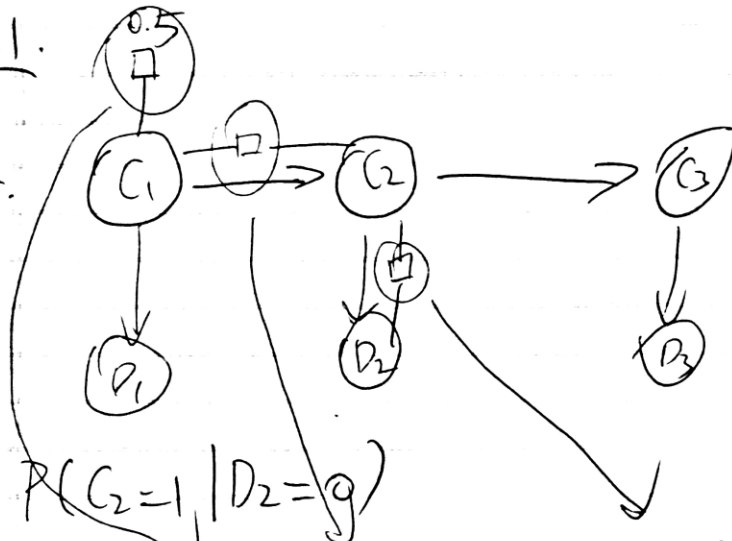


Homework 7

Problem 1.

1a.



$$P(C_2=1 | D_2=0)$$

$$= \sum_{C_1} P(C_1) P(C_2=1 | C_1) P(D_2=0 | C_2=1)$$

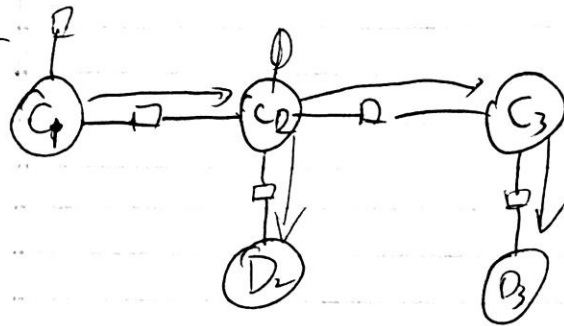
$$= P(C_1=0) P(C_2=1 | C_1=0) P(D_2=0 | C_2=1) + P(C_1=1) P(C_2=1 | C_1=1) P(D_2=0 | C_2=1)$$

$$= 0.5 \cdot \eta + 0.5(1-\epsilon) \cdot \eta = 0.5\eta + 0.5(1-\eta)\eta$$

$$P(C_2=0 | D_2=0) = 0.5(1-\epsilon) \cdot \eta + 0.5 \cdot \eta = 0.5\eta + 0.5(1-\eta)\eta$$

$$\Rightarrow P(C_2=1 | D_2=0) = \frac{0.5\eta}{0.5\eta + 0.5(1-\eta)} = \eta$$

1.b



$$P(C_2=1 | D_2=0, D_3=1)$$

multiply by

$$= \sum_{C_1} P(C_1) P(C_2=1 | C_1) P(D_2=0 | C_2=1) \quad \text{multiply by}$$

$$\sum_{C_3} P(C_3 | C_2=1) P(D_3=1 | C_3)$$

.148

$$= (0.5 \varepsilon \eta + 0.5 (1-\varepsilon) \eta) (\varepsilon \eta + (1-\varepsilon) (1-\eta))$$

$$= 0.5 \eta (\varepsilon \eta + (1-\varepsilon) (1-\eta)) \quad \text{--- ①}$$

$$P(C_2=0 | D_2=0, D_3=1) = (\text{Same formula})$$

$$= 0.5 (1-\eta) ((1-\varepsilon) \eta + \varepsilon (1-\eta)) \quad \text{--- ②}$$

$$\Rightarrow P(C_2=1 | D_2=0, D_3=1) = \frac{\text{①}}{\text{①} + \text{②}} = \frac{\eta (\varepsilon \eta + (1-\varepsilon) (1-\eta))}{(1-\eta) ((1-\varepsilon) \eta + \varepsilon (1-\eta)) + \eta (\varepsilon \eta + (1-\varepsilon) (1-\eta))}$$

1.c

i Plug in 1.a and 1.b, we get:

$$P(C_2=1|D_2=0) = 0.2$$

$$P(C_2=1|D_2=0, D_3=1) = 0.4157$$

ii The probability (posterior) increased for $C_2=1$ after adding $C_3=1$.

This is because knowing the car's (estimated) position at one more timestep helps us infer the car's position in another timestep.

iii From expression ⁽¹⁾(2) in 1.b,

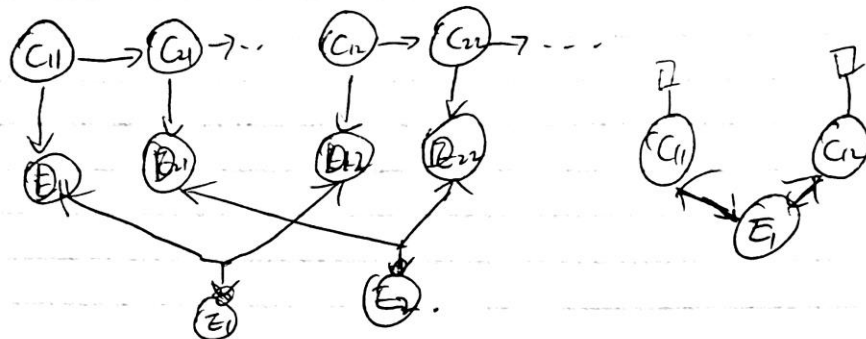
$$0.5\eta^2\varepsilon + 0.5\eta(1-\eta)(\cancel{1-\varepsilon}) = 0.5(1-\eta)(\cancel{1-\varepsilon})\eta + 0.5(1-\eta)^2\varepsilon$$

Only possible if $\varepsilon=0$.

i.e. the car does not move.

Problem 5.

5.a



$$P(C_{11}, e_1 = \epsilon_1) =$$

$$\frac{1}{2!} P(C_{11}) P(C_{21}) \left[P_N(e_{11}; \|a_1 - C_{11}\|, \sigma^2) P_N(e_{21}; \|a_1 - C_{21}\|, \sigma^2) + \right. \\ \left. \underset{\substack{\checkmark \\ =2}}{P_N(e_{11}; \|a_1 - C_{21}\|, \sigma^2) P_N(e_{21}; \|a_1 - C_{11}\|, \sigma^2)} \right]$$

5.b.

Obtain a general expr:

$$P(C_{11}=C_{11}, C_{12}=C_{12} \dots | E_1=e_1) = \frac{1}{K!} \overbrace{P(C_{11}=C_{11}) P(C_{12}=C_{12}) \dots P(C_{1K}=C_{1K})}^{(1)}$$

$$\rightarrow \sum_{\substack{\text{All permutations} \\ \text{of } C_i}} \left[P(e_{11}; \|a_1 - C_{11}\|, \sigma^2) P(e_{12}; \|a_1 - C_{12}\|, \sigma^2) \dots P(e_{1K}; \|a_1 - C_{1K}\|, \sigma^2) \right]$$

\Rightarrow ~~As~~ To maximize, we need to maximize (1).

However, if ① achieves maximum with \vec{c}_{11} , then
all ~~the~~ permutations of \vec{c}_{11} ($\{c_{11}, c_{12}, c_{13}, \dots\}$) will have the
same product $P(c_{11}=c_{11})P(c_{12}=c_{12}) \dots P(c_{1k}=c_{1k})$.
Since \vec{c}_{11} has $k!$ permutations, this proves
~~out the~~ that we have at least $k!$ assignments
to achieve max probability.

5-c

The arity of this probability is K . Thus, the treewidth is also K .

5-d