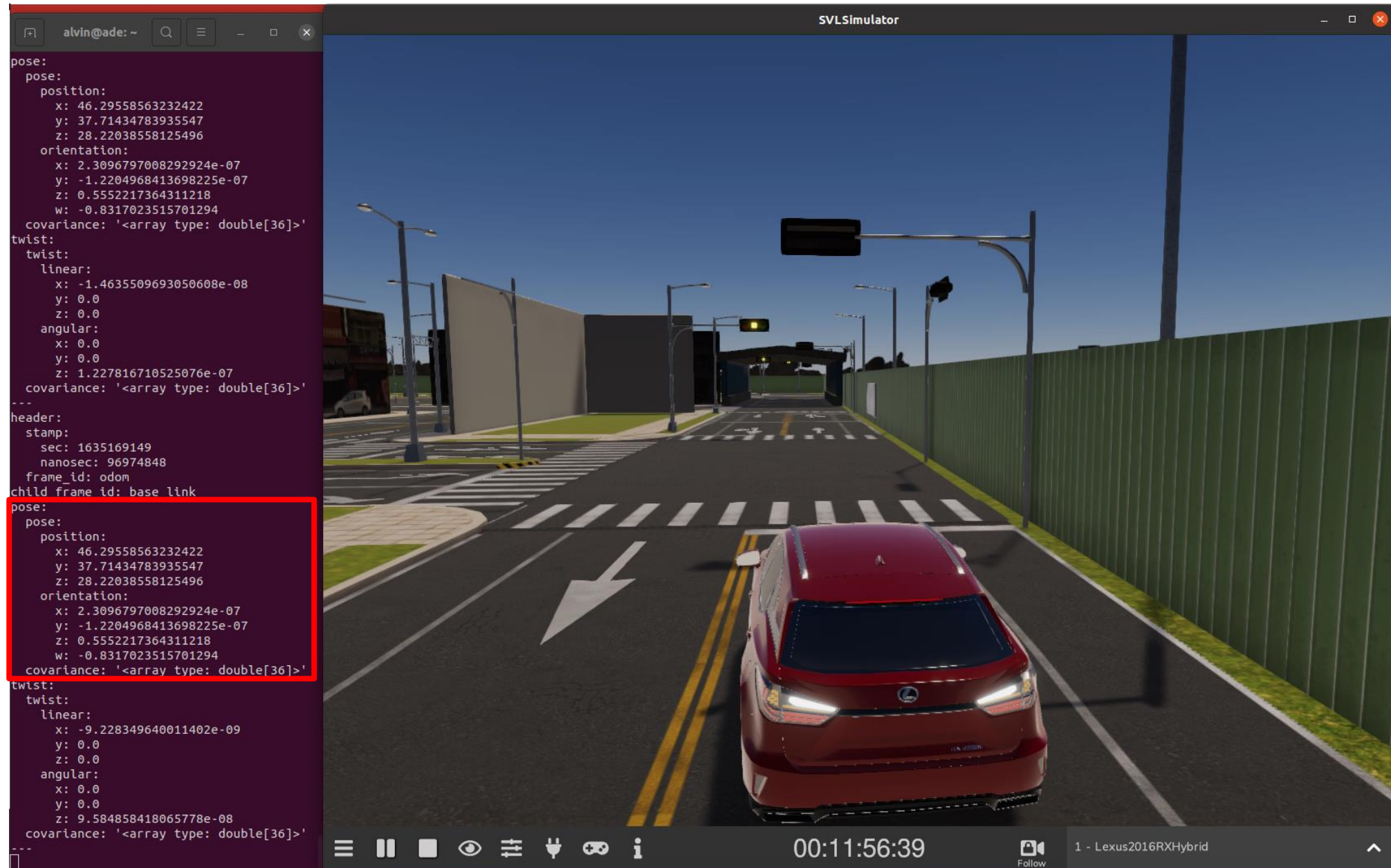


Lab 2 - Simulator


r09921006 莊志淵

Location #1

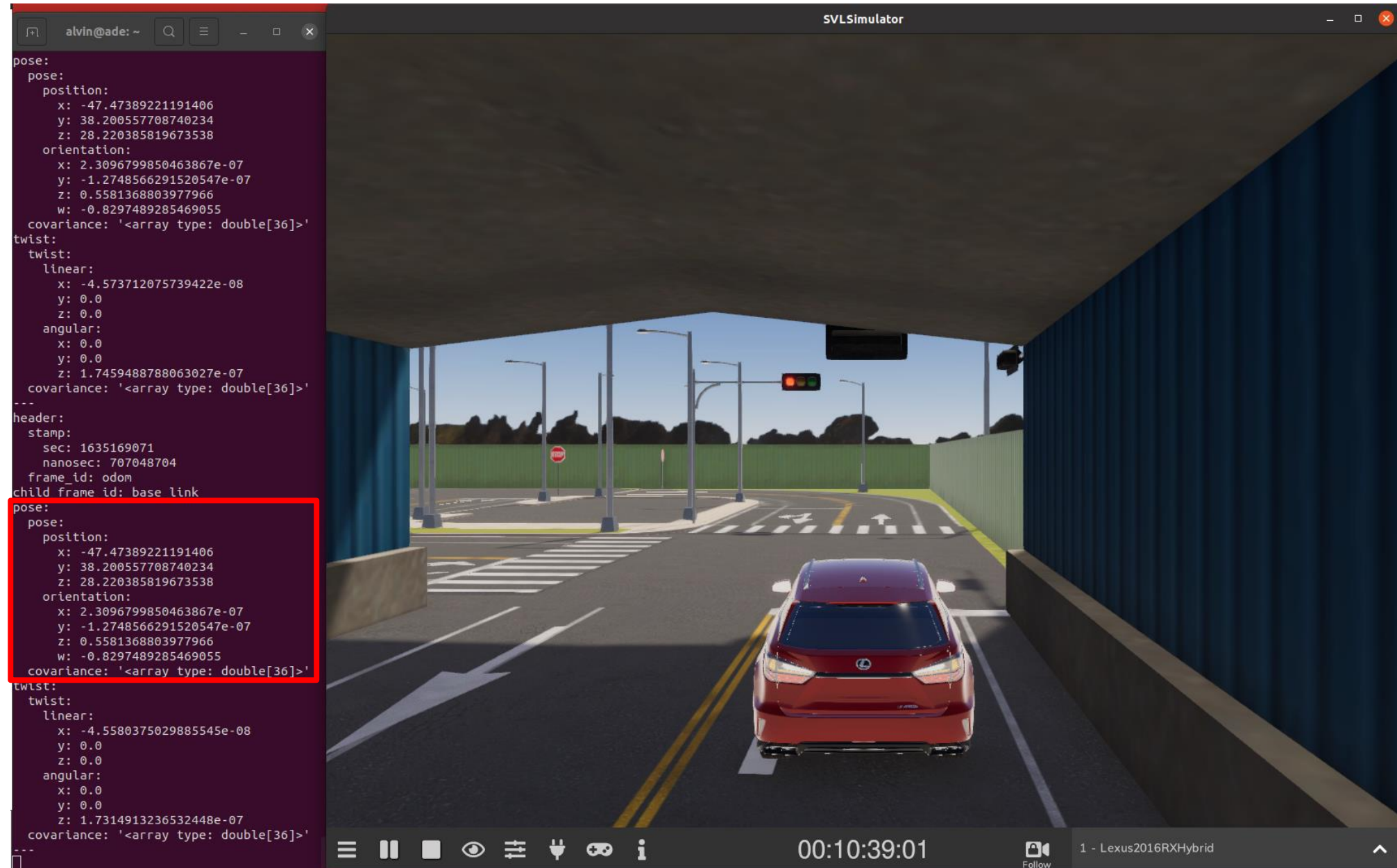


Location #2

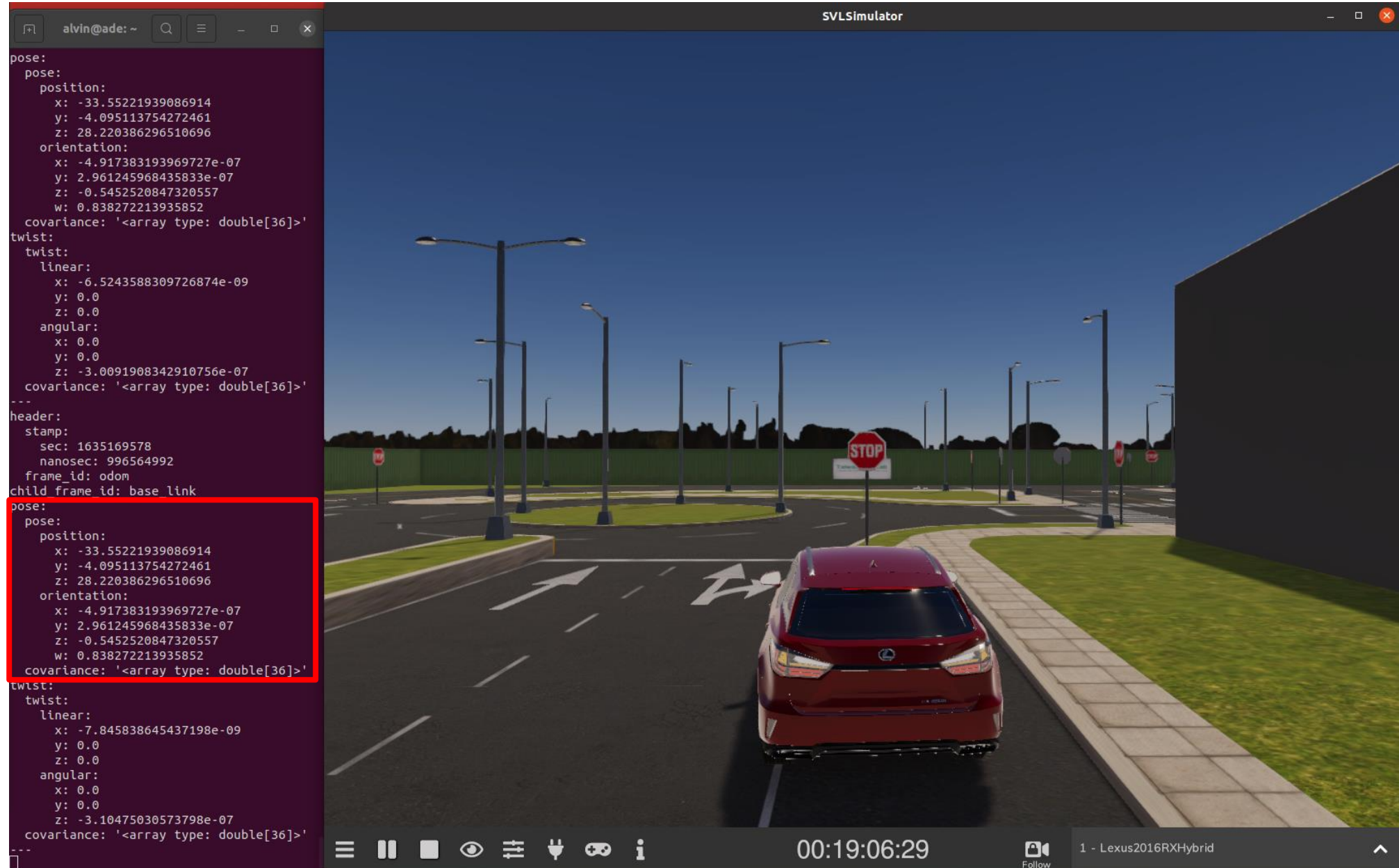
```
pose:
  pose:
    position:
      x: 10.587384223937988
      y: 15.747596740722656
      z: 28.220386505126953
    orientation:
      x: -2.3096797008292924e-07
      y: 1.2690749429111747e-07
      z: -0.5724284648895264
      w: 0.8199546933174133
  covariance: '<array type: double[36]>'
twist:
  twist:
    linear:
      x: -9.449941273942386e-09
      y: 0.0
      z: 0.0
    angular:
      x: 0.0
      y: 0.0
      z: 1.0010489859269e-07
  covariance: '<array type: double[36]>'
---
header:
  stamp:
    sec: 1635169443
    nanosec: 696694016
  frame_id: odom
  child frame id: base link
pose:
  pose:
    position:
      x: 10.587384223937988
      y: 15.747596740722656
      z: 28.220386505126953
    orientation:
      x: -2.3096797008292924e-07
      y: 1.2690749429111747e-07
      z: -0.5724284648895264
      w: 0.8199546933174133
  covariance: '<array type: double[36]>'
twist:
  twist:
    linear:
      x: -8.562929032507327e-09
      y: 0.0
      z: 0.0
    angular:
      x: 0.0
      y: 0.0
      z: 9.687603608199424e-08
  covariance: '<array type: double[36]>'
---
```



Location #3



Location #4



Location #5

