## STAT 3690 Lecture 04

zhiyanggeezhou.github.io

Zhiyang Zhou (zhiyang.zhou@umanitoba.ca)

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#### Covariance matrix of random vectors X and Y

- Random p-vector  $\mathbf{X} = [X_1, \dots, X_p]^{\top}$  and q-vector  $\mathbf{Y} = [Y_1, \dots, Y_q]^{\top}$
- Expectations of random vectors/matrices are taken entry-wisely, e.g.,  $\mu_{\mathbf{X}} = \mathbf{E}(\mathbf{X}) = [\mathbf{E}(X_1), \dots, \mathbf{E}(X_p)]^{\top}$ .
  - $E(\mathbf{AX} + \mathbf{a}) = \mathbf{AE}(\mathbf{X}) + \mathbf{a}$  as long as both  $\mathbf{AX} + \mathbf{a}$  and  $\mathbf{BY} + \mathbf{b}$  exist.
- Covariance matrix: the (i, j)-entry is the covariance between the i-th entry of **X** and j-th entry of **Y** 
  - $\Sigma_{\mathbf{XY}} = [\operatorname{cov}(X_i, Y_j)]_{p \times q} = \operatorname{E}[\{\mathbf{X} \operatorname{E}(\mathbf{X})\}\{\mathbf{Y} \operatorname{E}(\mathbf{Y})\}^{\top}] = \operatorname{E}(\mathbf{XY}^{\top}) \boldsymbol{\mu}_{\mathbf{X}}\boldsymbol{\mu}_{\mathbf{Y}}^{\top}$   $\Sigma_{\mathbf{AX} + \boldsymbol{a}, \mathbf{BY} + \boldsymbol{b}} = \mathbf{A}\boldsymbol{\Sigma}_{\mathbf{XY}}\mathbf{B}^{\top} \text{ as long as both } \mathbf{AX} + \boldsymbol{a} \text{ and } \mathbf{BY} + \boldsymbol{b} \text{ exist.}$

  - $-\Sigma_{\mathbf{XX}} \geq 0$ , i.e.,  $\Sigma_{\mathbf{XX}}$  is positive semi-definite
- Exercise: Verify the properties of covariance matrix
  - 1.  $\Sigma_{\mathbf{AX}+a,\mathbf{BY}+b} = \mathbf{A}\Sigma_{\mathbf{XY}}\mathbf{B}^{\top}$  as long as both  $\mathbf{AX}+a$  and  $\mathbf{BY}+b$  exist.

$$\Sigma_{AX+\alpha,BY+b} = E[\{AX+\alpha-E(AX+\alpha)\}^{S}B\}^{A}_{A} - E(BY+b)\}^{T}]$$

$$= E[A[X-E[X]]^{Y} - E[Y]^{T}B^{T}]$$

$$= AE[\{X-E[X]\}^{Y} - E[Y]^{T}]B^{T}$$

$$= A \Sigma \times Y B^{T}$$

Es Eigenvalues of Exx are all nonnegative

#### Sample covariance matrix

• 
$$(\mathbf{X}_i, \mathbf{Y}_i) \stackrel{\text{iid}}{\sim} (\mathbf{X}, \mathbf{Y}), i = 1, \dots, n$$

• Sample means: 
$$\bar{\mathbf{X}} = n^{-1} \sum_{i=1}^n \mathbf{X}_i$$
 and  $\bar{\mathbf{Y}} = n^{-1} \sum_{i=1}^n \mathbf{Y}_i$ 

• Sample covariance matrix:

$$\mathbf{S}_{\mathbf{XY}} = \frac{1}{n-1} \sum_{i=1}^{n} \{ (\mathbf{X}_i - \bar{\mathbf{X}}) (\mathbf{Y}_i - \bar{\mathbf{Y}})^{\top} \}$$

- Unbiasedness:  $E(S_{XY}) = \Sigma_{XY}$
- $-\mathbf{S}_{\mathbf{AX}+a,\mathbf{BY}+b} = \mathbf{AS}_{\mathbf{XY}}\mathbf{B}^{\top}$  as long as both  $\mathbf{AX}+a$  and  $\mathbf{BY}+b$  exist.
- $-\mathbf{S}_{\mathbf{X}\mathbf{X}} > 0$
- Implementation in R: cov() (or var() if  $\mathbf{X} = \mathbf{Y}$ )
- Exercise: Verify the properties of sample covariance matrix
  - 1.  $\mathrm{E}(\mathbf{S}_{\mathbf{X}\mathbf{Y}}) = \mathbf{\Sigma}_{\mathbf{X}\mathbf{Y}}$ . (Hint:  $(n-1)\mathbf{S}_{\mathbf{X}\mathbf{Y}} = \sum_{i=1}^{n} \mathbf{X}_{i}\mathbf{Y}_{i}^{\top} n\bar{\mathbf{X}}\bar{\mathbf{Y}}^{\top} = \sum_{i=1}^{n} \mathbf{X}_{i}\mathbf{Y}_{i}^{\top} n^{-1}\sum_{i,j} \mathbf{X}_{i}\mathbf{Y}_{j}^{\top}$ )
  - 2.  $\mathbf{S}_{\mathbf{AX}+a,\mathbf{BY}+b} = \mathbf{AS}_{\mathbf{XY}}\mathbf{B}^{\top}$  as long as both  $\mathbf{AX}+a$  and  $\mathbf{BY}+b$  exist.
  - 3.  $S_{XX} \ge 0$ .

$$\begin{split} \text{7. } & (m-1) \ E\left(S_{XY}\right) = \ \Sigma_{i} \ E\left(X_{i}Y_{i}^{T}\right) - n^{-1} \ \Sigma_{i,j} \ E\left(X_{i}Y_{j}^{T}\right) \\ & = \ \Sigma_{i} \ E\left(X_{i}Y_{i}^{T}\right) - n^{-1} \ \Sigma_{i,j} \ E\left(X_{i}Y_{j}^{T}\right) - n^{-1} \ \Sigma_{i\neq j} \ E\left(X_{i}Y_{j}^{T}\right) \\ & = \ \Sigma_{i} \ E\left(X_{i}Y_{i}^{T}\right) - n^{-1} \ \Sigma_{i} \ E\left(X_{i}Y_{i}^{T}\right) - n^{-1} \ \Sigma_{i\neq j} \ E\left(X_{i}Y_{j}^{T}\right) \ \left( \ \cdot \cdot \ X_{i} \ \bot Y_{j} \ \not - n^{-1} \ x_{i} \ \bot \right) \\ & = (n-1) \ E\left(X_{i}Y_{i}^{T}\right) - n^{-1} (n^{2}-n) \ E\left(X_{i} \ E\left(Y_{i}^{T}\right) \ \left( \ \cdot \cdot \ X_{i} \ \bot Y_{j} \right) \ \stackrel{\text{ind}}{=} \ \left(X_{i} \ Y_{i}\right) \ \stackrel{\text{ind}}{=} \ \left(X_{i} \ Y$$

# Method of moments (MOM) estimators for mean vectors and covariance matrices

- MOM imposes no specific distribution on X or Y
- Steps
  - 1. Equate raw moments to their sample counterparts:

$$\begin{cases} \mathbf{E}(\mathbf{X}) = \bar{\mathbf{X}} \\ \mathbf{E}(\mathbf{Y}) = \bar{\mathbf{Y}} \\ \mathbf{E}(\mathbf{X}\mathbf{Y}^{\top}) = n^{-1} \sum_{i} \mathbf{X}_{i} \mathbf{Y}_{i}^{\top} \end{cases} \Leftrightarrow \begin{cases} \boldsymbol{\mu}_{\mathbf{X}} = \bar{\mathbf{X}} \\ \boldsymbol{\mu}_{\mathbf{Y}} = \bar{\mathbf{Y}} \\ \boldsymbol{\Sigma}_{\mathbf{X}\mathbf{Y}} + \boldsymbol{\mu}_{\mathbf{X}} \boldsymbol{\mu}_{\mathbf{Y}}^{\top} = n^{-1} \sum_{i} \mathbf{X}_{i} \mathbf{Y}_{i}^{\top} \end{cases}$$

2. Solve the above equations w.r.t.  $\mu_{\mathbf{X}}$ ,  $\mu_{\mathbf{Y}}$  and  $\Sigma_{\mathbf{XY}}$  and obtain estimators

$$\begin{cases} \hat{\boldsymbol{\mu}}_{\mathbf{X}} = \bar{\mathbf{X}} \\ \hat{\boldsymbol{\mu}}_{\mathbf{Y}} = \bar{\mathbf{Y}} \\ \hat{\boldsymbol{\Sigma}}_{\mathbf{XY}} = n^{-1} \sum_{i} \mathbf{X}_{i} \mathbf{Y}_{i}^{\top} - \bar{\mathbf{X}} \bar{\mathbf{Y}}^{\top} = n^{-1} (n-1) \mathbf{S}_{\mathbf{XY}} \end{cases}$$

### Computing means and covariance matrices by R

```
options(digits = 4)
install.packages(c('rgl', 'MASS'))
set.seed(1)
# parameters
n = 1000
Mu = 1:3
Sigma = matrix(c(1, .5, .5,
              .5, 3, .5,
              .5, .5, 7),
            nrow = 3, ncol = 3)
# check the eligibility of Sigma and review the spectral decomposition
isSymmetric.matrix(Sigma)
eigen.Sig = eigen(Sigma)
(Lambda = diag(eigen.Sig$values))
(U = eigen.Sig$vectors)
(U %*% t(U))
(U %*% Lambda %*% t(U))
# generation of samples
samples = MASS::mvrnorm(n, Mu, Sigma)
# reference for various scatterplots https://www.statmethods.net/graphs/scatterplot.html
# scatterplots for paired RVs
pairs(samples)
# (spinning) 3D scatterplot
rgl::plot3d(samples[,1], samples[,2], samples[,3], col = "red", size = 6)
# sample mean vector for [V1, V2, V3]^T
(muHat = apply(samples, 2, mean))
(muHat = colMeans(samples))
# sample covariance matrix for [V1, V2, V3]^T
(S = var(samples))
(S = cov(samples))
# sample covariance matrix for V1 \& [V2, V3] ^T
cov(samples[,1], samples[,2:3])
# sample covariance matrix for V2 & [V3,V1]^T
cov(samples[,2], samples[,c(3,1)])
```