Adapt to ROS2 foxy.

Install

Get the code:

```
# open a new terminal
cd serial
mkdir build
```

Build:

```
cd build
cmake ..
make
```

Install:

```
sudo make install
```

like this:

也可以不用 make install ,直接和你想要调用本API的ROS2 节点放在同一个 src 下编译即可。有关于本串口操作包的 API 在线文档如下:

[serial: Serial Library](#)

本共 ROS Package 修改来自：

License

The MIT License

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