



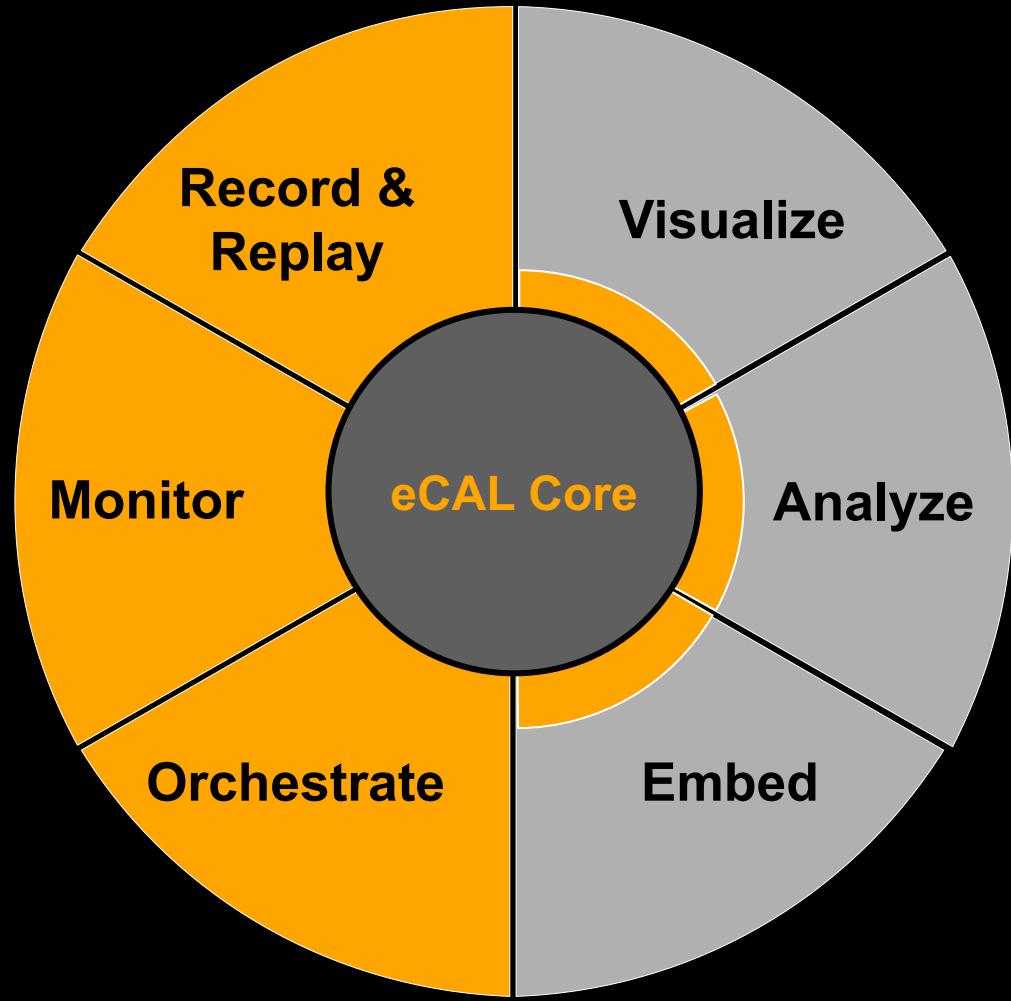
# eCAL ecosystem

## Visualizing Data using Foxglove Studio

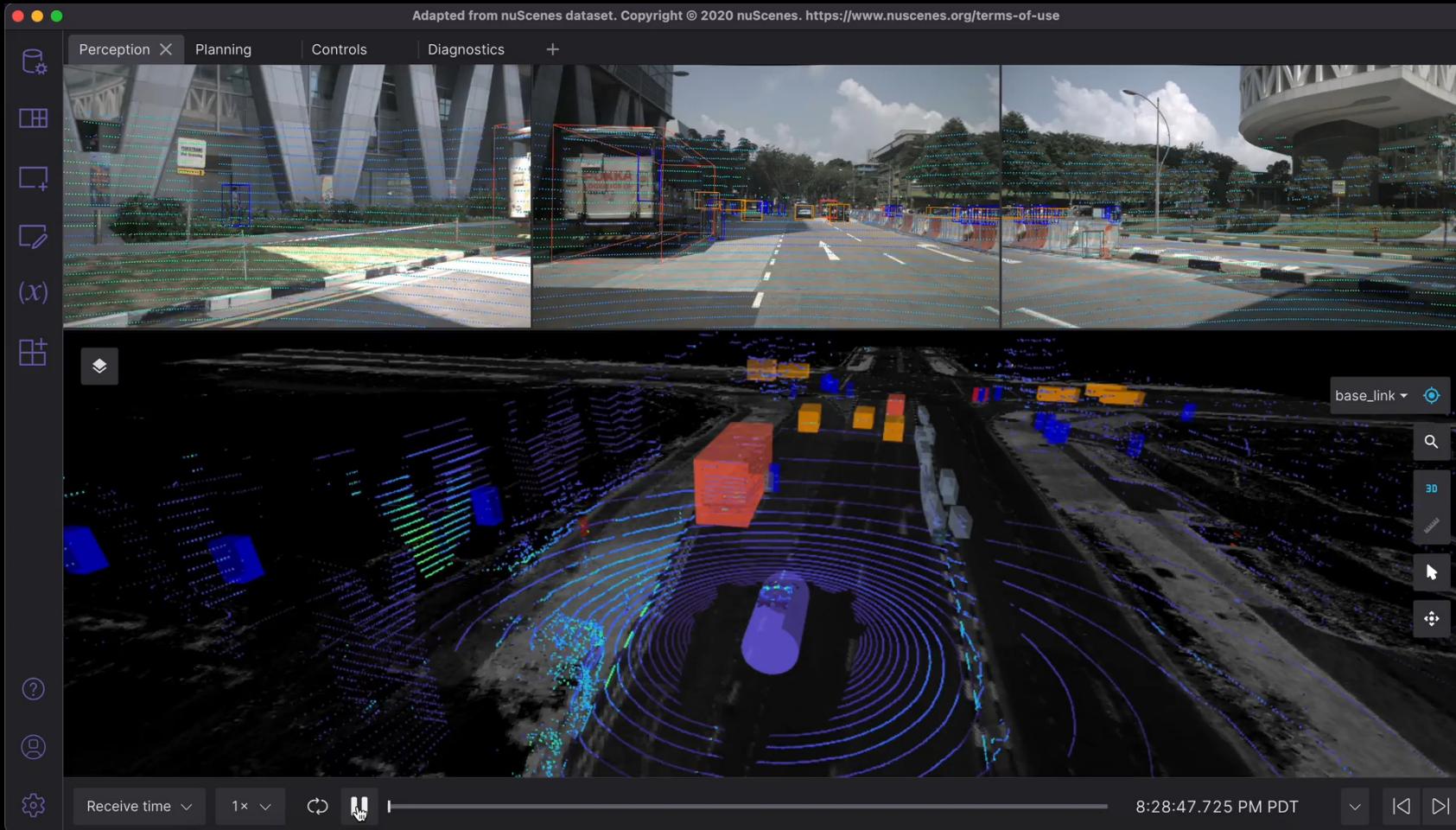
# About us



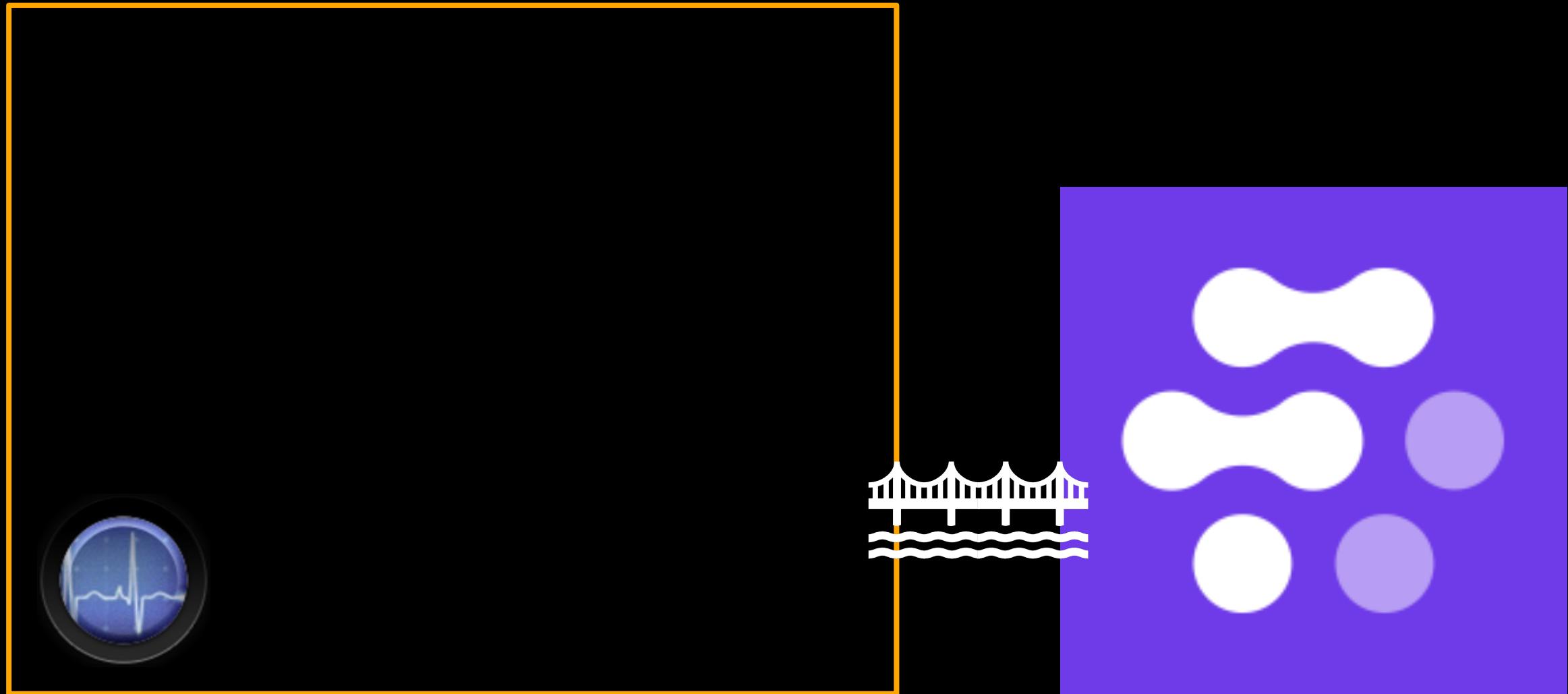
# eCAL ecosystem



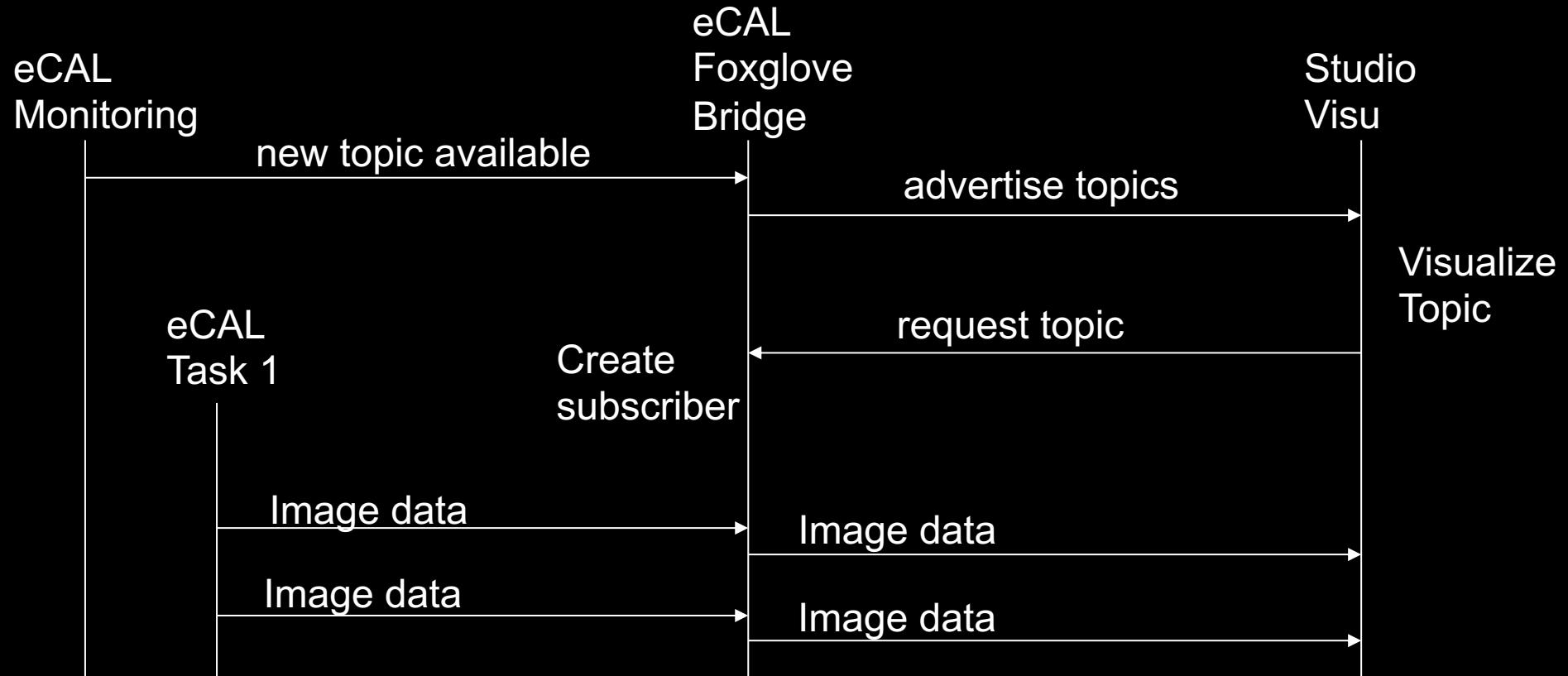
# Foxglove Studio



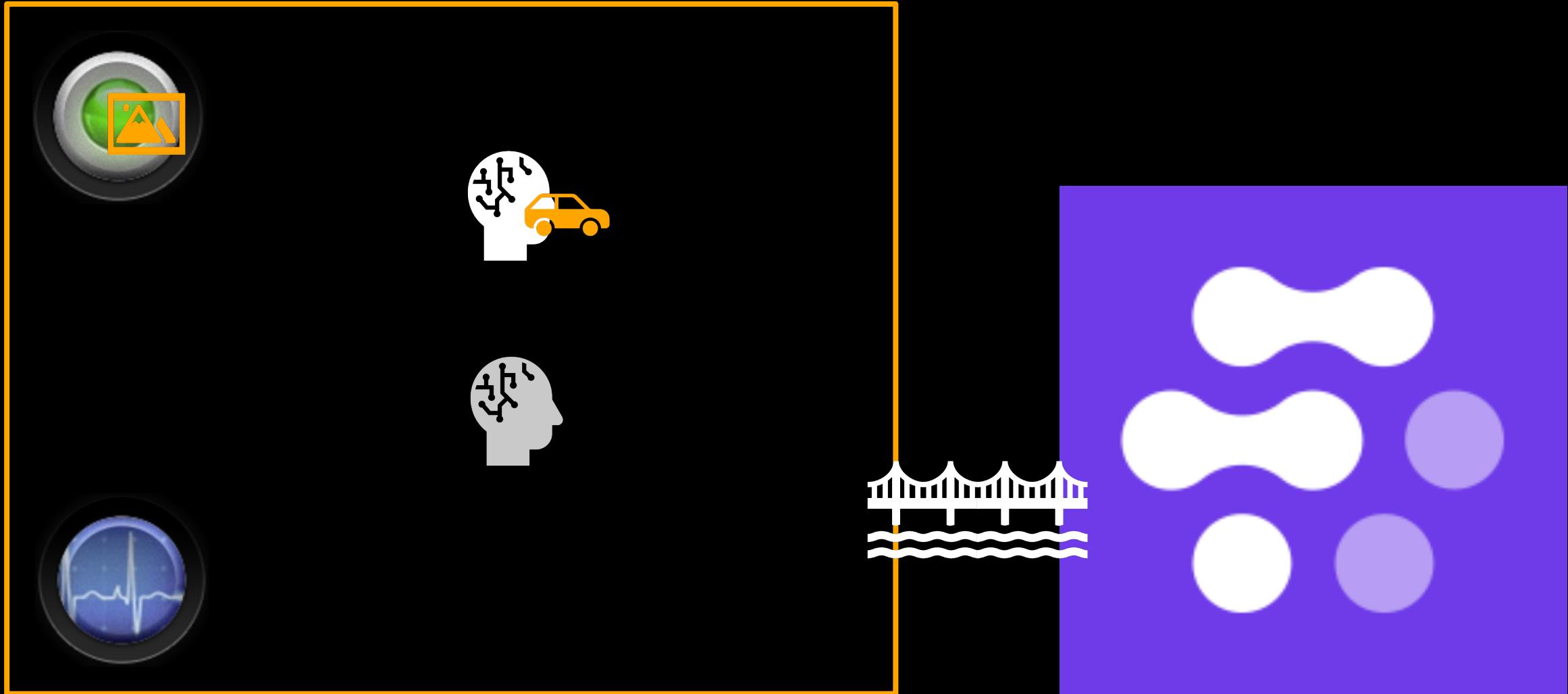
# eCAL Foxglove Bridge architecture



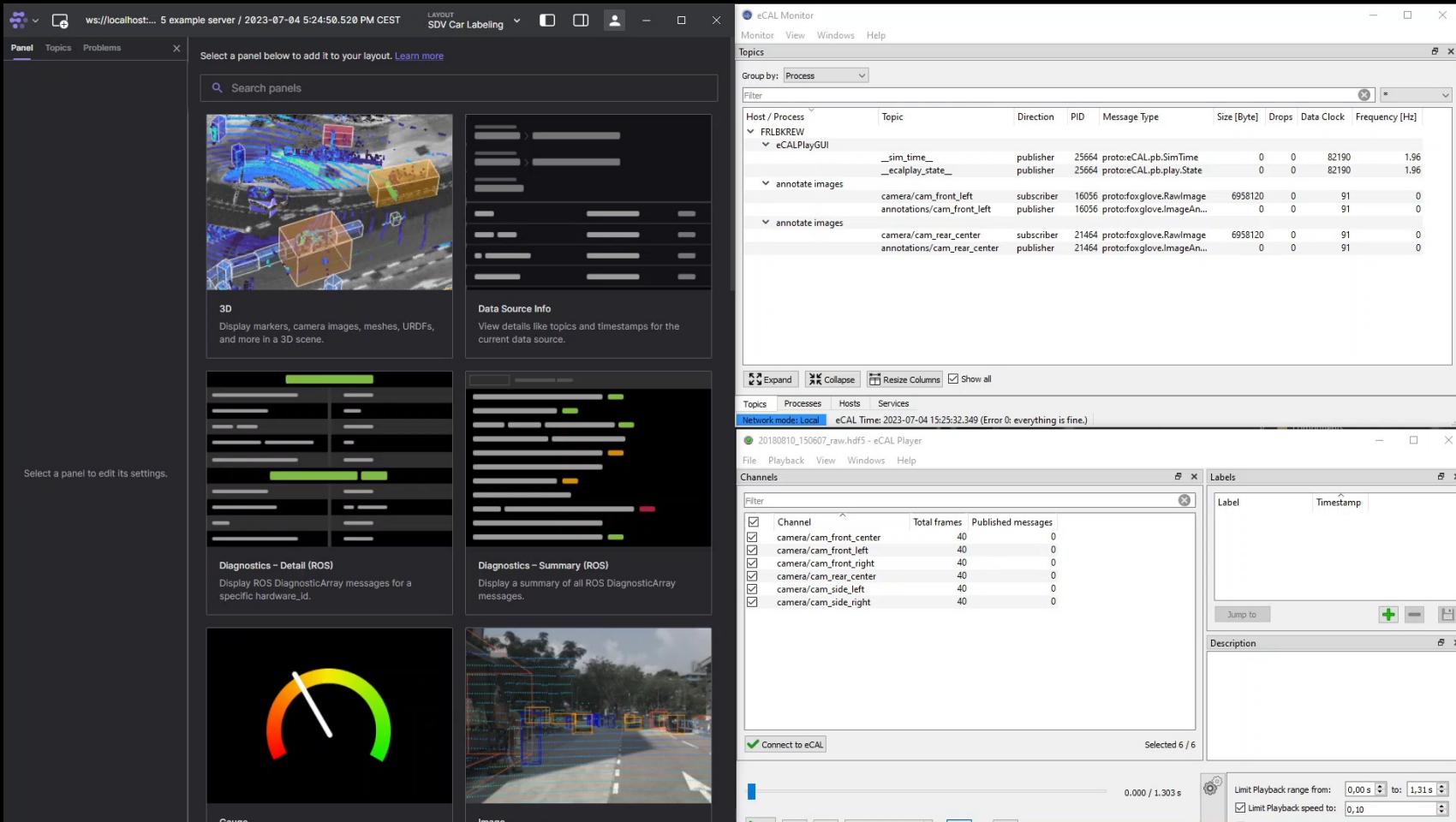
# eCAL Foxglove Bridge architecture



# Demo Setup



# Demo



# Summary

- eCAL comes with powerful tools
- eCAL has been integrated with existing tools
- Foxglove Studio is the newest integration for the eCAL ecosystem
- Which existing tool should we integrate next?

# Attributions

- eCAL: [Welcome to Eclipse eCAL™ — Eclipse eCAL™ \(eclipse-ecal.github.io\)](#)
- ROS: [ROS: Home](#)
- MathWorks: [MathWorks – Entwickler von MATLAB und Simulink - MATLAB & Simulink](#)
- Foxglove: [Foxglove - Visualizing and debugging your robotics data – Foxglove](#)
- Driving Dataset: [Driving Dataset | a2d2.audi](#)
- Object Detection: [Object detection task guide | MediaPipe | Google for Developers](#)