

Floyd Warshall Algorithm(All pair shortest path)

The Floyd-Warshall algorithm is an example of dynamic programming. It breaks the problem down into smaller subproblems, then combines the answers to those subproblems to solve the big, initial problem.

Given a weighted graph $g = (V, E)$, where $V = \{1, 2, \dots, n\}$. The Floyd Warshall algorithm gives the shortest path between any pair of nodes in the graph. Assume that weights are represented in a matrix $C[V][V]$, where $C[i][j]$ indicates the weight (or cost) between the nodes i and j . Also, $C[i][j] = \infty$, if there is no direct path from node i to node j .

Floyd's algorithm for all pair shortest path problems uses matrix $A[1\dots n][1\dots n]$ to compute the lengths of the shortest path. Initially

$$\begin{aligned} A[i, j] &= C[i][j] \text{ if } i \neq j \\ &= 0 \text{ if } i = j \end{aligned}$$

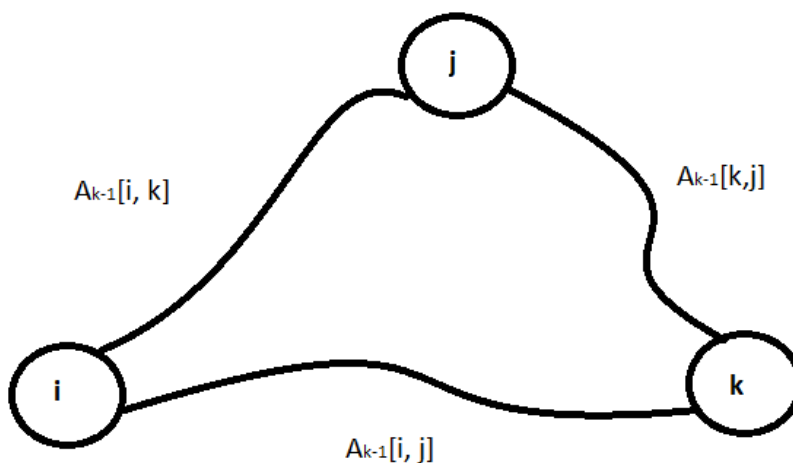
From the definition, $C[i, j] = \infty$, if there is no path from i to j . The algorithm makes n passes over A . Let A_0, A_1, \dots, A_n be the values of A on the n passes, with A_0 being the initial value.

Just after the $k-1$ th iteration, $A_{k-1}[i, j]$ = smallest length of any path from vertex i to vertex j that does not pass through the vertices $\{k+1, k+2, \dots, n\}$. That means, it passes through the vertices possibly through $\{1, 2, 3, \dots, k-1\}$.

In each iteration, the value $A[i][j]$ is updated with the minimum of $A_{k-1}[i, j]$ and $A_{k-1}[i, k] + A_{k-1}[k, j]$.

$$A[i][j] = \text{minimum of } (A_{k-1}[i, j], A_{k-1}[i, k] + A_{k-1}[k, j])$$

The k th pass explores whether the vertex k lies on an optimal path from i to j , for all i, j . The same is shown in diagram below



```

function floyd(C, A, n){
    // initialize 3 variables i, j and k
    i = 0

    while(i <= n-1)
        j = 0
        while(j <= n-1)
            A[i][j] = C[i][j]
            j++
        i++

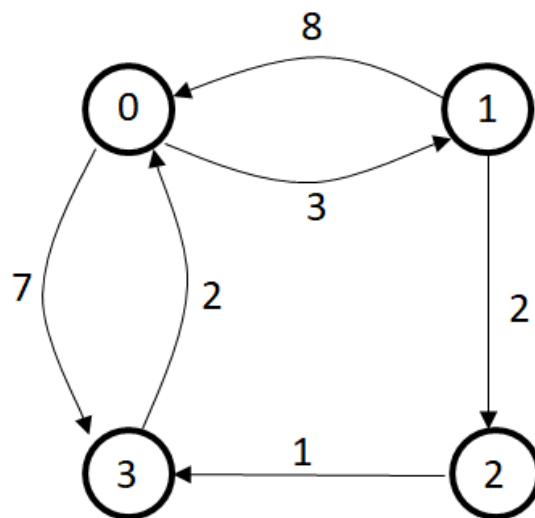
    i = 0
    while(i <= n-1)
        A[i][i] = 0
        i++

    k = 0
    while(k <= n-1)
        i = 0
        while(i <= n-1)
            j=0
            while(j <= n-1)
                if(A[i][k]+A[k][j] < A[i][j])
                    A[i][j] = A[i][k]+A[k][j]
            }
        }
}

```

Time Complexity = $O(n^3)$

Example: Consider the directed graph below



The adjacency matrix A for the above graph will be

	0	1	2	3
0	0	3	∞	7
1	8	0	2	∞
2	∞	∞	0	1
3	2	∞	∞	0

Now initially the matrix C will be the same as matrix A.

How is the update of vertices done?

Consider $k=0$, $i=1$ and $j=3$

$A[i][k] = 8$, $A[k][j] = 7$ and $A[i][j] = \infty$,

Therefore $A[i][k] + A[k][j] < A[i][j]$, so update $A[i][j] = 15$ which $A[i][k] + A[k][j]$

Now for different values of k , the C matrix will look like as shown below:

	0	1	2	3
0	0	3	∞	7
1	8	0	2	15
2	∞	∞	0	1
3	2	5	∞	0

k = 0

	0	1	2	3
0	0	3	5	7
1	8	0	2	15
2	∞	∞	0	1
3	2	5	7	0

k = 1

	0	1	2	3
0	0	3	5	6
1	8	0	2	3
2	∞	∞	0	1
3	2	5	7	0

k = 2

	0	1	2	3
0	0	3	5	6
1	5	0	2	3
2	3	6	0	1
3	2	5	7	0

k = 3

Note: Both Floyd warshall and Bellman Ford algorithm are an example of dynamic programming where as Dijkstra's Algorithm is based on greedy technique