

TUTORIAL-3 - Q2

$$(a) \quad y[n] = \{x[n] + x[n-1]\}/2$$

$$(b) \quad y[n] = \{x[n] - x[n-1]\}/2$$

$$(i) \quad h_a[n] = \{\delta[n] + \delta[n-1]\}/2$$

$$h_b[n] = \{\delta[n] - \delta[n-1]\}/2$$

$$(ii) \quad H_a(\omega) = \{e^{-j\omega} + 1\}/2$$

$$H_b(\omega) = \{1 - e^{-j\omega}\}/2$$

$$(iii) \quad x[n] = \cos \omega_0 n$$

$$\begin{aligned} y_a[n] &= \{\cos(\omega_0 n) + \cos(\omega_0(n-1))\}/2 \\ &= \cos[\omega_0(n-1/2)] \cos[\omega_0/2] \\ &= \left(\frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{4} \right) + \left(\frac{e^{j\omega_0(n-1)} + e^{-j\omega_0(n-1)}}{4} \right) \end{aligned}$$

$$\begin{aligned} y_b[n] &= \{\cos(\omega_0 n) - \cos(\omega_0(n-1))\}/2 \\ &= -\sin[\omega_0(n-1/2)] \sin[\omega_0/2] \\ &= \left(\frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{4} \right) - \left(\frac{e^{j\omega_0(n-1)} + e^{-j\omega_0(n-1)}}{4} \right) \end{aligned}$$

$$\therefore y_a[n] = \frac{e^{j\omega_0 n}}{4} [1 + e^{-j\omega_0}] + \frac{e^{-j\omega_0 n}}{4} [1 + e^{j\omega_0}]$$

$$\therefore y_b[n] = \frac{e^{j\omega_0 n}}{4} [1 - e^{-j\omega_0}] + \frac{e^{-j\omega_0 n}}{4} [1 - e^{j\omega_0}]$$

(iv) DTFT of $y_a[n]$: $Y_a(\omega) = \frac{[1+e^{-j\omega_0}]}{2} \times \frac{\delta[\omega-\omega_0]}{2}$
 $+ \frac{[1+e^{j\omega_0}]}{2} \times \frac{\delta[\omega+\omega_0]}{2}$

DTFT of $y_b[n]$: $Y_b(\omega) = \frac{[1-e^{-j\omega_0}]}{2} \times \frac{\delta[\omega-\omega_0]}{2}$
 $+ \frac{[1-e^{j\omega_0}]}{2} \times \frac{\delta[\omega+\omega_0]}{2}$

DTFT of $x[n]$: $X(\omega) = \mathcal{F}^{-1}[\cos(\omega_0 n)]$
 $= \mathcal{F}^{-1}\left[\frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{2}\right]$
 $= \frac{\delta[\omega-\omega_0]}{2} + \frac{\delta[\omega+\omega_0]}{2}$

$$X(\omega) \times H_a(\omega) = \left\{ \frac{e^{-j\omega} + 1}{2} \right\} \times \left[\frac{\delta(\omega-\omega_0)}{2} + \frac{\delta(\omega+\omega_0)}{2} \right]$$

$$= \left(\frac{1+e^{-j\omega_0}}{2} \right) \times \frac{\delta(\omega-\omega_0)}{2} + \left(\frac{1+e^{j\omega_0}}{2} \right) \times \frac{\delta(\omega+\omega_0)}{2}$$

We can see $Y_a(\omega) = H_a(\omega) \times X(\omega)$

This is true for $Y_b(\omega)$ too.

\therefore Since these are LSI systems, we see that frequency response of the system is equal to ratio of ~~and~~ [DTFT of output sequence] by [DTFT of input sequence].

$$(v) \quad H_a(\omega) = (1 + e^{-j\omega})/2$$

$$h_a[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_a(\omega) e^{j\omega n} d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{1}{2} (1 + e^{-j\omega}) e^{j\omega n} d\omega$$

$$= \frac{1}{4\pi} \left(\left[\frac{e^{j\omega n}}{jn} \right]_{-\pi}^{\pi} + \left[\frac{e^{j\omega(n-1)}}{j(n-1)} \right]_{-\pi}^{\pi} \right)$$

$$= \frac{1}{4\pi} \left[\frac{1}{jn} (2j \sin(n\pi)) + \frac{1}{j(n-1)} (2j \sin((n-1)\pi)) \right]$$

we know that $\frac{2\pi \sin(n\pi)}{n\pi} = \begin{cases} 2\pi & \text{when } n=0 \\ 0 & \text{else} \end{cases}$

similarly, $\frac{2\pi \sin((n-1)\pi)}{(n-1)\pi} = \begin{cases} 2\pi & \text{when } n=1 \\ 0 & \text{else} \end{cases}$

$$\Rightarrow h_a[n] = \frac{1}{4\pi} [2\pi \delta[n] + 2\pi \delta[n-1]]$$

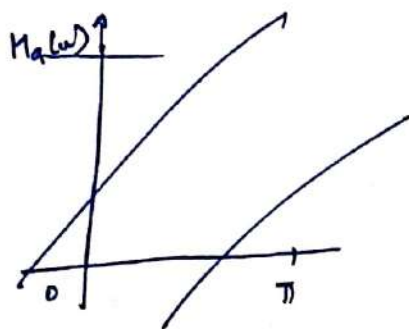
$$= \frac{1}{2} [\delta[n] + \delta[n-1]]$$

similarly for $H_b(\omega)$ and $h_b[n]$.

hence verified.

$$\because \lim_{x \rightarrow 0} \frac{\sin x}{x} = 1$$

$$(v) H_a(\omega) = \frac{(1 + e^{-j\omega})}{2} \quad H_b(\omega) = \frac{(1 - e^{-j\omega})}{2}$$

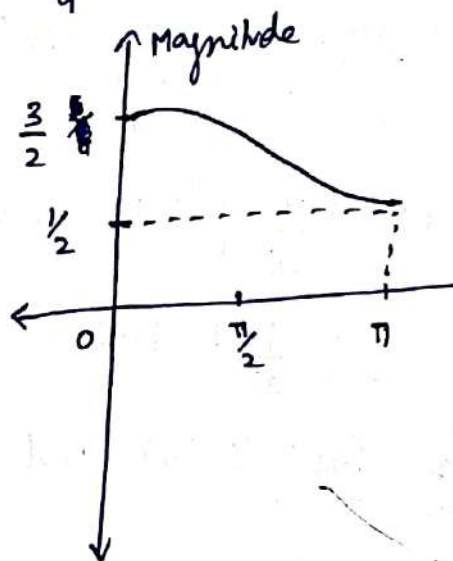
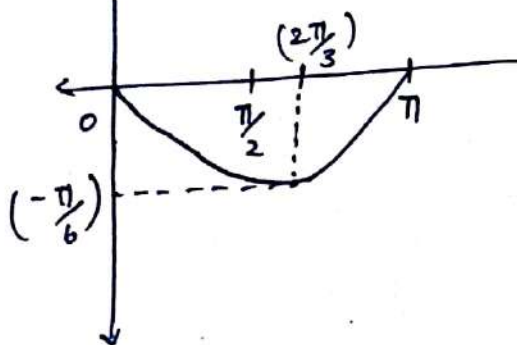


$$(vi) H_a(\omega) = \frac{(1 + e^{-j\omega})}{2} = 1 + \frac{(\cos \omega - j \sin \omega)}{2}$$

$$\text{Phase} = -\tan^{-1} \left(\frac{\sin(\omega)}{2 + \cos(\omega)} \right)$$

$$\text{Magnitude} = \sqrt{1 + \frac{\cos^2 \omega}{4} + \cos \omega + \frac{\sin^2 \omega}{4}} = \sqrt{\frac{5}{4} + \cos \omega}$$

Phase



$$H_b(\omega) = \frac{1 - e^{-j\omega}}{2} = 1 - \frac{\cos \omega}{2} + j \frac{\sin \omega}{2}$$

$$\text{Phase} = -\tan^{-1} \left(\frac{\sin \omega}{2 - \cos \omega} \right)$$

$$\text{Magnitude} = \sqrt{1 + \frac{\cos^2 \omega}{4} - \cos \omega + \frac{\sin^2 \omega}{4}} = \sqrt{\frac{5}{4} - \cos \omega}$$

