Matlab / Octave Notes

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Basic Operations

Variables

```
a = 3;
b = 'hi';
```

Output

Arthimetic Operations

Logical Opeartions

```
1 == 2  % false

1 ~= 2  % not equal to

1 && 0  % AND

1 || 0  % OR

xor(1, 0)
```

Vectors and Matrices

Vectors

In-built Functions

Mathematical

```
v = [0.26, 2.22, 4]
matrix = [1, 23; 30, 4; 5, 6]
log(3)
                % Logrithmic
exp([1, 2])
               % Exponential
abs([-1, 2, -3]) % Absolute
                 % similar to -1 * v
-V
[val, ind] = max(v) % Returns an array of which has max value and it's index
find([1, 0, 3, 2])
                   % Returns the indexes of all the non-zero elements
            % returns a 3x3 magic square matrix
magic(3)
sum(matrix) % Sum of a matrix
floor(v)
ceil(v)
```

Matrices

Iterators

Plotting

Control Statements

If else

```
v = zeros(10, 1);

i = 0;
while true,
    v(i) = i*i;
    if i == 6,
        break;
    else
        disp("Value is not 6")
```

```
end;
end;
```

For

```
v = zeros(10, 1);
for i=1:10,
    v(i) = i*i;
end;
```

While

```
v = zeros(10, 1);

i = 0;
while i < 5,
    v(i) = 10*i;
    i = i + 1;
end;</pre>
```

Functions

```
function y = squareNumber(x),
    y = x ^ 2;
end;
```

Sketching Multiple Graphs

Parameters(@(var),function,range,color)

```
fplot(@(t) exp(0.6667*t)-1.5,[-2 2],'b')
hold on
fplot(@(t) cos(t*t),[-2 2],'g')
hold off
grid on
```

Gauss_Seidel Method A

```
function xnew=gauss_seidel(A,b,xold)
n=size(A)*(1);
At=A;
xnew=xold;
for k=1:n
   At(k,k)=0;
end
for k=1:n
   xnew(k)=(b(k)-At(k,:)*xnew)/A(k,k);
end
end
```

Gauss_Seidel Method B

```
function GuassSeidel(A,B, convergeVal, maxIteration)
    N = length(B);
    X = zeros(N,1);
    err = ones(N,1);
    for i = 1:N
        j = 1:N;
        j(i) = [];
        C = abs(A(i,j));
        Check(i,1) = abs(A(i,i)) - sum(B);
    end
    iter = 0;
    while max(err) > convergeVal
        iter = iter + 1;
        Z = X;
        for i = 1:N
            j = 1:N;
            j(i) = [];
            Xtemp = X;
            Xtemp(i) = [];
            X(i,1) = (B(i,1) - sum(A(i,j) * Xtemp)) / A(i,i);
        end
        Xs = X;
        err = sqrt((X - Z).^2);
        if iter >= maxIteration
            break;
        end
    end
    disp("Solutions using Guass Seidel Model : ");
    disp(Xs)
    disp("Number of iterations :"),disp(iter);
end
```

Jacobi Method

```
% Method to solve a linear system via jacobi iteration
% A: matrix in Ax = b
% b: column vector in Ax = b
% N: number of iterations
% returns: column vector solution after N iterations

function sol = jacobi_method(A, b, N)
    diagonal = diag(diag(A)); % strip out the diagonal
    diag_deleted = A - diagonal; % delete the diagonal
    sol = zeros(size(b, 1), 1); % initial guess of zero

for i = 1:N
    % computing the matrix inverse
    sol = diagonal \ (b - diag_deleted * sol);
end

end
```

Finding coefficients of any equation with given data.

Example below of where x - stock price y-day of month

writing in the form of p0-ae^(0.01x)

```
% x and y values
x = [700 678 984 547 442 418 300]'
y = [6 12 20 5 6 3 2]'

% finding coefficients equation in the form p0-ae^(0.01x)

% first generate expression for your equation
expr = fittype({'1','-exp(0.01*(x))'},'coefficients',{'p0','a'});

% now fit the equation this will spit out your coefficients values
coeff = fit(x,y,expr);

% this sets the range of the graph
xx = linspace(0,2000);

%plotting graph
plot(x,y,'o',xx,coeff(xx),'r-');
legend('Data Points','Exponential curve fit','Location','best');
```