

# STAT 3690 Lecture Note

## Part II: Basics of statistical modelling

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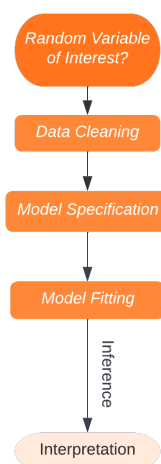
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“All models are wrong, but some are useful.”

— G. E. P. Box. (1976). *Journal of the American Statistical Association*, 71:791–799

## Statistical modelling



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## What is a statistical model?

- The (joint) distribution of the random variable(s) of interest
  - E.g., reformulate linear regression and logit regression models in terms of distributions

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## Recall the characterization of univariate distributions

- A random variable (RV), say  $X$ , is a real-valued function (defined on a sample space).
- The cumulative distribution function (cdf) of  $X$ , say  $F_X(x) = \Pr(X \leq x)$ ,  $x \in \mathbb{R}$ , if (right continuous)  $\lim_{t \rightarrow x_0^+} F_X(x) = F_X(x_0)$ , (non-decreasing)  $F_X(x_0) \leq F_X(x_1)$  for  $x_0 < x_1$ , and (ranging from 0 to 1)  $F_X(-\infty) = 0$  and  $F_X(\infty) = 1$ .
  - Reversely, any function satisfying the three properties must be a cdf for certain RV.

- Discrete RV
  - RV  $X$  takes countable different values
  - Probability mass function (pmf):  $p_X(x) = \Pr(X = x)$
- Continuous RV
  - RV  $X$  is continuous iff its cdf  $F_X$  is (absolutely) continuous, i.e., there exists  $f_X$ , s.t.

$$F_X(x) = \int_{-\infty}^x f_X(u) du, \quad \forall x \in \mathbb{R}.$$

- Probability density function (pdf):  $f_X(x) = F'_X(x)$ .
  - Moment-generating function (mgf)  $M_X(t) = E\{\exp(tX)\}$  if  $E\{\exp(tX)\} < \infty$  for  $t$  in a neighbourhood of 0
    - If the mgf exists, then  $E(X^k) = M_X^{(k)}(t) |_{t=0}$ .
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## Support of RV

- Support of  $X$ , say  $\text{supp}(X)$ , is  $\{x \in \mathbb{R} : p_X(x) \text{ (or } f_X(x)) > 0\}$ 
    - e.g., support of  $\text{Binom}(n, p)$  is  $\{0, \dots, n\}$ ; support of  $\mathcal{N}(0, 1)$  is  $\mathbb{R}$ .
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## Indicator function

- Given a set  $A$ , the indicator function of  $A$  is

$$\mathbf{1}_A(x) = \begin{cases} 1, & x \in A, \\ 0, & \text{otherwise.} \end{cases}$$

- Hence, e.g., if  $X \sim \text{Binom}(n, p)$ , then  $p_X(x) = \binom{n}{x} p^x (1-p)^{1-x}$ ,  $x \in \{0, \dots, n\}$ ,  $p \in (0, 1)$ , or equivalently,  $p_X(x) = \binom{n}{x} p^x (1-p)^{1-x} \mathbf{1}_{\{0, \dots, n\}}(x) \mathbf{1}_{(0,1)}(p)$
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## Characterization of joint/multivariate distributions

- Random (column) vector/vector-valued RV
  - $\mathbf{X} = [X_1, \dots, X_p]^\top$
- Joint cdf:  $F_{\mathbf{X}}(x_1, \dots, x_p) = \Pr(X_1 \leq x_1, \dots, X_p \leq x_p)$
- Joint distribution of continuous RVs

- Joint pdf:

$$f_{\mathbf{X}}(x_1, \dots, x_p) = \frac{\partial^p}{\partial x_1 \dots \partial x_p} F_{\mathbf{X}}(x_1, \dots, x_p)$$

- E.g., multivariate normal (MVN) distribution

- Joint distribution of discrete RVs

- Joint pmf:

$$p_{\mathbf{X}}(x_1, \dots, x_p) = \Pr(X_1 = x_1, \dots, X_p = x_p)$$

- E.g., categorical distribution & multinomial distribution

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- Exercise 2.1: Suppose that we independently observe an experiment that has  $m$  possible outcomes  $O_1, \dots, O_m$  for  $n$  times; e.g., sample  $n$  balls with replacement from a pool of balls of  $m$  colors. Let  $p_1, \dots, p_m$  denote probabilities of  $O_1, \dots, O_m$  in each experiment respectively. Let  $X_i$  denote the number of times that outcome  $O_i$  occurs in the  $n$  repetitions.
    - What is the distribution of  $X_i$ ?
    - What is the joint pmf of  $\mathbf{X} = [X_1, \dots, X_m]^\top$ ?
- 

```
xs = c(10, 4, 7, 9)
ps = c(.3, .4, .2, .1)
dmultinom(x = xs, prob = ps)

# verify that binomial is a special case of multinomial
xs = c(4, 6)
ps = c(.6, .4)
dmultinom(x = xs, prob = ps)
dbinom(x = xs[1], size = sum(xs), prob = ps[1])
```

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- Moment-generating function (mgf)  $M_{\mathbf{X}}(\mathbf{t}) = E\{\exp(\mathbf{t}^\top \mathbf{X})\}$  if there exists  $\delta > 0$  s.t.  $E\{\exp(\mathbf{t}^\top \mathbf{X})\} < \infty$  for all  $\mathbf{t} \in \{\mathbf{t} : \mathbf{t}^\top \mathbf{t} < \delta\}$ 
    - If the mgf of  $\mathbf{X}$  exists and  $X_i$  are independent of each other, then  $M_{\mathbf{X}}(\mathbf{t}) = \prod_{i=1}^p M_{X_i}(t_i)$ .
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## Marginalization

- $\mathbf{X} = [X_1, \dots, X_m]^\top$ ,
- $\mathbf{Y} = [X_1, \dots, X_q]^\top$ ,  $p > q$ , as part of  $\mathbf{X}$
- Marginal cdf of  $\mathbf{Y}$

$$F_{\mathbf{Y}}(x_1, \dots, x_q) = \lim_{x_{q+1}, \dots, x_m \rightarrow \infty} F_{\mathbf{X}}(x_1, \dots, x_m)$$

- Marginal pdf of  $\mathbf{Y}$  (when  $X_1, \dots, X_m$  are all continuous)

$$f_{\mathbf{Y}}(x_1, \dots, x_q) = \int_{\mathbb{R}^{m-q}} f_{\mathbf{X}}(x_1, \dots, x_m) dx_{q+1} \cdots x_m$$

- Marginal pmf of  $\mathbf{Y}$  (when  $X_1, \dots, X_m$  are all discrete)

$$p_{\mathbf{Y}}(x_1, \dots, x_q) = \sum_{x_{q+1}, \dots, x_m} p_{\mathbf{X}}(x_1, \dots, x_m)$$


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## Conditioning

- $\mathbf{X} = [X_1, \dots, X_m]^\top$  and  $\mathbf{Y} = [Y_1, \dots, Y_q]^\top$
- Conditional pdf of  $\mathbf{Y}$  given  $\mathbf{X}$

$$f_{\mathbf{Y}|\mathbf{X}}(y_1, \dots, y_q \mid x_1, \dots, x_m) = \frac{f_{\mathbf{X}, \mathbf{Y}}(x_1, \dots, x_m, y_1, \dots, y_q)}{f_{\mathbf{X}}(x_1, \dots, x_m)}$$

- Conditional pmf of  $\mathbf{Y}$  given  $\mathbf{X}$

$$p_{\mathbf{Y}|\mathbf{X}}(y_1, \dots, y_q \mid x_1, \dots, x_m) = \frac{p_{\mathbf{X}, \mathbf{Y}}(x_1, \dots, x_m, y_1, \dots, y_q)}{p_{\mathbf{X}}(x_1, \dots, x_m)}$$


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## Transformation of random vectors

- Derive the pdf of continuous  $\mathbf{Y} = \mathbf{g}(\mathbf{X})$  from the pdf of continuous  $\mathbf{X}$
- Prerequisite
  - $\mathbf{X} = [X_1, \dots, X_p]^\top$  and  $\mathbf{Y} = [Y_1, \dots, Y_p]^\top$
  - $\mathbf{g} = (g_1, \dots, g_p): \mathbb{R}^p \rightarrow \mathbb{R}^p$  is a continuous one-to-one map with inverse  $\mathbf{g}^{-1} = (h_1, \dots, h_p)$ , i.e.,  $Y_i = g_i(\mathbf{X})$  and  $X_i = h_i(\mathbf{Y})$
- Elaborate  $\text{supp}(\mathbf{Y}) = \{[y_1, \dots, y_p]^\top : [h_1(y_1, \dots, y_p), \dots, h_p(y_1, \dots, y_p)]^\top \in \text{supp}(\mathbf{X})\}$
- Jacobian matrix of  $\mathbf{g}^{-1}$  is  $\mathbf{J}_{\mathbf{g}^{-1}} = [\partial x_i / \partial y_j]_{p \times p} = [\partial h_i(y_1, \dots, y_p) / \partial y_j]_{p \times p}$ 
  - Also,  $|\det(\mathbf{J}_{\mathbf{g}^{-1}})| = |\det([\partial y_i / \partial x_j]_{p \times p})|^{-1} = |\det([\partial g_i(x_1, \dots, x_p) / \partial x_j]_{p \times p})|^{-1}$
- Then

$$f_{\mathbf{Y}}(y_1, \dots, y_p) = f_{\mathbf{X}}(h_1(y_1, \dots, y_p), \dots, h_p(y_1, \dots, y_p)) |\det(\mathbf{J}_{\mathbf{g}^{-1}})| \mathbf{1}_{\text{supp}(\mathbf{Y})}(y_1, \dots, y_p)$$


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- Exercise 2.2: Let  $\mathbf{X} = [X_1, X_2]^\top$  follow the standard bivariate normal, i.e., its pdf is

$$f_{\mathbf{X}}(x_1, x_2) = (2\pi)^{-1} \exp\{-(x_1^2 + x_2^2)/2\} \mathbf{1}_{\mathbb{R}^2}(x_1, x_2).$$

Find out the joint pdf of  $\mathbf{Y} = [Y_1, Y_2]^\top$ , where  $Y_1 = \sqrt{X_1^2 + X_2^2}$  and  $0 \leq Y_2 < 2\pi$  is the angle from the positive  $x$ -axis to the ray from the origin to the point  $(X_1, X_2)$ , that is,  $Y$  is  $X$  in the polar coordinate.

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- Exercise 2.3: Given positive  $\alpha, \beta$  and  $\theta$ ,  $\mathbf{X} = [X_1, X_2]^\top$  follow

$$f_{\mathbf{X}}(x_1, x_2) = \frac{1}{\Gamma(\alpha)\Gamma(\beta)\theta^{\alpha+\beta}} x_1^{\alpha-1} x_2^{\beta-1} \exp\left(-\frac{x_1 + x_2}{\theta}\right) \mathbf{1}_{\mathbb{R}^+ \times \mathbb{R}^+}(x_1, x_2),$$

where  $\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt$ , e.g.,  $\Gamma(n) = (n-1)!$  for positive integer  $n$ . Find out the joint pdf of  $\mathbf{Y} = [Y_1, Y_2]^\top$ , where  $Y_1 = X_1/(X_1 + X_2)$  and  $Y_2 = X_1 + X_2$ .

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## Mean matrix

- $\mathbf{E}(\mathbf{X}) = [\mathbf{E}(X_{ij})]_{n \times p}$ , where
    - Random  $n \times p$  matrix  $\mathbf{X} = [X_{ij}]_{n \times p}$
  - (Linearity)  $\mathbf{E}(\mathbf{A}\mathbf{X} + \mathbf{B}\mathbf{Y}) = \mathbf{A}\mathbf{E}(\mathbf{X}) + \mathbf{B}\mathbf{E}(\mathbf{Y})$ , where
    - Fixed  $\mathbf{A} \in \mathbb{R}^{\ell \times n}$  and  $\mathbf{B} \in \mathbb{R}^{\ell \times m}$
    - Random matrices  $\mathbf{X} = [X_{ij}]_{n \times p}$  and  $\mathbf{Y} = [Y_{ij}]_{m \times p}$
-

## Covariance matrix

- Random  $p$ -vector  $\mathbf{X} = [X_1, \dots, X_p]^\top$  and random  $q$ -vector  $\mathbf{Y} = [Y_1, \dots, Y_q]^\top$
  - Covariance matrix (defined via expectation)  $\Sigma_{\mathbf{XY}} = \text{cov}(\mathbf{X}, \mathbf{Y}) = \mathbb{E}[\{\mathbf{X} - \mathbb{E}(\mathbf{X})\}\{\mathbf{Y} - \mathbb{E}(\mathbf{Y})\}^\top]$ 
    - Also,  $\Sigma_{\mathbf{XY}} = \mathbb{E}(\mathbf{XY}^\top) - \mathbb{E}(\mathbf{X})\mathbb{E}(\mathbf{Y}^\top)$
    - The  $(i, j)$ -entry of  $\Sigma_{\mathbf{XY}}$  is  $\text{cov}(X_i, Y_j)$
  - $\Sigma_{\mathbf{AX+a, BY+b}} = \mathbf{A}\Sigma_{\mathbf{XY}}\mathbf{B}^\top$  for fixed  $\mathbf{A} \in \mathbb{R}^{m \times p}$ ,  $\mathbf{a} \in \mathbb{R}^m$ ,  $\mathbf{B} \in \mathbb{R}^{\ell \times q}$  and  $\mathbf{b} \in \mathbb{R}^\ell$
  - $\Sigma_{\mathbf{X}} \geq 0$ , where  $\Sigma_{\mathbf{X}} = \text{cov}(\mathbf{X})$  is short for  $\Sigma_{\mathbf{XX}} = \text{cov}(\mathbf{X}, \mathbf{X})$
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## Sample covariance matrix

- Samples  $\mathbf{X}_k = [X_{k1}, \dots, X_{kp}]^\top$  and  $\mathbf{Y}_k = [Y_{k1}, \dots, Y_{kq}]^\top$ ,  $k = 1, \dots, n$
- $(\mathbf{X}_k, \mathbf{Y}_k) \stackrel{\text{iid}}{\sim} (\mathbf{X}, \mathbf{Y})$ , where  $\mathbf{X} = [X_1, \dots, X_p]^\top$  and  $\mathbf{Y} = [Y_1, \dots, Y_q]^\top$
- Sample mean vectors
  - $\bar{\mathbf{X}} = n^{-1} \sum_{k=1}^n \mathbf{X}_k = [\bar{X}_{\cdot 1}, \dots, \bar{X}_{\cdot p}]^\top$ 
    - \*  $\bar{X}_{\cdot i} = n^{-1} \sum_{k=1}^n X_{ki}$
  - $\bar{\mathbf{Y}} = n^{-1} \sum_{k=1}^n \mathbf{Y}_k = [\bar{Y}_{\cdot 1}, \dots, \bar{Y}_{\cdot q}]^\top$ 
    - \*  $\bar{Y}_{\cdot j} = n^{-1} \sum_{k=1}^n Y_{kj}$
- Sample covariance matrix:

$$\mathbf{S}_{\mathbf{XY}} = \frac{1}{n-1} \sum_{k=1}^n \{(\mathbf{X}_k - \bar{\mathbf{X}})(\mathbf{Y}_k - \bar{\mathbf{Y}})^\top\}$$

- The  $(i, j)$ -entry of  $\mathbf{S}_{\mathbf{XY}}$  is  $(n-1)^{-1} \sum_{k=1}^n (X_{ki} - \bar{X}_{\cdot i})(Y_{kj} - \bar{Y}_{\cdot j})$ , i.e., the sample covariance between  $X_i$  (the  $i$ th entry of  $\mathbf{X}$ ) and  $Y_j$  (the  $j$ th entry of  $\mathbf{Y}$ )
  - Unbiasedness:  $\mathbb{E}(\mathbf{S}_{\mathbf{XY}}) = \Sigma_{\mathbf{XY}}$
  - $\mathbf{S}_{\mathbf{AX+a, BY+b}} = \mathbf{A}\mathbf{S}_{\mathbf{XY}}\mathbf{B}^\top$  for  $\mathbf{A} \in \mathbb{R}^{m \times p}$ ,  $\mathbf{a} \in \mathbb{R}^m$ ,  $\mathbf{B} \in \mathbb{R}^{\ell \times q}$  and  $\mathbf{b} \in \mathbb{R}^\ell$
  - $\mathbf{S}_{\mathbf{X}} \geq 0$
  - Implementation in R: `cov()` (or `var()` if  $\mathbf{X} = \mathbf{Y}$ )
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## Computing sample mean vectors and sample covariance matrices via R

```
options(digits = 4)
set.seed(1)

# mean vector and covariance matrix
(Mu = runif(3))
A = matrix(runif(15), nrow = 3, ncol = 5)
(Sigma = A %*% t(A))

# generation of samples
n = 100
sample = MASS::mvrnorm(n, Mu, Sigma)
colnames(sample) = c('W', 'H', 'BP')
head(sample)

# reference for various scatterplots https://www.statmethods.net/graphs/scatterplot.html
```

```

# scatterplots for paired features
pairs(sample)
# (spinning) 3D scatterplot
rgl::plot3d(sample[,1], sample[,2], sample[,3], col = "red", size = 6)

# sample mean vector for  $[V1, V2, V3]^T$ 
(MuHat = apply(sample, 2, mean))
(MuHat = colMeans(sample))
# sample covariance matrix for  $[W, H, BP]^T$ 
## following the definition
S = 0; for (i in 1:n){S = S + 1/(n-1) * (sample[i,]-MuHat) %*% t(sample[i,]-MuHat)}; S
## via var()
(S = var(sample))
## via cov()
(S = cov(sample))

var(sample[,2], sample[,1])

# sample covariance matrix for  $W$  &  $[H, BP]^T$ 
cov(sample[,1], sample[,2:3])
# sample covariance matrix for  $H$  &  $[BP, W]^T$ 
cov(sample[,2], sample[,c(3,1)])

# another sample
(Mu2 = runif(2))
A2 = matrix(runif(10), nrow = 2, ncol = 5)
(Sigma2 = A2 %*% t(A2))
sample2 = MASS::mvrnorm(n, Mu2, Sigma2)
colnames(sample2) = c('CH', 'HR')
head(sample2)
cov(sample, sample2)
sample_c = cbind(sample, sample2)
cov(sample_c)
cov(sample, sample2)

```