



NSF Engineering Research Center  
for Computer Integrated Surgical  
Systems and Technology

WHITING  
SCHOOL OF  
ENGINEERING  
THE JOHNS HOPKINS UNIVERSITY

## Validation of Statistical Atlases

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## Validation of Statistical Atlases

- Given an atlas with mean shape  $\bar{S}$ , modes  $U$  and a new shape instance  $S^{new}$

- Compute  $\lambda$  using

$$\lambda = U^T (S^{new} - \bar{S})$$

- and estimate the new shape instance as follows

$$S_{est}^{new} = \bar{S} + U\lambda$$



## Validation of Statistical Atlases

- Given  $S^{new}$  and  $S_{est}^{new}$

A variety of error metrics can be computed

- Vector based metrics

- L1 norm

$$\varepsilon = \sum_k |S^{new}[k] - S_{est}^{new}[k]|$$

- L2 norm

$$\varepsilon = \|S^{new} - S_{est}^{new}\|_2$$

- Mahalanobis distance  $\varepsilon = \sqrt{(S^{new} - S_{est}^{new})^T \Sigma^{-1} (S^{new} - S_{est}^{new})}$

- Angle between shape vectors

$$\theta = \alpha \cos\left(\frac{S^{new} \cdot S_{est}^{new}}{\|S^{new}\| \|S_{est}^{new}\|}\right)$$

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## Validation of Statistical Atlases

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- Mesh based metrics
  - Vertex to vertex correspondence errors
  - Surface distance between meshes using ICP
- Volume based metrics – voxelize the mesh and compare the volumes
  - Volume overlap

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## Leave out validation

Given set of models  $\{\dots S^k \dots\}$ , do the following

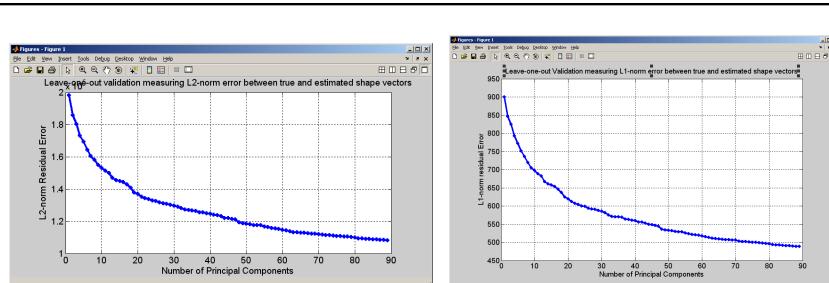
for  $k = 1$  to  $N$  do

$$\begin{aligned}\bar{S}, \mathbf{U} &= \text{Compute statistical atlas } (\{\dots S^{k-1}, S^{k+1} \dots\}) \\ \vec{\lambda} &= \mathbf{U}^T (S^k - \bar{S}) \\ E^k &= S^k - (\bar{S} + \mathbf{U} \vec{\lambda})\end{aligned}$$

Compute statistics on the  $\{\dots E^k \dots\}$

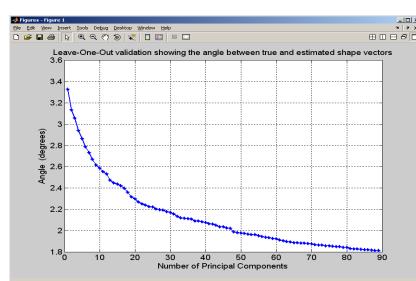
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L2-norm

L1-norm

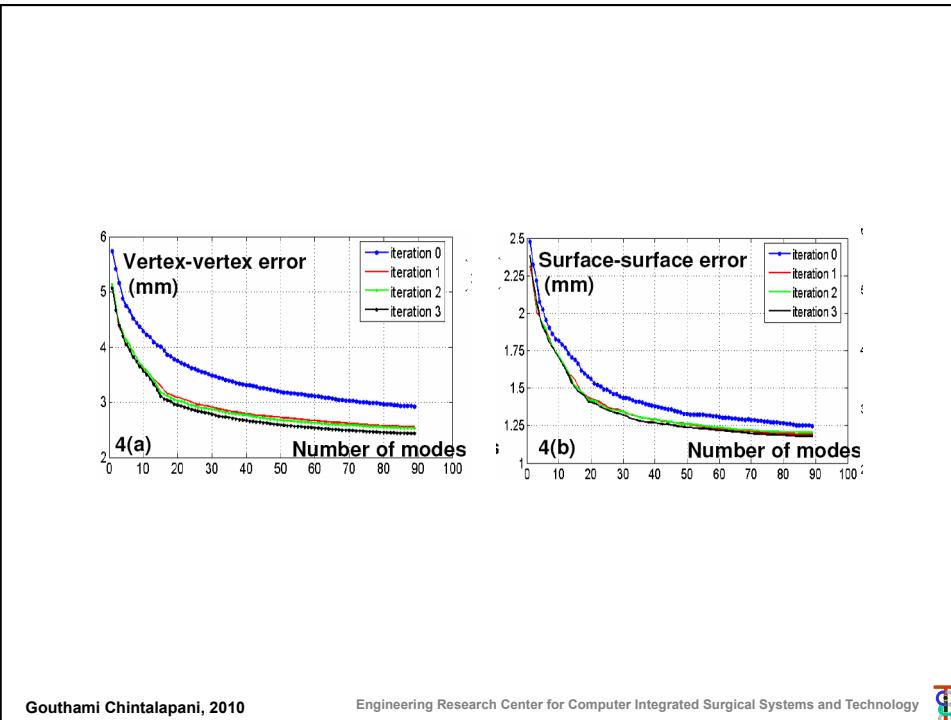


angle

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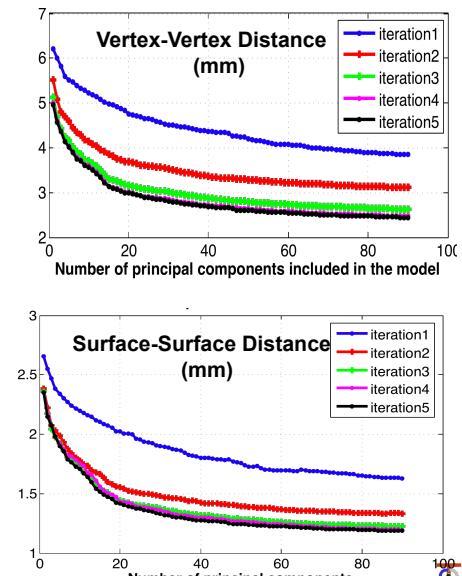
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## Leave-Out Validation Experiments

- # of iterations: 5
- # of data sets: 110
- # of data sets in atlas: 90
- # of data sets left out: 20
- Given a left-out dataset,  $s_j$  compute the estimated shape from atlas using

$$\begin{aligned}\lambda &= U^*(s_j - \bar{S}) \\ s_j^{est} &= \bar{S} + U\lambda\end{aligned}$$



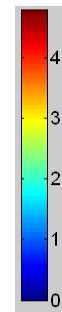
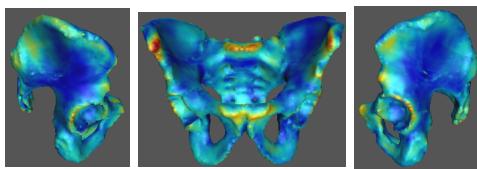
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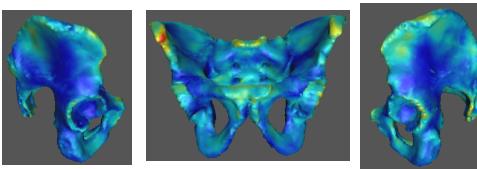


## Distribution of Surface Registration Errors

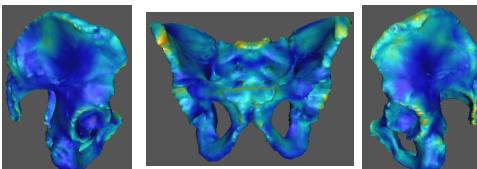
Iteration n 1



Iteration n 3



Iteration n 5



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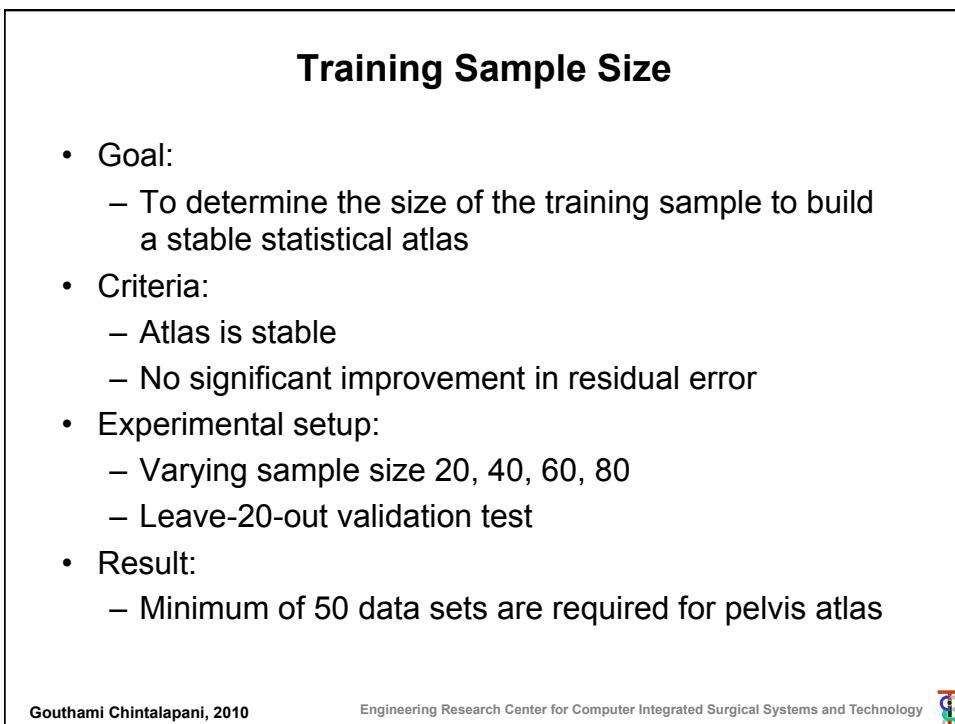
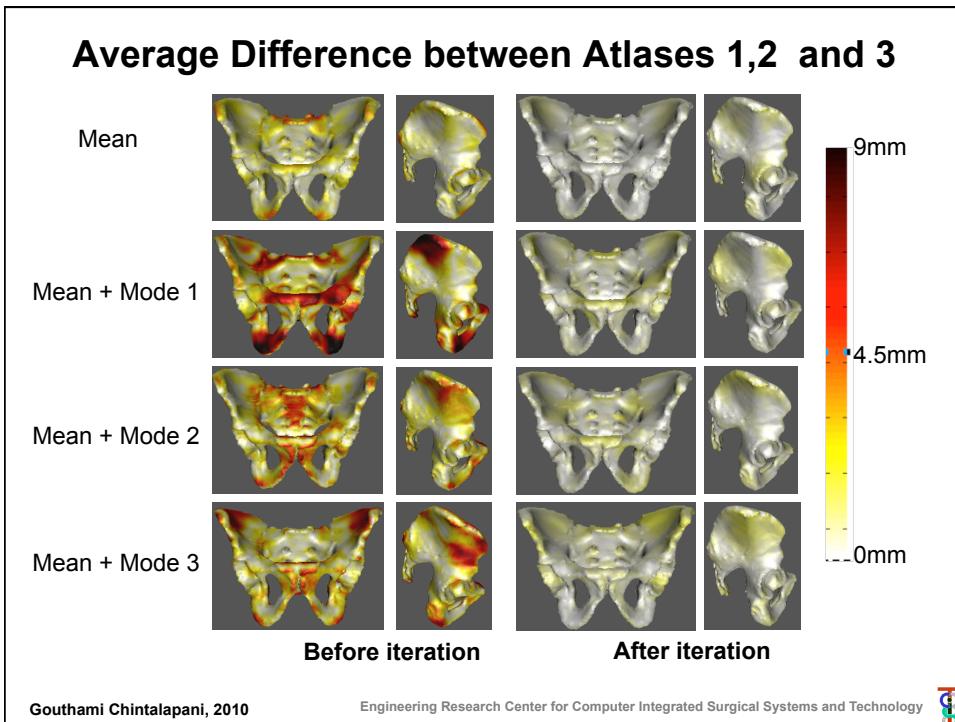
## Choice of Initial Template

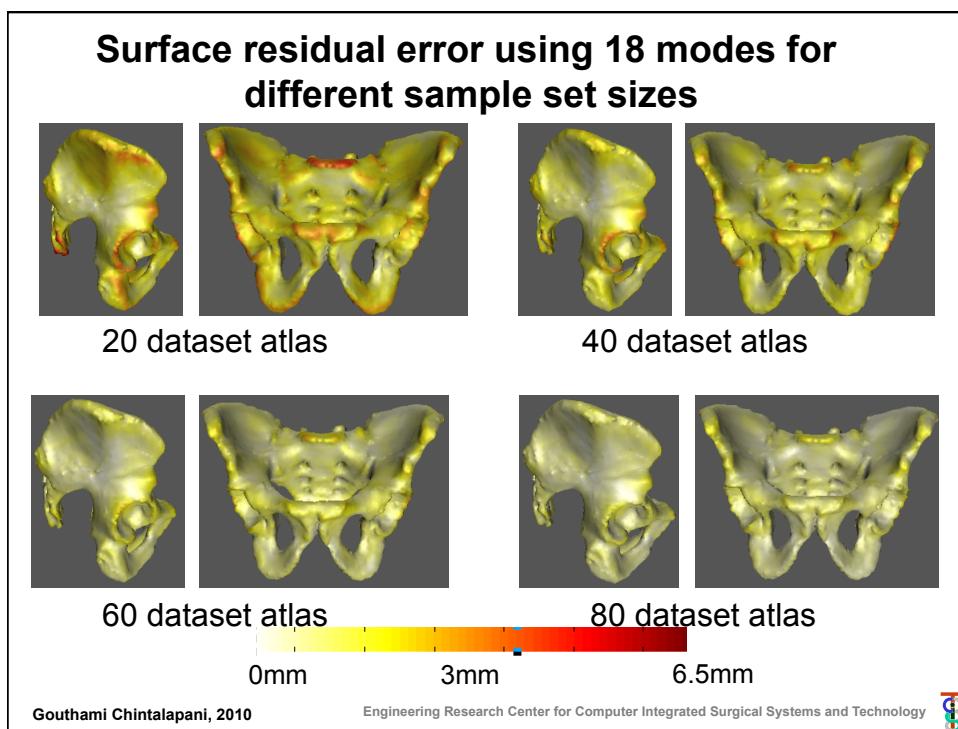
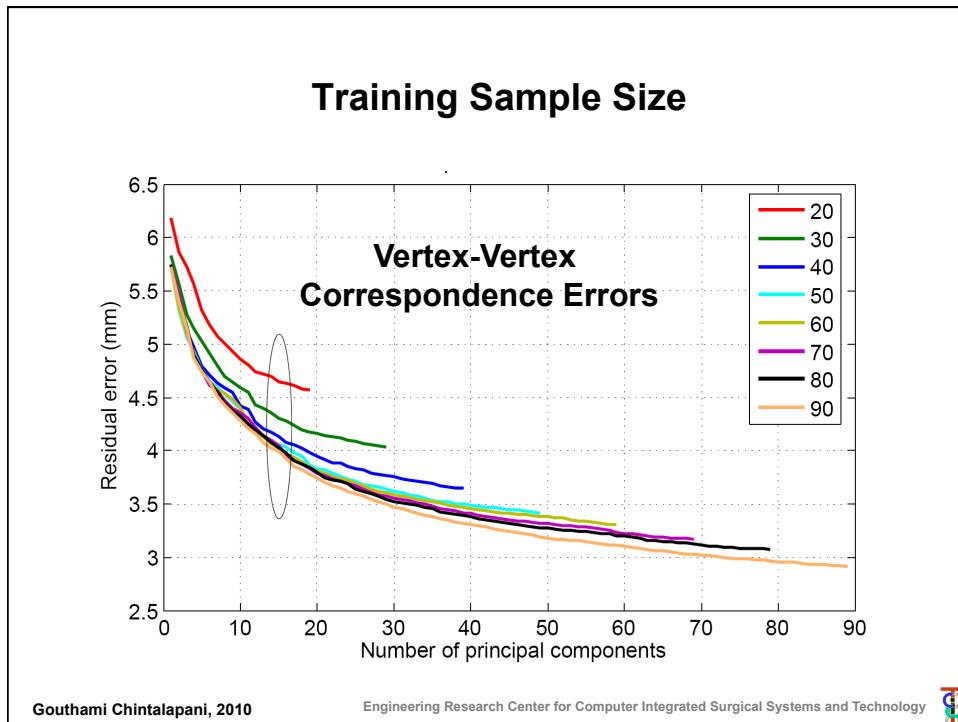
- Claim:
  - iterative method does not depend on the choice of template
- Criteria:
  - Mean shape converges
  - Modes exhibit similar deformation patterns
- Experimental setup:
  - Three random templates
  - Atlases with and without bootstrapping compared
- Result:
  - All three atlases exhibit similar deformation patterns after bootstrapping

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## Stability Analysis – Mean Shape

