receive\_status is set by a Uart observer to inform the completion of reception and DataFrame is filled by the observer

parse\_status is set by the parser function if the emergency is detected

Main Function Should implement the logic of button

## EVD(Emergency vehicle detection) - receive\_status: int - DataFrame: int[] - Parser\_status: int + EVD\_ParseFrame(int[]) + EVD\_MainFunction()

## Control leds using Pwm not Dio

Led	
+ Led_Color: int	
- Led_TurnOn(int channel_id) - Led_TurnOff(int channel_id) + LedMainFunction()	

Main Function Should implement the logic of button
The logic is to check the button status and consider (pressed)
if the pressed level (a range of value determined later)
is detected 10 consecutive times

Button
- Button\_status: int
+ Button\_GetReading(): int
+ Button\_GetStatus(): int
+ Button\_MainFunction()

Main Function Should implement the logic of button Main function should handle the transition between the 2 SS displays.

activeSS determine which display is active

SS(seven segment)

- SS\_status1: int
- SS\_status2: int

- SS\_Write(int shape)
+ SS\_MainFunction()