

ANSYS USER Material Subroutine USERMAT

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1. INTRODUCTION

The user material routine, USERMAT, is an ANSYS user-programmable feature for use with the 18x family elements, which include LINK180, SHELL181, PLANE182, PLANE183, SOLID185, SOLID186, SOLID187, BEAM188 and BEAM189. Its function is to allow user to write their own material constitutive equations within a newly developed general material framework for the 18x family elements. This subroutine is called at all material integration points of these elements during the solution phase. The input parameters for the USERMAT subroutine is defined by command **TB,USER**.

This report provides guidelines on how to write a user material routine using USERMAT.

2. USER MATERIAL ROUTINE (USERMAT)

The user material routine, USERMAT, is used to define material stress-strain relation, the mechanical constitutive behavior of materials. It can be used in any ANSYS analysis procedure that requires mechanical behavior. If the state variables are used in the USERMAT routine, the number of state variables must be defined by the command **TB, STATE**. For every Newton-Raphson iteration, USERMAT is called at every material integration point. ANSYS passes in stresses, strains and state variables as the values at the beginning of the time increment, and the current strain increment, USERMAT then updates the stresses and state variables to the values at the end of the time increment. USERMAT must also provide the material Jacobian matrix, $\partial\sigma_{ij}/\partial\epsilon_{ij}$.

Stress, strain and material Jacobian tensors are stored in vector or matrix forms. The order of components for the stress, the strain and other tensors is

3D stress state:

11, 22, 33, 12, 23, 13,

2D plane stress/strain and axisymmetric stress states:

11, 22, 33, 12,

Stress state for BEAM188/189:

11, 13, 12.

Stress state for LINK180:

11.

The order of components for material Jacobian matrix is

3D stress state:

1111	1122	1133	1112	1123	1113
2211	2222	2233	2212	2223	2213
3311	3322	3333	3312	3323	3313
1211	1222	1233	1212	1223	1213
2311	2322	2333	2312	2323	2313
1311	1322	1333	1312	1323	1313

2D plane strain and axisymmetric stress states:

1111	1122	1133	1112
2211	2222	2233	2212
3311	3322	3333	3312
1211	1222	1233	1212

2D plane stress states:

1111	1122	1112
2211	2222	2212
1211	1222	1212

BEAM188/189:

1111	1113	1112
1311	1313	1312
1211	1213	1212

LINK180:

1111.

User subroutine interface USERMAT:

```
subroutine usermat(  
&          matId, elemId, kDomIntPt, kLayer, kSectPt,  
&          ldstep, isubst, keycut,  
&          nDirect, nShear, ncomp, nStatev, nProp,  
&          Time, dTime, Temp, dTemp,  
&          stress, statev, dsdePl, sedEl, sedPl, epseq,  
&          Strain, dStrain, epsPl, prop, coords,  
&          tsstif, epsZZ,  
&          var1, var2, var3, var4, var5,  
&          var6, var7, var8)  
  
  INTEGER  
&          matId, elemId,  
&          kDomIntPt, kLayer, kSectPt,  
&          ldstep, isubst, keycut,  
&          nDirect, nShear, ncomp, nStatev, nProp  
  DOUBLE PRECISION  
&          Time,      dTime,      Temp,      dTemp,  
&          sedEl,     sedPl,     epseq,     epsZZ  
  DOUBLE PRECISION  
&          stress (ncomp ), statev (nStatev),  
&          dsdePl (ncomp, ncomp),  
&          Strain (ncomp ), dStrain (ncomp ),  
&          epsPl  (ncomp ), prop   (nProp ),  
&          coords (3),      rotateM (3,3),  
&          defGrad_t(3,3),  defGrad(3,3),  
&          tsstif  (2)
```

3. TABLE COMMANDS

TB, USER command

To use the user material option, the **TB, USER** command must be first issued so that the user material can be defined. The table command for USER material option is:

TB,USER, matId, NTEMPS, NPTS

matId material reference number,

NTEMPS Number of temperature points (temperature is defined by **TBTEMP**),

NPTS Number of material constants at a given temperature point (material constants is defined by **TBDATA**).

The temperatures and material constants are defined through commands **TBTEMP** and **TBDATA** as standard ANSYS procedures. The material properties at an intermediate temperature point are interpolated and passed to the USERMAT subroutine. An example of defining a user material option is as follows:

```
tb,user,1,2,4                ! define mat. 1 as user mat. with 2
                             ! temperatures and 4 data points
                             ! at each temp. point.
tbtemp,1.0                   ! first temp.
tbdata,1,19e5, 0.3, 1e3,100, ! 4 mat constants for 1 temp.
tbtemp,2.0                   ! second temp.
tbdata,1,21e5, 0.3, 2e3,100, ! 4 mat constants for 2 temp.
```

TB, STATE command

If state variables are used in the USERMAT subroutine, the number of the state variables need to be firstly defined by command **TB, STATE**:

TB,STATE, matId, , NPTS

matId material reference number,

NPTS Number of the state variables to be used in USERMAT.

This command is used only for defining the number of the state variables and must be always associated with a user material option. No temperatures or data are associated with this command. State variables are initialized to zero at beginning of an analysis. An example of defining the number of the state variables is as follows:

```
tb,state,1,,4,              ! define mat. 1 has 4 state variables
```

4. VARIABLE DESCRIPTION

Input arguments

The following variables are passed in as information for use by the subroutine, they must not be changed in the user material subroutine USERMAT.

matId	Integer variable contains material index number.
elemId	Integer variable contains element number.
kDomIntPt	Integer variable contains material integration point number.
kLayer	Integer variable contains integer variable, Layer number.
kSectPt	Integer variable contains section point number.
ldstep	Integer variable contains load step number.
isubst	Integer variable contains substep number
nDirect	Number of direct components of the stress or strain vector at material point.
nShear	Number of shear components of the stress or strain vector at material point, this is engineering components.
ncomp	Total number of the stress or strain components at material point (nDirect + nShear).
nstatev	Number of state variables. This is defined by NPTS through command TB, STATE .
nProp	Number of material constants, defined by NPTS in command TB,USER .
Temp	Double precision variable contains the current temperature.
dTemp	Double precision variable contains the current temperature increment.
Time	Double precision variable contains the total time at the beginning of the time increment.
dTime	Double precision variable contains the current time increment.
Strain	Double precision array contains the total strains at the beginning of the time increment. Array size is ncomp. If there are thermal strains, the strain passed

into USERMAT are the mechanical strains only. The thermal strains (defined by command **MP, ALPHA** and temperature load) have been subtracted from the total strains. For large deformation problem (NLGEOM, ON), the strain components have been updated to account for rigid body rotation before they are passed to USERMAT and are approximately the logarithmic strains.

dStrain	Double precision array contains current strain increments. Array size is ncomp. As "Strain" array, it contains the mechanical strain increments only. The thermal strain increments (if there is any) have been subtracted from total strains increments.
prop	Double precision array contains the material constants defined by TB,USER and TBDATA . Array size is nProp. Array prop contains the material constants at current temperature point.
coords	Double precision array contains the current coordinates of the material integration points. Array size is 3.
rotateM	Double precision matrix contains the incremental rotation matrix. Matrix size is 3x3. This matrix is the increment of rigid body rotation to account for large deformation. It is a unit matrix for small deformation analysis.
defGrad_t	Double precision matrix contains deformation gradient at the beginning of the time increment. The matrix size is 3x3. The matrix components DefGrad_t(i,j) are equivalent to deformation gradient Fij at the beginning of the time increment.
defGrad	Double precision matrix contains current deformation gradient. The matrix size is 3x3. The matrix components DefGrad(i,j) are equivalent to deformation gradient Fij at the current time.

Input output arguments

stress	Double precision array contains the stresses. Its size is defined by ncomp. The stress measure is the "true" stress. It is passed as the values of stresses at beginning of time increment and must be updated to the values of stress at the end of the time increment. For finite deformation problems, the stresses have been rotated to account for rigid body motion before they are passed in
--------	---

using the Hughes-Winget rotation matrix, and thus only co-rotational part of stress integration needs to be done in the USERMAT.

statev	Double precision array contains the state variables. Its size is defined by command TB, STATE . It is passed as the values of state variables at the beginning of the time increment and must be updated to the values of the state variables at the end of the time increment. For finite deformation problems, any vector or tensor type of state variables must be rotated to account for rigid body motion before they are used any constitutive calculations. Rotation matrix, rotatM, is passed in for the purpose.
epspl	Double precision array contains the plastic strains. The strain measure is the "true" strain. Its size is defined by ncomp. It is passed as the values of the plastic strains at the beginning of the time increment and must be updated to the values of the plastic strains at the end of the time increment. For finite deformation problems, the plastic strains have been rotated to account for rigid body motion before they are passed in using the Hughes-Winget rotation matrix (Hughes, 1980).
sedEl	Elastic work. It is used for output purpose only and has no effect on the solution.
sedPl	Plastic work. It is used for output purpose only and has no effect on the solution.
sedCr	Creep work. It is used for output purpose only and has no effect on the solution.

Output arguments

Following list of variables must be updated in the user material subroutine.

keycut	Integer variable as key for loading bisection/cut control: 0 - no bisect/cut, 1 - bisect/cut, By default, keycut is 0. Set keycut to 1 when USERMAT experiences convergency difficulty in the solution of the integration of the constitutive equations. The bisect/cut factor is determined by ANSYS solution control.
epsZZ	strain component at out of plane direction for plane stress state

Required when the thickness change is accounted in plane stress or shell elements

tsstif(2) Transver shear stiffness

Tsstif(1) - GXZ

Tsstif(2) - GYZ

dsdePl(ncomp,ncomp)

Double precision array contains the material Jacobian matrix, $\partial\sigma_{ij}/\partial\epsilon_{ij}$. Here $\partial\sigma_{ij}$ and $\partial\epsilon_{ij}$ are the stress and the strain increments respectively. dsdePl(i,j) denotes the change in the i-th stress component at the end of the time increment caused by an change of the j-th strain component. By default, ANSYS assumes that the element stiffness matrix is symmetric, therefore user must provide a symmetric material Jacobian matrix even it is unsymmetric. However, if an unsymmetric material Jacobian matrix is desired, an element key option, KEYOPT(5)=1, can be used to define the unsymmetric stiffness matrix for the PLANE and the SOLID elements.

5. SPECIFICATIONS

User material subroutine, USERMAT, is currently applicable for the elements 180, 181, 182, 183, 185, 186, 187, 188 and 189 with all the key options. However, a different material constitutive integration must be provided for the various stress states such as general 3D, plane stress and beam with or without shear stress components. For SHELL181, a plane stress algorithm for the material constitutive integration must be used. To ensure the overall numerical stability, the user should make sure that the integration scheme implemented in this subroutine is stable. ANSYS always uses full Newton-Raphson scheme for global solution to achieve better convergence rate. The material Jacobian matrix, dsdePl(i,j), must be consistent with the material constitutive integration scheme for the better convergence rate of the overall Newton-Raphson scheme.

6. RESTRICTIONS

This user subroutine is only applicable to elements LINK180, SHELL181, PLANE182, PLANE183, SOLID185, SOLID186, SOLID187, BEAM188 and BEAM189.

Currently the state variables used in USERMAT.F are not available in ANSYS 5.6 post-processors, such as POST1 and POST26, for post-processing purposes. However, it is expected that in ANSYS 5.6.1, the post-processors will be able to process the state variables.

USERMAT is not intended for application of modeling incompressible elastic materials, such as hyperelastic materials. A special treatment such as penalty approach may be needed to ensure the incompressibility. In any case, if the material exhibits nearly incompressible behavior, the user must ensure that a finite tangent bulk modulus is used.

7. UTILITY ROUTINES

vzero(**a**,n)

Initialize array **a** to zero. n is dimension of array **a**.

vmult(**a**,**b**,n,c)

Multiply a vector **a** by a constant c and output as vector **b**, $\mathbf{b}=\mathbf{a}*c$, n is dimension of arrays.

vmult1(**a**,n,c)

Multiply a vector **a** by a constant c and output as itself, $\mathbf{a}=\mathbf{a}*c$, n is dimension of array.

maxb(**a**,**b**,**c**,na,nb,nc,n1,n2,n3)

Multiply two double precision matrices and output as **c**, $\mathbf{c}=\mathbf{a}*\mathbf{b}$, na number of rows in matrix **a**, nb number of rows in matrix **b**, and nc number of rows in matrix **c**. n1 number of rows in matrix **c** to fill, n2 number of columns in matrix **c** to fill, n3 number of columns in matrix **a** and number of rows in matrix **b** to work with (the two need to be the same for the inner product).

REFERENCES

1. Hughes, T.J.R. and Winget, J. (1980), "Finite Rotation Effects in Numerical Integration of Rate Constitutive Equations Aarising in Large-Deformation Analysis", International Journal for Numerical Methods in engineering, Vol. 15, No. 9, pp. 1413-1418.

APPENDIX

1. Example of a user material subroutine

An example of a simple bilinear plasticity material model, which is the same as TB,BISO, is used to demonstrate the user material subroutine USERMAT. The subroutine is for 3D, plane strain and axisymmetric stress states. The 3D solid element 185 is used for the analysis. Comparison is made with the prediction by ANSYS **TB,BISO** material option.

The example is a two elements test case under simple tension. Element 1 has material defined by TB,USER option, while element 2 has material defined by the TB, BISO option. A 100% of deformation is applied to both elements. Finite deformation (NLGEOM, ON) is considered. POST26 results of stresses components (Sxx, Syy) and plastic strain components (EPxx, EPyy) are printed for both elements. There are expected to be the same.

2. INPUT data:

```
/batch,list
/title, mvpl-um01, gal, usermat.F test case
/com,
/com, This is a single element test case for testing usermat.F
/com, usermat.F is user materials subroutine for 18x elements.
/com, The material subroutine provided as the example
/com, is the same as the TB, BISO.
/com, A side by side comparison is made for two 185 elements,
/com, among which one is defined by TB,BISO, and another
/com, is defined as TB,USER. They are expected to produce
/com, the same results.
/com, uniaxial tension stress, large deformation.
/com,
/nopr
/nolist
/prep7

ele1=185
ele2=185
mat1=1
mat2=2

et,1,ele1
keyopt,1,2,1
mat,mat1
block,0,1,0,1,0,1
esize,,1
vmesh,1
```

```
mat,mat2
block,0,1,0,1,0,1
esize,,1
vmesh,2

elist

! define material 1 by tb,biso

mp,ex ,mat1,20e5
mp,nuxy,mat1,0.3
tb,biso,mat1,2,4
tbtemp,1.0
tbdata,1,1e3,100,
tbtemp,2.0
tbdata,1,2e3,100,

! define material 2 by tb,user

tb,user,mat2,2,4
tbtemp,1.0                                ! first temp.
tbdata,1,19e5, 0.3, 1e3,100,             ! E, posn, sigy, H
tbtemp,2.0
tbdata,1,21e5, 0.3, 2e3,100,
tb,state,mat2,,1

! boundary condition

nsel,s,loc,x
d,all,ux
nall
nsel,s,loc,y
d,all,uy
nall
nsel,s,loc,z
d,all,uz
nall
fini

/solu
tunif,1.5
nlgeom,on
nsel,s,loc,y,1
nsubst,20,100,1
d,all,uy,1.0
time,1
nall
outres,,-10
outpr,all,-10
solv

fini
/post26
esol,2,1,,s,x,SX_BISO
esol,3,2,,s,x,SX_USER
esol,4,1,,s,y,SY_BISO
esol,5,2,,s,y,SY_USER
```

```
esol,6,1,,eppl,x,EPX_BISO
esol,7,2,,eppl,x,EPX_USER
esol,8,1,,eppl,y,EPY_BISO
esol,9,2,,eppl,y,EPY_USER
```

```
prvar,2,3,4,5
prvar,6,7,8,9
```

```
fini
```

```
/exit,no save
```

3. Output of POST26 results:

***** ANSYS POST26 VARIABLE LISTING *****

TIME	1 S X SX_BISO	2 S X SX_USER	1 S Y SY_BISO	2 S Y SY_USER
0.10000	-0.188102E-02	-0.188102E-02	1509.45	1509.45
0.28750	-0.110968	-0.110968	1525.07	1525.07
0.45625	-0.814415	-0.814415	1536.67	1536.67
0.66204	-1.73160	-1.73160	1548.95	1548.95
0.89592	-1.86240	-1.86240	1561.97	1561.97
1.0000	-0.176924E-01	-0.176924E-01	1569.16	1569.16

***** ANSYS POST26 VARIABLE LISTING *****

TIME	1 EPPLX EPX_BISO	2 EPPLX EPX_USER	1 EPPLY EPY_BISO	2 EPPLY EPY_USER
0.10000	-0.472687E-01	-0.472687E-01	0.945374E-01	0.945374E-01
0.28750	-0.125917	-0.125917	0.251834	0.251834
0.45625	-0.187417	-0.187417	0.374835	0.374835
0.66204	-0.253409	-0.253409	0.506818	0.506818
0.89592	-0.319141	-0.319141	0.638282	0.638282
1.0000	-0.345853	-0.345853	0.691707	0.691707

4. List of user subroutine USERMAT.F:

```
subroutine usermat(
&          matId, elemId,kDomIntPt, kLayer, kSectPt,
&          ldstep,isubst,keycut,
&          nDirect,nShear,ncomp,nStatev,nProp,
&          Time,dTime,Temp,dTemp,
&          stress,statev,dsdePl,sedEl,sedPl,epseq,
&          Strain,dStrain, epsPl, prop, coords,
&          rotateM, defGrad_t, defGrad,
&          tsstif, epsZZ,
```

```

&                var1, var2, var3, var4, var5,
&                var6, var7, var8)
C*****
C    *** primary function ***
C
C        user defined material constitutive model
C
C    Attention:
C        User must define material constitutive law properly
C        according to the stress state such as 3D, plain strain
C        and axisymmetry, plane stress and beam.
C
C        a 3D material constitutive model can be used for
C        plain strain and axisymmetric cases.
C
C        When using shell elements, the plane stress algorithm
C        must be used.
C
C        The following demonstrates a USERMAT subroutine for
C        a plasticity model in 3D stress state. The plasticity
C        model is the same as TB, BISO.
C        See "ANSYS user material subroutine USERMAT" for detailed
C        description of how to write a USERMAT routine.
C
C*****
C
C    input arguments
C    =====
C        matId      (int,sc,i)          material #
C        elemId     (int,sc,i)          element #
C        kDomIntPt  (int,sc,i)          "k"th domain integration point
C        kLayer     (int,sc,i)          "k"th layer
C        kSectPt    (int,sc,i)          "k"th Section point
C        ldstep     (int,sc,i)          load step number
C        isubst     (int,sc,i)          substep number
C        nDirect    (int,sc,in)         # of direct components
C        nShear     (int,sc,in)         # of shear components
C        ncomp      (int,sc,in)         nDirect + nShear
C        nstatev    (int,sc,l)         Number of state variables
C        nProp      (int,sc,l)         Number of material constants
C
C        Temp       (dp,sc,in)          temperature at beginning of
C                                         time increment
C        dTemp      (dp,sc,in)          temperature increment
C        Time       (dp,sc,in)          current time
C        dTime      (dp,sc,in)          current time increment
C
C        Strain     (dp,ar(ncomp),i)    Strain at beginning of time increment
C        dStrain    (dp,ar(ncomp),i)    Strain increment
C        prop       (dp,ar(nprop),i)    Material constants defined by TB,USER
C        coords     (dp,ar(3),i)        current coordinates
C        rotateM    (dp,ar(3,3),i)      Rotation matrix for finite deformation
C
C    update
C        defGrad_t  (dp,ar(3,3),i)      Deformation gradient at time t
C        defGrad    (dp,ar(3,3),i)      Deformation gradient at time t+dt
C
C    input output arguments

```



```

c      =====
c      stress      (dp,ar(nTesn),io)      stress
c      statev      (dp,ar(nstatev),io)    statev
c      sedEl       (dp,sc,io)             elastic work
c      sedPl       (dp,sc,io)             plastic work
c      epseq       (dp,sc,io)             equivalent plastic strain
c      var?        (dp,sc,io)             not used, they are reserved arguments
c                                         for further development
c
c      output arguments
c      =====
c      keycut      (int,sc,io)             loading bisect/cut control
c                                         0 - no bisect/cut
c                                         1 - bisect/cut
c                                         (factor will be determined by ANSYS
solution control)
c      dsdePl      (dp,ar(ncomp,ncomp),io) material jacobian matrix
c
c*****
c
c      ncomp      6      for 3D
c      ncomp      4      for plane strain/stress, axisymmetric
c      ncomp      1      for 1D
c
c      stressss and strains, plastic strain vectors
c      11, 22, 33, 12, 23, 13      for 3D
c      11, 22, 33, 12              for Plane strain/stress, axisymmetry
c      11                          for 1D
c
c      material jacobian matrix
c      3D
c      dsdePl      | 1111  1122  1133  1112  1123  1113 |
c      dsdePl      | 2211  2222  2233  2212  2223  2213 |
c      dsdePl      | 3311  3322  3333  3312  3323  3313 |
c      dsdePl      | 1211  1222  1233  1212  1223  1213 |
c      dsdePl      | 2311  2322  2333  2312  2323  2313 |
c      dsdePl      | 1311  1322  1333  1312  1323  1313 |
c      plane strain/stress, axisymmetric
c      dsdePl      | 1111  1122  1133  1112 |
c      dsdePl      | 2211  2222  2233  2212 |
c      dsdePl      | 3311  3322  3333  3312 |
c      dsdePl      | 1211  1222  1233  1212 |
c      for plane stress entities in third colum/row are zero
c      1d
c      dsdePl      | 1111 |
c
c*****
#include "impcom.inc"
c
      INTEGER
&          matId, elemId,
&          kDomIntPt, kLayer, kSectPt,
&          ldstep, isubst, keycut,
&          nDirect, nShear, ncomp, nStatev, nProp
      DOUBLE PRECISION
&          Time,      dTime,      Temp,      dTemp,
&          sedEl,     sedPl,     epseq,     epsZZ

```

```

DOUBLE PRECISION
&          stress (ncomp ), statev (nStatev),
&          dsdePl (ncomp,ncomp),
&          Strain (ncomp ), dStrain (ncomp ),
&          epsPl (ncomp ), prop (nProp ),
&          coords (3), rotateM (3,3),
&          defGrad_t(3,3), defGrad(3,3),
&          tsstif (2)
C
C***** User defined part *****
C
C --- parameters
C
      INTEGER          NEWTON, mcomp
      DOUBLE PRECISION HALF, THIRD, ONE, TWO, SMALL, ONEHALF,
&          ZERO, TWOTHIRD, ONEDM02, ONEDM05, sqTiny
      PARAMETER (ZERO      = 0.d0,
&          HALF      = 0.5d0,
&          THIRD      = 1.d0/3.d0,
&          ONE      = 1.d0,
&          TWO      = 2.d0,
&          SMALL      = 1.d-08,
&          sqTiny      = 1.d-20,
&          ONEDM02      = 1.d-02,
&          ONEDM05      = 1.d-05,
&          ONEHALF      = 1.5d0,
&          TWOTHIRD      = 2.0d0/3.0d0,
&          NEWTON      = 10,
&          mcomp      = 6
&          )
C
C --- local variables
C
C      sigElp (dp,ar(6 ),1)          trial stress
C      dsdeEl (dp,ar(6,6),1)          elastic moduli
C      sigDev (dp,ar(6 ),1)          deviatoric stress tensor
C      dfds (dp,ar(6 ),1)          derivative of the yield function
C      JM (dp,ar(6,6),1)          2D matrix for a 4 order tensor
C      pEl (dp,sc ,1)          hydrostatic pressure stress
C      qEl (dp,sc ,1)          von-mises stress
C      pleq_t (dp,sc ,1)          equivalent plastic strain at
C                                  beginnig of time increment
C      pleq (dp,sc ,1)          equivalent plastic strain at end
C                                  of time increment
C      dpleq (dp,sc ,1)          incremental equivalent plastic
strain
C      cpleq (dp,sc ,1)          correction of incremental
C                                  equivalent plastic strain
C      sigy_t (dp,sc ,1)          yield stress at beginnig of time
increments
C      sigy (dp,sc ,1)          yield stress at end of time
C                                  increment
C      young (dp,sc ,1)          Young's modulus
C      posn (dp,sc ,1)          Poiss's ratio
C      sigy0 (dp,sc ,1)          initial yield stress
C      dsigdep (dp,sc ,1)          plastic slope
C      twoG (dp,sc ,1)          two time of shear moduli

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c      threeG      (dp,sc      ,1)      three time of shear moduli
c      funcf      (dp,sc      ,1)      nonlinear function to be solved
c                                          for dpleq
c      dFdep      (dp,sc      ,1)      derivative of nonlinear function
c                                          over dpleq
c
c --- temporary variables for solution purpose
c      i, j
c      threeOv2qEl, oneOv3G, qElOv3G, con1, con2, fratio
c
DOUBLE PRECISION sigElp(mcomp), dsdeEl(mcomp,mcomp), G(mcomp),
&                sigDev(mcomp), JM      (mcomp,mcomp), dfds(mcomp)

DOUBLE PRECISION var1, var2, var3, var4, var5,
&                var6, var7, var8, var9, var10

DATA G/1.0D0,1.0D0,1.0D0,0.0D0,0.0D0,0.0D0/
c
INTEGER          i, j
DOUBLE PRECISION pEl,   qEl,   pleq_t,  sigy_t , sigy,
&                cpleq, dpleq,  pleq,
&                young, posn,   sigy0,   dsigdep,
&                elast1,elast2,
&                twoG,  threeG,  oneOv3G, qElOv3G, threeOv2qEl,
&                funcf, dFdep,   fratio,  con1,   con2
c*****
c
      keycut      = 0
      dsigdep     = ZERO
      pleq_t      = statev(1)
      pleq        = pleq_t
c *** get Young's modulus and Poisson's ratio, initial yield stress and others
      young       = prop(1)
      posn        = prop(2)
      sigy0       = prop(3)
c *** calculate the plastic slope
      dsigdep     = young*prop(4)/(young-prop(4))
      twoG        = young / (ONE+posn)
      threeG      = ONEHALF * twoG
c
c *** calculate elastic stiffness matrix (3d)
c
c
      elast1=young*posn/((1.0D0+posn)*(1.0D0-TWO*posn))
      elast2=young/(TWO*(1.0D0+posn))
      dsdeEl(1,1)=(elast1+TWO*elast2)*G(1)*G(1)
      dsdeEl(1,2)=elast1*G(1)*G(2)+elast2*TWO*G(4)*G(4)
      dsdeEl(1,3)=elast1*G(1)*G(3)+elast2*TWO*G(5)*G(5)
      dsdeEl(1,4)=elast1*G(1)*G(4)+elast2*TWO*G(1)*G(4)
      dsdeEl(1,5)=elast1*G(1)*G(5)+elast2*TWO*G(1)*G(5)
      dsdeEl(1,6)=elast1*G(1)*G(6)+elast2*TWO*G(4)*G(5)
      dsdeEl(2,2)=(elast1+TWO*elast2)*G(2)*G(2)
      dsdeEl(2,3)=elast1*G(2)*G(3)+elast2*TWO*G(6)*G(6)
      dsdeEl(2,4)=elast1*G(2)*G(4)+elast2*TWO*G(1)*G(4)
      dsdeEl(2,5)=elast1*G(2)*G(5)+elast2*TWO*G(1)*G(5)
      dsdeEl(2,6)=elast1*G(2)*G(6)+elast2*TWO*G(2)*G(6)
      dsdeEl(3,3)=(elast1+TWO*elast2)*G(3)*G(3)

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```
dsdeEl(3,4)=elast1*G(3)*G(4)+elast2*TWO*G(5)*G(6)
dsdeEl(3,5)=elast1*G(3)*G(5)+elast2*TWO*G(5)*G(3)
dsdeEl(3,6)=elast1*G(3)*G(6)+elast2*TWO*G(6)*G(3)
dsdeEl(4,4)=elast1*G(4)*G(4)+elast2*(G(1)*G(2)+G(4)*G(4))
dsdeEl(4,5)=elast1*G(4)*G(5)+elast2*(G(1)*G(6)+G(5)*G(4))
dsdeEl(4,6)=elast1*G(4)*G(6)+elast2*(G(4)*G(6)+G(5)*G(2))
dsdeEl(5,5)=elast1*G(5)*G(5)+elast2*(G(1)*G(3)+G(5)*G(5))
dsdeEl(5,6)=elast1*G(5)*G(6)+elast2*(G(4)*G(3)+G(5)*G(6))
dsdeEl(6,6)=elast1*G(6)*G(6)+elast2*(G(2)*G(3)+G(6)*G(6))
do i=1,ncomp-1
  do j=i+1,ncomp
    dsdeEl(j,i)=dsdeEl(i,j)
  end do
end do

c
c *** calculate the trial stress and
c copy elastic moduli dsdeEl to material Jacobian matrix
do i=1,ncomp
  sigElp(i) = stress(i)
  do j=1,ncomp
    dsdePl(j,i) = dsdeEl(j,i)
    sigElp(i) = sigElp(i)+dsdeEl(j,i)*dStrain(j)
  end do
end do

c *** hydrostatic pressure stress
pEl = -THIRD * (sigElp(1) + sigElp(2) + sigElp(3))
c *** compute the deviatoric stress tensor
sigDev(1) = sigElp(1) + pEl
sigDev(2) = sigElp(2) + pEl
sigDev(3) = sigElp(3) + pEl
sigDev(4) = sigElp(4)
sigDev(5) = sigElp(5)
sigDev(6) = sigElp(6)
c *** compute von-mises stress
qEl =
& sigDev(1) * sigDev(1)+sigDev(2) * sigDev(2)+
& sigDev(3) * sigDev(3)+
& TWO*(sigDev(4) * sigDev(4)+ sigDev(5) * sigDev(5)+
& sigDev(6) * sigDev(6))
qEl = sqrt( ONEHALF * qEl)
c *** compute current yield stress
sigy = sigy0 + dsigdep * pleq

c
fratio = qEl / sigy - ONE
c *** check for yielding
IF (sigy .LE. ZERO.or.fratio .LE. -SMALL) GO TO 500
c
sigy_t = sigy
threeOv2qEl = ONEHALF / qEl
c *** compute derivative of the yield function
DO i=1, ncomp
  dfds(i) = threeOv2qEl * sigDev(i)
END DO
oneOv3G = ONE / threeG
qElOv3G = qEl * oneOv3G
c *** initial guess of incremental equivalent plastic strain
dpleq = (qEl - sigy) * oneOv3G
```

```

pleq      = pleq_t + dpleq
c
c *** Newton-Raphson procedure for return mapping iteration
DO i = 1,NEWTON
    sigy    = sigy0 + dsigdep * pleq
    funcf    = qEl0v3G - dpleq - sigy * one0v3G
    dFdep    = - ONE - dsigdep * one0v3G
    cpleq    = -funcf / dFdep
    dpleq    = dpleq + cpleq
c    --- avoid negative equivalent plastic strain
    dpleq    = max (dpleq, sqTiny)
    pleq     = pleq_t + dpleq
    fratio   = funcf/qEl0v3G
c ***    check convergence
    IF (((abs(fratio) .LT. ONEDM05           ) .AND.
&      (abs(cpleq) .LT. ONEDM02 * dpleq)) .OR.
&      ((abs(fratio) .LT. ONEDM05           ) .AND.
&      (abs(dpleq) .LE. sqTiny             ))) GO TO 100
    END DO
c
c *** Unconvergence, set keycut to 1 for bisect/cut
    keycut   = 1
    GO TO 990
100 CONTINUE
c
c *** update stresses
    con1 = twoG * dpleq
    DO i = 1 , ncomp
        stress(i) = sigElp(i) - con1 * dfds(i)
    END DO
c
c *** update plastic strains
    DO i = 1 , nDirect
        epsPl(i) = epsPl(i) + dfds(i) * dpleq
    END DO
    DO i = nDirect + 1 , ncomp
        epsPl(i) = epsPl(i) + TWO * dfds(i) * dpleq
    END DO
    epseq = pleq
c *** Update state variables
    statev(1) = pleq
c *** Update plastic work
    sedPl = sedPl + HALF * (sigy_t+sigy)*dpleq
c
c *** Material Jacobian matrix
c
    IF (qEl.LT.sqTiny) THEN
        con1 = ZERO
    ELSE
        con1 = threeG * dpleq / qEl
    END IF
    con2 = threeG/(threeG+dsigdep) - con1
    con2 = TWOTHIRD * con2
    DO i=1,ncomp
        DO j=1,ncomp
            JM(j,i) = ZERO
        END DO
    END DO

```

```
      END DO
      DO i=1,nDirect
        DO j=1,nDirect
          JM(i,j) = -THIRD
        END DO
        JM(i,i) = JM(i,i) + ONE
      END DO
      DO i=nDirect + 1,ncomp
        JM(i,i) = HALF
      END DO
      DO i=1,ncomp
        DO j=1,ncomp
          dsdePl(i,j) = dsdeEl(i,j) - twoG
&          * ( con2 * dfds(i) * dfds(j) + con1 * JM(i,j) )
        END DO
      END DO
c
      goto 600
500 continue

c *** Update stress in case of elastic/unloading
      do i=1,ncomp
        stress(i) = sigElp(i)
      end do

      600 continue
c *** Claculate elastic work
      sedEl = ZERO
      DO i = 1 , ncomp
        sedEl = sedEl + stress(i)*(Strain(i)+dStrain(i)-epsPl(i))
      END DO
      sedEl = sedEl * HALF
c
      990 CONTINUE
c
      return
      end
```