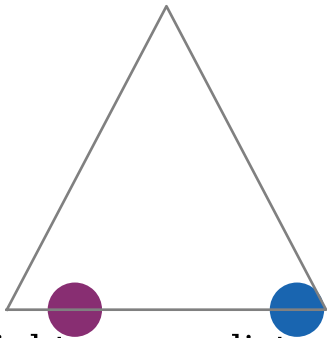


r_lanechange



$r_{\text{freeright}}$

$r_{\text{distancefront}}$