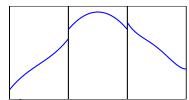
Amath 574

Local P-adaptivity with the Discontinuous Galerkin Method

Devin Light Scott Moe

March 13th, 2015

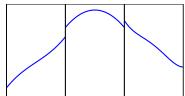




Conservation law weak form:

Multiply by test function:

$$\frac{1}{2} \int_{-1}^{1} \varphi^{(\ell)} \Big\{ q_{,t} + f(q)_{,x} \Big\} d\xi = 0$$



Conservation law weak form:

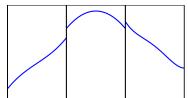
Multiply by test function:

$$\frac{1}{2} \int_{-1}^{1} \varphi^{(\ell)} \Big\{ q_{,t} + f(q)_{,x} \Big\} d\xi = 0$$

Integrate by parts

$$\frac{1}{2} \int_{-1}^{1} \varphi^{(\ell)} q_{,t} d\xi = \frac{1}{\Delta x} \left(\int_{-1}^{1} f\left(q^{h}\right) \varphi_{\xi}^{(k)} d\xi - \left[(\varphi^{(k)} f(q))|_{\xi=1} - (\varphi^{(k)} f(q))|_{\xi=-1} \right] \right)$$





Conservation law weak form:

Multiply by test function:

$$\frac{1}{2} \int_{-1}^{1} \varphi^{(\ell)} \Big\{ q_{,t} + f(q)_{,x} \Big\} \, d\xi = 0$$

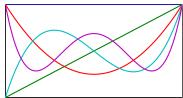
Integrate by parts

$$\frac{1}{2} \int_{-1}^{1} \varphi^{(\ell)} q_{,t} d\xi = \frac{1}{\Delta x} \left(\int_{-1}^{1} f\left(q^{h}\right) \varphi_{\xi}^{(k)} d\xi - \left[(\varphi^{(k)} f(q))|_{\xi=1} - (\varphi^{(k)} f(q))|_{\xi=-1} \right] \right)$$

■ Galerkin ansatz:

$$q(t,\xi) \sim \sum_{k=0}^{N} Q^{(k)}(t) \, \varphi^{(k)}(\xi)$$

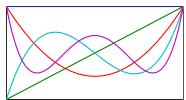




Conservation law weak form:

■ Use an Orthogonal Basis:

$$\frac{1}{2} \int_{-1}^{1} \varphi^{(\ell)} q_{,t} = \frac{1}{2k+1} \dot{Q}^{(k)}$$



Conservation law weak form:

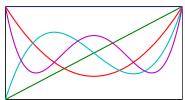
■ Use an Orthogonal Basis:

$$rac{1}{2} \int_{-1}^{1} arphi^{(\ell)} q_{,t} = rac{1}{2k+1} \dot{Q}^{(k)}$$

Semi-discrete:

$$\dot{Q}_{i}^{(k)} = \frac{2k+1}{\Delta x} \int_{-1}^{1} f\left(q^{h}\right) \varphi_{\xi}^{(k)} d\xi - \frac{2k+1}{\Delta x} \left[\varphi^{(k)}(1) F_{i+\frac{1}{2}} - \varphi^{(k)}(-1) F_{i-\frac{1}{2}}\right]$$





Conservation law weak form:

■ Use an Orthogonal Basis:

$$rac{1}{2} \int_{-1}^{1} arphi^{(\ell)} q_{,t} = rac{1}{2k+1} \dot{Q}^{(k)}$$

Semi-discrete:

$$\dot{Q}_{i}^{(k)} = \frac{2k+1}{\Delta x} \int_{-1}^{1} f\left(q^{h}\right) \varphi_{\xi}^{(k)} d\xi - \frac{2k+1}{\Delta x} \left[\varphi^{(k)}(1) F_{i+\frac{1}{2}} - \varphi^{(k)}(-1) F_{i-\frac{1}{2}}\right]$$

• For k = 0:

$$\dot{Q}_{i}^{(0)} = -\frac{1}{\Delta x} \left[F_{i+\frac{1}{2}} - F_{i-\frac{1}{2}} \right]$$



Orthogonal Series

- For continuous functions series coefficients converge.
- Coefficients give us a proxy for error.



Convergence of Orthogonal Series to |x|

10⁰

Orthogonal Series

- For continuous functions series coefficients converge.
- Coefficients give us a proxy for error.
- Small coefficients have little effect on our solution.



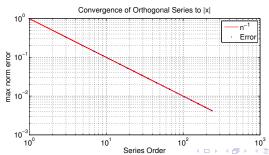
Convergence of Orthogonal Series to |x|

10⁰

Orthogonal Series

- For continuous functions series coefficients converge.
- Coefficients give us a proxy for error.
- Small coefficients have little effect on our solution. If f has a derivative ν of bounded variation

$$||f-f_p|| \leq \sum_{i=p+1}^{\infty} |c_k \varphi^{(k)}(\xi)| \leq \frac{1}{\nu(p-\nu)^{\nu}}$$



hp-Adaptivity

- Discretize domain with cells of size h
- h-adaptivity → Adaptive Mesh Refinement

hp-Adaptivity

- Discretize domain with cells of size h
- h-adaptivity → Adaptive Mesh Refinement
- Discretize using piecewise continuous polynomials of order p.
- lacktriangledown p-adaptivity ightarrow Add higher order polynomials:

$$q(t,\xi) = \sum_{k=0}^{p} Q^{(k)}(t) \varphi^{(k)}(\xi)$$

hp-Adaptivity

- Discretize domain with cells of size h
- h-adaptivity → Adaptive Mesh Refinement
- Discretize using piecewise continuous polynomials of order p.
- p-adaptivity → Add higher order polynomials:

$$q(t,\xi) = \sum_{k=0}^{p} Q^{(k)}(t) \varphi^{(k)}(\xi)$$

■ For smooth functions: higher order polynomials → MUCH better approximation



■ For DG p can be different on each cell

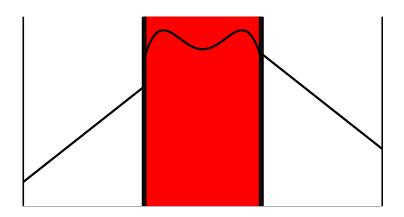


- For DG p can be different on each cell
- The highest coefficient gives an indication of error on each cell
- Each coefficient requires extra work

- For DG p can be different on each cell
- The highest coefficient gives an indication of error on each cell
- Each coefficient requires extra work
- Idea:
 - 1 Very small coefficients \rightarrow can be ignored
 - **2** Large coefficients \rightarrow need more resolution

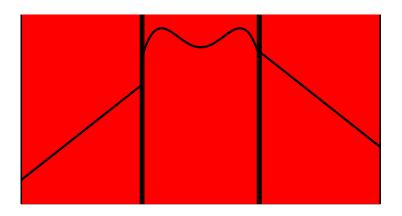
- For DG p can be different on each cell
- The highest coefficient gives an indication of error on each cell
- Each coefficient requires extra work
- Idea:
 - 1 Very small coefficients \rightarrow can be ignored
 - **2** Large coefficients \rightarrow need more resolution
- This is complicated by the PDE
 - All PDEs propagate information
 - Hyperbolic PDEs \rightarrow propagation speed is finite
 - 3 Cells with high-order neighbors may soon become high-order

Buffer Regions





Buffer Regions



Pick a maximum order p_M and project initial conditions Our p-adaptive algorithm:

Pick a maximum order p_M and project initial conditions

Our p-adaptive algorithm:

1 Eliminate coefficients below a tolerance ϵ

Pick a maximum order p_M and project initial conditions

Our p-adaptive algorithm:

- $lue{1}$ Eliminate coefficients below a tolerance ϵ
- Determine time-interval between local order modifications
- **Set buffer region (determined from characteristic speeds)**



Pick a maximum order p_M and project initial conditions

Our p-adaptive algorithm:

- $lue{1}$ Eliminate coefficients below a tolerance ϵ
- Determine time-interval between local order modifications
- **3** Set buffer region (determined from characteristic speeds)
- 4 Evolve coefficients over the interval



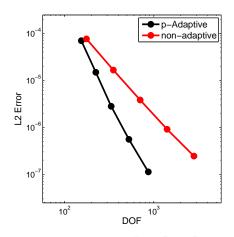
Pick a maximum order p_M and project initial conditions

Our p-adaptive algorithm:

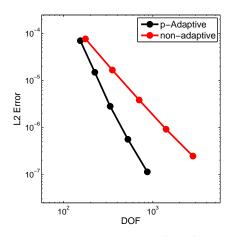
- f I Eliminate coefficients below a tolerance ϵ
- Determine time-interval between local order modifications
- Set buffer region (determined from characteristic speeds)
- 4 Evolve coefficients over the interval
- 5 Repeat until we have reached the final time



Both methods similarly accurate

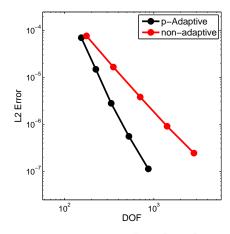


Both methods similarly accurate p-Adaptive uses less DOFs!

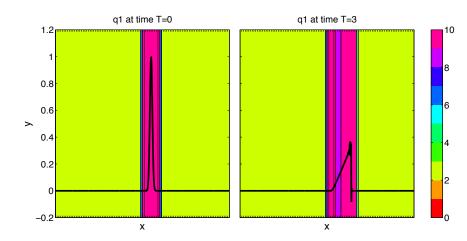


Both methods similarly accurate p-Adaptive uses less DOFs!

Less DOFs \rightarrow Less CPU time



Burger's Equation



Conclusions

- Modifying local polynomial degree can be an efficient method of adding/removing DOFs in problems which demand efficiency
 - Atmospheric modeling, Seismology, etc..

Conclusions

- Modifying local polynomial degree can be an efficient method of adding/removing DOFs in problems which demand efficiency
 - Atmospheric modeling, Seismology, etc..
- 2 Works best where solution is smooth
 - Coefficients decay quickly

Conclusions

- Modifying local polynomial degree can be an efficient method of adding/removing DOFs in problems which demand efficiency
 - Atmospheric modeling, Seismology, etc..
- 2 Works best where solution is smooth
 - Coefficients decay quickly
- 3 Not as great where solutions are discontinuous
 - Coefficients decay slowly

The Future

- Local high order time stepping (Local Lax-Wendroff method)
- Simultaneous h-p adaptivity
- 3 Limiting?
- 4 Adaptive quadrature



References

- J.-F. Remacle, J. E. Flaherty, and M. S. Shephard, "An adaptive discontinuous galerkin technique with an orthogonal basis applied to compressible flow problems," *SIAM review*, vol. 45, no. 1, pp. 53–72, 2003.
- [2] M. J. Berger and R. J. LeVeque, "Adaptive mesh refinement using wave-propagation algorithms for hyperbolic systems," *SIAM Journal on Numerical Analysis*, vol. 35, no. 6, pp. 2298–2316, 1998.
- [3] C. Eskilsson, "An hp-adaptive discontinuous galerkin method for shallow water flows," *International Journal for Numerical Methods in Fluids*, vol. 67, no. 11, pp. 1605–1623, 2011.
- [4] G. Tumolo, L. Bonaventura, and M. Restelli, "A semi-implicit, semi-lagrangian, p-adaptive discontinuous galerkin method for the shallow water equations," *Journal of Computational Physics*, vol. 232, no. 1, pp. 46–67, 2013.

Thank you!

Questions?

