2000 Hz

Example Linear Phase FIR Filter Design Using the Optimal Method (Mitra, 7.10)

```
% Mitra, Example 7.27
 % Design of Lowpass Filter with the following specs
                       % passband ripple in dB
Ap = 0.5;
As = 40.0;
                       % stopband ripple in dB
Fp = 800.0;
                       % pass frquency in Hz
                                                                         800 Hz 1000 Hz
                       % stop frquency in Hz
Fs = 1000.0;
FT = 4000.0;
                       % sampling frquency in Hz
%
                       % delta_p, or delta_1 = 0.055939
dp = 1-10^{(-Ap/20)};
ds=10^{(-As/20)};
                       % delta_s, or delta_2 = 0.01
dw=2*pi*(Fs-Fp)/FT;
% estimate filter order using empirical formula (Lec #17, p. 9)
M1 = ceil((-10.0*log10(dp*ds)-13.0)/(2.324*dw)) % Gives M1 = 27 (Type 2)
% or estimate filter order using the more accurate remezord function
                      % band edges in Hz
fedge = [Fp Fs];
Hd = [1 \ 0]; % ideal Hd in each band
                      % delta in each band
deltas=[dp ds];
[M2, FN, Hmag, Wt] = remezord(fedge, Hd, deltas, FT)
% The output values prepare for the filter design using remez
% M2 is the filter order = 28 (a more accurate estimate; Type 1)
% FN = F/FT/2 of band edges (Matlab normalizes all frequencies by FT/2) = [0 0.4 0.5 1]
% Hmag is the desired magnitude vector at FN = [1 \ 1 \ 0 \ 0]
% Wt is the weight vector = [1.0 5.5939];
%
% Design the filter using remez
b = remez(M2, FN, Hmag, Wt);
% Check the design
```

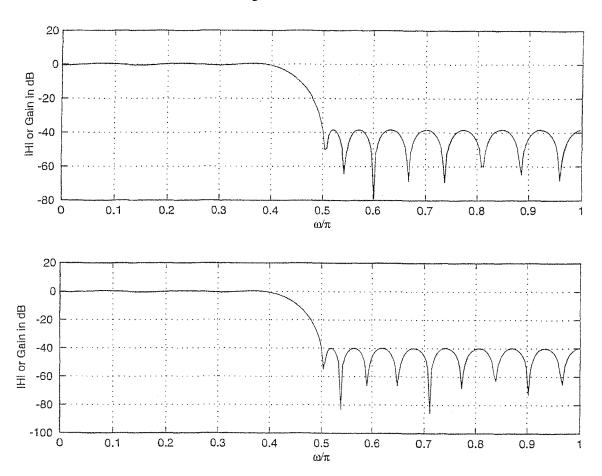
subplot(2,1,1)
[H,w]=freqz(b,1,256);
plot(w/pi, 20*log10(abs(H))), grid
xlabel('\omega\pi'), ylabel('lHl or Gain in dB')

% Both Ap and As specs are not met (see also Fig. 7.33 of Mitra)
% need to increase the filter order and try again
%

M2= 30;
b = remez(M2, FN, Hmag, Wt);

subplot(2,1,2)
[H,w]=freqz(b,1,256);
plot(w/pi, 20*log10(abs(H))), grid
xlabel('\omega\pi'), ylabel('lHl or Gain in dB')
subplot

% Looks Ok now (see also Mitra, Fig. 7.34)

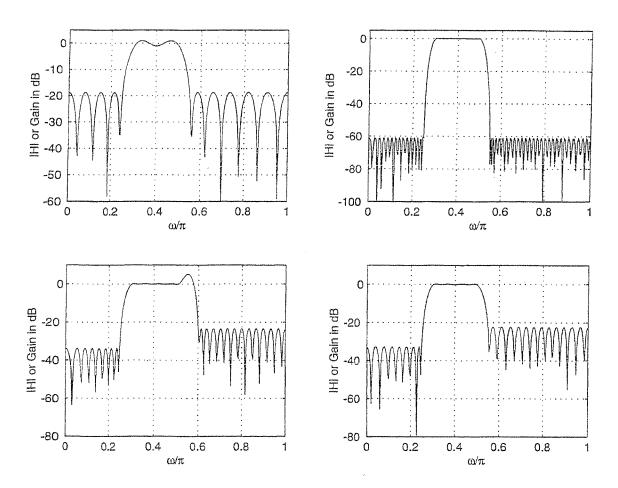


```
% Mitra 7.28 and 7.29. Design of Bandpass Filter
 M=26; % compouted from specs using remezord (details skipped here)
 FN=[0 0.25 0.3 0.5 0.55 1];
                                      % Band edges F(Hz)/(FT(Hz)/2)
 Hmag=[0 \ 0 \ 1 \ 1 \ 0 \ 0];
                                      % ideal H at frequence edges FN
 Wt=[1]
                                      % weight vector in each band
             1
                   1];
 b = remez(M, FN, Hmag, Wt);
 % Check the design
 subplot(2,1,1)
 [H,w] = freqz(b,1,256);
 plot(w/pi, 20*log10(abs(H))), grid
 axis([0 \ 1 \ -60 \ 5]);
                                                                0.25 0.3 0.5 0.55
 xlabel('\omega\pi'), ylabel('|H| or Gain in dB')
                                                                                            F/F_5/2)
% Larger Filter order yields better performance
% largere stop band attenuation As and sharper transitions between bands
% Can also control deltas in different bands
M=110;
Wt = [1 \ 0.1 \ 1];
b = remez(M, FN, Hmag, Wt);
subplot(2,1,2)
[H,w] = freqz(b,1,256);
plot(w/pi, 20*log10(abs(H))), grid
axis([0 \ 1 \ -100 \ 5]);
subplot
% Unexpected behavior can occur in the transition bands ("don't care" regions)
M=60;
FN=[0 0.25 0.3 0.5 0.6 1];
Hmag=[0 \ 0 \ 1]
                 1 0 0];
Wt=[1]
                   0.3];
             1
b = remez(M, FN, Hmag, Wt);
subplot(2,2,3)
[H,w] = freqz(b,1,256);
plot(w/pi, 20*log10(abs(H))), grid
xlabel('\omega\pi'), ylabel('lHl or Gain in dB')
axis([0 1 -80 10]);
subplot
```

% A slight adjustment in filter order or band edges can yield acceptable behavior

```
FN=[0\ 0.25\ 0.3\ 0.5\ 0.55\ 1]; \\ b=remez(M,\ FN,\ Hmag,\ Wt); \\ % 0.6 changed to 0.55 (sharper transition)
```

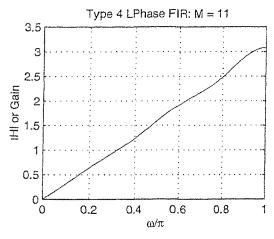
subplot(2,2,4)
[H,w]=freqz(b,1,256);
plot(w/pi, 20*log10(abs(H))), grid
xlabel('\omega\pi'), ylabel('|H| or Gain in dB')
axis([0 1 -80 10]);
subplot

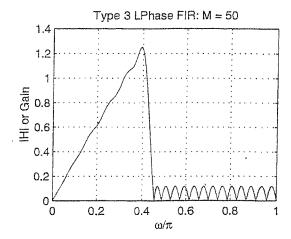


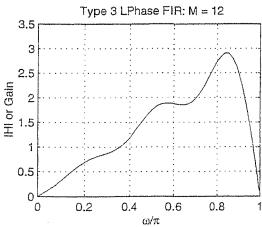
```
% Mitra Examples 7.30 and 7.31: Design of Differentiators
clear, close all
                              % Type 4; has a zero at w = 0 which is OK
M = 11;
FN = [0 \ 1];
Hmag = pi*[0 1];
                                                      |H(e^{j\omega})|
b=remez(M,FN,Hmag,'differentiator');
subplot(2,2,1)
[H,w] = freqz(b,1,256);
plot(w/pi, abs(H)), grid
xlabel('\omega/\pi'), ylabel('lH| or Gain')
title(['Type 4 LPhase FIR: M = ',num2str(M)])
                                                                O
axis([0 1 0 3.5]);
% See also Fig. 7.38 of Mitra
% Can use Type 3, but must accept a zero |H| at w = pi
                              % Type 3; has a zero at w = pi
M = 12:
FN = [0 \ 0.9];
Hmag = pi*[0 0.9];
b=remez(M,FN,Hmag,'differentiator');
subplot(2,2,2)
[H,w] = freqz(b,1,256);
plot(w/pi, abs(H)), grid
xlabel('\omega\pi'), ylabel('|H| or Gain')
title([Type 3 LPhase FIR: M = ',num2str(M)])
axis([0 1 0 3.5]);
% For the case of noisy signals, differentiators amplify the noise in
% the high frequency band outside the signal bandwidth. It's important
% therefore to limit a differentiator bandwidth to the signal bandwidth
%
                % a high order filter yields smaller fluctuations and sharper transition
FN = [0 \ 0.4 \ 0.45 \ 1]; \ \% \ 0.4 = (Matlab) Normalized bandwidth = B(Hz)/(FT(Hz)/2)
Hmag = pi*[0 0.4 0 0];
b=remez(M,FN,Hmag,'differentiator');
```

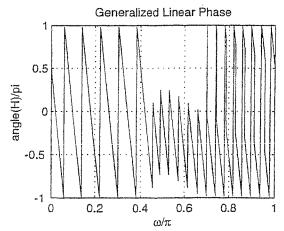
subplot(2,2,3)
[H,w]=freqz(b,1,1024);
plot(w/pi, abs(H)), grid
xlabel('\omega\pi'), ylabel('|H| or Gain')
title(['Type 3 LPhase FIR: M = ',num2str(M)])
axis([0 1 0 1.4]);

subplot(2,2,4)
plot(w/pi, angle(H)/pi), grid
xlabel('\omega\pi'), ylabel('angle(H)/pi')
title(['Generalized Linear Phase'])
axis([0 1 -1 1]);









```
% Mitra Examples 7.32: Design of Hilbert Transformers
 %
% Same Ideas
                                                                       Hilbert
clear, close all
M = 20;
FN = [0.1 \ 0.9];
Hmag = [1 1];
                                                        00.1
                                                                                      0.91
b=remez(M,FN,Hmag,'Hilbert');
                                                                                          F/(F5/2)
subplot(2,2,1)
[H,w] = freqz(b,1,1024);
plot(w/pi, abs(H)), grid
xlabel('\omega/\pi'), ylabel('!Hl or Gain')
title(['Hilbert Transformer'])
axis([0 1 0 1.2]);
subplot(2,2,3)
plot(w/pi, angle(H)/pi), grid
xlabel('\omega\\pi'), ylabel('angle(H)/pi ')
title(['Generalized Linear Phase'])
axis([0 1 -1 1]);
%
% Trying to force sharper transitions may yield larger ripples
M = 20;
FN = [0.05 \ 0.95];
Hmag = [1]
              1];
b=remez(M,FN,Hmag,'Hilbert');
subplot(2,2,2)
[H,w] = freqz(b,1,1024);
plot(w/pi, abs(H)), grid
xlabel('\omega/\pi'), ylabel('lHl or Gain')
title(['Hilbert Transformer: Type 3'])
axis([0 1 0 1.2]);
```

% Will Type 4 filter also work?

% Note again that the optimal method does not control the bahavior of H % over the transitions bands.

M = 21; FN = [0.05 0.95]; Hmag = [1 1];

b=remez(M,FN,Hmag,'Hilbert');

subplot(2,2,4)
[H,w]=freqz(b,1,1024);
plot(w/pi, abs(H)), grid
xlabel(\omega\pi'), ylabel('|H| or Gain')
title(['Hilbert Transformer: Type 4'])
axis([0 1 0 1.2]);

