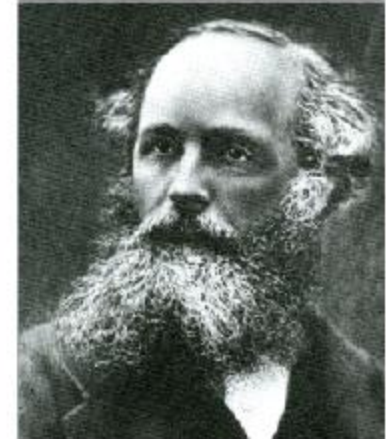
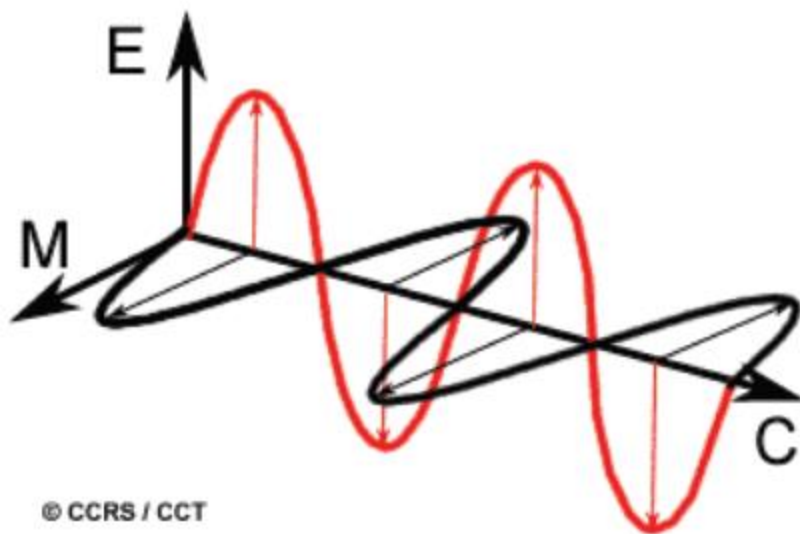


Electromagnetic radiation: wave model

- James Clerk Maxwell (1831-1879) – Scottish mathematician and physicist
- Wave model of EM energy
 - Unified existing laws of electricity and magnetism (Newton, Faraday, Kelvin, Ampère)
 - Oscillating electric field produces a magnetic field (and vice versa) – propagates an EM wave
 - Can be described by 4 differential equations
 - Derived speed of EM wave in a vacuum

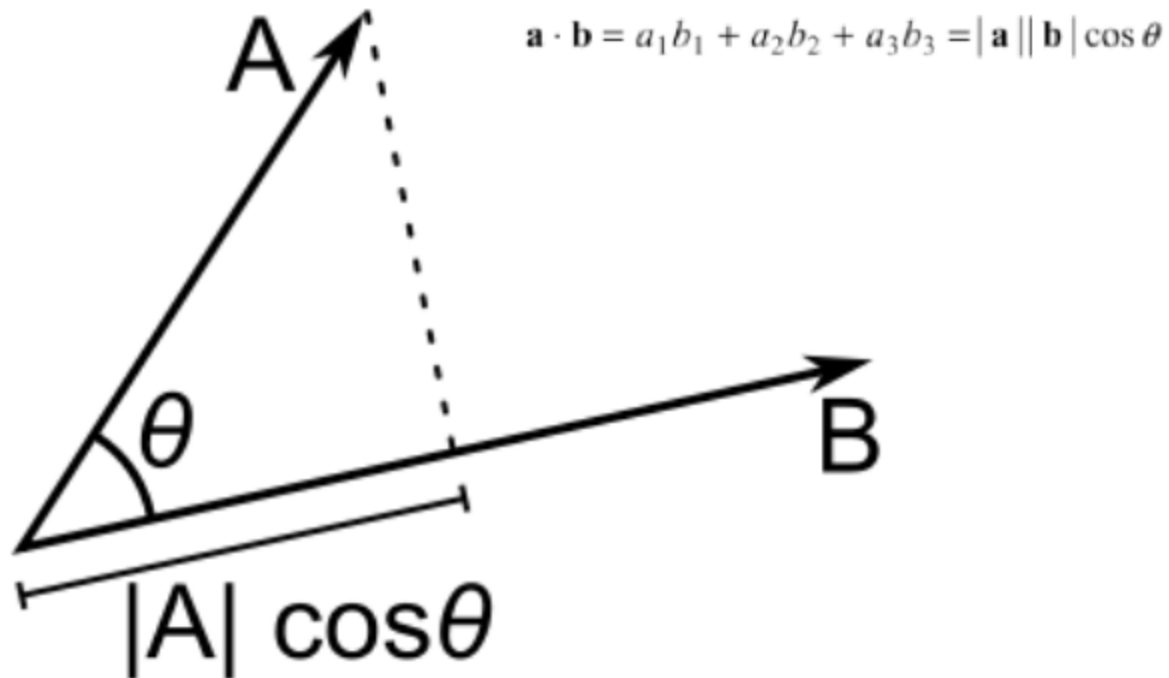


Electromagnetic radiation



- EM wave is:
- Electric field (E) perpendicular to magnetic field (M)
- Travels at velocity, c ($3 \times 10^8 \text{ ms}^{-1}$, in a vacuum)

Dot (scalar) product

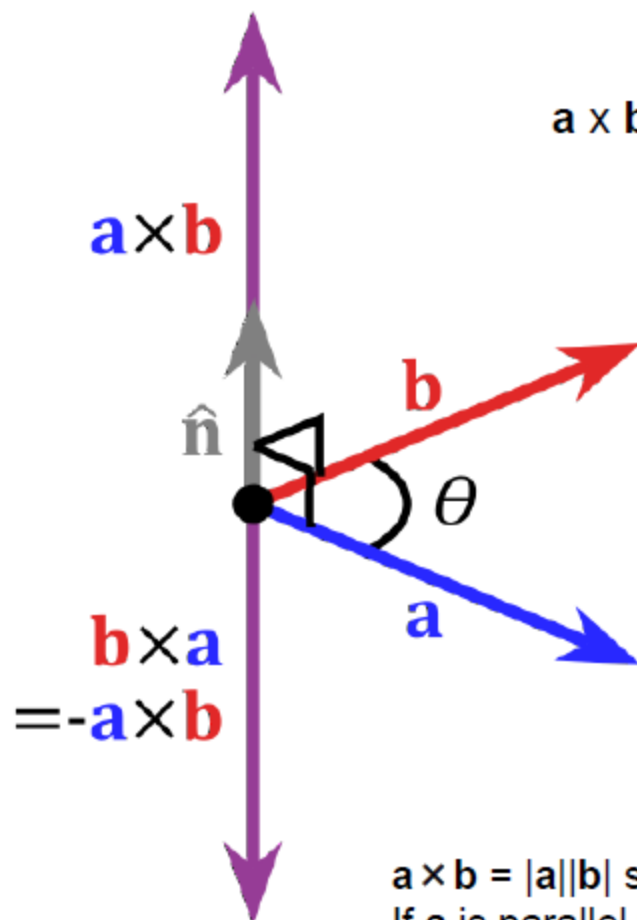


$$\mathbf{A} \cdot \mathbf{B} = |\mathbf{A}| |\mathbf{B}| \cos \theta$$

If \mathbf{A} is perpendicular to \mathbf{B} , the dot product of \mathbf{A} and \mathbf{B} is zero

Cross (vector) product

$$\mathbf{a} \times \mathbf{b} = [(a_2b_3 - a_3b_2), (a_3b_1 - a_1b_3), (a_1b_2 - a_2b_1)]$$



$$\mathbf{a} \times \mathbf{b} = |\mathbf{a}||\mathbf{b}| \sin \theta \mathbf{n}$$

If \mathbf{a} is parallel to \mathbf{b} , the cross product of \mathbf{a} and \mathbf{b} is zero

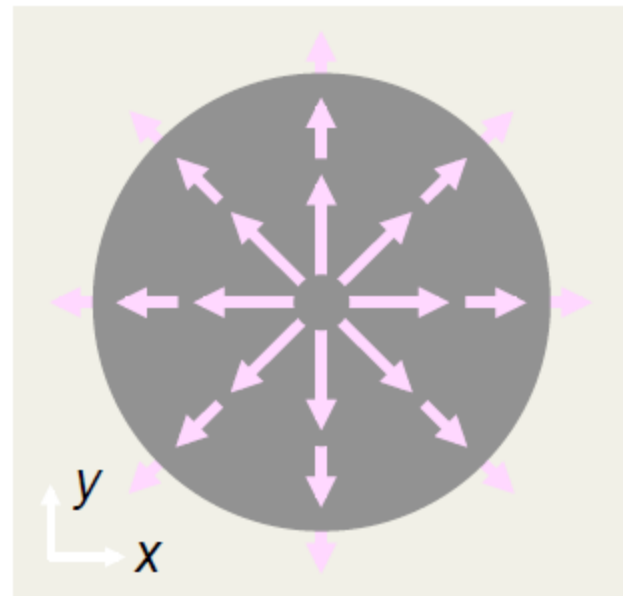
Div, Grad, Curl

The **Divergence** of a vector function (scalar):

$$\nabla \cdot f = \frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z}$$

The **Divergence** is nonzero if there are sources or sinks.

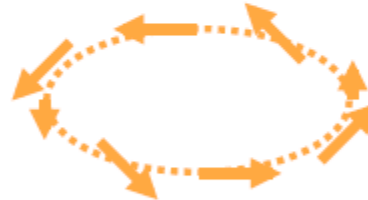
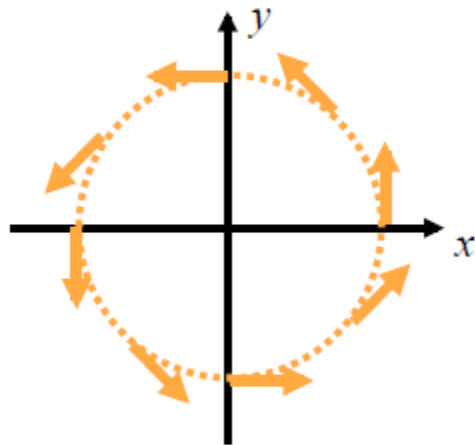
A 2D source with a large divergence:



Div, Grad, Curl

The **Curl** of a vector function \vec{f} :

$$\vec{\nabla} \times \vec{f} \equiv \left(\frac{\partial f_z}{\partial y} - \frac{\partial f_y}{\partial z}, \frac{\partial f_x}{\partial z} - \frac{\partial f_z}{\partial x}, \frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y} \right)$$



Functions that tend to **curl around** have large curls.

Div, Grad, Curl

The **Laplacian** of a scalar function :

$$\begin{aligned}\nabla^2 f &\equiv \vec{\nabla} \cdot \vec{\nabla} f = \vec{\nabla} \cdot \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) \\ &= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}\end{aligned}$$

The **Laplacian of a vector** function is the same,
but for each component of \vec{f} :

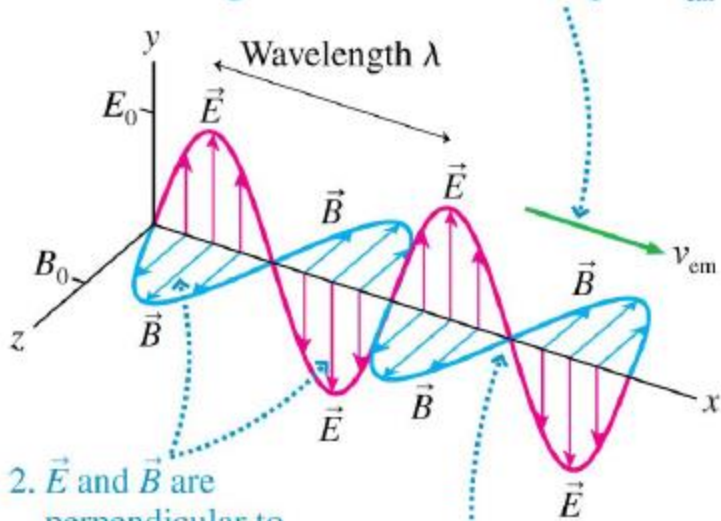
$$\nabla^2 \vec{f} = \left(\frac{\partial^2 f_x}{\partial x^2} + \frac{\partial^2 f_x}{\partial y^2} + \frac{\partial^2 f_x}{\partial z^2}, \frac{\partial^2 f_y}{\partial x^2} + \frac{\partial^2 f_y}{\partial y^2} + \frac{\partial^2 f_y}{\partial z^2}, \frac{\partial^2 f_z}{\partial x^2} + \frac{\partial^2 f_z}{\partial y^2} + \frac{\partial^2 f_z}{\partial z^2} \right)$$

The Laplacian tells us the curvature of a vector function.

The propagation direction of a light wave

FIGURE 35.19 A sinusoidal electromagnetic wave.

1. A sinusoidal wave with frequency f and wavelength λ travels with wave speed v_{em} .



2. \vec{E} and \vec{B} are perpendicular to each other and to the direction of travel. The fields have amplitudes E_0 and B_0 .

3. \vec{E} and \vec{B} are in phase. That is, they have matching crests, troughs, and zeros.

$$\vec{v} = \vec{E} \times \vec{B}$$

Right-hand screw rule

Maxwell's Equations

- Four equations relating electric (**E**) and magnetic fields (**B**) – vector fields

$$\nabla \cdot E = \frac{\rho}{\epsilon_0}$$

- ϵ_0 is **electric permittivity of free space** (or vacuum permittivity - a constant) – *resistance to formation of an electric field in a vacuum*

$$\nabla \cdot B = 0$$

- $\epsilon_0 = 8.854188 \times 10^{-12}$ Farad m⁻¹

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

- μ_0 is **magnetic permeability of free space** (or magnetic constant - a constant) – *resistance to formation of a magnetic field in a vacuum*

$$\nabla \times B = \mu_0 J + \epsilon_0 \mu_0 \frac{\partial E}{\partial t}$$

- $\mu_0 = 1.2566 \times 10^{-6}$ T.m/A (T = Tesla; SI unit of magnetic field)

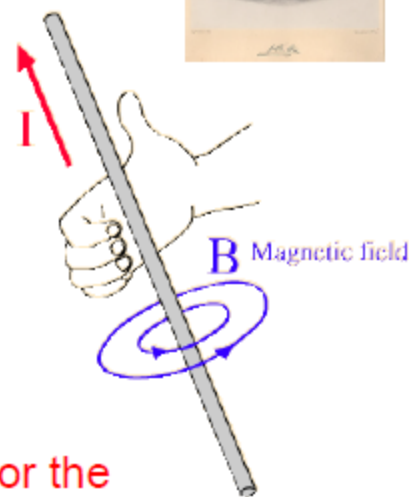
Note: $\nabla \cdot$ is 'divergence' operator and $\nabla \times$ is 'curl' operator

Biot-Savart Law (1820)



- Jean-Baptiste Biot and Felix Savart (French physicist and chemist)
- The magnetic field **B** at a point a distance **R** from an infinitely long wire carrying current **I** has magnitude:

$$B = \frac{\mu_0 I}{2\pi R}$$



- Where μ_0 is the **magnetic permeability of free space or the magnetic constant**
- Constant of proportionality linking magnetic field and distance from a current
- Magnetic field strength decreases with distance from the wire
- $\mu_0 = 1.2566 \times 10^{-6} \text{ T.m/A}$ (T = Tesla; SI unit of magnetic field)

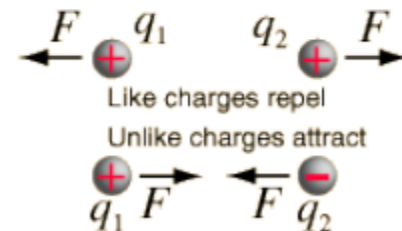
Coulomb's Law (1783)



- Charles Augustin de Coulomb (French physicist)
- The magnitude of the electrostatic force (F) between two point electric charges (q_1, q_2) is given by:

$$F = \frac{q_1 q_2}{4 \pi \epsilon_0 r^2}$$

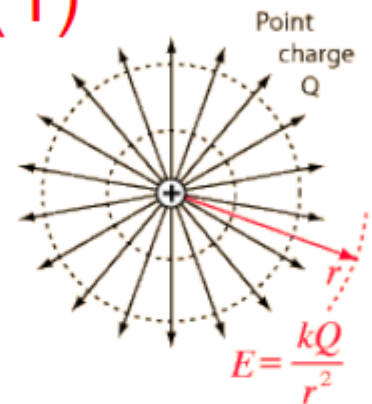
- Where ϵ_0 is the **electric permittivity or electric constant**
- Like charges repel, opposite charges attract
- $\epsilon_0 = 8.854188 \times 10^{-12}$ Farad m^{-1}





Maxwell's Equations (1)

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

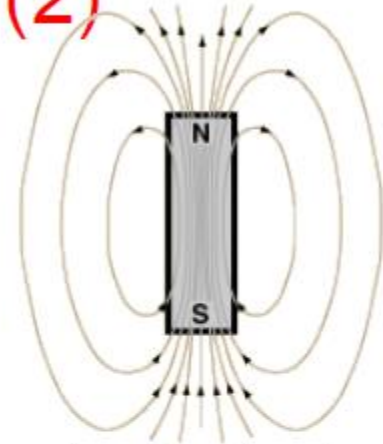


- **Gauss' law for electricity:** the electric flux out of any closed surface is proportional to the total charge enclosed within the surface; i.e. a charge will radiate a measurable field of influence around it.
- \mathbf{E} = electric field, ρ = net charge inside, ϵ_0 = vacuum permittivity (constant)
- Recall: divergence of a vector field is a measure of its tendency to converge on or repel from a point.
- Direction of an electric field is the direction of the force it would exert on a positive charge placed in the field
- If a region of space has more electrons than protons, the total charge is negative, and the direction of the electric field is negative (inwards), and vice versa.



Maxwell's Equations (2)

$$\nabla \cdot \mathbf{B} = 0$$



- **Gauss' law for magnetism:** the net magnetic flux out of any closed surface is zero (i.e. magnetic monopoles do not exist)
- \mathbf{B} = magnetic field; magnetic flux = $\mathbf{B}A$ (A = area perpendicular to field \mathbf{B})
- Recall: divergence of a vector field is a measure of its tendency to converge on or repel from a point.
- Magnetic sources are dipole sources and magnetic field lines are loops – we cannot isolate N or S 'monopoles' (unlike electric sources or point charges – protons, electrons)
- Magnetic monopoles *could* exist, but have never been observed



Maxwell's Equations (3)

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$



- **Faraday's Law of Induction:** the curl of the electric field (\mathbf{E}) is equal to the negative of rate of change of the magnetic flux through the area enclosed by the loop
- \mathbf{E} = electric field; \mathbf{B} = magnetic field
- Recall: curl of a vector field is a vector with magnitude equal to the maximum 'circulation' at each point and oriented perpendicularly to this plane of circulation for each point.
- Magnetic field weakens \rightarrow curl of electric field is positive and vice versa
- Hence changing magnetic fields affect the curl ('circulation') of the electric field – basis of electric generators (moving magnet induces current in a conducting loop)



Maxwell's Equations (4)

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \epsilon_0 \mu_0 \frac{\partial \mathbf{E}}{\partial t}$$

- **Ampère's Law**: the curl of the magnetic field (\mathbf{B}) is proportional to the electric current flowing through the loop

AND to the rate of change of the electric field. ← added by Maxwell

- \mathbf{B} = magnetic field; \mathbf{J} = current density (current per unit area); \mathbf{E} = electric field
- The curl of a magnetic field is basically a measure of its strength
- First term on RHS: in the presence of an electric current (\mathbf{J}), there is always a magnetic field around it; \mathbf{B} is dependent on \mathbf{J} (e.g., *electromagnets*)
- Second term on RHS: a changing electric field generates a magnetic field.
- Therefore, generation of a magnetic field does not require electric current, only a changing electric field. An oscillating electric field produces a variable magnetic field (as $d\mathbf{E}/dt$ changes)

Putting it all together....

- An oscillating electric field produces a variable magnetic field. A changing magnetic field produces an electric field....and so on.
- In 'free space' (vacuum) we can assume current density (J) and charge (ρ) are zero i.e. there are no electric currents or charges
- Equations become:

$$\nabla \cdot E = 0$$

$$\nabla \cdot B = 0$$

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times B = \epsilon_0 \mu_0 \frac{\partial E}{\partial t}$$