

STAT 3690 Lecture 03

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“All models are wrong, but some are useful.”

— G. E. P. Box. (1976). *Journal of the American Statistical Association*, 71:791–799

Statistical modelling

- What is a statistical model?
 - (Joint) distribution of random variable (RV) of interest
- Rephrase linear regression and logit regression models in terms of distributions

Characterizing/representing univariate distributions

- (scalar-valued) RV X : a real-valued function defined on a sample space Ω
- Cumulative distribution function (cdf): $F_X(x) = \Pr(X \leq x)$
 - right continuous with respect to x
 - non-decreasing w.r.t. x
 - ranging from 0 to 1
- Discrete RV
 - RV X takes countable different values.
 - probability mass function (pmf): $p_X(x) = \Pr(X = x)$
- Continuous RV
 - RV X is continuous iff its cdf F_X is absolutely continuous with respect to x , i.e., $\exists f_X$, s.t.

$$F_X(x) = \int_{-\infty}^x f_X(u) du \quad \forall x \in \mathbb{R}.$$

- probability density function (pdf): $f_X(x) = F'_X(x)$.
- Characteristic function
- Moment-generating function

Characterizing/representing joint/multivariate distributions

- Random vector/vector-valued RV
 - $\mathbf{X} = [X_1, \dots, X_p]^\top$
- Joint cumulative distribution function (joint cdf): $F_{\mathbf{X}}(x_1, \dots, x_p) = \Pr(X_1 \leq x_1, \dots, X_p \leq x_p)$
 - right continuous w.r.t. each x_i
 - non-decreasing w.r.t. each x_i

- ranging from 0 to 1
- Joint distribution of continuous RVs
 - Joint pdf/density:

$$f_{\mathbf{X}}(x_1, \dots, x_p) = \frac{\partial^p}{\partial x_1 \cdots \partial x_p} F_{\mathbf{X}}(x_1, \dots, x_p)$$

- Multivariate normal (MVN) distribution
- Joint distribution of discrete RVs
 - Joint pmf:

$$p_{\mathbf{X}}(x_1, \dots, x_p) = \Pr(X_1 = x_1, \dots, X_p = x_p)$$

- Multinomial distribution
- Multivariate characteristic/moment-generating functions

- Exercise: Suppose that we independently observe an experiment that has p possible outcomes O_1, \dots, O_p for n times. Let p_1, \dots, p_k denote probabilities of O_1, \dots, O_p in each experiment respectively. Let X_i denote the number of times that outcome O_i occurs in the n repetitions. What is the joint pmf of $\mathbf{X} = [X_1, \dots, X_p]^\top$?

Marginalization

- $\mathbf{X} = [X_1, \dots, X_p]^\top$ $\mathbf{Y} = [X_1, \dots, X_q]^\top$, and $q < p$.
- Marginal cdf

$$F_{\mathbf{Y}}(x_1, \dots, x_q) = \lim_{x_i \rightarrow \infty \text{ for all } i > q} F_{\mathbf{X}}(x_1, \dots, x_p)$$

- Marginal pdf of \mathbf{Y} (when X_1, \dots, X_p are all continuous)

$$f_{\mathbf{Y}}(x_1, \dots, x_q) = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} f_{\mathbf{X}}(x_1, \dots, x_p) dx_{q+1} \cdots dx_p$$

- Marginal pmf of \mathbf{Y} (when X_1, \dots, X_p are all discrete)

$$p_{\mathbf{Y}}(x_1, \dots, x_q) = \sum_{x_{q+1}=-\infty}^{\infty} \cdots \sum_{x_p=-\infty}^{\infty} p_{\mathbf{X}}(x_1, \dots, x_p)$$

- “marginal” is used to distinguish pdf/pmf of \mathbf{Y} from the joint pdf/pmf of \mathbf{X} .

Conditioning = joint/marginal

$\mathbf{Y} = [y_1, \dots, y_q]^\top$ and $\mathbf{X} = [x_1, \dots, x_p]^\top$

- Conditional pdf of \mathbf{Y} given \mathbf{X}

$$f_{\mathbf{Y}|\mathbf{X}}(y_1, \dots, y_q \mid x_1, \dots, x_p) = \frac{f_{\mathbf{X}, \mathbf{Y}}(x_1, \dots, x_p, y_1, \dots, y_q)}{f_{\mathbf{X}}(x_1, \dots, x_p)}$$

- Conditional pmf of \mathbf{Y} given \mathbf{X}

$$p_{\mathbf{Y}|\mathbf{X}}(y_1, \dots, y_q \mid x_1, \dots, x_p) = \frac{p_{\mathbf{X}, \mathbf{Y}}(x_1, \dots, x_p, y_1, \dots, y_q)}{p_{\mathbf{X}}(x_1, \dots, x_p)}$$

Transformation of random variables (p -dimensional case)

- Let $g = (g_1, \dots, g_p): \mathbb{R}^p \rightarrow \mathbb{R}^p$ be a one-to-one map with inverse $g^{-1} = (g_1^{-1}, \dots, g_p^{-1})$.
- $\mathbf{Y} = g(\mathbf{X})$ and $\mathbf{X} = g^{-1}(\mathbf{Y})$ are both continuous p -random vectors.
- Jacobian matrix of g^{-1} is $\mathbf{J} = [\partial g_i^{-1}(y_1, \dots, y_p) / \partial y_j]_{p \times p} = [\partial x_i / \partial y_j]_{p \times p}$.
– $|\det(\mathbf{J})| = |\det([\partial y_i / \partial x_j]_{p \times p})|^{-1}$ if replace x_j with $g^{-1}(y_1, \dots, y_p)$
- $f_{\mathbf{X}}$ is known. Then

$$f_{\mathbf{Y}}(y_1, \dots, y_p) = f_{\mathbf{X}}(h_1^{-1}(y_1, \dots, y_p), \dots, h_p^{-1}(y_1, \dots, y_p)) |\det(\mathbf{J})|$$

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- Exercise: Let $\mathbf{X} = [X_1, X_2]^\top$ follow the standard bivariate normal, i.e., its pdf is

$$f_{\mathbf{X}}(x_1, x_2) = (2\pi)^{-1} \exp\{-(x_1^2 + x_2^2)/2\}, \quad (x_1, x_2) \in \mathbb{R}^2.$$

Find out the joint pdf of $\mathbf{Y} = [Y_1, Y_2]^\top$, where $Y_1 = \sqrt{X_1^2 + X_2^2}$ and $0 \leq Y_2 < 2\pi$ is angle from the positive x -axis to the ray from the origin to the point (X_1, X_2) , that is, Y is X in polar co-ordinates.

Covariance matrix of random vectors \mathbf{X} and \mathbf{Y}

- Random p -vector $\mathbf{X} = [X_1, \dots, X_p]^\top$ and q -vector $\mathbf{Y} = [Y_1, \dots, Y_q]^\top$
- Expectations of random vectors/matrices are taken entry-wisely, e.g., $\boldsymbol{\mu}_{\mathbf{X}} = \mathbf{E}(\mathbf{X}) = [\mathbf{E}(X_1), \dots, \mathbf{E}(X_p)]^\top$.
– $\mathbf{E}(\mathbf{A}\mathbf{X} + \mathbf{a}) = \mathbf{A}\mathbf{E}(\mathbf{X}) + \mathbf{a}$ for arbitrary non-random legit \mathbf{A} and \mathbf{a}
- Covariance matrix: the (i, j) -entry is the covariance between the i -th entry of \mathbf{X} and j -th entry of \mathbf{Y}
– $\boldsymbol{\Sigma}_{\mathbf{XY}} = [\text{cov}(X_i, Y_j)]_{p \times q} = \mathbf{E}[\{\mathbf{X} - \mathbf{E}(\mathbf{X})\}\{\mathbf{Y} - \mathbf{E}(\mathbf{Y})\}^\top] = \mathbf{E}(\mathbf{XY}^\top) - \boldsymbol{\mu}_{\mathbf{X}}\boldsymbol{\mu}_{\mathbf{Y}}^\top$

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- Exercise: Prove that $\boldsymbol{\Sigma}_{\mathbf{AX} + \mathbf{a}, \mathbf{BY} + \mathbf{b}} = \mathbf{A}\boldsymbol{\Sigma}_{\mathbf{XY}}\mathbf{B}^\top$ for arbitrary non-random legit \mathbf{A} , \mathbf{a} , \mathbf{B} and \mathbf{b} .

Sample covariance matrix

- $(\mathbf{X}_i, \mathbf{Y}_i) \stackrel{\text{iid}}{\sim} (\mathbf{X}, \mathbf{Y}), i = 1, \dots, n$
- Sample means: $\bar{\mathbf{X}}$ and $\bar{\mathbf{Y}}$
- Sample covariance matrix:

$$\mathbf{S}_{\mathbf{XY}} = \frac{1}{n-1} \sum_{i=1}^n \{(\mathbf{X}_i - \bar{\mathbf{X}})(\mathbf{Y}_i - \bar{\mathbf{Y}})^\top\}$$

- Unbiasedness: $\mathbf{E}(\mathbf{S}_{\mathbf{XY}}) = \boldsymbol{\Sigma}_{\mathbf{XY}}$
- Implementation in R : `cov()` (or `var()` if $\mathbf{X} = \mathbf{Y}$)

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- Exercise: Prove that $\mathbf{E}(\mathbf{S}_{\mathbf{XY}}) = \boldsymbol{\Sigma}_{\mathbf{XY}}$.
– Hint: $(n-1)\mathbf{S}_{\mathbf{XY}} = \sum_{i=1}^n \mathbf{X}_i \mathbf{Y}_i^\top - n\bar{\mathbf{X}}\bar{\mathbf{Y}}^\top = \sum_{i=1}^n \mathbf{X}_i \mathbf{Y}_i^\top - n^{-1} \sum_{i,j} \mathbf{X}_i \mathbf{Y}_j^\top$

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- Exercise: Prove that $\mathbf{S}_{\mathbf{AX} + \mathbf{a}, \mathbf{BY} + \mathbf{b}} = \mathbf{A}\mathbf{S}_{\mathbf{XY}}\mathbf{B}^\top$ for arbitrary non-random legit \mathbf{A} , \mathbf{a} , \mathbf{B} and \mathbf{b} .

Method of moments (MOM) estimator for mean vectors and covariance matrices

- MOM imposes no specific distribution on \mathbf{X} or \mathbf{Y}
- Steps
 - Equate raw moments to their sample counterparts:

$$\begin{cases} E(\mathbf{X}) = \bar{\mathbf{X}} \\ E(\mathbf{Y}) = \bar{\mathbf{Y}} \\ E(\mathbf{X}\mathbf{Y}^\top) = n^{-1} \sum_i \mathbf{X}_i \mathbf{Y}_i^\top \end{cases} \Leftrightarrow \begin{cases} \boldsymbol{\mu}_{\mathbf{X}} = \bar{\mathbf{X}} \\ \boldsymbol{\mu}_{\mathbf{Y}} = \bar{\mathbf{Y}} \\ \boldsymbol{\Sigma}_{\mathbf{XY}} + \boldsymbol{\mu}_{\mathbf{X}} \boldsymbol{\mu}_{\mathbf{Y}}^\top = n^{-1} \sum_i \mathbf{X}_i \mathbf{Y}_i^\top \end{cases}$$

- Solve the above equations w.r.t. $\boldsymbol{\mu}_{\mathbf{X}}$, $\boldsymbol{\mu}_{\mathbf{Y}}$ and $\boldsymbol{\Sigma}_{\mathbf{XY}}$ and obtain estimators

$$\begin{cases} \hat{\boldsymbol{\mu}}_{\mathbf{X}} = \bar{\mathbf{X}} \\ \hat{\boldsymbol{\mu}}_{\mathbf{Y}} = \bar{\mathbf{Y}} \\ \hat{\boldsymbol{\Sigma}}_{\mathbf{XY}} = n^{-1} \sum_i \mathbf{X}_i \mathbf{Y}_i^\top - \bar{\mathbf{X}} \bar{\mathbf{Y}}^\top = n^{-1} (n-1) \mathbf{S}_{\mathbf{XY}} \end{cases}$$

Computing means and covariance matrices by R