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% EE254
                                                                  Prof. Essam Marouf
% DSP II
                                                                  Matlab Handout #1
% Models of Random Signals
%
% 1) White Gaussian Noise Model
clear, close all
N=300:
                                            % number of samples
n=[1:N];
                                            % discrete-time sample index
%
% Generate four 1xN realizations of a white noise vector (zero mean, standard dev = 0.3)
% and store in the rows of matrix X
sigma v=0.3:
for k=1:4,
x(k,:)=sigma_v*randn(size(n));
                                            % each new call to rand reseeds the random
                                            % number generator
end
% plot the four signal realizatons displaced 2 unit along the vertical axis
plot(n,x(1,:),n,x(2,:)+2,n,x(3,:)+4,n,x(4,:)+6),
xlabel('Sample, n'), ylabel('x(n)'),
title('White Noise Realizations')
pause
                                 White Noise Realizations
                                100
                                            150
                                                                              300
                                                       200
                                                                   250
                                         Sample, n
% 2) AR(2) Signal Model: Filter 1
% ------
                                            % All-pole IIR Filter Coefficients
a=[1 -0.1 -0.8];
b=1;
c=roots(a)
       C =
                0.9458
               -0.8458
% This filter emphasizes low frequencies at its output; this may be
% seen from a plot of its amplitude response:
nn=256;
                                            \% 0 \le w \le pi (digital frequency)
[H,w]=freqz(b,a,nn);
                                     % plot of |H| (amplitude response)
plot (w/pi, abs(H), '-')
xlabel('Normalized Frequency, w(rad)/pi'),
ylabel(|H|), title (Filter 1: b=1, a=[1 -0.1 -0.8])
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pause
%
% The AR(2) signal models are generated by filtering the white noise
% through the filter above
for k=1:4.
y1(k,:)=filter(b,a,x(k,:));
end
% plot the four signal realizatons displaced 2 unit along the vertical axis
plot(n,y1(1,:),n,y1(2,:)+2,n,y1(3,:)+4,n,y1(4,:)+6),
xlabel('Sample, n'), ylabel('y(n)'),
title('AR(2) Signal Realizations: a=[1 -0.1 -0.8]')
pause
% Autocorrelation Function rxx(m) (see lecture notes)
rxx(1)=sigma v^2/(1-a(3)^2-(a(2)^2*(1-a(3))/(1+a(3)));
% rxx(1) is really rxx(0), a(2) is a(1), ...etc; Matlab indices start from 1
rxx(2)=rxx(1)*(-a(2))/(1+a(3));
NN=101:
for m=3:NN;
 rxx(m)=-a(2)*rxx(m-1)-a(3)*rxx(m-2);
plot([0:NN-1], rxx,'+',[0:NN-1], rxx,'-')
xlabel('m'), ylabel('rxx(m)'),
title('Autocorrelation Function: a=[1 -0.1 -0.8]') ,pause
% AR(2) Signal Model: Filter 2
% -----
a=[1\ 0.1\ -0.8];
b=1;
c=roots(a)
C =
     -0.9458
      0.8458
% Again, two real roots.
% This filter emphasizes high frequencies at its output; this may be
% seen from a plot of its amplitude response:
% ......Code is the same as before; omitted for brevity
% AR(2) Signal Model: Filter 3
% -----
a=[1 -0.975 0.95];
b=1:
c=roots(a)
C =
    0.4875 + 0.8440i
    0.4875 - 0.8440i
% Complex conjugate pole pair (Bandpass filter).
% ......Code is the same as before; omitted for brevity
```







