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Subject : Embedded System
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Term End Examination.

(1)

1] (6)

Registration number = 071

Delay = 071

Code

```
#include <reg51.h>
sbit mybit = P2^4;

void MSDelay (unsigned int itime)
{
    unsigned int i, j;
    for (int i = 0; i < itime; i++)
    {
        for (int j = 0; j < 1000; j++);
    }
}

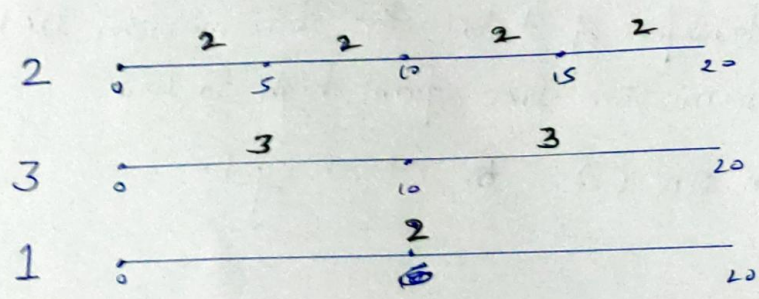
void main ()
{
    while (1)
    {
        mybit = ~mybit;
        MSDelay (071);
    }
}
```


Priority.

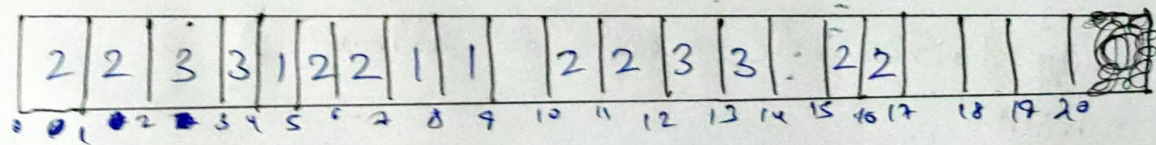
It is highest for the process which has least running time period. Thus 2 has highest priority then 3 and lastly 1.

$$\therefore 2 > 3 > 1$$

Representation and Flow



Thus, process 2 executes 2 times for every 5 time units, process 3 executes 3 times for every 10 time units, and process 1 executes 2 times for every 20 time units.



3)(b)

(4)

Rate Monotonic Scheduling.

Release time for all tasks = 0s

Process.	Execution Time	Time Period.
1	2	20
2	3	5
3	2	10

Firstly,

$$n(2^{1/n} - 1) = 3(2^{1/3} - 1) = 0.7977$$

$$u = 2/20 + 3/5 + 2/10 = 0.9$$

$$\therefore u < 1$$

\therefore the combined utilization of 3 process is less than the threshold of these processes that means the above set of processes once scheduled and thus satisfy the Equation of the algorithm.

Scheduling time.

We calculate the LCM of time period of all processes.

$$\text{LCM}(20, 5, 10), \text{ i.e., } 20$$

Thus we can schedule 20 time units.

- When the parity bit matches the data, the UART knows that the transmission was free of errors.

Therefore,

Total no. of 1's = 3

and 3 is an ODD number

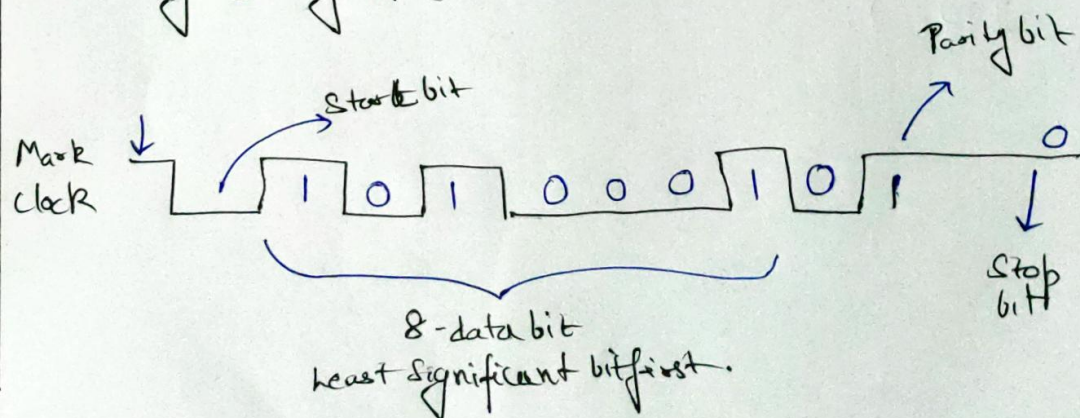
\therefore parity bit = 1

Stop bit

To signal the end of the data packet, the sending UART drives the data transmission line from the low voltage to a high voltage of (1) to (2) bit of duration.

It is the last bit of the packet and it indicates the end of the packet.

Timing Diagram



5]

⑥

```
#include <reg51.h>
```

```
sbit READ_ADC = P0^0;
```

```
sbit WRITE_ADC = P0^1;
```

```
sbit INTR_ADC = P0^2;
```

```
char temp[7] = "000C";
```

```
unsigned char ADC_value;
```

```
int C;
```

```
for
```

```
void delay_ms (unsigned int time)
```

```
{
```

```
int i, j;
```

```
for (i = 0; i < time; i++)
```

```
for (j = 0; j < time; j++)
```

```
}
```

```
void main ()
```

```
{
```

```
P0 = 0x00;
```

```
P1 = 0x00;
```

```
P2 = 0x00;
```

```
P3 = 0x00;
```

```
IE = 0x41;
```

```
IT0 = 1;
```

```
}
```


Void ~~ISR~~

Void ISR-ex (Void)
{

PI = 0xFF;

INTR-ADC = 1;

READ-ADC = 1;

WRITE-ADC = 1;

while (1)

{

WRITE-ADC = 0

delay-ms(1);

WRITE-ADC = 1;

while (INTR-ADC == 1);

READ-ADC = 0;

ADC-value = P3;

C = ADC-value * 1.95;

if (C > 99)

temp[0] = 1 + 48;

else {

temp[0] = 1;

temp[1] = (C/10) * 10 + 48;

temp[2] = C * 10 + 48;

temp[5] = 223;

}

delay-ms(10)

READ-ADC = 3;

delay-ms = 1000;

}

}

(8)

Here, I am using external entering in which
I am taking input of temperature from
sensor and converting it to $^{\circ}\text{C}$ using
ADC.

PTC

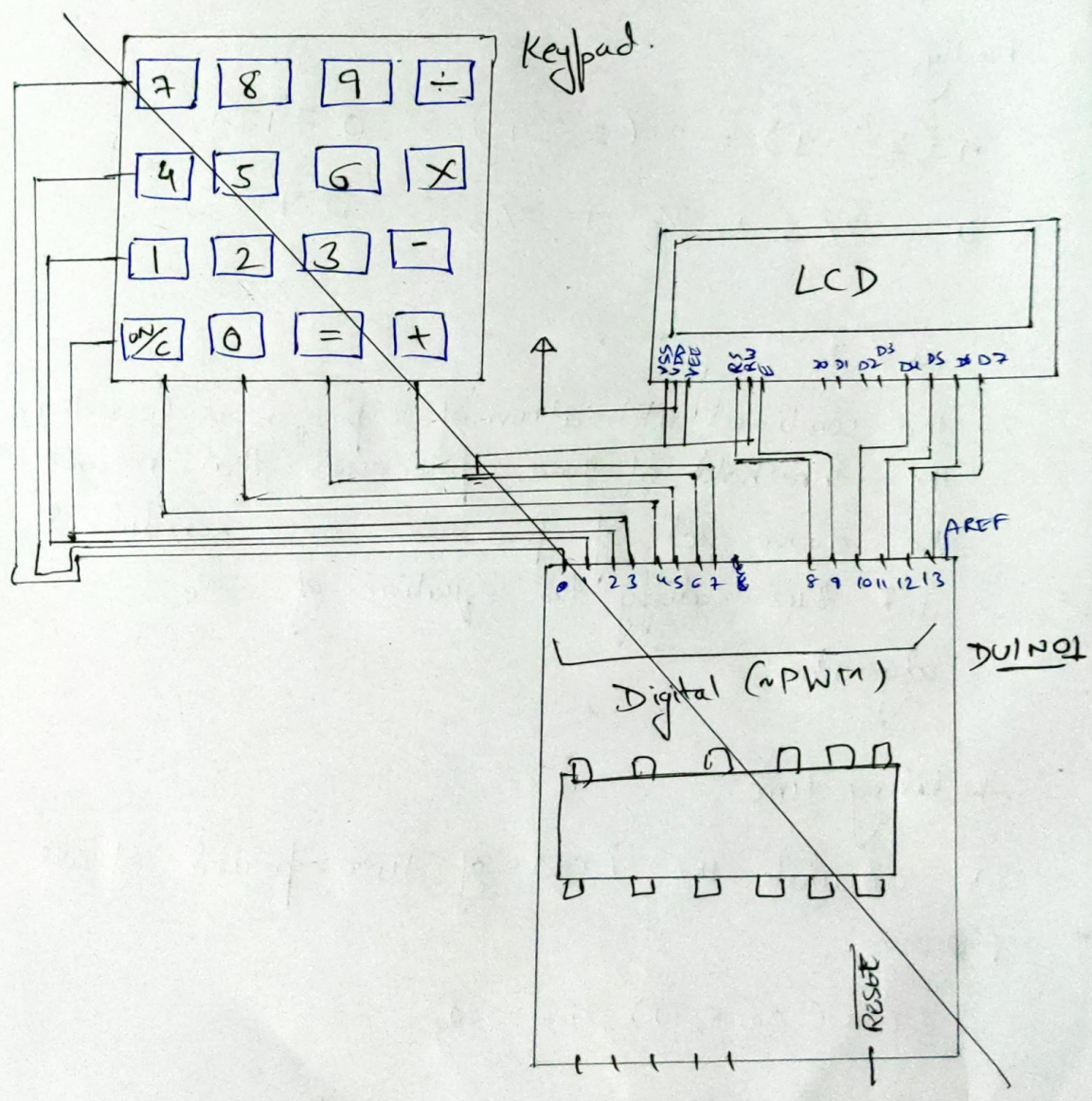
4] SMART VENTING MACHINE

9

Materials

- Arduino
- 16x2 LCD Display
- 4x4 Keypad.
- Breadboard and connecting wires.

Connection Diagram



8051 Microcontroller

