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```
function [Nei agent, A] = findneighbors(nodes, n, r)
%This function is to find alpha and beta neighbors
%Created by Anthony Bugatto
% Inputs: positions of nodes (nodes),
         %dinensions of the simulation(n)
         %active range for alpha agents(r)
% Outputs: indices of alpha neighbors (Nei_agent)
          %Adjacency Matrix (A)
%*****Find neighbors of alpha agent******
num_nodes = size(nodes,1);
dif = cell(num_nodes,1); % save the difference between each alpha agent and all
   other nodes
                        % each element of cell is a matrix(size:num_nodes x n)
distance alpha = zeros(num nodes, num nodes); % save the distance (norm) between
    each agent and all other nodes
                              % each column for one node
Nei_agent = cell(num_nodes,1); %Save the indices of neighbors of each agent
                              %each element of cell is a matrix (maximum size
                                 num nodes x 1)
for i = 1:num nodes
   dif{i} = repmat(nodes(i,:),num_nodes,1) - nodes;
   tmp = dif{i}; %recall cell i th of dif
   for j = 1:num nodes
       d_{tmp(j,:)} = norm(tmp(j,:)); %compute distance between each alpha agent
           and all other nodes
    end
   distance_alpha(i,:)= d_tmp;
end
for k = 1:num nodes
    Nei_agent{k} = find(distance_alpha(:,k) < r & distance_alpha(:,k) \sim= 0); %
       find the neighbors of agent i
end
A = zeros(num nodes, num nodes);
for i = 1:num nodes
    for j = 1:num nodes
       if i ~= i
           dist_2nodes = norm(nodes(j,:) - nodes(i,:));
           if dist 2nodes < r && dist 2nodes ~= 0
               A(i,j) = 1;
           end
       end
   end
end
```

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