

Probabilistic Models for PDEs with Random Coefficients

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Fred J. Hickernell² Nick Hengartner¹

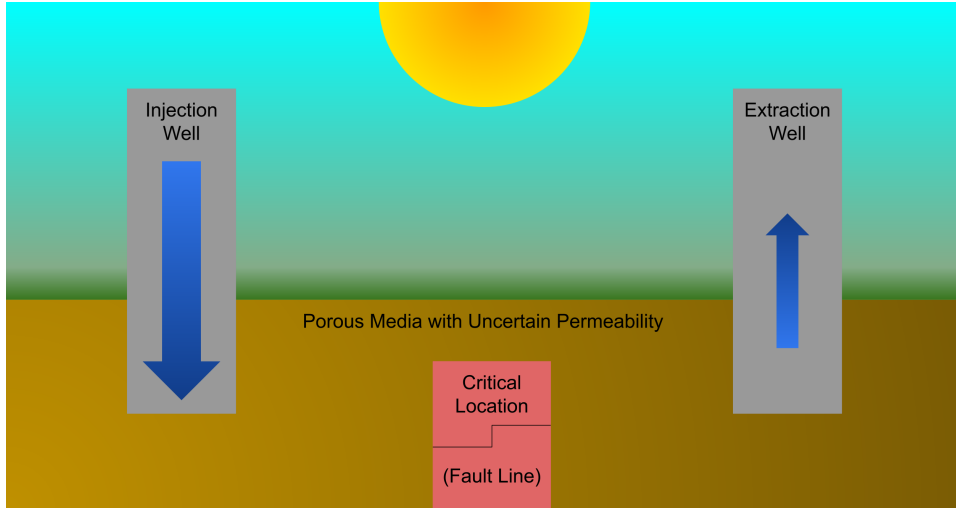
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Control Extraction Rate to Manage Pressure at Critical Location

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Random Permiability in Porous Media Induces Random Pressure

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Random Permiability in Porous Media Induces Random Pressure

Darcy's equation $\nabla \cdot (G(x) \cdot \nabla p(E, G, x)) = f(E, x)$ models pressure in porous media

- $G(x)$ a **random** *Gaussian permeability field*, known only by statistical properties
- $p(x)$ the **random** *pressure solution*

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Following Pachalieva et al.¹, we model the *flow rate* as

$$f(x, E) = \begin{cases} I, & x = x_{\text{injection}} \\ -E, & x = x_{\text{extraction}} \\ 0, & \text{else} \end{cases}.$$

- I , the **fixed** *injection rate*
- E , the **variable** *extraction rate*

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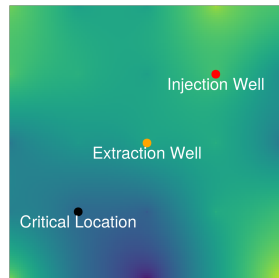
- Given critical location x_{critical} e.g. fault line
- Given *pressure threshold* \bar{p} at the critical location
- $p^c(E, G) := p(E, G, x_{\text{critical}})$, the *critical pressure*

Want **online** choice of smallest E which gives high *confidence*

$$P(p^c(E, G) \leq \bar{p})$$

in keeping low enough pressure at the critical location

Birds-Eye View



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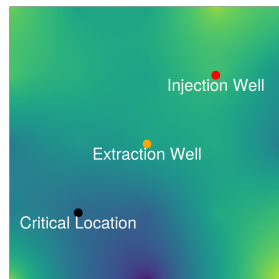
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Challenges

- Must approximate $P(p^c(E, G) \leq \bar{p})$ for many different E values
- Approximating $P(p^c(E, G) \leq \bar{p})$ requires many samples of $G(x)$ e.g. over 10,000

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Represent $G(x)$ as an Infinite Sum, Approximate $G(x)$ by a Finite Sum

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Karhunen-Loève series expansion of permeability field $G(x)$

$$G(x) = \sum_{j=1}^{\infty} \sqrt{\lambda_j} Z_j \varphi_j(x)$$

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Since $\lambda_1 \geq \lambda_2 \geq \lambda_3 \geq \dots$, we approximate $G(x)$ by a sum of s terms

$$G(x) \approx \sum_{j=1}^s \sqrt{\lambda_j} Z_j \varphi_j(x)$$

$$\mathbf{Z} = (Z_1, \dots, Z_s)^T \sim \mathcal{N}(0, I_s)$$

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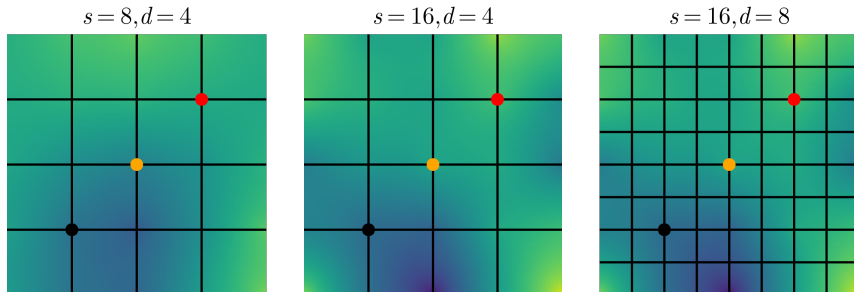
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Numerical solution uses DPFEHM: <https://github.com/OrchardLANL/DPFEHM.jl>

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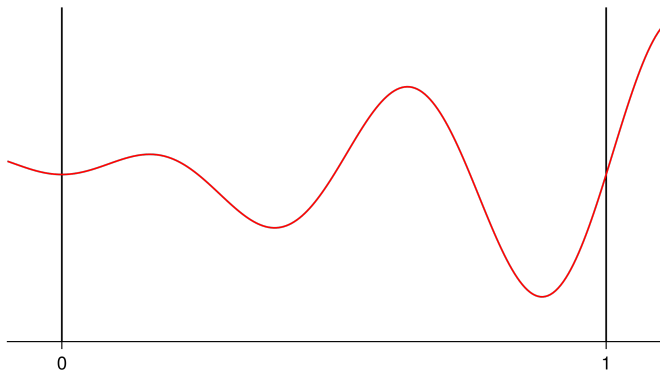
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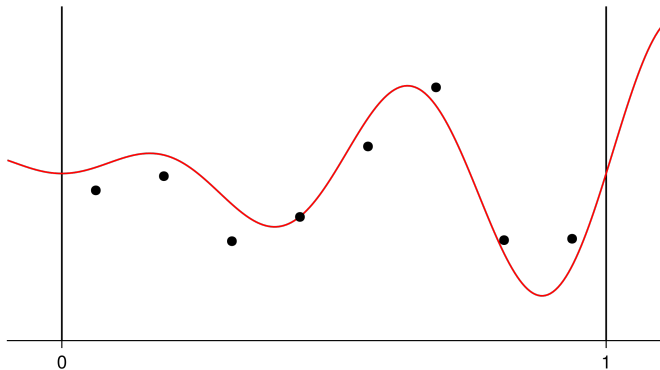


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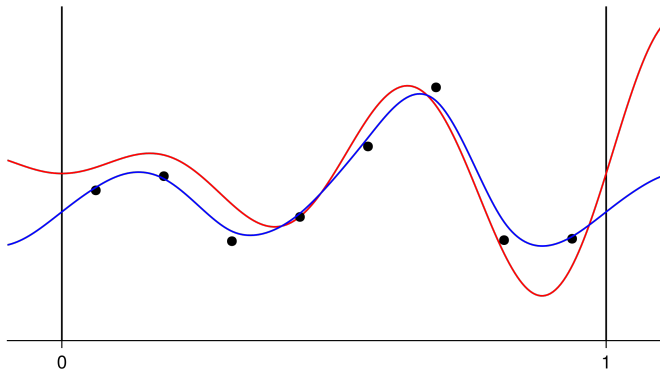


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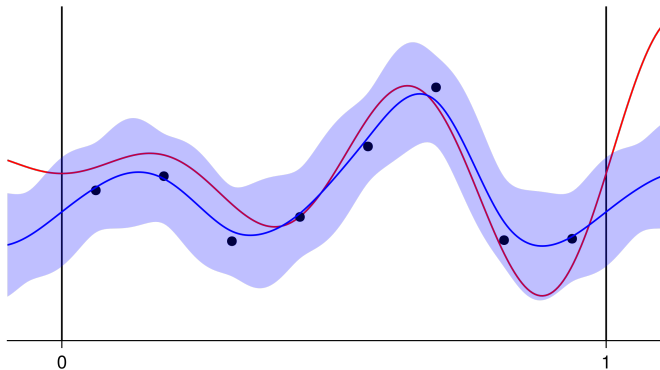


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Structuring Nodes and Kernel Enables $\mathcal{O}(n \log n)$ Scaling for GPs

²R. Jagadeeswaran and Fred J. Hickernell. “Fast automatic Bayesian cubature using lattice sampling”. In: *Statistics and Computing* 29.6 (2019), pp. 1215–1229. ISSN: 1573-1375. DOI: [10.1007/s11222-019-09895-9](https://doi.org/10.1007/s11222-019-09895-9). URL: <http://dx.doi.org/10.1007/s11222-019-09895-9>.

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- \therefore Can construct GPs with $\mathcal{O}(n \log n)$ cost when we have control over nodes [▶ details](#)

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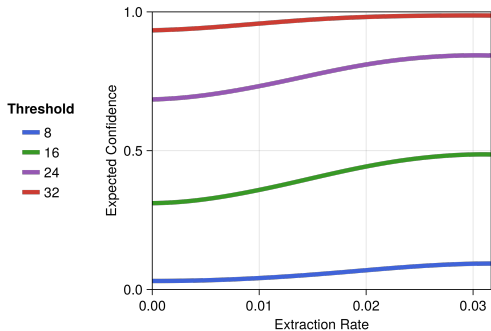
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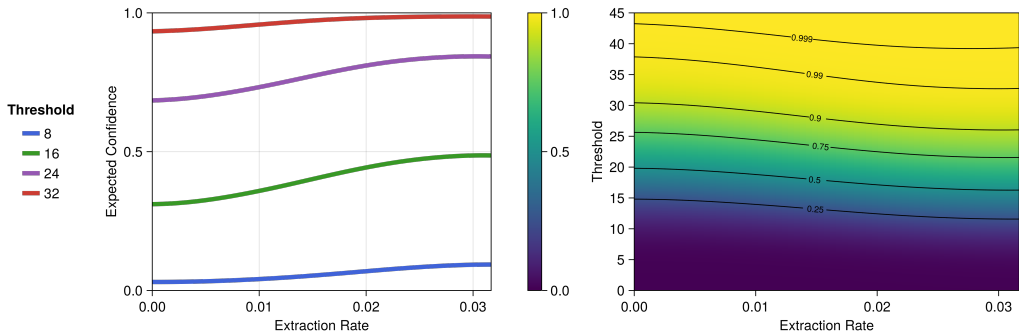
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- Hyperparameter optimization also costs $\mathcal{O}(n \log n)$ for specially structured GPs

Estimate $P(p^c(E, G) \leq \bar{p})$ Online with Gaussian Process Surrogate

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- **Efficient:** Gaussian process construction in $\mathcal{O}(n \log n)$ instead of $\mathcal{O}(n^3)$ cost
- **Error Aware:** Gaussian process noise calibrated to numerical error
- **Transferable:** Methodology applicable to other PDEs with random coefficients

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- $P(p_{s,d}^c(E, \mathbf{Z}) \leq \bar{p}) \neq P(p^c(E, G) \leq \bar{p})$ generally

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- ∴ Inexpensive to estimate confidence $P(p^c(E, G) \leq \bar{p})$ online using surrogate

Noisy *Quasi*-Gaussian Process Surrogate

Assume $p_{s,d}^c(t) = p^c(t) + \varepsilon$, $\varepsilon \sim \mathcal{N}(0, \zeta_{s,d})$

numerical solution = solution + Gaussian noise

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3. Posterior mean $m_n(t) = \mathbb{E}[p^c(t)|Y]$ and covariance $k_n(t, t') = \text{Cov}[p(t), p(t')|Y]$.

$$m_n(t) = K_T(t) [K_{TT} + \zeta I_n]^{-1} Y$$

costs $\mathcal{O}(n^3)$ where $K_T(t) = (k(t, t_i))_{i=1}^n$, $K_{TT} = (k(t_i, t_j))_{i,j=1}^n$.

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Quasi-Gaussian Process Regression

Choose special $(t_i)_{i=1}^n$ and k so $[K_{TT} + \zeta I_n]^{-1} Y$ costs $\mathcal{O}(n \log n)$.

Estimating Bound on Standard Deviation of GP Noise

$$\sqrt{\zeta_{s_T, d_T}} = \|p^c - p_{s_T, d_T}^c\| = \sqrt{\mathbb{E} \left[p^c(t) - p_{s_T, d_T}^c(t) \right]^2}, \quad \forall t$$

Rewrite as telescoping sum

$$\sqrt{\zeta_{s_T, d_T}} := \|p^c - p_{s_T, d_T}^c\| \leq \sum_{j=T}^{\infty} \underbrace{\|p_{s_{j+1}, d_j}^c - p_{s_j, d_j}^c\|}_{\Delta_{s_{j+1}}} + \sum_{j=T}^{\infty} \underbrace{\|p_{s_{j+1}, d_{j+1}}^c - p_{s_{j+1}, d_j}^c\|}_{\Delta_{d_{j+1}}}.$$

Models $\|\Delta_{s_j}\| = 2^{b_s} s_j^{a_s}$ and $\|\Delta_{d_j}\| = 2^{b_d} d_j^{a_d}$ with $s_j = v_s 2^j$ and $d_j = v_d 2^j$ imply

$$\sqrt{\zeta_{s_T, d_T}} \leq \sum_{j=T+1}^{\infty} 2^{b_s} s_j^{a_s} + \sum_{j=T+1}^{\infty} 2^{b_d} d_j^{a_d} = 2^{b_s} v_s^{a_s} \frac{2^{(T+1)a_s}}{1 - 2^{a_s}} + 2^{b_d} v_d^{a_d} \frac{2^{(T+1)a_d}}{1 - 2^{a_d}} := \sqrt{\bar{\zeta}_{s_T, d_T}}.$$

Simple Linear Regression Convergence Models

