Aleksei G. Sorokin 1 , Sou-Cheng T. Choi 1,2 , Fred J. Hickernell 1 , Mike McCourt 3 , Jagadeeswaran Rathinavel 4

 1 Illinois Institute of Technology (IIT), Department of Applied Mathematics 2 Kamakura Corporation 3 SigOpt, an Intel company 4 Wi-Tronix LLC

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Rewrite an Integral as an Expectation

Applications in applied statistics, finance, computer graphics, ...

$$\mu = \int_{\mathcal{T}} g(\boldsymbol{t}) \lambda(\boldsymbol{t}) d\boldsymbol{t} = \int_{[0,1]^d} g(\boldsymbol{\Psi}(\boldsymbol{x})) \lambda(\boldsymbol{\Psi}(\boldsymbol{x})) |\boldsymbol{\Psi}'(\boldsymbol{x})| d\boldsymbol{x} = \int_{[0,1]^d} f(\boldsymbol{x}) d\boldsymbol{x} = \mathbb{E}[f(\boldsymbol{X})]$$
$$\boldsymbol{X} \sim \mathcal{U}[0,1]^d$$

Original Integrand $g: \mathcal{T} \to \mathbb{R}$

True Measure $\lambda: \mathcal{T} \to \mathbb{R}^+$ e.g. probability density or 1 for Lebesgue measure

Transformation $\mathbf{\Psi}:[0,1]^d
ightarrow \mathcal{T}$ with Jacobian $|\mathbf{\Psi}'(m{x})|$

Transformed Integrand $f:[0,1]^d \to \mathbb{R}$

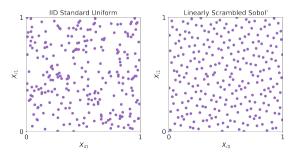
QMCPy automatically approximates integrals

Approximate the Integral by Sampling Well

$$\text{sample mean} = \hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n f(\boldsymbol{x}_i) \approx \int_{[0,1]^d} f(\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x} = \mu = \text{mean}$$

Simple Monte Carlo: $x_1, x_2, \dots \stackrel{\mathsf{IID}}{\sim} \mathcal{U}[0,1]^d$

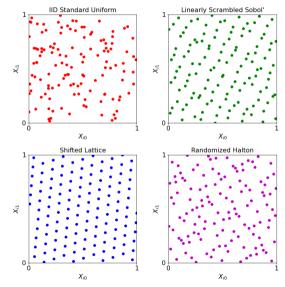
Quasi-Monte Carlo: $\boldsymbol{x}_1, \boldsymbol{x}_2, \dots \overset{\mathsf{LD}}{\sim} \mathcal{U}[0,1]^d$ (Low-Discrepancy)



Sample Generators

Sobol' Example

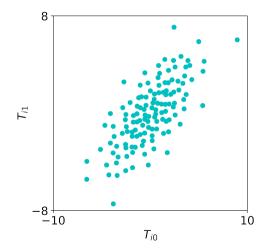
```
>>> import qmcpy as qp
>>> sobol = qp.Sobol(2)
>>> sobol.gen_samples(2**3)
array([[0.387, 0.146],
       [0.552, 0.506],
       [0.169, 0.901],
       [0.771, 0.258],
       [0.303, 0.724],
       [0.639, 0.116],
       [0.023, 0.48].
       [0.922, 0.867]])
```



True Measure Transforms: Apply change of variables

Gaussian Example

$$\Psi(\boldsymbol{X}) = \boldsymbol{a} + A\boldsymbol{\Phi}^{-1}(\boldsymbol{X}) \sim \mathcal{N}(\boldsymbol{a}, \boldsymbol{\Sigma} = AA^T)$$



Integrand Examples: Define the original integrand

Keister Example [1]

```
\mu = \int_{\mathbb{R}^d} \cos(\|\boldsymbol{t}\|) \exp(-\|\boldsymbol{t}\|^2) \,\mathrm{d}\boldsymbol{t}
        = \int_{\mathbb{R}^d} \underbrace{\pi^{d/2} \cos(\|\boldsymbol{t}\|)}_{\boldsymbol{t}} \underbrace{\mathcal{N}(\boldsymbol{t}|\boldsymbol{0},\boldsymbol{\mathsf{I}}/2)}_{\boldsymbol{t}} \, \mathrm{d}\boldsymbol{t}
         = \int_{[0,1]^d} \pi^{d/2} \cos(\|\mathbf{\Psi}(\boldsymbol{x})\|) \, \mathrm{d}\boldsymbol{x}
      = \int_{[0,1]^d} \underbrace{g(\boldsymbol{\Psi}(\boldsymbol{x}))}_{f(\boldsymbol{x})} \, \mathrm{d}\boldsymbol{x}
```

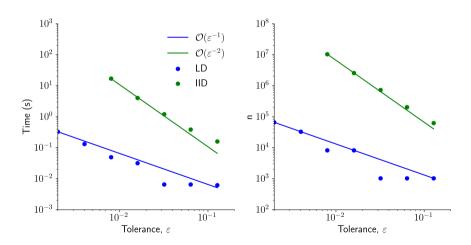
```
>>> from numpy import sqrt,pi,cos
>>> def my keister(t):
d = t.shape[1]
norm = sqrt((t**2).sum(1))
k = pi**(d/2)*cos(norm)
... return k
>>> sob5 = qp.Sobol(5)
>>> gauss_sob = qp.Gaussian(sob5,
       mean = 0, covariance = 1/2)
>>> keister = qp.CustomFun(
... true_measure = gauss_sob,
g = my \text{ keister}
\rightarrow > x = sob5.gen samples(2**20)
>>> y = keister.f(x)
>>> mu hat = y.mean()
>>> mu hat
1.1353362571289711
```

Stopping Criterion: Determine n so $|\mu - \hat{\mu}_n| < \epsilon$

```
>>> data
Samples n required for
                                      LDTransformData
                                           solution
                                                               1.135
           Monte Carlo: \mathcal{O}(\epsilon^{-2})
                                           error bound
                                                               9.69e - 05
     Quasi-Monte Carlo: \mathcal{O}(\epsilon^{-1})
                                          n_{total}
                                                               2^(20)
                                           time integrate
                                                               0.611
QMC is significantly more efficient!
                                     CubQMCSobolG
                                           abs_tol
                                                               1.00e - 04
                                           rel tol
                                                               0
Sobol' Cubature Example [2]
                                     Gaussian
>>> sc = qp.CubQMCSobolG(
                                           mean
          integrand = keister,
                                                               2^(-1)
                                           covariance
          abs_tol = 1e-4)
                                     Sobol
. . .
>>> sol,data = sc.integrate()
                                          Ы
                                                               5
                                           randomize
```

QMC Beats MC

Standard Keister Integrand in 5 Dimensions



Future Work

Develop support for

- vectorized stopping criteria $\mathbf{f} = (f_1, \dots, f_{\tilde{d}})$
- combined error bounds
 - $\mu = \mu_1/\mu_2 = \int_{[0,1]^d} f_1(x) dx / \int_{[0,1]^d} f_2(x) dx$
 - Sobol'/sensitivity indices
- higher order digital nets and stopping criteria
- other package components
 - PyTorch's generators
 - SciPy's measures
 - TF Quant Finance's integrands

QMCPy Resources

- PyPI: pypi.org/project/qmcpy/
- GitHub: github.com/QMCSoftware/QMCSoftware
- Documentation: qmcpy.readthedocs.io
- Blogs: qmcpy.org
- MCQMC2020 Tutorial
 - Slides: qmcpy.org/mcqmc-2020-tutorial/
 - Notebook: tinyurl.com/QMCPyTutorial
 - "Quasi-Monte Carlo Software" Article [3]



References

- 1. Keister, B. D. Multidimensional Quadrature Algorithms. *Computers in Physics* **10**, 119–122 (1996).
- 2. Hickernell, F. J. & Jiménez Rugama, L. A. Reliable Adaptive Cubature Using Digital Sequences. 2014. arXiv: 1410.8615 [math.NA].
- Choi, S.-C. T., Hickernell, F. J., Jagadeeswaran, R., McCourt, M. J. & Sorokin, A. G. *Quasi-Monte Carlo Software*. arXiv:2102.07833 [cs.MS]. 2021. arXiv: 2102.07833 [cs.MS].