Z-Wave device has a data holder entry for each Command Class supported. During the inclusion and interview of the device the Command Class structure is instantiated in the data holder and filled with certain data. Command Class commands change values of the corresponding data holder structure. The follow list shows the public commands of the Command Classes supported with their parameters and the data holder objects changed.

In Expert UI navigate to Expert tab under Configuration page of a device to execute commands of the supported Command Classes and visualizes all data holder elements in as tree in a simplified UI.

8.1 Command Class Basic (0x20/32)

Version 1, Supported and Controlled

The Basic Command Class is the wildcard command class. Almost all Z-Wave devices support this command class but they interpret it's commands in different ways. A thermostat will handle a Basic Set Command in a different way than a Dimmer but both accept the Basic Set command and act. Used for generic interoperability between devices. You should always use more specific Command Classes where possible.

Data holders:

• level: Generic switching level of the device controlled

Command Basic Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Basic Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: level updated

Command Basic Set

Syntax: Set(value, successCallback = NULL, failureCallback = NULL)

Description: Send Basic Set

Parameter value: Value

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: level updated

8.2 Command Class Wakeup (0x84/132)

Version 2, Controlled

Allows to manage periodical wakeup of sleeping battery operated device. Upon wakeup device will notify one node listed in nodeId. NB! If the device can wake up by interrupt (user interaction, button press, sensor trigger), it might happen that the device never wakes up. This

can happen if you wake up the device by interrupe each time before internal chip wakeup period (usually from 1 to 4 minutes) reaches. (Z-Wave chip can not count for remaining time to next wakeup, so will restart timer again). This means that strictly speaking you can not rely on long time no wake up as an indicator of lost/damaged device or battery empty. NB! To save battery it is recommended to tune wakeup period to one week or even more for devices that do only need to report battery on wakeup (remote controls). For sensors it is recommended to have at least one hour wakeup period.

Data holders:

• interval: Wakeup interval in seconds

• nodeId: Node to notify about wakeup

• min: Minimal possible wakeup interval

• max: Maximal possible wakeup interval

• default: Factory default wakeup interval

• step: Step for wakeup interval (values are rounded to next or previous step)

• last Wakeup: Last time the device has sent us wake notification (Unix timestamp)

• lastSleep: Last time the device was sent into sleep mode (Unix timestamp)

Command Wakeup Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Wakeup Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: interval and nodeId updated

Command Wakeup CapabilitiesGet

Syntax: CapabilitiesGet(successCallback = NULL, failureCallback = NULL)

 ${\bf Description:} \ {\bf Send} \ {\bf Wakeup} \ {\bf CapabilityGet}$

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: min, max, default, step updated

Command Wakeup Sleep

Syntax: Sleep(successCallback = NULL, failureCallback = NULL)

Description: Send Wakeup NoMoreInformation (Sleep)

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: lastSleep updated

Command Wakeup Set

Syntax: Set(interval, notificationNodeId, successCallback = NULL, failureCallback = NULL)

Description: Send Wakeup Set

Parameter interval: Wakeup interval in seconds

Parameter notificationNodeId: Node Id to be notified about wakeup

 $\label{eq:constraint} Parameter \ success Callback: \ Custom \ function \ to \ be \ called \ on \ function \ success. \ NULL$

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: interval and nodeId updated

8.3 Command Class NoOperation (0x00/0)

Used to check if device is reachable by sending empty packet.

8.4 Command Class Battery (0x80/128)

Version 1, Controlled

Allows monitoring the battery charging level of a device.

Data holders:

- last: Last battery level reported (0..100%)
- lastChange: Time (UNIX timestamp) when the battery was replaced last time (time of the moment when the value reported was way bigger than previous one)
- history: Subtree with history
- [% value]: Time when battery level reached this % value (0, 10, 20,... 100)

Command Battery Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Battery Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: last updated. lastChange updated if battery level is way higher than it was

before, history updated if reached next 10% step

8.5 Command Class ManufacturerSpecific (0x72/114)

Version 2, Supported and Controlled

Reports vendor information, product type and ID and device serial number.

Data holders:

• vendorId: Vendor ID assigned by Sigma Designs

• vendor: Vendor name

• productId: Product ID

• productType: Product Type ID

• serialNumber: Product Serial Number

Command ManufacturerSpecific Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send ManufacturerSpecific Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command ManufacturerSpecific DeviceIdGet

Syntax: DeviceIdGet(type, successCallback = NULL, failureCallback = NULL)

Description: Send ManufacturerSpecific Device Id Get

Parameter type: Device Id type to request

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.6 Command Class Proprietary (0x88/136)

Version 1, Controlled

Allows to transfer manufacturer proprietary data. Data format is manufacturer specific.

Data holders:

• bytes: Binary bytes array of raw data

Command Proprietary Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Proprietary Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command Proprietary Set

Syntax: Set(data, successCallback = NULL, failureCallback = NULL)

Description: Send Proprietary Set

Parameter data: Data to set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.7 Command Class Configuration (0x70/112)

Version 1, Controlled

Used to set certian configuration valeus that change the behavior of the device. Z-Wave requires that every device works out of the box without further configuration. However different configuration value significantly enhance the value a device. Z-Wave does not provide any information about the configuration values by wireless commands. User have to look into the device manual to learn about configuration parameters. The Device Description Record (ZDDX), incoprotated by Z-Way gives information about valid parameters and the meaning of the values to be set.

Data holders:

• [paramId]: Configuration parameter subtree.

• val: Value assigned

• **size**: Size of that parameter (1, 2 or 4 bytes)

Command Configuration Get

Syntax: Get(parameter, successCallback = NULL, failureCallback = NULL)

Description: Send Configuration Get

Parameter parameter: Parameter number (from 1 to 255)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: parameter subtree updated or created if absent

Command Configuration Set

Syntax: Set(parameter, value, size = 0, successCallback = NULL, failureCallback = NULL)

Description: Send Configuration Set

Parameter parameter: Parameter number (from 1 to 255)

Parameter value: Value to be sent (negative and positive values are accepted, but will be stripped to size)

Parameter size: Size of the value (1, 2 or 4 bytes). Use 0 to guess from previously reported value if any. 0 means use size previously obtained Get

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: parameter subtree updated or created if absent

${\bf Command\ Configuration\ SetDefault}$

Syntax: SetDefault(parameter, successCallback = NULL, failureCallback = NULL)

Description: Send Configuration SetDefault

Parameter parameter: Parameter number to be set to device default

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: parameter subtree updated or created if absent

8.8 Command Class SensorBinary (0x30/48)

Version 2, Controlled

Allows receive binary sensor states.

Data holders:

- typemask: Internal. Bit mask of the supported types
- [sensorType]: Subtree for sensor type Id
- sensorTypeString: Description of sensor type
- level: Triggered/idle status

Command SensorBinary Get

Syntax: Get(sensorType = -1, successCallback = NULL, failureCallback = NULL)

Description: Send SensorBinary Get

Parameter sensor Type: Type of sensor to query information for .0xFF to query information for the first available sensor type. -1 to query information for all supported sensor types

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: sensorType subtree updated

8.9 Command Class Association (0x85/133)

Version 2, Supported and Controlled

Allows to manage the association groups: adding and removing nodeIDs in the association groups.

Data holders:

- groups: Number of association groups in the device
- \bullet [groupId]: Group subtree, where groupId = 1..groups
- max: Number of nodes the group can hold
- **nodes**: Array with nodes in the group
- nodesToFollow: Internal
- specificGroup: Number of specific association groups in the device

Command Association Get

Syntax: Get(groupId = 0, successCallback = NULL, failureCallback = NULL)

Description: Send Association Get

Parameter groupId: Group Id (from 1 to 255). 0 requests all groups

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: Subtree corresponding to the group updated

Command Association Set

Syntax: Set(groupId, includeNode, successCallback = NULL, failureCallback = NULL)

Description: Send Association Set (Add)

Parameter groupId: Group Id (from 1 to 255)

Parameter includeNode: Node to be added to the group

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: Subtree corresponding to the group updated

Command Association Remove

Syntax: Remove(groupId, excludeNode, successCallback = NULL, failureCallback = NULL)

NULL)

Description: Send Association Remove

Parameter group Id: Group Id (from 1 to 255)

Parameter excludeNode: Node to be removed from the group

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: Subtree corresponding to the group updated

Command Association GroupingsGet

Syntax: GroupingsGet(successCallback = NULL, failureCallback = NULL)

Description: Send Association GroupingsGet

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: Update number of supported groups and interview all groups

8.10 Command Class Meter (0x32/50)

Version 4, Controlled

Allows to read different kind of meters. Z-Wave differentiates different meter types and different meter scales. Please refer to the file translations/Scales.xml for details about possible meter types and values.

Data holders:

• scalemask: Internal. Bit mask with supported scales

• resettable: Flag to indicate of the meter can be resetted

• [scaleId]: Meter scale subtree

• scale: Meter scale id

• scaleString: Meter scale name

• **sensorType**: Sensor type id

• sensorTypeString: Sensor type name

• val: Meter value

• ratetype: Rate type

delta: Delta from the last value requested

• **previous**: Previous value requested

Command Meter Get

Syntax: Get(scale = -1, successCallback = NULL, failureCallback = NULL)

Description: Send Meter Get

Parameter scale: Desired scale. -1 for all scales

 $\label{eq:constraint} Parameter \ success Callback: \ Custom \ function \ to \ be \ called \ on \ function \ success. \ NULL$

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: scale subtree updated

Command Meter Reset

Syntax: Reset(successCallback = NULL, failureCallback = NULL)

Description: Send Meter Reset

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: scale subtree updated

Command Meter Supported

Syntax: Supported(successCallback = NULL, failureCallback = NULL)

Description: Send Meter SupportedGet

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.11 Command Class Meter Pulse (0x35/53)

Version 1, Controlled

Allows to gather information from pulse meters.

Data holders:

• val: Meter pulse value

Command MeterPulse Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send MeterPulse Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.12 Command Class SensorMultilevel (0x31/49)

Version 9, Controlled

Allows to read different kind of sensor. Z-Wave differentiates different sensor types and different scales of this sensor. Please refer to the file /translations/scales.xml for details about possible sensor types and values.

Data holders:

- typemask: Internal. Bit mask of the supported types
- [sensorTypeId]: Subtree for sensor type Id
- sensorTypeString: Description of sensor type
- scale: Scale Id
- scaleString: Scale description
- val: Value
- **size**: Internal. Size of the value (1, 2 or 4 bytes)
- precision: Internal. Precision used in value (number of digits after decimal dot)
- **deviceScale**: Internal. Scale Id on the device's side (if local conversion is used, like C-;F)

Command SensorMultilevel Get

Syntax: Get(sensorType = -1, successCallback = NULL, failureCallback = NULL)

Description: Send SensorMultilevel Get

Parameter sensor Type: Type of sensor to be requested. -1 means all sensor types supported by the device

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: sensorTypeId subtree updated

8.13 Command Class Sensor Configuration (0x9E/158)

Version 1, Controlled

Allows to configure senors specific configuration like trigger level. Works in conjunction with SensorMultilevel Command Class. In modern devices replaced by Configuration Command Class.

Data holders:

 \bullet ${\bf sensorType} :$ Sensor type Id

• sensorTypeString: Sensor type descirption

• val: Trigger value

• scale: Scale of trigger value

• scaleString: Scale description

• size: Internal. Size of the value (1, 2 or 4 bytes)

• precision: Internal. Precision used in value (number of digits after decimal dot)

Command SensorConfiguration Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send SensorConfiguration Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: all dataholders are updated

Command SensorConfiguration Set

Syntax: Set(mode, value, successCallback = NULL, failureCallback = NULL)

Description: Send SensorConfiguration Set

Parameter mode: Value set mode

Parameter value: Value

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: all dataholders are updated

8.14 Command Class SwitchAll (0x27/39)

Version 1, Supported and Controlled

Controls the behavior of a actuator on Switch All commands. Also allows to send Switch All commands.

Data holders:

- mode: Which type of SwitchAll On/Off commands to react on: 0 for none, 1 to react on Off only, 2 to react on On only, 255 to react on both
- onOff: Allows to trigger SwitchAll On/Off commands from other devices. Set to False on Off command received and True on On command.

Command SwitchAll Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send SwitchAll Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: mode updated

Command SwitchAll Set

Syntax: Set(mode, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchAll Set

Parameter mode: SwitchAll Mode: see definitions below

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: mode updated

Command SwitchAll SetOn

Syntax: SetOn(successCallback = NULL, failureCallback = NULL)

Description: Send SwitchAll Set On

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command SwitchAll SetOff

Syntax: SetOff(successCallback = NULL, failureCallback = NULL)

Description: Send SwitchAll Set Off

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.15 Command Class SwitchBinary (0x25/37)

Version 1, Supported and Controlled

Allows to control On/Off switches, actuators, electrical power switches and trap On/Off control commands from other devices.

Data holders:

 \bullet level: State: False for Off, True for On

Command SwitchBinary Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send SwitchBinary Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: level updated

Command SwitchBinary Set

Syntax: Set(value, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchBinary Set

Parameter value: Value

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: level updated

8.16 Command Class SwitchMultilevel (0x26/38)

Version 1, Supported and Controlled

Allows to control all actuators with multilevel switching functions, primarily Dimmers and Motor Controlling devices as well as trap dim events sent by remotes.

Data holders:

• level: State 0...99 = 0...100%, 255 for On on last value (or on maximum - device specific)

• startChange: Dimming up or down. Updated on dimming start. Allows to trap events from remotes to controller.

• stopChange: Updated on dimming end. Allows to trap events from remotes to controller.

prevLevel: Internal primary: Unused

• secondary: Unsued

Command SwitchMultilevel Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send SwitchMultilevel Get

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: level updated

Command SwitchMultilevel Set

Syntax: Set(level, duration = 0xff, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchMultilevel Set

Parameter level: Level to be set

Parameter duration: Duration of change:. 0 instantly. 0x01...0x7f in seconds. 0x80...0xfe in minutes mapped to 1...127 (value 0x80=128 is 1 minute). 0xff use device factory default

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: level updated

Command SwitchMultilevel StartLevelChange

Syntax: StartLevelChange(dir, duration = 0xff, ignoreStartLevel = TRUE, startLevel = 50, incdec = 0, step = 0xff, successCallback = NULL, failureCallback = NULL)

 $Description: \ Send \ Switch Multilevel \ Start Level Change$

Parameter dir: Direction of change: 0 to incrase, 1 to decrase

Parameter duration: Duration of change:. 0 instantly. 0x01...0x7f in seconds. 0x80...0xfe in minutes mapped to 1...127 (value 0x80=128 is 1 minute). 0xff use device factory default

Parameter ignoreStartLevel: If set to True, device will ignore start level value and will use it's curent value

Parameter startLevel: Start level to change from

Parameter incdec: Increment/decrement type for step:. 0 Increment. 1 Decrement. 2 Reserved. 3 No Inc/Dec

Parameter step: Step to be used in level change in percentage. 0...99 mapped to 1...100%. 0xff uses device factory default

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: level updated

Command SwitchMultilevel StopLevelChange

 $Syntax:\ StopLevelChange(successCallback = NULL,\ failureCallback = NULL)$

Description: Send SwitchMultilevel StopLevelChange

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: level updated

8.17 Command Class MultiChannelAssociation (0x8E/142)

Version 3, Supported and Controlled

This is an extention to the Association Command Class. It follows the same logic as the Association Command Class and has the same commands but accepts different instance values.

Data holders:

- **groups**: Number of association groups in the device (can be smaller than the number of groups in Association)
- [groupId]: Group subtree, where groupId = 1..groups
- max: Number of nodes/instances the group can hold
- **nodesInstances**: Array with nodes/instances in the group. Each pair is represented by two elements (node, instance).
- nodesInstancesToFollow: Internal

Command MultiChannelAssociation Get

Syntax: Get(groupId = 0, successCallback = NULL, failureCallback = NULL)

Description: Send MultiChannelAssociation Get

Parameter groupId: Group Id (from 1 to 255). 0 requests all groups

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: Subtree corresponding to the group updated

Command MultiChannelAssociation Set

Syntax: Set(groupId, includeNode, includeInstance, successCallback = NULL, failureCallback = NULL)

Description: Send MultiChannelAssociation Set (Add)

Parameter groupId: Group Id (from 1 to 255)

Parameter includeNode: Node to be added to the group

Parameter includeInstance: Instance of the node to be added to the group

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: Subtree corresponding to the group updated

Command MultiChannelAssociation Remove

Syntax: Remove(groupId, excludeNode, excludeInstance, successCallback = NULL, failureCallback = NULL)

Description: Send MultiChannelAssociation Remove

Parameter groupId: Group Id (from 1 to 255)

Parameter excludeNode: Node to be removed from the group

Parameter excludeInstance: Instance of the node to be removed from the group

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: Subtree corresponding to the group updated

Command MultiChannelAssociation GroupingsGet

Syntax: GroupingsGet(successCallback = NULL, failureCallback = NULL)

Description: Send MultiChannelAssociation GroupingsGet

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.18 Command Class MultiChannel (0x60/96)

Version 3, Supported and Controlled

Allows to communicate with internal parts of device called channels or instances. Implemented transparently by the library.

Data holders:

• endPoints: Number of endpoints

• [endPointId]: Endpoint ID

• aggregated: Number of aggregated endpoints

• [endPointId]: Aggregated endpoint ID (numbering starts from endPoints + 1)

• **dynamic**: Flag describing if endpoins are dynamic (their number and type can change over time)

• identical: Internal. Flag describing if endpoins are identical

• myInstance: Internal

• doneIds: Internal

Command MultiChannel Get

 $Syntax: \ Get(ccId, \ successCallback = NULL, \ failureCallback = NULL)$

Description: Send MultiChannel Get (MultiInstance V1 command). Reports number of channels supporting a defined Command Class. Depricated by MutliChannel V2, needed for old devices only

Parameter ccId: Command Class Id in question

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command MultiChannel EndpointFind

Syntax: EndpointFind(generic, specific, successCallback = NULL, failureCallback = NULL)

Description: Send MultiChannel Endpoint Find. Note that MultiChannel EndpointFind Report is not supported as useless. But one can still trap the response packet in logs

Parameter generic: Generic type in search

Parameter specific: Specific type in search

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command MultiChannel EndpointGet

Syntax: EndpointGet(successCallback = NULL, failureCallback = NULL)

Description: Send MultiChannel Endpoint Get. Get the number of available endpoints

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command MultiChannel CapabilitiesGet

 $Syntax:\ CapabilitiesGet(endpoint, successCallback = NULL, failureCallback = NULL)$

Description: Send MultiChannel Capabilities Get. Request information about the specified endpoint

Parameter endpoint: Endpoint in question

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

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${\bf Command\ MultiChannel\ Aggregated Members Get}$

Syntax: Aggregated Members Get (endpoint, success Callback = NULL, failure Callback = NULL)

Description: Send MultiChannel Aggregated Members Get. Request information about endpoints in the specified aggregated endpoint (v4 and above)

Parameter endpoint: Aggregated endpoint in question

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.19 Command Class Node Naming (0x77/119)

Version 1, Controlled

Allows assigning a readable string for a name and a location to a physical device. The two strings are stored inside the device and can be obtained upon request. There are no restrictions to the name except the maximum length up to 16 characters.

Data holders:

• nodename: Node name

• nameEncoding: NodeNmae encoding

• location: Location

• locationEncoding: Location encoding

Command NodeNaming Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send NodeNaming GetName and GetLocation

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: nodename, nameEncoding, location and locationEncoding updated

Command NodeNaming GetName

Syntax: GetName(successCallback = NULL, failureCallback = NULL)

Description: Send NodeNaming GetName

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: nodename and nameEncoding updated

Command NodeNaming GetLocation

Syntax: GetLocation(successCallback = NULL, failureCallback = NULL)

Description: Send NodeNaming GetLocation

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: location and locationEncoding updated

Command NodeNaming SetName

Syntax: SetName(name, successCallback = NULL, failureCallback = NULL)

Description: Send NodeNaming SetName

Parameter name: Value

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: nodename and nameEncoding updated

Command NodeNaming SetLocation

Syntax: SetLocation(location, successCallback = NULL, failureCallback = NULL)

Description: Send NodeNaming SetLocation

Parameter location: Value

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: location and locationEncoding updated

8.20 Command Class Thermostat SetPoint (0x43/67)

 $Version \ 3, \ Controlled$

Allows to set a certain setpoint to a thermostat (set temperature to maintain). The command class can be applied to different kind of thermostats (heating, cooling, ...), hence it has various modes.

Data holders:

• [modeId]: Subtree for mode

• modeName: Mode description

• scale: Scale Id

• scaleString: Scale description

• val: Temperature to maintain

- setVal: Last set temperature to maintain (might differ from val until thermostat wakeup)
- **min**: Minimal temperature value supported by the device
- max: Maximal temperature value supported by the device
- **size**: Internal. Size of the value (1, 2 or 4 bytes)
- **precision**: Internal. Precision used in value (number of digits after decimal dot)
- **deviceScale**: Internal. Scale Id on the device side (if local conversion is used, like C-iF)
- deviceScaleString: Internal. Scale description of the device
- modemask: Internal. Bit mask with supported modes
- \bullet danfossBugFlag: Internal

Command ThermostatSetPoint Get

 $Syntax: \ Get(mode = -1, \ successCallback = \ NULL, \ failureCallback = \ NULL)$

Description: Send ThermostatSetPoint Get

Parameter mode: Thermostat Mode. -1 requests for all modes

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: modeId subtree updated

Command ThermostatSetPoint Set

Syntax: Set(mode, value, successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatSetPoint Set

Parameter mode: Thermostat Mode

Parameter value: temperature

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: modeId subtree updated

8.21 Command Class Thermostat Mode (0x40/64)

Version 3, Controlled

Allows to switch a heating/cooling actuator in different modes.

Data holders:

• modemask: Internal. Bit mask with supported modes

• mode: Current mode

• [modeId]: Mode subtree

• modeName: Mode description

Command ThermostatMode Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatMode Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command ThermostatMode Set

Syntax: Set(mode, successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatMode Set

Parameter mode: Thermostat Mode

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.22 Command Class Thermostat Fan Mode (0x44/68)

Version 4, Controlled

Allows to controls fan modes in thermostats.

Data holders:

• modemask: Internal. Bit mask with supported modes

• mode: Current mode

• [modeId]: Mode subtree

modeName: Mode description

• on: Reports if fan is currently On (True) or Off (False)

Command ThermostatFanMode Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatFanMode Get

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: mode and on updated

Command ThermostatFanMode Set

Syntax: Set(on, mode, successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatFanMode Set

Parameter on: TRUE to turn fan on (and set mode), FALSE to comletely turn off (mode is ignored)

Parameter mode: Thermostat Fan Mode

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: mode and on updated

8.23 Command Class Thermostat Fan State (0x45/69)

Version 2, Controlled

Allows to determine the operating state of the fan. V2 is not yet implemented.

Data holders:

• state: Fan current state (0 Off, 1 Running)

Command ThermostatFanState Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatFanState Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: state and on updated

8.24 Command Class Thermostat Operating State (0x42/66)

Version 2, Controlled

Allows to determine the operating state of the thermostat and state change history.

Data holders:

- state: Current operation state
- statemask: Internal. Bit mask of supported logs for each state
- [stateId]: Subtree with state log info
- today: Number of minutes thermostat was in this state today (since 0:00)
- yesterday: Number of minutes thermostat was in this state yesterday (since 0:00)

Command ThermostatOperatingState Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatOperatingState Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: state updated

Command ThermostatOperatingState LoggingGet

Syntax: LoggingGet(state, successCallback = NULL, failureCallback = NULL)

Description: Send ThermostatOperatingState Logging Get

Parameter state: State number to get logging for. 0 to get log for all supported states

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: stateId subtree updated updated

8.25 Command Class Alarm Sensor (0x9C/156)

Version 1, Controlled

Deprecated Command Class. Now Alarm/Notification is used instead.

Data holders:

• alarmMap: Internal. Bit mask of supported alarm types

• alarms: Unused

• [alarmTypeId]: Alarm type subtree

• **srcId**: Source of event

• sensorState: Alarm state

• sensorTime: Alarm time (according to the sender)

• typeString: Name of alarm type

Command AlarmSensor SupportedGet

Syntax: SupportedGet(successCallback = NULL, failureCallback = NULL)

Description: Send AlarmSensor SupportedGet

Parameter success Callback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: List of supported types updated

Command AlarmSensor Get

Syntax: Get(type = -1, successCallback = NULL, failureCallback = NULL)

Description: Send AlarmSensor Get. Requests the status of the alarm sensor of a

given type

Parameter type: Alarm type to get. -1 means get all types

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: Alarm type subtree updated

8.26 Command Class Door Lock (0x62/98)

Version 2, Controlled

Allows to operate an electronic door lock. This Command Class is ALWAYS encapsulated in Security. Door lock modes are the following:.

- 0x00 Door Unsecured (Open).
- 0x01 Door Unsecured with timeout.
- 0x10 Door Unsecured for inside Door Handles.
- 0x11 Door Unsecured for inside Door Handles with timeout.
- 0x20 Door Unsecured for outside Door Handles.
- 0x21 Door Unsecured for outside Door Handles with timeout.
- 0xFE Door/Lock Mode Unknown (bolt not fully retracted/engaged).
- 0xFF Door Secured (closed).

Data holders:

- mode: Operating mode of the lock
- insideMode: Bit mask describing if a specific handles (1..4) can open the door from inside
- outsideMode: Bit mask describing if a specific handles (1..4) can open the door from outside
- lockMinutes: Time remaind before autolock (minutes, 0xFE for no autolock)
- lockSeconds: Time remaind before autolock (seconds, 0xFE for no autolock)
- **condition**: Bit mask describing lock components: bit 0: Door Open(0)/Close(1), bit 1: Bolt Locked(0)/Unlocked(1), bit 2: Latch Open(0)/Close(1)
- insideState: Bit mask describing if a specific handles (1..4) can open the door from inside
- outsideState: Bit mask describing if a specific handles (1..4) can open the door from outside
- timeoutMinutes: Timeout for autolock (minutes, 0xFE for no autolock)
- timeoutSeconds: Timeout for autolock (seconds, 0xFE for no autolock)
- opType: 0x01 for constant operation, 0x02 for autolock

Command DoorLock Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send DoorLock Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: mode, insideMode, outsideMode, lockMinutes, lockSeconds and condition

updated

Command DoorLock ConfigurationGet

Syntax: ConfigurationGet(successCallback = NULL, failureCallback = NULL)

Description: Send DoorLock Configuration Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: insideState, outsideState, timeoutMinutes, timeoutSeconds, opType updated

Command DoorLock Set

Syntax: Set(mode, successCallback = NULL, failureCallback = NULL)

Description: Send DoorLock Set

Parameter mode: Lock mode

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: mode, insideMode, outsideMode, lockMinutes, lockSeconds and condition

updated

Command DoorLock ConfigurationSet

 $Syntax:\ ConfigurationSet (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ ConfigurationSet (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ inside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ lock Min,\ lock Sec,\ successful Syntax;\ Configuration Set (op Type,\ outside State,\ lock Min,\ lock Sec,\ successful Syntax;\ lock Min,\ lock$

 ${\it cessCallback} = {\it NULL}, \, {\it failureCallback} = {\it NULL})$

Description: Send DoorLock Configuration Set

Parameter opType: Operation type

Parameter outsideState: State of outside door handle

Parameter insideState: State of inside door handle

Parameter lockMin: Lock after a specified time (minutes part)

Parameter lockSec: Lock after a specified time (seconds part)

 $\label{eq:continuous} Parameter \ success Callback: \ Custom \ function \ to \ be \ called \ on \ function \ success. \ NULL$

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: insideState, outsideState, timeoutMinutes, timeoutSeconds, opType updated

8.27 Command Class Door Lock Logging (0x4C/76)

Version 1, Controlled

Allows to receive reports about all successful and failed activities of the electronic door lock. Event types are the following:.

- 1 Lock Command: Keypad access code verified lock command.
- 2 Unlock Command: Keypad access code verified unlock command.
- 3 Lock Command: Keypad lock button pressed.
- 4 Unlock command: Keypad unlock button pressed.
- 5 Lock Command: Keypad access code out of schedule.
- 6 Unlock Command: Keypad access code out of schedule.
- 7 Keypad illegal access code entered.
- 8 Key or latch operation locked (manual).
- 9 Key or latch operation unlocked (manual).
- 10 Auto lock operation.
- 11 Auto unlock operation.
- 12 Lock Command: Z-Wave access code verified.
- 13 Unlock Command: Z-Wave access code verified.
- 14 Lock Command: Z-Wave (no code).
- 15 Unlock Command: Z-Wave (no code).
- 16 Lock Command: Z-Wave access code out of schedule.
- 17 Unlock Command Z-Wave access code out of schedule.
- 18 Z-Wave illegal access code entered.
- 19 Key or latch operation locked (manual).
- 20 Key or latch operation unlocked (manual).
- 21 Lock secured.
- 22 Lock unsecured.
- 23 User code added.
- 24 User code deleted.
- 25 All user codes deleted.
- 26 Master code changed.
- 27 User code changed.
- 28 Lock reset.

- 29 Configuration changed.
- 30 Low battery.
- 31 New Battery installed.

Data holders:

• maxRecords: Maximum number of records the lock can store. Olded records are reused first

• [recordId]: Subtree storing log record

• **time**: Time of the event

• **event**: Event type

• uId: UserID (from UserCode Command Class)

• **eventString**: Event type description

Command DoorLockLogging Get

Syntax: Get(record = 0, successCallback = NULL, failureCallback = NULL)

Description: Send DoorLockLogging Get

Parameter record: Record number to get, or 0 to get last records

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

ii camback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: record subtree updated

8.28 Command Class User Code (0x63/99)

Version 1, Controlled

Allows to define individual user entry code in electrnic door lock.

Data holders:

• maxUsers: Maximum number of supported users

• [userId]: User subtree

• code: User code

• **status**: Status of the user: 0 for available (no code set), 1 for occupied (code set), 2 for reserved by administrator

• hasCode: Flag if a valid code is set (in case device reports occupied, but code is not valid (less than 4 symbols) or code not set but old is still reported by the device)

Command UserCode Get

Syntax: Get(user = -1, successCallback = NULL, failureCallback = NULL)

Description: Send UserCode Get

Parameter user: User index to get code for (1...maxUsers). -1 to get codes for all

users

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId subtree updated

Command UserCode Set

Syntax: Set(user, code, status, successCallback = NULL, failureCallback = NULL)

Description: Send UserCode Set

Parameter user: User index to set code for (1...maxUsers). 0 means set for all users

Parameter code: Code to set (4...10 characters long)

Parameter status: Code status to set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId subtree updated

Command UserCode SetRaw

Syntax: SetRaw(user, code, status, successCallback = NULL, failureCallback = NULL)

Description: Send UserCode Set (raw)

Parameter user: User index to set code for (1...maxUsers). 0 means set for all users

Parameter code: Code to set (4...10 bytes long)

Parameter status: Code status to set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId subtree updated

8.29 Command Class Time (0x8A/138)

Version 2, Supported and Controlled

Allows to report to devices in Z-Wave network time and date as well as time zone offset and daylight savings parameters. The data formats are based on the International Standard ISO 8601.

Command Time TimeGet

Syntax: TimeGet(successCallback = NULL, failureCallback = NULL)

Description: Send Time TimeGet

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command Time DateGet

Syntax: DateGet(successCallback = NULL, failureCallback = NULL)

Description: Send Time DateGet

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command Time OffsetGet

Syntax: OffsetGet(successCallback = NULL, failureCallback = NULL)

Description: Send Time TimeOffsetGet

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.30 Command Class Time Parameters (0x8B/139)

Version 1, Controlled

Used to set date and time. Time zone offset and daylight savings may be set in the Time Command Class. The data formats are based on the International Standard ISO 8601.

Command TimeParameters Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send TimeParameters Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command TimeParameters Set

Syntax: Set(successCallback = NULL, failureCallback = NULL)

Description: Send TimeParameters Set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.31 Command Class Clock (0x81/129)

Version 1, Supported and Controlled

Sync clock on the device with controller system clock.

Command Clock Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Clock Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: reported value ignored

Command Clock Set

Syntax: Set(successCallback = NULL, failureCallback = NULL)

Description: Send Clock Set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.32 Command Class Scene Activation (0x2B/43)

Version 1, Supported and Controlled

Allows to activate scenes on devices and trap scene activation events from remotes.

Data holders:

- currentScene: Scene activated from remote
- dimmingDuration: Dimming duration for the activated scene

Command SceneActivation Set

Syntax: Set(sceneId, dimmingDuration = 0xff, successCallback = NULL, failureCallback = NULL)

Description: Send SceneActivation Set

Parameter sceneId: Scene Id

Parameter dimmingDuration: Dimming duration

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.33 Command Class Scene Controller Conf (0x2D/45)

Version 1, Controlled

Allows to set scene Id to be activated using SceneActivation Command Class on a remote.

Data holders:

- [groupId]: Subtree for a given association group number (defined by Association Command Class)
- scene: Scene to activate for all devices in the group
- duration: Duration for scene activation

Command SceneControllerConf Get

Syntax: Get(group = 0, successCallback = NULL, failureCallback = NULL)

Description: Send SceneControllerConf Get

Parameter group: Group Id. 0 requests all groups

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: group subtree updated

Command SceneControllerConf Set

Syntax: Set(group, scene, duration = 0x0, successCallback = NULL, failureCallback = NULL)

Description: Send SceneControllerConf Set

Parameter group: Group Id

Parameter scene: Scene Id

Parameter duration: Duration

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: group subtree updated

8.34 Command Class Scene Actuator Conf (0x2C/44)

Version 1, Controlled

Allows to configure actuators to set specified level on a given scene activation by SceneActivation Command Class.

Data holders:

• [sceneId]: Subtree for scene

• **level**: Level to set on scene activation

• **dimming**: Default dimming duration to use

• currentScene: Currently activated scene

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Command SceneActuatorConf Get

Syntax: Get(scene = 0, successCallback = NULL, failureCallback = NULL)

Description: Send SceneActuatorConf Get

Parameter scene: Scene Id. 0 means get current scene

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: scene subtree updated, currentScene updated (if scene = 0)

Command SceneActuatorConf Set

Syntax: Set(scene, level, dimming = 0xff, override = TRUE, successCallback = NULL, failureCallback = NULL)

Description: Send SceneActuatorConf Set

Parameter scene: Scene Id

Parameter level: Level

Parameter dimming: Dimming

Parameter override: If false then the current settings in the device is associated with

the Scene Id. If true then the Level value is used

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: scene subtree updated

8.35 Command Class Indicator (0x87/135)

Version 1, Controlled

Operates the indicator on the device if available. Can be used to identify a device or use the indicator for special purposes (show away/at home mode).

Data holders:

• stat: Status of the indicator

Command Indicator Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Indicator Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: stat updated

Command Indicator Set

Syntax: Set(val, successCallback = NULL, failureCallback = NULL)

Description: Send Indicator Set

Parameter val: Value to set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: stat updated

8.36 Command Class Protection (0x75/117)

Version 2, Controlled

Allows to disable local and RF control of the device.

Data holders:

- state: Local control state (0 = Unprotected, 1 = Protected by sequence, 2 = Protected)
- rfState: Control via RF state (0 = Unprotected, 1 = No RF control, 2 = No RF response at all)
- exclusive: Flag describing if exclusive control via RF is supported
- timeout: Flag describing if timeout of protection of control via RF is supported
- stateCap: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support
- rfStateCap: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support
- exclusiveCap: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support
- timeoutCap: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support

Command Protection Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Protection Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: state, rfState updated

Command Protection Set

Syntax: Set(state, rfState = 0, successCallback = NULL, failureCallback = NULL)

Description: Send Protection Set

Parameter state: Local control protection state

Parameter rfState: RF control protection state

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: state and rfState updated

Command Protection ExclusiveGet

Syntax: ExclusiveGet(successCallback = NULL, failureCallback = NULL)

Description: Send Protection Exclusive Control Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command Protection ExclusiveSet

Syntax: ExclusiveSet(controlNodeId, successCallback = NULL, failureCallback = NULL)

Description: Send Protection Exclusive Control Set

Parameter controlNodeId: Node Id to have exclusive control over destination node

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command Protection TimeoutGet

Syntax: TimeoutGet(successCallback = NULL, failureCallback = NULL)

Description: Send Protection Timeout Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command Protection TimeoutSet

Syntax: TimeoutSet(timeout, successCallback = NULL, failureCallback = NULL)

Description: Send Protection Timeout Set

Parameter timeout: Timeout in seconds. 0 is no timer set. -1 is infinite timeout. max value is 191 minute (11460 seconds). values above 1 minute are rounded to 1 minute boundary

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.37 Command Class Schedule Entry Lock (0x4E/78)

Version 3, Controlled

Allows to define individual time intervals for access to a door lock per user. Refers to users defined by User Code Command Class.

Data holders:

• weekDaySlots: Number of weekday slots supported

• yearSlots: Number of date slots supported

• [userId]: Subtree for userId

• Weekday: Subtree for weekday schedule

• [slotId]: Subtree slotId

• dayOfWeek: Day of week

• startHour: Start hour

• startMinute: Start minute

• **stopHour**: Stop hour

• stopMinute: Stop minute

• Year: Subtree for date schedule

• [slotId]: Subtree slotId

• startYear: Start year

• startMonth: Start month

• startDay: Start day

• startHour: Start hour

• startMinute: Start minute

• **stopYear**: Stop year

• **stopMonth**: Stop month

• **stopDay**: Stop day

• **stopHour**: Stop hour

• stopMinute: Stop minute

Command ScheduleEntryLock Enable

 $Syntax:\ Enable(user,\ enable,\ successCallback=NULL,\ failureCallback=NULL)$

Description: Send ScheduleEntryLock Enable(All)

Parameter user: User to enable/disable schedule for. 0 to enable/disable for all users

Parameter enable: TRUE to enable schedule, FALSE otherwise

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command ScheduleEntryLock WeekdayGet

 $Syntax:\ WeekdayGet(user,\ slot,\ successCallback=NULL,\ failureCallback=NULL)$

Description: Send ScheduleEntryLock Weekday Get

Parameter user: User to get schedule for. 0 to get for all users

Parameter slot: Slot to get schedule for. 0 to get for all slots

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId-¿Weekday-¿slotId subtree updated

Command ScheduleEntryLock WeekdaySet

Syntax: WeekdaySet(user, slot, dayOfWeek, startHour, startMinute, stopHour, stop-

Minute, successCallback = NULL, failureCallback = NULL)

Description: Send ScheduleEntryLock Weekday Set

Parameter user: User to set schedule for

Parameter slot: Slot to set schedule for

Parameter day OfWeek: Weekday number (0..6).
 $0 = \mbox{Sunday}.$. $6 = \mbox{Saturday}$

Parameter startHour: Hour when schedule starts (0..23)

Parameter startMinute: Minute when schedule starts (0..59)

Parameter stopHour: Hour when schedule stops (0..23)

Parameter stopMinute: Minute when schedule stops (0..59)

 $\label{eq:constraint} Parameter \ success Callback: \ Custom \ function \ to \ be \ called \ on \ function \ success. \ NULL$

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId-¿Weekday-¿slotId subtree updated

Command ScheduleEntryLock YearGet

Syntax: YearGet(user, slot, successCallback = NULL, failureCallback = NULL)

Description: Send ScheduleEntryLock Year Get

Parameter user: User to enable/disable schedule for. 0 to get for all users

Parameter slot: Slot to get schedule for. 0 to get for all slots

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId-¿Year-¿slotId subtree updated

Command ScheduleEntryLock YearSet

Syntax: YearSet(user, slot, startYear, startMonth, startDay, startHour, startMinute, stopYear, stopMonth, stopDay, stopHour, stopMinute, successCallback = NULL, failureCallback = NULL)

Description: Send ScheduleEntryLock Year Set

Parameter user: User to set schedule for

Parameter slot: Slot to set schedule for

Parameter startYear: Year in current century when schedule starts (0..99)

Parameter startMonth: Month when schedule starts (1..12)

Parameter startDay: Day when schedule starts (1..31)

Parameter startHour: Hour when schedule starts (0..23)

Parameter startMinute: Minute when schedule starts (0..59)

Parameter stop Year: Year in current century when schedule stops (0..99)

Parameter stopMonth: Month when schedule stops (1..12)

Parameter stopDay: Day when schedule stops (1..31)

Parameter stopHour: Hour when schedule stops (0..23)

Parameter stopMinute: Minute when schedule stops (0..59)

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: userId-¿Year-¿slotId subtree updated

8.38 Command Class Climate Control Schedule (0x46/70)

Version 1, Supported and Controlled

Obsolete but still partly implemented for legacy support.

Data holders:

 \bullet $\mathbf{overrideType} :$ Type of current override

• overrideState: State of override

Command ClimateControlSchedule OverrideGet

Syntax: OverrideGet(successCallback = NULL, failureCallback = NULL)

Description: Send ClimateControlSchedule Override Get

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command ClimateControlSchedule OverrideSet

Syntax: OverrideSet(overrideType, overrideState, successCallback = NULL, failure-Callback = NULL)

Description: Send ClimateControlSchedule Override Set

Parameter override Type: Override type to set. (0 no override, 1 temporary override, 2 permanent override)

Parameter overrideState: Override state. -128 (0x80) ... -1 (0xFF): setpoint -12.8 ... -0.1 degrees. 0 (0x00): setpoint. 1 (0x01) ... 120 (0x78): setpoint +0.1 ... +12 degrees. 121 (0x79): frost protection. 122 (0x7A): energy saving. 123 (0x7B) ... 126 (0x7D): reserved. 127 (0x7F): unused

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.39 Command Class MeterTableMonitor (0x3D/61)

Version 2, Controlled

Allows to read historical and accumulated values in physical units from a water meter or other metering device (gas, electric etc.) and thereby enabling automatic meter reading capabilities.

Data holders:

• adminId: Meter administrator ID

• Id: Customer ID

• rateType: Type of rate (export or import)

• payMeter: Specifies the way the account is done

• **meterType**: Meter type

• meterTypeString: Meter description

- dataSetMask: Internal. Bit mask with type of data set supported
- dataSetHistoryMask: Internal. Bit mask with type of data set history supported
- maxHistory: Max number of records the device can store
- statusMask: Internal. Bit mask with type of events supported
- maxEvents: Max number of events the device can store
- [dataSetId]: Subtree for data set
- val: Meter value for this data set
- **time**: Time corresponding to the value
- scale: Scale ID
- scaleString: Scale description
- history: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support
- status: Subtree with statuses
- [statuseId]: Subtree with specific status ID
- statusString: Status descirption
- active: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support
- time: Requires Z-Wave specification re-read. Please contact Z-Wave.Me support

Command MeterTableMonitor StatusDateGet

Syntax: StatusDateGet(maxResults = 0, startDate, endDate, successCallback = NULL, failureCallback = NULL)

Description: Send Status Table
Monitor Status Get for a range of dates

Parameter maxResults: Maximum number of entries to get from log. 0 means all matching entries

Parameter startDate: Start date and time (local UNIX time)

Parameter endDate: End date and time (local UNIX time)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

${\bf Command\ Meter Table Monitor\ Status Depth Get}$

Syntax: StatusDepthGet(maxResults = 0, successCallback = NULL, failureCallback = NULL)

Description: Send Status Table Monitor Status Get for specified depth

Parameter maxResults: Number of entries to get from log. 0 means current status only. 0xFF means all entries

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command MeterTableMonitor CurrentDataGet

Syntax: CurrentDataGet(setId = 0, successCallback = NULL, failureCallback = NULL)

Description: Send StatusTableMonitor Current Data Get

Parameter setId: Index of dataset to get data for. 0 to get data for all supported datasets

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command MeterTableMonitor HistoricalDataGet

Syntax: HistoricalDataGet(setId = 0, maxResults = 0, startDate, endDate, success-Callback = NULL, failureCallback = NULL)

Description: Send StatusTableMonitor Historical Data Get

Parameter setId: Index of dataset to get data for. 0 to get data for all supported datasets

Parameter maxResults: Maximum number of entries to get from log. 0 means all matching entries

Parameter startDate: Start date and time (local UNIX time)

Parameter endDate: End date and time (local UNIX time)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.40 Command Class Alarm (0x71/113)

Version 5, Controlled

Also known as Notification Command Class. Used to report alarm events from binary sensors. Starting from version 3 all types are strictly defines:.

- 0x01 Smoke.
- 0x02 CO.
- 0x03 CO2.
- 0x04 Heat.
- 0x05 Water.
- 0x06 Access Control.
- 0x07 Burglar.
- 0x08 Power Management.
- 0x09 System.
- 0x0a Emergency.
- 0x0b Clock.

Data holders:

- V1supported: boolean flag saying if version 1 (deprecated) is supported
- V1event : structure to store V1 events
- alarmType: V1 alarm type
- level: V1 status
- typeMask: bit mask of supported alarm types
- [typeId]: subtree to store events of specific alarm types
- typeString: name of the alarm type
- status: flag with alarm status (alarm enabled/disabled)
- eventMask: bit mask of supported events of this alarm type
- **event**: last event ID
- eventString: last event name
- eventParameters: last event parameters
- eventSequence: internal

Command Alarm Get

Syntax: Get(type = 0, event = 0, successCallback = NULL, failureCallback = NULL)

Description: Send Alarm Get. Requests the status of a specific event of a specific alarm type

Parameter type: Type of alarm to get level for. 0 to get level for all supported alarms (v2 and higher). 0xFF to get level for first supported alarm (v2 and higher)

Parameter event: Notification event to get level for. This argument is ignored prior to Notification v3. Must be 0 if type is 0xFF

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: Alarm type subtree updated

Command Alarm Set

Syntax: Set(type, level, successCallback = NULL, failureCallback = NULL)

Description: Send Alarm Set (v2 and higher). Enable/disable alarms of a specific type

Parameter type: Type of alarm to set level for

Parameter level: Level to set (0x0 = off, 0xFF = on, other values are reserved)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: Alarm type subtree updated

8.41 Command Class PowerLevel (0x73/115)

Version 1, Supported and Controlled

Used to set device power level and to test the link to a other devices in the network.

Data holders:

- level: Current power level (0 for normal power, 1..9 for -1..-9 dBm)
- **timeout**: Timeout of the power level set (after timeout the device turns back to normal power)
- [nodeId]: Subtree with report of a test with nodeId
- status: Current test status (0 = Failed, 1 = Successfully finished, 2 = In progress)
- totalFrames: Total frames sent
- acknowledgedFrames: Acknowledged frames from total sent

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Command PowerLevel Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send PowerLevel Get

Parameter success Callback: Custom function to be called on function success. NULL $\,$

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: level and timeout updated

Command PowerLevel Set

Syntax: Set(level, timeout, successCallback = NULL, failureCallback = NULL)

Description: Send PowerLevel Set

Parameter level: Power level to set (from 0 to 9)

Parameter timeout: Timeout in seconds

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: level and timeout updated

Command PowerLevel TestNodeGet

Syntax: TestNodeGet(successCallback = NULL, failureCallback = NULL)

Description: Send PowerLevel Test Node Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: subtree with report for the given node updated

${\bf Command\ PowerLevel\ TestNodeSet}$

Syntax: TestNodeSet(testNodeId, level, frameCount, successCallback = NULL, failureCallback = NULL)

Description: Send PowerLevel Test Node Set. Starts sending specified number of NOP packets to a given device at a given power level. Once finished, unsolicited report MIGHT be sent by the device (at any time you can use TestNodeGet)

Parameter testNodeId: Node to set test packets to

Parameter level: Power level to use (from 0 to 9)

Parameter frameCount: Number of test frames to send (from 1 to 65535)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: subtree with report for the given node updated

8.42 Command Class Z-Wave Plus Info (0x5E/94)

Version 2, Supported and Controlled

Describes device Z-Wave Plus role and type.

Data holders:

• plusVersion: Z-Wave Plus version

• roleType: Z-Wave Plus role type

• roleTypeString: Z-Wave Plus role type description

• nodeType: Z-Wave Plus node type

• installerIcon: Icon for installer

• userIcon: Icon for user

Command ZWavePlusInfo Get

 $Syntax: \ Get(successCallback = NULL, \ failureCallback = NULL)$

Description: Send ZWave+ Info Get

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.43 Command Class Firmware Update (0x7A/122)

Version 4, Controlled

Allows to update firmware of the device (OTA, Over-The-Air upgrade).

Data holders:

- upgradeable: Flag representing if the firmware is upgradable
- firmwareCount: Number of firmwares that can be updated using OTA (for multi chip devices, 0 is Z-Wave chip only)
- updateStatus: Indicated the status of the update process
- waitTime: Time the device will take before rebooting with newly upgraded firmware
- manufacturerId: Manufacturere ID
- firmwareId: Firmware Id
- firmware[n]: Firmware Id of firmware [n]
- checksum: Checksum of the firmware
- fragmentTransmitted: Number of fragments transmitted (useful to make progress bar)
- **fragmentCount**: Number of fragments to be transmitted in total (useful to make progress bar)
- fragmentSize: Internal
- firmwareData: Internal

Command FirmwareUpdate Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send Firmware Metadata Get

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: upgradeable, firmwareCount, updateStatus, manufacturerId, manufacturerId, firmwareId, firmware[n], checksum updated

Command Firmware Update Perform

Syntax: Perform(manufacturerId, firmwareId, firmwareTarget, data, successCallback = NULL, failureCallback = NULL)

Description: Send Firmware Update Request Get. On process start Z-Way sets fragmentCount: devices.N.instances.0.commandClasses.122.data.fragmentCount = 3073 (0x00000c01). Then it asks the device to start the process. The device can refuse it (i.e. if local confirmation timed out). If confirmed, the device will send us a report with adjusted fragment size (if it wants Z-Way to send by smaller packets) and report "Ready" (updateStatus = 255, see below). devices.N.instances.0.commandClasses.122.data.updateStatus = 255 (0x000000ff). devices.N.instances.0.commandClasses.122.data.fragmentCount =3277 (0x00000ccd). At this point fragment Transmitted ==0. devices. N. instances. 0. command Classes. 122. =0. Then device starts asking Z-Way for different packets. Z-Way will update fragmentTransmitted to allow track the process. Once done (fragmentCount == fragmentTransmitted), the device will send again a report if the flashing was successful. updateStatus contains the status: checksum error = 0, assemble error = 1, success, restart manually = 254, success, automatic restart = 255. waitTime refers to the time device will take to reboot. devices. N. instances. 0. command Classes. 122. data. update Status =255 (0x000000ff). devices.N.instances.0.commandClasses.122.data.waitTime =5(0x00000005)

Parameter manufacturerId: Manufacturer Id (2 bytes)

Parameter firmwareId: Firmware Id (2 bytes)

Parameter firmwareTarget: Firmware target number (0 for main chip, 1..255 for additional chips). Used only for CC v3 and above

Parameter data: Firmware image data in binary format (use hex2bin to convert from Intel Hex)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: updateStatus, waitTime, fragmentCount, fragmentTransmitted updated

8.44 Command Class Association Group Information (0x59/89)

Version 1, Supported and Controlled

Describes association groups defined by Association Command Class and command sent to group members.

Data holders:

• [groupId]: Subtree for grouId

• **groupName**: Group name

• **profile**: Group profile Id

• **mode**: Internal. Reserved.

• eventCode: Internal. Reserved

• **commands**: Subtree for commands

- [commandClassId]: Command Class Id of the command sent to group members
- [commandId]: Command Id corresponding to Command Class Id
- **dynamic**: Flag describing if the list can change and periodic request to update information is suggested

Command AssociationGroupInformation GetInfo

Syntax: GetInfo(groupId, successCallback = NULL, failureCallback = NULL)

Description: Send AGI Get Info

Parameter groupId: Group Id to get info for (0 for all groups)

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command AssociationGroupInformation GetName

Syntax: GetName(groupId, successCallback = NULL, failureCallback = NULL)

Description: Send AGI Get Name

Parameter groupId: Group Id to get info for (0 for all groups)

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command AssociationGroupInformation GetCommands

Syntax: GetCommands(groupId, successCallback = NULL, failureCallback = NULL)

Description: Send AGI Get Commands

Parameter groupId: Group Id to get info for (0 for all groups)

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.45 Command Class SwitchColor (0x33/51)

Version 3, Controlled

Allows to control color for multicolor lights including LED bulbs and LED strips. Device reports it's capabilities:.

- 0 Warm White (0x00...0xFF: 0...100%).
- 1 Cold White (0x00:...0xFF: 0...100%).
- 2 Red (0x00...0xFF: 0...100%).
- 3 Green (0x00...0xFF: 0...100%).
- 4 Blue (0x00...0xFF: 0...100%).
- 5 Amber (for 6ch Color mixing) (0x00...0xFF: 0...100%).
- 6 Cyan (for 6ch Color mixing) (0x00...0xFF: 0...100%).
- 7 Purple (for 6ch Color mixing) (0x00...0xFF: 0...100%).
- 8 Indexed Color (0x00...0x0FF: Color Index 0...255).

Data holders:

- capabilityMask: Internal. Bit mask with supported capabilities
- [capabilityId]: Subtree for capabilityId
- capabilityString: Capability description
- level: Level of capability

Command SwitchColor Get

Syntax: Get(capabilityId, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchColor Get

Parameter capabilityId: Capability Id

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command SwitchColor Set

Syntax: Set(capabilityId, state, duration = 0xff, successCallback = NULL, failure-Callback = NULL)

Description: Send SwitchColor Set

Parameter capabilityId: Capability Id

Parameter state: State to be set for the capability

Parameter duration: Duration of change:. 0 instantly. 0x01...0x7f in seconds. 0x80...0x6e in minutes mapped to 1...127 (value 0x80=128 is 1 minute). 0xff use device factory default

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command SwitchColor SetMultiple

Syntax: SetMultiple(capabilityIds, states, duration = 0xff, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchColor SetMultiple

Parameter capabilityIds: Array of capabilities to set

Parameter states: Array of state values to be set for the capabilities

Parameter duration: Duration of change: 0 instantly. 0x01...0x7f in seconds. 0x80...0xfe in minutes mapped to 1...127 (value 0x80=128 is 1 minute). 0xff use device factory default

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command SwitchColor StartStateChange

Syntax: StartStateChange(capabilityId, dir, ignoreStartLevel = TRUE, startLevel = 50, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchColor StartStateChange

Parameter capabilityId: Capability Id to start changing state for

Parameter dir: Direction of change: 0 to incrase, 1 to decrase

Parameter ignoreStartLevel: If set to True, device will ignore start level value and will use it's curent value

Parameter startLevel: Start level to change from

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command SwitchColor StopStateChange

Syntax: StopStateChange(capabilityId, successCallback = NULL, failureCallback = NULL)

Description: Send SwitchColor StopStateChange

Parameter capabilityId: Capability Id to stop changing state for

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

8.46 Command Class BarrierOperator (0x66/102)

Version 1, Controlled

Allows to control barriers and garage doors as well as their signal lamps.

Data holders:

• state: Barrier state

• signalMask: Internal. Bit mask of available signals

• [signalId]: Subtree for signal

• **signalTypeString**: Signal description

• **state**: Signal state

Command BarrierOperator Get

Syntax: Get(successCallback = NULL, failureCallback = NULL)

Description: Send BarrierOperator Get

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command BarrierOperator Set

 $Syntax: \ Set(state, \ success Callback = NULL, \ failure Callback = NULL)$

Description: Send BarrierOperator Set

Parameter state: State to set

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Command BarrierOperator SignalGet

 $Syntax: \ SignalGet(signalType, \ successCallback = NULL, \ failureCallback = NULL)$

Description: Send BarrierOperator Signal Get

Parameter signalType: Signal subsystem type to get state for

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Command BarrierOperator SignalSet

Syntax: SignalSet(signalType, state, successCallback = NULL, failureCallback = NULL)

Description: Send BarrierOperator Signal Set

Parameter signal Type: Signal subsystem type to set state for

Parameter state: State to set

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.47 Command Class SimpleAVControl (0x94/148)

Version 4, Supported and Controlled

Allows to control A/V devices.

Data holders:

• bitmask: Bit mask with supported keys. Refer to Expert UI pyzw_zwave.js or Sigma Designs documentation for description of buttons.

• bitmasks: Internal

 \bullet sequence Number: Internal

• reportsNumber: Internal

Command SimpleAVControl Set

Syntax: Set(keyAttribute, avCommand, successCallback = NULL, failureCallback = NULL)

Description: Send SimpleAVControl Set

Parameter key Attribute: 0 for key Down, 1 for key Up, 2 for key Alive (repeated every $100...200~\mathrm{ms}$)

Parameter avCommand: Command to be sent. One of 465 predefined in Z-Wave protocol

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

8.48 Command Class Security (0x98/152)

Version 1, Supported and Controlled

This Command Class is transparently implemented in the library. There are no functions to execute.

Data holders:

- controller-¿data-¿secureControllerId: Node Id of secure controller: node that established secure channel when we are secondary controller (this data is on controller data tree)
- device-¿data-¿secureChannelEstablished: Flag describing if security interview was successful and secure channel is established (this data is on device data tree)
- secureNodeInfoFrame: Secure Node Information Frame
- security Abandoned: Security interview failed

• scheme: Secure scheme supported

• securityRequested: Internal

• rNonce: Internal

• rNonceAckWait: Internal

canStream: InternalfirstPart: Internal

• sequenceId: Internal

• toFollow: Internal

8.49 Command Class CRC16 (0x56/86)

Version 1, Supported and Controlled

This Command Class is transparently implemented in the library to use better 16 bits packet checksum. There are no functions to execute.

Data holders:

• crc16Requested: Internal

8.50 Command Class MultiCmd (0x8F/143)

Version 1, Supported and Controlled

This Command Class is transparently implemented in the library to save battery life time. There are no functions to execute.

Data holders:

• maxNum: Max number of packets to be encapsulated. Can be tunned to lower (to workaround buggy devices, 1 to turn off) or rise (to get bettery performance)

8.51 Command Class Application Status (0x22/34)

Version 1, Supported and Controlled

This Command Class is transparently implemented in the library to retry on device Busy report. There are no functions to execute.

8.52 Command Class Version (0x86/134)

Version 2, Supported and Controlled

Allows to get version of each Command Class supported by the device as well as firmware version.

Data holders:

- commandClass-¿data-¿version: Version of specific Command Class (this data is on Command Class data tree)
- ZWLib: SDK library type
- ZWProtocolMajor: SDK version major
- ZWProtocolMinor: SDK version minor
- SDK: SDK description

- applicationMajor: Application version major
- applicationMinor: Application version minor
- hardware Version: Hardware revision of the device
- firmwareCount: Number of chips (firmwares) in the device (excluding Z-Wave chip)
- [firmwareId]: Subtree for firmwareId information
- major: Additional chip application version major
- **minor**: Additional chip application version major

8.53 Command Class DeviceResetLocally (0x5A/90)

Version 1, Supported and Controlled

Reports to the controller that device was resetted locally (using local button operation).

Data holders:

• reset: Becomes True if the device sent us DeviceResetLocally notification. This means the device is certainly not in our network anymore

8.54 Command Class Central Scene (0x5B/91)

Version 1, Supported and Controlled

Allows to receive central controller oriented scene actions. Scenes are triggered by pushing a button on a remote control or wall controller.

Data holders:

- maxScenes: Number of scenes supported
- currentScene: Last activated scene
- **keyAttribute**: Button (or key) action: 0 for key press, 1 for key release, 2 for key held down (should bre repeated at least every 200ms)
- sequence: Internal. To ignore duplicate packats.

Chapter 9

Function Class Reference

Function Class GetSerialAPICapabilities

Syntax: GetSerialAPICapabilities(successCallback = NULL, failureCallback = NULL)

Description: Request Serial API capabilities

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: capabilities, manufacturerId, manufacturerProductId, manufacturerProduct-Type, APIVersion, vendor

Function Class SerialAPISetTimeouts

Syntax: Serial API Set Timeouts (ack Timeout, byte Timeout, success Callback = NULL, failure Callback = NULL)

Description: Set Serial API timeouts

Parameter ackTimeout: Time for the stick to wait for ACK (in 10ms units)

Parameter byteTimeout: Time for the stick to assemble a full packet (in 10ms units)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: cur Serial APIAck Timeout 10ms, cur Serial APIByte Timeout 10ms, old Serial API-Ack Timeout 10ms, old Serial APIByte Timeout 10ms

Function Class SerialAPIGetInitData

Syntax: Serial API Get Init Data (success Callback = NULL, failure Callback = NULL)

Description: Request initial information about devices in network

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: ZWVersion, ZWaveChip, list of Z-Wave devices is generated

Function Class SerialAPIApplicationNodeInfo

Syntax: SerialAPIApplicationNodeInfo(listening, optional, flirs1000, flirs250, genericClass, specificClass, nif, successCallback = NULL, failureCallback = NULL)

Description: Set controller node information

Parameter listening: Listening flag

Parameter optional: Optional flag (set if device supports more CCs than described as mandatory for it's Device Type)

Parameter flirs1000: FLiRS 1000 flag (hardware have to be based on FLiRS library to support it)

Parameter flirs250: FLiRS 250 flag (hardware have to be based on FLiRS library to support it)

Parameter genericClass: Generic Device Type

Parameter specificClass: Specific Device Type

Parameter nif: New NIF

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class WatchDogStart

Syntax: WatchDogStart(successCallback = NULL, failureCallback = NULL)

Description: Start WatchDog

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class WatchDogStop

Syntax: WatchDogStop(successCallback = NULL, failureCallback = NULL)

Description: Stop WatchDog

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class GetHomeId

Syntax: GetHomeId(successCallback = NULL, failureCallback = NULL)

Description: Request Home Id and controller Node Id

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: homeId, nodeId

Function Class GetControllerCapabilities

Syntax: GetControllerCapabilities(successCallback = NULL, failureCallback = NULL)

Description: Request controller capabilities (primary role, SUC/SIS availability)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: isInOthersNetwork, isPrimary, isRealPrimary, isSUC, isSUC, SISPresent

Function Class GetVersion

 $Syntax: \ GetVersion(successCallback = NULL, \ failureCallback = NULL)$

Description: Request controller hardware version

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report:\ ZWLib,\ ZWProtocolMajor,\ ZWProtocolMinor,\ libType,\ SDK,\ devices[ctrlId].data.ZWLib,\ devices[ctrlId].data.ZWProtocolMajor,\ devices[ctrlId].data.ZWProtocolMinor,\ devices[ctrlId].data.SDK$

Function Class GetSUCNodeId

Syntax: GetSUCNodeId(successCallback = NULL, failureCallback = NULL)

Description: Request SUC Node Id

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: SUCNodeId

Function Class EnableSUC

Syntax: EnableSUC(enable, sis, successCallback = NULL, failureCallback = NULL)

Description: Enable or disable SUC/SIS functionality of the controller

Parameter enable: True to enable functionality, False to disable

Parameter sis: True to enable SIS functionality, False to enable SUC only

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class SetSUCNodeId

Syntax: SetSUCNodeId(nodeId, enable, sis, successCallback = NULL, failureCallback = NULL)

Description: Assign new SUC/SIS or disable existing

Parameter nodeId: Node Id to be assigned/disabled as SUC/SIS

Parameter enable: True to enable, False to disable

Parameter sis: True to assign SIS role, False to enable SUC role only

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class MemoryGetByte

Syntax: MemoryGetByte(offset, successCallback = NULL, failureCallback = NULL)

Description: Read single byte from EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: memoryGetData, memoryGetAddress

Function Class MemoryGetBuffer

Syntax: MemoryGetBuffer(offset, length, successCallback = NULL, failureCallback = NULL)

Description: Read multiple bytes from EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter length: Number of byte to be read

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: memoryGetData, memoryGetAddress

Function Class MemoryPutByte

Syntax: MemoryPutByte(offset, data, successCallback = NULL, failureCallback = NULL)

Description: Write single byte to EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter data: Byte to be written

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class MemoryPutBuffer

Syntax: MemoryPutBuffer(offset, data, successCallback = NULL, failureCallback = NULL)

Description: Write multiple bytes to EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter data: Bytes to be written

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class NVMGetId

Syntax: NVMGetId(successCallback = NULL, failureCallback = NULL)

Description: Read type of extended EEPROM

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Report: memoryCapacity, memoryManufacturerId, memoryType

$Function\ Class\ NVMExtReadLongByte$

 $Syntax:\ NVMExtReadLongByte(offset,\ successCallback = NULL,\ failureCallback = NULL)$

Description: Read single byte from extended EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report:\ memoryGetData,\ memoryGetAddress$

$Function\ Class\ NVMExtReadLongBuffer$

Syntax: NVMExtReadLongBuffer(offset, length, successCallback = NULL, failure-Callback = NULL)

Description: Read multiple bytes from exended EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter length: Number of byte to be read

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: memoryGetData, memoryGetAddress

$Function\ Class\ NVMExtWriteLongByte$

Syntax: NVMExtWriteLongByte(offset, data, successCallback = NULL, failureCallback = NULL)

Description: Write single byte to extended EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter data: Byte to be written

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class NVMExtWriteLongBuffer

Syntax: NVMExtWriteLongBuffer(offset, data, successCallback = NULL, failure-Callback = NULL)

Description: Write multiple bytes to extended EEPROM

Parameter offset: Offset in application memory in EEPROM

Parameter data: Bytes to be written

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class IsFailedNode

Syntax: IsFailedNode(nodeId, successCallback = NULL, failureCallback = NULL)

Description: Checks if node is failed

Parameter nodeId: Node Id to be checked

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: device[node_id].data.isFailed

Function Class SendDataAbort

Syntax: SendDataAbort(successCallback = NULL, failureCallback = NULL)

Description: Abort send data. Note that this function works unpredictably in multi callback environment!

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class SerialAPISoftReset

Syntax: SerialAPISoftReset(successCallback = NULL, failureCallback = NULL)

Description: Soft reset. Restarts Z-Wave chip

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class SendData

Syntax: SendData(nodeId, data, description = NULL, successCallback = NULL, failureCallback = NULL)

Description: Send data. Packets are sent in AUTO_ROUTE mode with EXPLRER_FRAME enabled for listening devices (ignored if not supported by the hardware [based on 5.0x branch])

Parameter nodeId: Destination Node Id (NODE_BROADCAST to send non-routed broadcast packet)

Parameter data: Paket payload

Parameter description: Packet description for queue inspector and logging

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: devices[node_id].data.lastSend

Function Class SendDataSecure

Syntax: SendDataSecure (nodeId, data, description = NULL, successCallback = NULL, failureCallback = NULL)

Description: Send data using security. Packets are sent in AUTO_ROUTE mode with EXPLRER_FRAME enabled for listening devices (ignored if not supported by the hardware [based on 5.0x branch]). Explicitly use security

Parameter nodeId: Destination Node Id (NODE_BROADCAST to send non-routed broadcast packet)

Parameter data: Paket payload

Parameter description: Packet description for queue inspector and logging

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: devices[node_id].data.lastSend

Function Class GetNodeProtocolInfo

 $Syntax: \ GetNodeProtocolInfo(nodeId, \ successCallback = NULL, \ failureCallback = NULL)$

Description: Get node protocol info

Parameter nodeId: Node Id of the device in question

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: devices[node_id].data.isListening, devices[node_id].data.isRouting, devices[node_id].data.optional, devices[node_id].data.sensor1000, devices[node_id].data.sensor250, devices[node_id].data.infoProtocolSpecific

${\bf Function~Class~Get Routing Table Line}$

Syntax: GetRoutingTableLine(nodeId, removeBad = FALSE, removeRepeaters = FALSE, successCallback = NULL, failureCallback = NULL)

Description: Get routing table line

Parameter nodeId: Node Id of the device in question

Parameter removeBad: Exclude failed nodes from the listing

Parameter removeRepeaters: Exclude repeater nodes from the listing

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: devices[node_id].data.neighbours

Function Class AssignReturnRoute

Syntax: AssignReturnRoute(nodeId, destId, successCallback = NULL, failureCallback = NULL)

Description: Assign return route to specified node. Get Serial API capabilities

Parameter nodeId: Node Id of the device that have to store new route

Parameter destId: Destination Node Id of the route

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class AssignSUCReturnRoute

 $Syntax: \ Assign SUCReturn Route (node Id, \ success Callback = NULL, \ failure Callback = NULL)$

Description: Assign return route to SUC

Parameter nodeId: Node Id of the device that have to store route to SUC

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class DeleteReturnRoute

 $Syntax: \ \ DeleteReturnRoute(nodeId, \ successCallback = NULL, \ failureCallback = NULL)$

Description: Delete return route

Parameter nodeId: Node Id of the device that have to delete all assigned return routes

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Function Class DeleteSUCReturnRoute

 $Syntax:\ Delete SUCReturn Route (node Id,\ success Callback = NULL,\ failure Callback = NULL)$

Description: Delete return route to SUC

Parameter nodeId: Node Id of the device that have to delete route to SUC

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class SetDefault

Syntax: SetDefault(successCallback = NULL, failureCallback = NULL)

Description: Reset the controller. Note: this function will delete ALL data from the Z-Wave chip and restore it to factory default! Sticks based on 4.5x and 6.x SDKs will also generate a new Home Id

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report:\ last Excluded Device,\ last Included Device$

Function Class SendSUCNodeId

Syntax: SendSUCNodeId(nodeId, successCallback = NULL, failureCallback = NULL)

Description: Send SUC Node Id. Informs portable and static controllers about new or deleted SUC/SIS

Parameter nodeId: Node Id of the device that have to be informed about new or deleted SIC/SIS

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Function Class SendNodeInformation

Syntax: SendNodeInformation(nodeId, successCallback = NULL, failureCallback = NULL)

Description: Send NIF of the stick

Parameter nodeId: Destination Node Id (NODE_BROADCAST to send non-routed broadcast packet)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class RequestNodeInformation

Syntax: RequestNodeInformation(nodeId, successCallback = NULL, failureCallback = NULL)

Description: Request NIF of a device

Parameter nodeId: Node Id to be requested for a NIF

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report: \ devices [node_id]. data.node Info Frame$

Function Class RemoveFailedNode

Syntax: Remove FailedNode(node
Id, successCallback = NULL, failure Callback = NULL)

Description: Remove failed node from network. Before removing SDK will check that the device is really unreachable

Parameter nodeId: Node Id to be removed from network

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: lastExcludedDevice

Function Class ReplaceFailedNode

Syntax: Replace FailedNode
(nodeId, successCallback = NULL, failureCallback = NULL)

Description: Replace failed node with a new one. Be ware that a failed node can be replaced by a node of another type. This can lead to probles!. Always request device NIF and force re-interview after successful replace process

Parameter nodeId: Node Id to be replaced by new one

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: lastIncludedDevice, controllerState

Function Class RequestNetworkUpdate

Syntax: RequestNetworkUpdate(successCallback = NULL, failureCallback = NULL)

Description: Request network topology update from SUC/SIS. Note that this process may also fail due more than 64 changes from last sync. In this case a re-inclusion of the controller (self) is required

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class RequestNodeNeighbourUpdate

Syntax: RequestNodeNeighbourUpdate(nodeId, successCallback = NULL, failure-Callback = NULL)

Description: Request neighbours update for specific node

Parameter nodeId: Node Id to be requested for it's neighbours

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: devices[node_id].data.neighbours

Function Class SetLearnMode

Syntax: SetLearnMode(startStop, successCallback = NULL, failureCallback = NULL)

Description: Set/stop Learn mode. Tries first classical inclusion then falls back to NWI automatically

Parameter startStop: Start Learn mode if True, stop if False

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: controllerState, lastExcludedDevice, lastIncludedDevice

Function Class AddNodeToNetwork

 $Syntax:\ AddNodeToNetwork(startStop,\ highPower=TRUE,\ successCallback=NULL,\ failureCallback=NULL)$

Description: Start/stop Inclusion of a new node. Available on primary and inclusion controllers

Parameter startStop: Start inclusion mode if True, stop if False

Parameter highPower: Use full power during this operation if True. On False use low power mode

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report:\ controller State,\ last Excluded Device,\ last Included Device$

Function Class RemoveNodeFromNetwork

Syntax: RemoveNodeFromNetwork(startStop, highPower = FALSE, successCallback = NULL, failureCallback = NULL)

Description: Start/stop exclusion of a node. Note that this function can be used to exclude a device from previous network before including in ours. Available on primary and inclusion controllers

Parameter startStop: Start exclusion mode if True, stop if False

Parameter highPower: Use full power during this operation if True. On False use low power mode

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: controllerState, lastExcludedDevice, lastIncludedDevice

Function Class RemoveNodeIdFromNetwork

Syntax: RemoveNodeIdFromNetwork(nodeId, startStop, highPower = FALSE, successCallback = NULL, failureCallback = NULL)

Description: Start/stop exclusion of a node id. Note that this function can be used to exclude a device from previous network before including in ours. Available on primary and inclusion controllers

Parameter nodeId: NodeId to exclude. If 0 or ¿ 232, any node will be excluded (like with zway_fc_remove_node_from_network / RemoveNodeFromNetwork)

Parameter startStop: Start exclusion mode if True, stop if False

Parameter high Power: Use full power during this operation if True. On False use low power mode

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report: \ controller State, \ last Excluded Device, \ last Included Device$

Function Class ControllerChange

 $Syntax:\ Controller Change (start Stop,\ high Power = TRUE,\ success Callback = NULL,\ failure Callback = NULL)$

Description: Set new primary controller (also known as Controller Shift). Same as Inclusion, but the newly included device will get the role of primary. Available only on primary controller

Parameter startStop: Start controller shift mode if True, stop if False

Parameter highPower: Use full power during this operation if True. On False use low power mode

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report:\ controller State,\ last Excluded Device,\ last Included Device$

Function Class CreateNewPrimary

Syntax: CreateNewPrimary(startStop, successCallback = NULL, failureCallback = NULL)

Description: Create new primary controller by SUC controller. Same as Inclusion, but the newly included device will get the role of primary. Available only on SUC. Be careful not to create two primary controllers! This can lead to network malfunction!

Parameter startStop: Start create new primary mode if True, stop if False

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

 $Report:\ controller State,\ last Excluded Device,\ last Included Device$

Function Class ZMEFreqChange

Syntax: ZMEFreqChange(freq, successCallback = NULL, failureCallback = NULL)

Description: Change Z-Wave.Me Z-Stick 4 frequency. This function is specific for Z-Wave.Me hardware

Parameter freq: 0x01 RU. 0x02 IN. 0x03 US. 0x04 ANZ. 0x05 HK. 0x06 CN. 0x07 JP. 0x08 KR. 0x09 IL. 0x0A MY. 0xFF request current frequency (ZME firmwares prior to 5.03 don't support this feature)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: frequency

Function Class RFPowerLevelSet

Syntax: RFPowerLevelSet(level, successCallback = NULL, failureCallback = NULL)

Description: Set RF power level to specified value

Parameter level: 0 to 9

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class RFPowerLevelGet

Syntax: RFPowerLevelGet(successCallback = NULL, failureCallback = NULL)

Description: Get RF power level current value

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Function Class SendTestFrame

Syntax: SendTestFrame(nodeId, level, successCallback = NULL, failureCallback = NULL)

Description: Send test frame to a node at a specified RF level

Parameter nodeId: Node Id to make test against

Parameter level: 0 to 9

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class FlashAutoProgSet

 $Syntax: \ FlashAutoProgSet(successCallback = NULL, \ failureCallback = NULL)$

Description: Put Z-Wave chip in Atuo Prog mode for USB/UART reflashing

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class ExploreRequestInclusion

Syntax: ExploreRequestInclusion(successCallback = NULL, failureCallback = NULL)

Description: Request NWI. Called from SetLearnMode

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class ExploreRequestExclusion

Syntax: ExploreRequestExclusion(successCallback = NULL, failureCallback = NULL)

Description: Request NWE

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Function Class ZMEBootloaderFlash

Syntax: ZMEBootloaderFlash(addr, successCallback = NULL, failureCallback = NULL)

Description: Start reflashing bootloader of Z-Wave.Me firmware for 5th generation Z-Wave chip. This function is specific for Z-Wave.Me hardware

Parameter addr: address of new bootloader location in 2K sectors

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class ZMECapabilities

 $\begin{array}{l} {\rm Syntax:} \ \ {\rm ZMECapabilities}({\rm data} = {\rm NULL}, \ {\rm successCallback} = {\rm NULL}, \ {\rm failureCallback} \\ = {\rm NULL}) \end{array}$

Description: Get or set firmware capabilities. This function is specific for Z-Wave.Me hardware

Parameter data: data to set (NULL to get)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: caps, uuid

Function Class ZMEPHISetLED

Syntax: ZMEPHISetLED(led, status, successCallback = NULL, failureCallback = NULL)

Description: Activate LEDs on Philio hw. This function is specific for Philio hardware

Parameter led: LED id: 0x10 (Logo), 0x11 (Around), 0x12 (Misc)

Parameter status: LED status 2 (Off), 4 (On), 8 (Flash), 16 (Slow flash), 32 (Slow dimming)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Function Class ZMEPHIGetButton

Syntax: ZMEPHIGetButton(button, successCallback = NULL, failureCallback = NULL)

Description: Get button state on Philio hw. This function is specific for Philio hardware

Parameter button: 0: Tamper Key, 1: Function Key A, 2: Function Key B

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: philiohw.tamper, philiohw.funcA, philiohw.funcB

Function Class ZMEPHIGetPower

Syntax: ZMEPHIGetPower(successCallback = NULL, failureCallback = NULL)

Description: Get power state on Philio hw. This function is specific for Philio hardware

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: philiohw.powerFail, philiohw.batteryLevel, philiohw.charging, philiohw.batteryFail

Function Class ZMEPHIGetBattery

Syntax: ZMEPHIGetBattery(successCallback = NULL, failureCallback = NULL)

Description: Get battery state on Philio hw. This function is specific for Philio hardware

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: philiohw.batteryADCLevel

Function Class ZMEPHIGetRTC

Syntax: ZMEPHIGetRTC(successCallback = NULL, failureCallback = NULL)

Description: Get RTC from Philio hw. This function is specific for Philio hardware

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Report: set system time

Function Class ZMEPHISetRTC

Syntax: ZMEPHISetRTC(successCallback = NULL, failureCallback = NULL)

Description: Set RTC on Philio hw. This function is specific for Philio hardware

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class InjectPacket

Syntax: InjectPacket(nodeId, data, successCallback = NULL, failureCallback = NULL)

Description: Inject command in Z-Way as it was received via Z-Wave. This function is for debugging only

Parameter nodeId: Source Node Id

Parameter data: Paket payload (should looks like ccId, ccCmd, data,)

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class GetBackgroundRSSI

Syntax: GetBackgroundRSSI(successCallback = NULL, failureCallback = NULL)

Description: Get background noise level

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class SerialAPISetup

Syntax: Serial APISetup
(function, enable, successCallback = NULL, failureCallback = NULL)

Description: Configure Z-Wave Serial API

Parameter function: Configure specific Serial API function. Currently only enable/disable IMA is supported (function = 0x02)

Parameter enable: Set feature state: True to enable, False to disable

Parameter successCallback: Custom function to be called on function success. NULL if callback is not needed

Function Class ClearNetworkStats

Syntax: ClearNetworkStats(successCallback = NULL, failureCallback = NULL)

Description: Clear statistics gathered by the Z-Wave protocol

Parameter success Callback: Custom function to be called on function success. NULL $\,$

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Function Class GetNetworkStats

Syntax: GetNetworkStats(successCallback = NULL, failureCallback = NULL)

Description: Get statistics gathered by the Z-Wave protocol

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Function Class GetPriorityRoute

Syntax: GetPriorityRoute(nodeId, successCallback = NULL, failureCallback = NULL)

Description: Get the route with the highest priority

Parameter nodeId: Node ID we are interested in

Parameter successCallback: Custom function to be called on function success. NULL

if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL

if callback is not needed

Function Class SetPriorityRoute

Syntax: SetPriorityRoute(nodeId, repeater1, repeater2, repeater3, repeater4, route-

Speed, successCallback = NULL, failureCallback = NULL)

Description: Set the route with the highest priority

Parameter nodeId: Node ID we are interested in

Parameter repeater 1: Hop #1 in the route. Value 0 means direct range. Values $\ensuremath{\natural}$ 232

clears the priority route and LWR (Last Working Route is selected by the protocol)

Parameter repeater2: Hop #2 in the route. Value 0 means end of route

Parameter repeater3: Hop #3 in the route. Value 0 means end of route

Parameter repeater 4: Hop #4 in the route. Value 0 means end of route

Parameter route Speed: Baudrate to use: 1 for $9.6~{\rm kbps},\,2$ for $40~{\rm kbps},\,3$ for $100~{\rm kbps}.$ Value $0~{\rm means}$ end of route

Parameter success Callback: Custom function to be called on function success. NULL if callback is not needed

Parameter failureCallback: Custom function to be called on function failure. NULL if callback is not needed

Function Class SetPromiscuousMode

Syntax: SetPromiscuousMode(enable, successCallback = NULL, failureCallback = NULL)

Description: Enable or disable promiscuous mode

Parameter enable: True to enable functionality, False to disable

Parameter success Callback: Custom function to be called on function success. NULL if callback is not needed