

0.1 Sesquilinear forms

0.1.1 Bilinear form recap

A bilinear form takes two vectors and produces a scalar from the underlying field.

The function is linear in addition in both arguments.

$$\phi(au + x, bv + y) = \phi(au, bv) + \phi(au, y) + \phi(x, bv) + \phi(x, y)$$

The function is also linear in multiplication in both arguments.

$$\phi(au + x, bv + y) = a\phi(u, v) + a\phi(u, y) + b\phi(x, v) + \phi(x, y)$$

They can be represented as:

$$\phi(u, v) = v^T M u$$

0.1.2 Sesquilinear forms

Like bilinear forms, sesquilinear are linear in addition:

$$\phi(au + x, bv + y) = \phi(au, bv) + \phi(au, y) + \phi(x, bv) + \phi(x, y)$$

Sesquilinear forms however are only multiplicatively linear in the second argument.

$$\phi(au + x, bv + y) = b\phi(au, v) + \phi(au, y) + b\phi(x, v) + \phi(x, y)$$

In the first argument they are “twisted”

$$\phi(au + x, bv + y) = \bar{a}b\phi(u, v) + \bar{a}\phi(u, y) + b\phi(x, v) + \phi(x, y)$$

0.1.3 The real field

For the real field, $\bar{b} = b$ and so the sesquilinear form is the same as the bilinear form.

0.1.4 Representing sesquilinear forms

We can show the sesquilinear form as $v^* M u$

0.1.5 Stuff

$$f(M) = f([v_1, v_2])$$

We introduce e_i , the element vector. This is 0 for all entries except for i where it is 1. Any vector can be shown as a sum of these vectors multiplied by a scalar.

$$f(M) = f([\sum_{i=1}^m a_{1i}e_i, \sum_{i=1}^m a_{2i}e_i])$$

$$f(M) = \sum_{k=1}^m f([a_{1k}e_k, \sum_{i=1}^m a_{2i}e_i])$$

$$f(M) = \sum_{k=1}^m \sum_{i=1}^m f([a_{1k}e_k, a_{2i}e_i])$$

Because this is linear in scalars:

$$f(M) = \sum_{k=1}^m \sum_{i=1}^m a_{1k}^* a_{2i} f([e_k, e_i])$$

$$f(M) = \sum_{k=1}^m \sum_{i=1}^m a_{1k}^* a_{2i} e_k^* M e_i$$

0.1.6 Orthonormal basis and $M = I$

$$f(M) = \sum_{k=1}^m \sum_{i=1}^m a_{1k}^* a_{2i} e_k^* M e_i$$

$$f(M) = \sum_{k=1}^m \sum_{i=1}^m a_{1k}^* a_{2i} e_k^* e_i$$

$$f(M) = \sum_{k=1}^m \sum_{i=1}^m a_{1k}^* a_{2i} \delta_i^k$$

$$f(M) = \sum_{i=1}^m a_{1i}^* a_{2i}$$