## https://aliosmanulusoy.github.io/

EDUCATION	Post-doctoral researcher, MPI for Intelligent Systems Advised by Michael J. Black and Andreas Geiger. Research on 3D reconstruction and 3D deep learning.	2014-2017
	<ul><li>Ph.D. in Engineering, Brown University</li><li>Advised by Joseph L. Mundy.</li><li>Research on probabilistic methods for 3D reconstruction.</li></ul>	2008-2014
	Sc.M. in Applied Mathematics, Brown University Coursework on probability and statistics.	2008-2011
	<b>B.S.</b> in Computer Engineering, Bilkent University CGPA 3.88/4.0, graduated 3rd out of $\tilde{1}50$ students.	2004-2008
Employment History	Microsoft HoloLens (Redmond, WA).  Senior Scientist - Localization and mapping for Azure Spatial Anchors.  Scientist II - Surface reconstruction and scene understanding.	2019-now 2017-2019
	Vision Systems Inc. (Providence, RI) Research scientist. Computer Vision start-up led by Prof. Joseph L. Mundy.	Summer 2014
	Vistek (Istanbul, Turkey) Software engineering intern. Computer Vision start-up led by Prof. Aytül Erçil.	Summer 2014
	Siemens (Istanbul, Turkey). Software engineering intern.	Summer 2006
Honors and Awards	International Conf. on 3D Vision (3DV) Best Paper Award	2015
	Outstanding Reviewer Awards Computer Vision and Pattern Recognition (CVPR) European Conference on Computer Vision (ECCV)	2017, 2018, 2019 2016
	NVIDIA Hardware Donation - A Nvidia Tesla K20c graphics card	2013
Publications	Please find my publications at https://aliosmanulusoy.github.io/.	
ACADEMIC SERVICE	Phd Thesis committee Kumar Shaurya Shankar - Robotics Institute, Carnegie Mellon Univers	ity 2020
	Reviewer Conf. on Computer Vision and Pattern Recognition (CVPR) European Conference on Computer Vision (ECCV) Conf. on 3D Vision (3DV) ACM SIGGRAPH ASIA	2016 - present 2016 2017, 2018 2016

	Transactions on Pattern Recognition and Machine Intelligence	2018, 2019 2018, 2020 2013, 2014
	Organizer, Workshop on Computer Vision Applications for Mixed Reality Headsets, he junction CVPR	eld in con- 2019
Invited Talks and Posters	Patches, Planes and Probabilities: A Non-local Prior for Volumetric 3D Recons Lines, Planes and Manhattan Models for 3-D Mapping Workshop at IROS 2017	truction
	Towards Probabilistic Volumetric Reconstruction using Ray Potentials Microsoft International Workshop on Computer Vision University of North Carolina at Chapel Hill	2017 2016 2015
	Probabilistic and Volumetric Reconstruction of Time-Varying 3-d Scenes MPI Intelligent Systems - ETH Learning Systems Workshop Harvard University GE Global Research Center	2015 2015 2014
	Image-based 4-d Modeling Using 3-d Change Detection MIT Vision Systems Inc.	2014 2013
	Probabilistic and Volumetric Reconstruction of General Dynamic 3-d Scenes, Greater New York Area Multimedia and Vision Meeting	2013