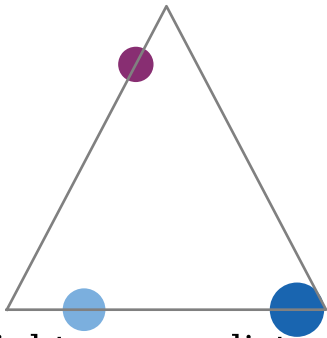


r_lanechange



r_freeright

r_distancefront