

# HW5 Report - ARAP

## Features and Implementations

### Helper classes

parameterizer.h/cpp: this serves as the parent class without any actual implementation, ARAP, or ASAP class can both inherit this class.  
parameterizer\_arap.h/.cpp:

- We have public functions: `void initialize(shared_ptr< OpenMesh >)` to set up the matrix, decompose it with the solver, and execute the first kickoff boundary mapping; `void iterate(int num_iteration)` which does the heavy lifting as the name suggests; then `std::map< int, Vector2d> get_parameterization()`, which simply grants us access to the private field `current_position`.
- We call these three in order in `node_arap.cpp`.

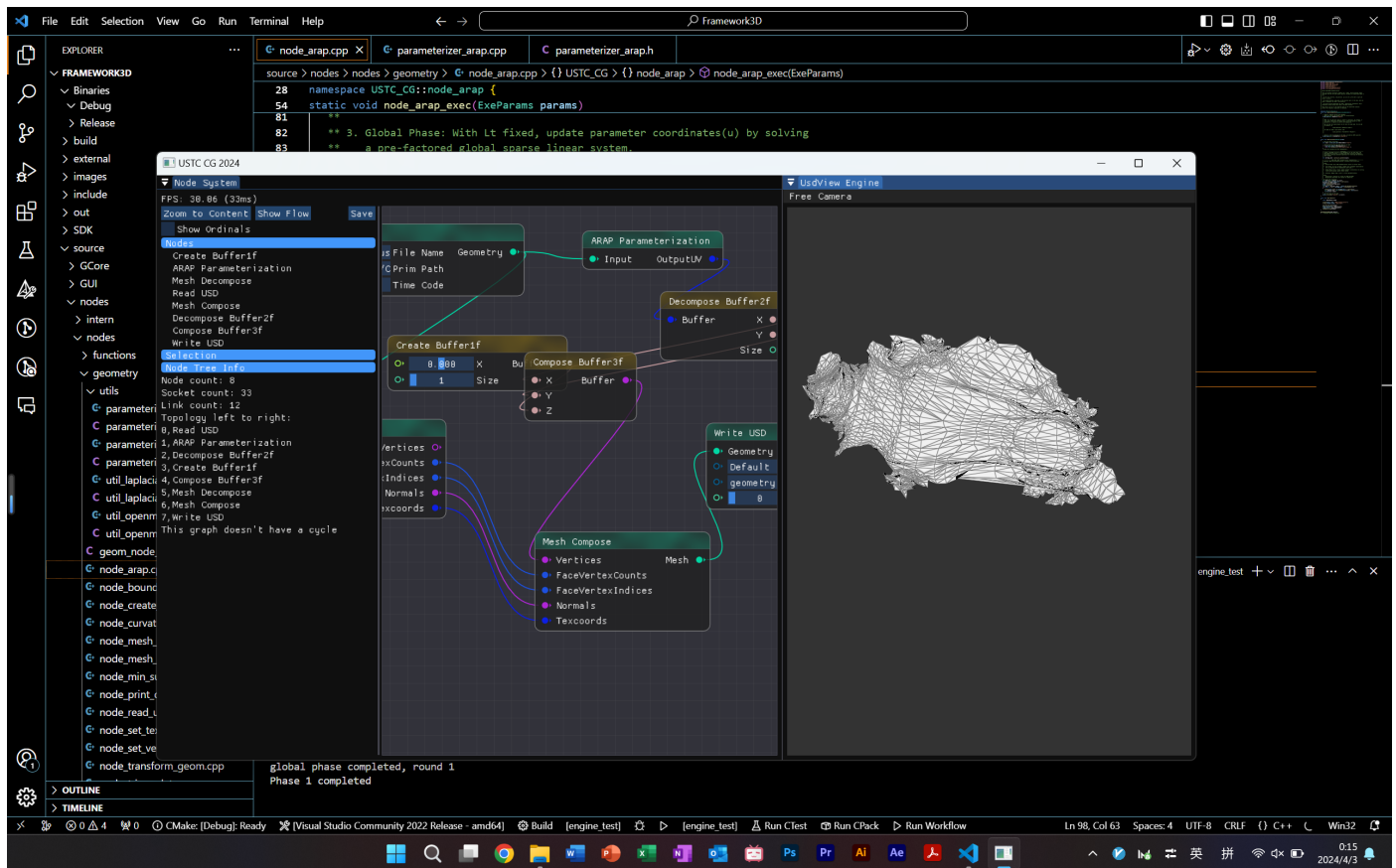
As for private functions: we have

- `global_phase(int phase_count)` which solves the equation, it calls `assemble_targets()` first, then solves the equation with the private field solver and the matrix  $A$  initialized in `initialize()`.
- `local_phase()`, it constructs the  $2 \times 2$  cross-variance matrices  $S_i(u)$ , which are stored in a private field `std::map< std::pair< int, int>, Matrix2d> L`, i.e. a mapping from half edges to matrices. Then we call `SVD()` to further update  $L$ .
- Finally, `iterate()` is just calling `local_phase()` and `global_phase()` in a for loop.

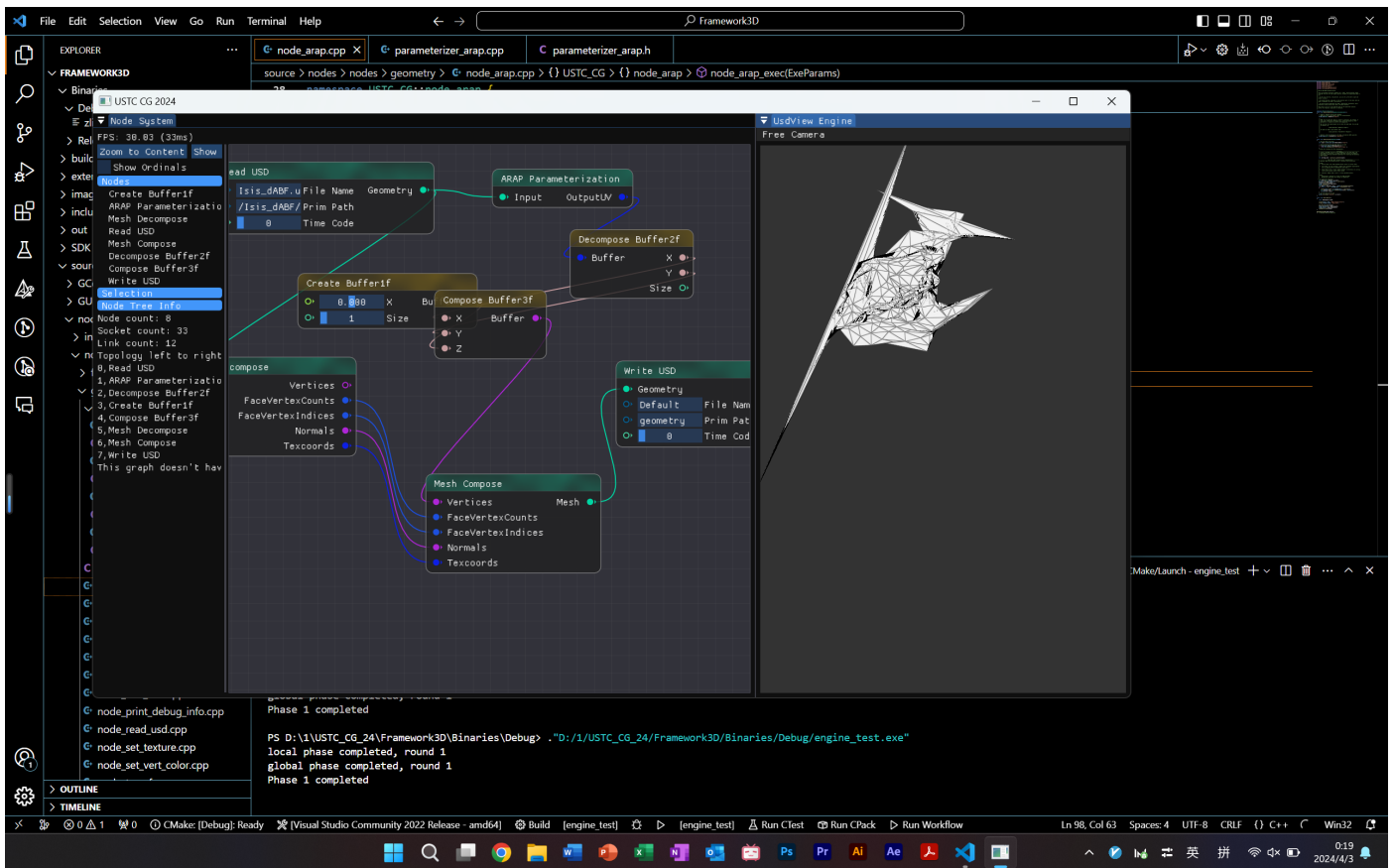
## Results

All the following results use only 1 iteration.

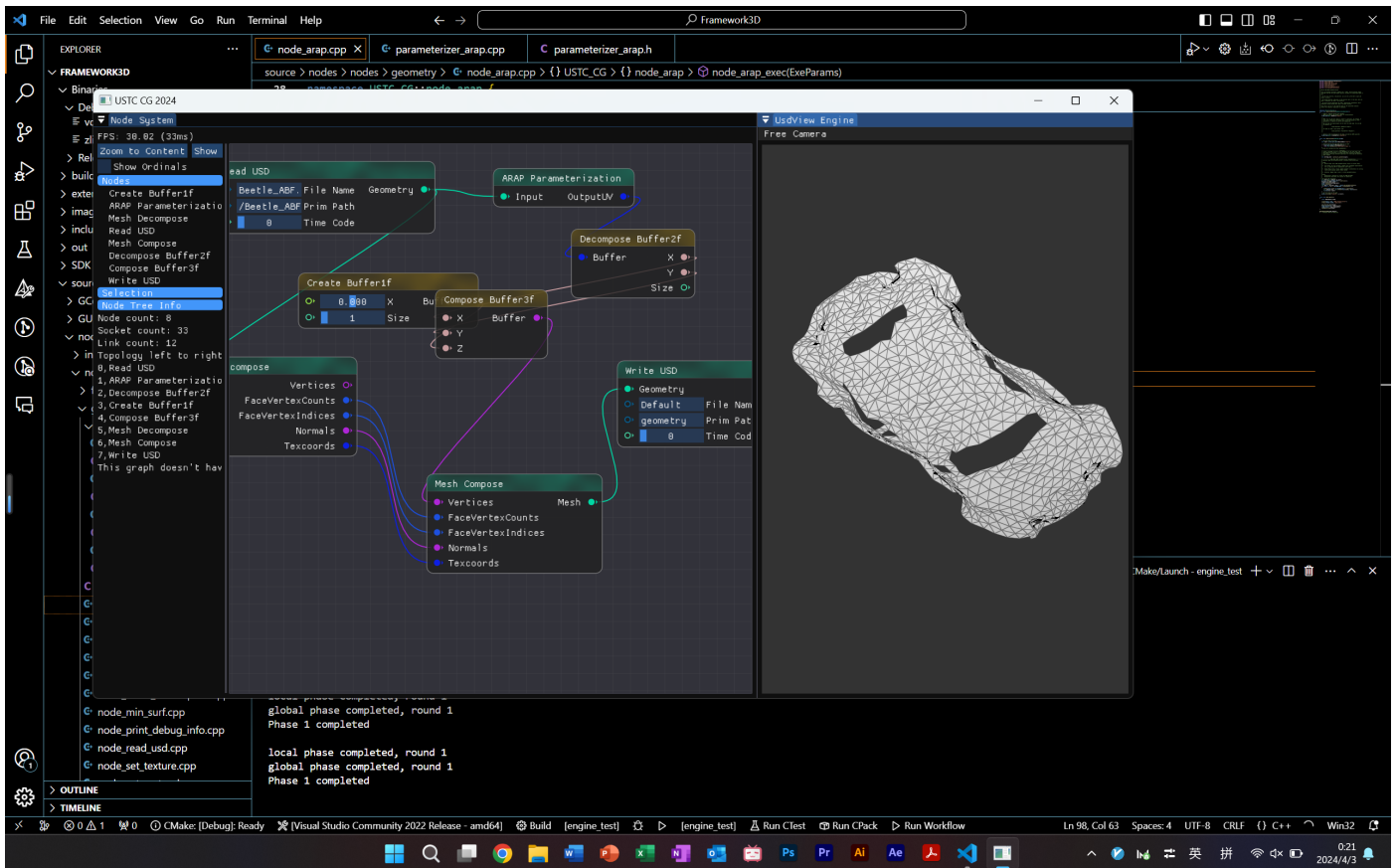
Cow:



Isis:



## Beetle:



## Issues and Future Work

- I haven't implemented the fix points, now only the first iteration gives a decent result. I might have to check if the mapping of vertices is in order because the mesh appears to be messy.

- do some node programming: make it easier to select the initial boundary mapping method, enable num\_iteration selection in the node, etc.