

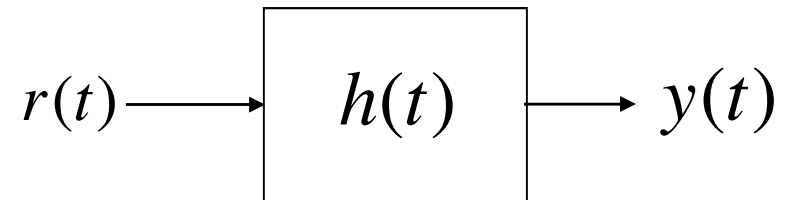
Matched Filter Properties

Maximum SNR Property

- Assume AWGN
- The optimally sampled output of the matched filter yields the highest signal-to-noise ratio (SNR) of any filter
- Next, show that the filter that maximizes the SNR is the matched filter

Set Up

- Suppose $r(t) = s(t) + n(t)$, where $n(t)$ is WGN with spectral height $N_o/2$, and $s(t)$ is a signal with a finite duration T
- Let $r(t)$ be the input to a filter with impulse response $h(t)$
- Let $y(t)$ be the output



Signal and Noise Parts

- The signal part of the output is

$$y_s(t) = \int_0^t s(u)h(t-u)du$$

- The noise part of the output is

$$y_n(t) = \int_0^t n(u)h(t-u)du$$

Signal-to-noise Ratio

$$\begin{aligned}\text{SNR} &= \frac{y_s^2(t)}{E[y_n^2(t)]} \\ &= \frac{\left[\int_0^t s(u)h(t-u)du \right]^2}{E\left(\left[\int_0^t n(u)h(t-u)du \right]^2 \right)}\end{aligned}$$

Denominator

$$\begin{aligned} & E[y_n^2(t)] \\ &= E\left\{\left[\int_0^t n(u)h(t-u)du\right]\left[\int_0^t n(v)h(t-v)dv\right]\right\} \\ &= \int_0^t \int_0^t E\{n(u)n(v)\}h(t-u)h(t-v)dudv \end{aligned}$$

Invoke White Noise Model

$$\begin{aligned} & E[y_n^2(t)] \\ &= \int_0^t \int_0^t \frac{N_0}{2} \delta(u-v) h(t-u) h(t-v) du dv \\ &= \frac{N_0}{2} \int_0^t h^2(t-u) du \end{aligned}$$

SNR So Far

- To optimize the SNR, choose $h(u)$ to maximize the numerator

$$\text{SNR} = \frac{\left[\int_0^t s(u)h(t-u)du \right]^2}{\frac{N_0}{2} \int_0^t h^2(t-u)du}$$

Cauchy-Schwarz Inequality

- Say S and Q are two points in a Hilbert space, then

$$\langle S, Q \rangle^2 \leq |S|^2 |Q|^2$$

with equality when $Q=cS$

Cauchy-Schwarz for Signals

- Let S and Q be points in the Hilbert space of square-integrable functions
- Then,

$$\left[\int_0^t s(u)q(u)du \right]^2 \leq \int_0^t s^2(u)du \int_0^t q^2(u)du$$

- Equality is reached when $cs(u) = q(u)$

Apply Cauchy-Schwartz

- Recall numerator of SNR

$$\left[\int_0^t s(u)h(t-u)du \right]^2$$

- Pick $h(t-u)$ to be equal to $cs(u)$
- The resulting filter is matched to $s(u)$

Simplify Optimal SNR

- Substitute $h(t-u)=cs(u)$

$$\text{SNR}^{\text{opt}}(t) = \frac{\left[c \int_0^t s^2(u) du \right]^2}{\frac{N_0 c^2}{2} \int_0^t s^2(u) du} = \frac{\int_0^t s^2(u) du}{\frac{N_0}{2}}$$

Optimize t

- If $s(t)$ has finite duration T , then SNR is maximized by setting $t=T$

$$\text{SNR}^{\text{opt}} = \frac{\int_0^T s^2(u) du}{\frac{N_0}{2}} = \frac{2\mathcal{E}_s}{N_0}$$

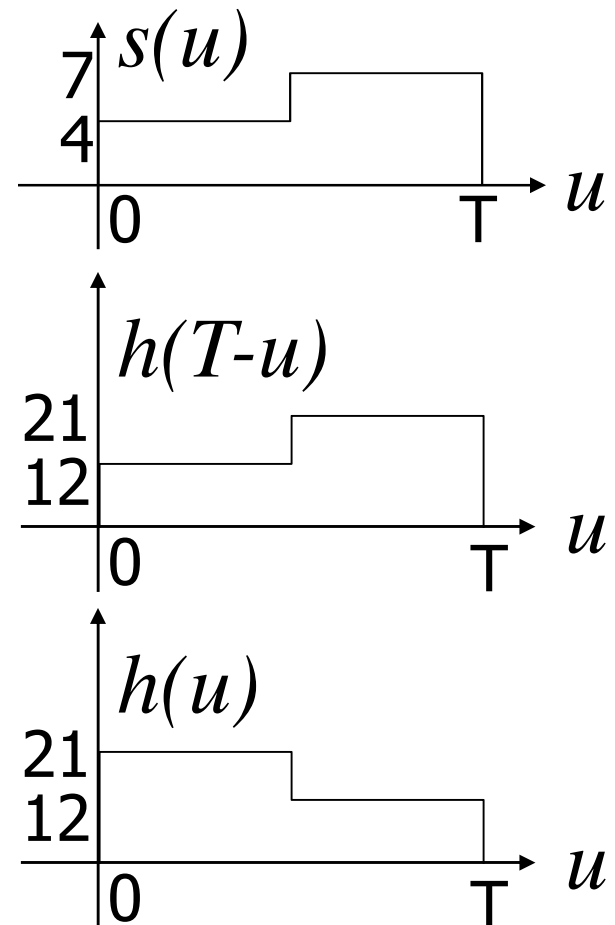
Max SNR Filter = Matched Filter

- Therefore, the filter that maximizes the SNR has the impulse response

$$h(T - u) = cs(u)$$

or

$$h(u) = cs(T - u)$$



Matched Filter Frequency Response

- Take Fourier Transform of the Matched Filter impulse response

$$\begin{aligned} H(f) &= \int_0^T h(u) e^{-j2\pi fu} du \\ &= c \int_0^T s(T-u) e^{-j2\pi fu} du \end{aligned}$$

Let $r=T-u$

$$\begin{aligned} H(f) &= c \int_0^T s(T-u) e^{-j2\pi fu} du \\ &= c \int_T^0 s(r) e^{-j2\pi f(T-r)} (-dr) \\ &= c e^{-j2\pi fT} \int_0^T s(r) e^{j2\pi fr} dr = c e^{-j2\pi fT} [S(f)]^* \end{aligned}$$

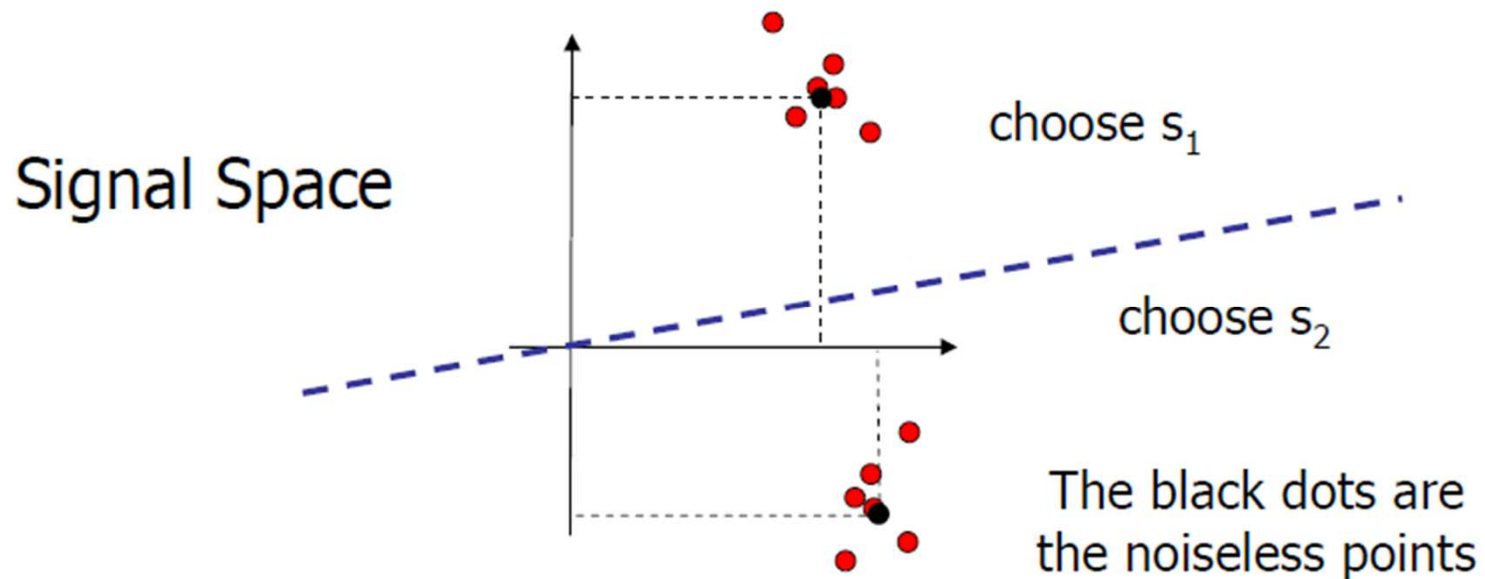
Matched in Frequency Domain

- The magnitude of the matched filter response is just a scaled version of the signal's F.T.

$$|H(f)| = c|S(f)|$$

Relation to Optimum Detection

- Recall optimum detector is the minimum distance detector



Alternative form of Minimum Distance Receiver

- Expand the signal space distance between the received vector \mathbf{r} and the noiseless signal point \mathbf{s}_m

$$\|\mathbf{r} - \mathbf{s}_m\|^2 = \|\mathbf{r}\|^2 - 2\langle \mathbf{r}, \mathbf{s}_m \rangle + \|\mathbf{s}_m\|^2$$

$$\hat{m}_{opt} = \arg \min_m \left[-2\langle \mathbf{r}, \mathbf{s}_m \rangle + \mathcal{E}_m \right]$$

If Signals are Equal Energy

- The minimum distance receiver can be implemented as a bank of matched filters

$$\hat{m}_{opt} = \arg \min_m \left[-2 \langle \mathbf{r}, \mathbf{s}_m \rangle + \mathcal{E}_m \right]$$

$$= \arg \max_m \langle \mathbf{r}, \mathbf{s}_m \rangle$$

$$= \arg \max_m \int_0^T r(t) s_m(t) dt$$

Summary

- When the input is signal plus WGN, then the filter that maximizes the SNR is the matched filter
- The proof is an application of the Cauchy-Schwarz Inequality
- The filter “matches” (has the same shape as) the signal in magnitude in the frequency domain