

F2806x USB Bootloader

USER'S GUIDE



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1 Introduction

The Texas Instruments® boot loader is a small piece of code that can be programmed in flash to act as an application loader as well as an update mechanism for applications running on a C2000 microcontroller. The boot loader is designed to upgrade the application using the USB Device Firmware Upgrade (DFU) mechanism. The boot loader is customizable via source code modifications, or simply deciding at compile time which routines to include. Since full source code is provided, the boot loader can be completely customized.

Source Code Overview

The following is an overview of the organization of the source code provided with the boot loader.

<code>aes_config_opts.h</code>	Configuration header for aes encryption and decryptions routines.
<code>bl_entrytable.asm</code>	Bootloader and Application Entry points.
<code>bl_check.c</code>	The code to check if a firmware update is required, or if a firmware update is being requested by the user.
<code>bl_check.h</code>	Prototypes for the update check code.
<code>bl_commands.h</code>	The list of commands and return messages supported by the boot loader.
<code>bl_config.h</code>	A template for the boot loader configuration file. This contains all of the possible configuration values.
<code>bl_decrypt.c</code>	The code to perform an in-place decryption of the downloaded firmware image. No decryption is actually performed in this file; this is simply a stub that can be expanded to perform the require decryption.
<code>bl_decrypt.h</code>	Prototypes for the in-place decryption routines.
<code>bl_hooks.h</code>	Provides hooks for user supplied functions.
<code>bl_sym.h</code>	C prototypes for linker and assembly symbols.
<code>bl_usb.c</code>	Main functions implementing the USB DFU protocol boot loader.
<code>bl_usbfuncs.c</code>	A cut-down version of the USB library containing support for enumeration and the endpoint 0 transactions required to implement the USB DFU device.
<code>bl_usbfuncs.h</code>	Prototypes for the functions provided in <code>bl_usbfuncs.c</code> .
<code>crc.h</code>	Prototypes CPU and VCU CRC routines.

<code>F2806x_BL_MemCopy.c</code>	Memory copy functions for use in both normal and failsafe boot modes.
<code>F2806x_CodeStartBranch.asm</code>	Special Code start branch that supports two flash entry locations.
<code>F2806x_CSMPasswords.asm</code>	Code Security passwords. ONLY MODIFY IF YOU WANT TO LOCK THE DEVICE!
<code>Flash2806x_API_Config.h</code>	Flash API configuration header.
<code>Flash2806x_API_Library.h</code>	Flash API function prototypes.
<code>usbdfu.h</code>	Type definitions, labels related to the USB Device Firmware Upgrade class boot loader.

Practical Use

This bootloader is an example piece of software and should be treated as a guide on implementing your own or used as a starting point for an end application bootloader. As with any embedded code you should do your best to understand how each piece of the solution works. The bootloader may be used unmodified with end application code that follows the same memory map and structure as the `bl_app` example project.

To evaluate the DFU USB Bootloader example you should follow these steps:

- Import the `boot_loader` and `bl_app` projects into CCS. The projects can be found in `examples\bl_app` and `MWare\boot_loader`.
- Build each of the projects
- Load the bootloader project into the flash of the target device and execute it.
- Connect the target device's USB port to the host PC.
- When Windows asks about drivers, point it to the `boot_usb.inf` driver file found in `MWare\windows_drivers`. Two options will be presented: Select the first if you have a 32 bit system and the second if you are using a 64 bit system.
- Run `dfuprog -e` to enumerate the DFU enabled devices attached to the system. If your device shows up everything is working correctly.
- Run `dfuprog -c` to clear the flash of the target device.
- Run `dfuprog -f bl_app_i.hex` to load the `bl_app` example application to the board. You may optionally append the `-r` option to reset the target device and boot the `bl_app` application after programming is complete.

The bootloader solution requires that the application to be loaded follow a predefined memory map, have entry addresses and application signatures (CRC) at predefined locations that are known by both the bootloader and the end application. The end application must also be passed to the `dfuprog` utility in a special hex image file format. The `bl_app` example automatically does this when the project is built using the `bl_app_hex.cmd`. Please refer to this file for the options one must pass to the `hex2000` utility to correctly generate a hex file for the `dfuprog` software. These specially formatted hex files are the only supported file format for programming the device using the bootloader.

2 Startup Code

The start-up code contains the minimal set of code required to configure a vector table, initialize memory, copy the boot loader from flash to SRAM, and execute from SRAM. The start-up code is contained in `rts2800_bl.lib`, with `F28069_bl.cmd` containing the linker script used to place the vector table, code segment, and data segments into the appropriate locations in memory.

At boot time one of two things can happen depending on how the bootloader is configured. During a normal boot, the typical boot28 assembly code initializes the processor, copies `cinit` and `pinit` and jumps to the bootloader's main function. There the bootloader checks for a valid application or a forced update, and then jumps to the application or starts the bootloader. The bootloader can also be built with a failsafe mode that minimizes chances that the bootloader could be corrupted. If this mode is enabled and the failsafe condition occurs (discussed in greater detail later in this guide), the bootloader will begin execution in the `boot28_f` file and perform the same initializations it would during a normal boot. Instead of jumping to main though the bootloader will enter the `FailsafeEntry` function (found in `bl_usb.c`). By definition there is no application present in the failsafe mode, so the bootloader is immediately started in this case.

The boot loader's code and its corresponding linker script use a memory layout that exists entirely in SRAM. This means that the load address of the code and read-only data are not the same as the execution address. Once the boot loader calls the application, all SRAM becomes usable by the application.

After a reset, the start-up code checks to see if an application update should be performed by calling `CheckForceUpdate()`. If an update is not required, the bootloader then check for a valid application. At a minimum the bootloader must find a valid address at the application entry pointer `pAppEntry`. A secondary CRC check can also optionally be performed using linker generated CRC tables. For more information on linker generated CRC tables please see SPRU513d Assembly Language Tools User Guide. Assuming an update is required, it is at this point that the bootloader kernel is copied from flash to SRAM. After the copy has completed the microcontroller is initialized by calling `ConfigureUSB()` after which the function `UpdaterUSB()` configures the USB interface for device mode.

The check for an application update (in `CheckForceUpdate()`) consists of checking the beginning of the application area and optionally checking the state of a GPIO pin. The GPIO pin check can be enabled with `ENABLE_UPDATE_CHECK` in the `bl_config.h` header file, in which case an update can be forced by changing the state of a GPIO pin (for example, with a push button). If the application is valid and the GPIO pin is not requesting an update, the application is called. Otherwise, an update is started by entering the main loop of the boot loader.

Additionally, the application can call the boot loader in order to perform an application-directed update. In this case, the boot loader assumes that the application has already configured the USB peripheral. This allows the boot loader to use the peripheral as is to perform the update. The boot loader also assumes that the interrupt to the core has been left enabled as well, which means that that application should not call `DINT` before calling the boot loader. Once the application calls the boot loader, the boot loader copies itself to SRAM, branches to the SRAM copy of the boot loader, and starts the update by calling `UpdaterUSB()`. The application should enter the boot-loader via the `AppUpdaterUSB` function whose address can be found via the `pBootEntry` pointer (in `bl_entrytable.asm`).

3 USB Device (DFU) Update

When performing a USB update, the boot loader calls `ConfigureUSB()` to configure the USB controller and prepare the boot loader to update the firmware. The USB update mechanism allows the boot loader to be entered from a functioning application as well as from startup when no application has been downloaded to the microcontroller. The boot loader provides the main routine for performing the USB update in the `UpdaterUSB()` function which is used in both cases.

When the USB boot loader is invoked from a running application, the boot loader will reconfigure the USB controller to publish the required descriptor set for a Device Firmware Upgrade (DFU) class device. If the main application had previously been offering any USB device class, it must remove the device from the bus by calling `USBDevDisconnect()` prior to entering the boot loader.

The USB boot loader also assumes that the main application is using the PLL as the source of the system clock.

The USB boot loader allows a USB host to upgrade the firmware on a USB device. To make use of it, therefore, the board running the boot loader must be capable of acting as a USB device.

3.1 USB Device Firmware Upgrade Overview

The USB boot loader enumerates as a Device Firmware Upgrade (DFU) class device. This standard device class specifies a set of class-specific requests and a state machine that can be used to download and flash firmware images to a device and, optionally, upload the existing firmware image to the USB host. The full specification for the device class can be downloaded from the USB Implementer's Forum web site at http://www.usb.org/developers/devclass_docs#approved.

All communication with the DFU device takes place using the USB control endpoint, endpoint 0. The device publishes a standard device descriptor with vendor, product and device revisions as specified in the `bl_config.h` header file used to build the boot loader binary. It also publishes a single configuration descriptor and a single interface descriptor where the interface class of `0xFE` indicates an application-specific class and the subclass of `0x01` indicates "Device Firmware Upgrade". Attached to the interface descriptor is a DFU Functional Descriptor which provides information to the host on DFU-specific device capabilities such as whether the device can perform upload operations and what the maximum transfer size for upload and download operations is.

DFU functions are initiated by means of a set of class-specific requests. Each request, which follows the standard USB request format, performs some operation and moves the DFU device between a series of well-defined states. Additional requests allow the host to query the current state of the device to determine whether, for example, it is ready to receive the next block of download data.

A DFU device may operation in one of two modes - "Run Time" mode or "DFU" mode. In "Run Time" mode, the device publishes the DFU interface and functional descriptors alongside any other descriptors that the device requires for normal operation. It does not, however, need to respond to any DFU class-specific requests other than `DFU_DETACH` which indicates that it should switch to "DFU" mode.

In "DFU" mode, the device supports all DFU functionality and can perform upload and download operations as specified in its DFU functional descriptor.

The USB boot loader supports only "DFU" mode operation. If an main application wishes to publish DFU descriptors and respond to the `DFU_DETACH` request, it can cause a switch to "DFU" mode on receiving a `DFU_DETACH` request by removing itself from the USB bus using a call to

USBDevDisconnect() before transferring control to the USB boot loader by making a call to [AppUpdaterUSB\(\)](#).

3.1.1 DFU Requests

Requests supported by the USB boot loader are as follow:

DFU_DNLOAD	<p>This OUT request is used to send a block of binary data to the device. The DFU class specification does not define the content and format of the binary data but typically this will be either binary data to be written to some position in the device's flash memory or a device-specific command. The request payload size is constrained by the maximum packet size specified in the DFU functional descriptor. In this implementation, that maximum is set to 1024 bytes.</p> <p>After sending a DFU_DNLOAD request, the host must poll the device status and wait until the state reverts to DNLOAD_IDLE before sending another request. If the host wishes to indicate that it has finished sending download data, it sends a DFU_DNLOAD request with a payload length of 0.</p>
DFU_UPLOAD	<p>This IN request is used to request a block of binary data from the device. The data returned is device-specific but will typically be the contents of a region of the device's flash memory or a device-specific response to a command previously sent via a DFU_DNLOAD request. As with DFU_DNLOAD, the maximum amount of data that can be requested is governed by the maximum packet size specified in the DFU functional descriptor, here 1024 bytes.</p>
DFU_GETSTATUS	<p>This IN request allows the host to query the current status of the DFU device. It is typically used during download operations to determine when it is safe to send the next block of data. Depending upon the state of the DFU device, this request may also trigger a state change. During download, for example, the device enters DNLOAD_SYNC state after receiving a block of data and remains there until the data has been processed and a DFU_GETSTATUS request is received at which point the state changes to DNLOAD_IDLE.</p>
DFU_CLRSTATUS	<p>This request is used to reset any error condition reported by the DFU device. If an error is reported via the response to a DFU_GETSTATUS request, that error condition is cleared when this request is received and the device returns to IDLE state.</p>
DFU_GETSTATE	<p>This IN request is used to query the current state of the device without triggering any state change. The single byte of data returned indicates the current state of the DFU device.</p>

DFU_ABORT	This request is used cancel any partially complete upload or download operation and return the device to IDLE state in preparation for some other request.
-----------	--

3.1.2 DFU States

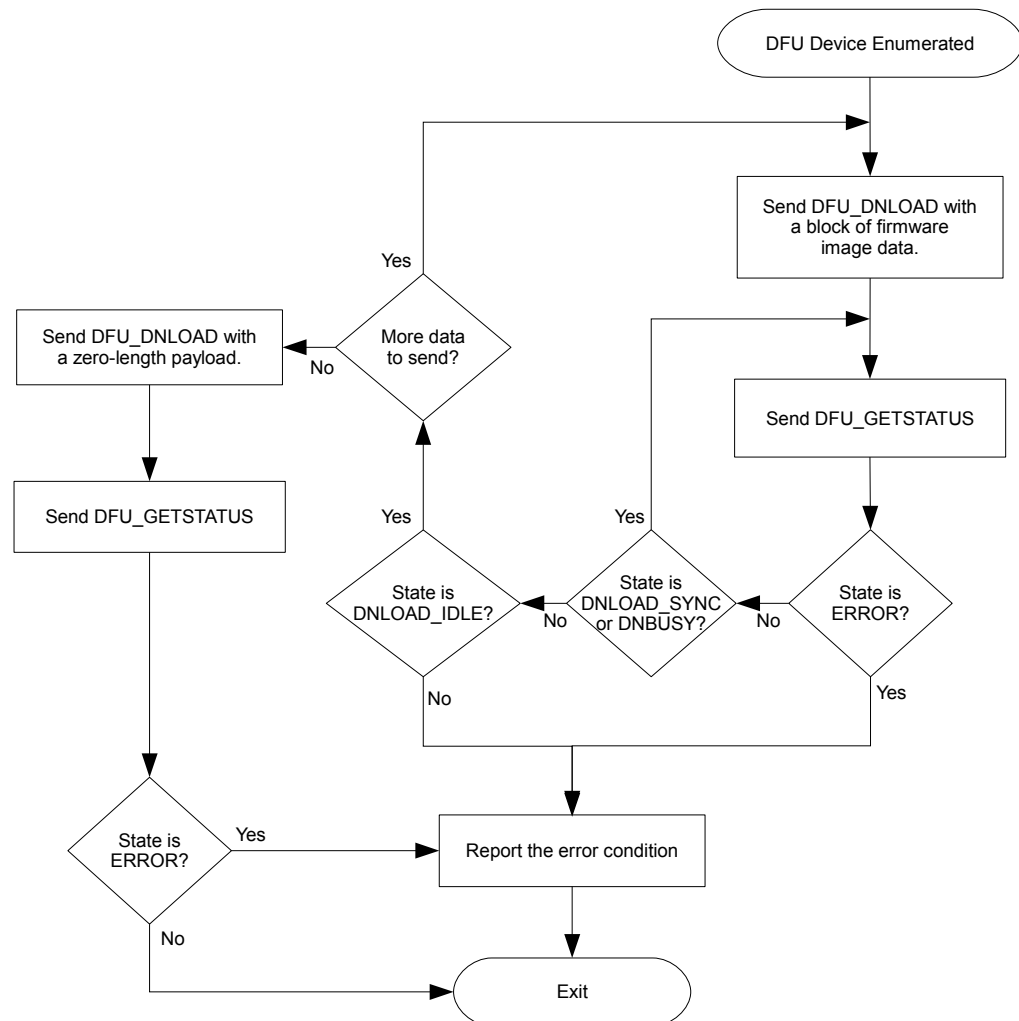
During operation, the DFU device transitions between a set of class-defined states. The host must query the current state to determine when a new operation can be performed or to determine the cause of any errors reported. These states are:

IDLE	The IDLE state indicates to the host that the DFU device is ready to start an upload or download operation.
DNLOAD_SYNC	After each DFU_DNLOAD request is received, DNLOAD_SYNC state is entered. This state remains in effect until the host issues a DFU_GETSTATUS request at which point the state will change to DNLOAD_IDLE if the last download operation has completed or DNBUSY otherwise.
DNLOAD_IDLE	This state indicates that a download operation is in progress and that the device is ready to receive another DFU_DNLOAD request with the next block of data.
DNBUSY	<p>This state is reported if a DFU_GETSTATUS request is received while a block of downloaded data is still being processed. The host must refrain from issuing another DFU_GETSTATUS request for a time specified in the structure returned following the request. After this time, the device state reverts to DNLOAD_SYNC.</p> <p>To reduce the USB boot loader image size, this state is not supported. Instead of reporting DNBUSY, the USB boot loader remains in state DNLOAD_SYNC until the previous data has been processed then transitions to DNLOAD_IDLE on receipt of the first DFU_GETSTATUS request following completion of block programming.</p>
MANIFEST_SYNC	<p>The end of a download operation is signaled by the host sending a DFU_DNLOAD request with a 0 length payload. When this request is received, the DFU device transitions from state DNLOAD_IDLE to MANIFEST_SYNC. This state indicates that the complete firmware image has been received and the device is waiting for a DFU_GETSTATUS request before finalizing programming of the image.</p> <p>The USB boot loader programs downloaded blocks as they are received so does not need to perform any additional processing after all blocks have been received. It also reports that it is “manifest tolerant”, indicating to the host that it will still respond to requests after a download has completed. As a result, the device will transition from this state to IDLE once the DFU_GETSTATUS request is received.</p>

MANIFEST	<p>This state indicates to the host that the device is programming a previously- received firmware image and is entered on receipt of a DFU_GETSTATUS request while a device that is not manifest tolerant is in MANIFEST_SYNC state.</p> <p>This state is not used by the USB boot loader since it is manifest tolerant and reverts to IDLE state after completion of a download.</p>
MANIFEST_WAIT_RESET	<p>This state indicates that a device which is not manifest tolerant has finished writing a downloaded image and is waiting for a USB reset to signal it to boot the new firmware.</p> <p>This state is not used by the USB boot loader since it is manifest tolerant and reverts to IDLE state after completion of a download.</p>
UPLOAD_IDLE	<p>Following receipt of a DFU_UPLOAD request, the device remains in this state until it receives another DFU_UPLOAD request asking for less than the maximum transfer size of data. This indicates that the upload is complete and the device will transition back to IDLE state.</p>
ERROR	<p>The ERROR state is entered when some error occurs. The device remains in this state until the host sends a DFU_CLRSTATUS request at which point the state reverts to IDLE and that error code, which is reported in the data returned in response to DFU_GETSTATUS, is cleared.</p>

3.1.3 Typical Firmware Download Sequence

The following flow chart illustrates a typical firmware image download sequence from the perspective of the host application.



3.2 TI-Specific USB Download Commands

The DFU class specification provides the framework necessary to download and upload firmware files to the USB device but does not specify the actual format of the binary data that is transferred. As a result, different device implementations have used different methods to perform operations which are not defined in the standard such as:

- Setting the address that a downloaded binary should be flashed to.
- Setting the address and size of the area of flash whose contents are to be uploaded.
- Erasing sections of the flash.
- Querying the size of flash and writeable area addresses.

The USB boot loader implementation employs a small set of commands which can be sent to the DFU device via a DFU_DNLOAD request when the device is in IDLE state. Each command takes the form of an 8 byte structure which defines the operation to carry out and provides any required additional parameters.

To ensure that a host application which does not have explicit support for TI-specific commands can still be used to download binary firmware images to the device, the protocol is defined such that only a single 8 byte header structure need be placed at the start of the binary image being downloaded. This header and the DFU-defined suffix structure can both be added using the supplied “dfuwrap” command-line application, hence providing a single binary that can be sent to a device running the TI USB boot loader using a standard sequence of DFU_DNLOAD requests with no other embedded commands or device-specific operations required. An application which does understand the TI-specific commands may make use of them to offer additional functionality that would not otherwise be available.

3.2.1 Querying Command Support

Since the device-specific commands defined here are sent to the DFU device in DFU_DNLOAD requests, the possibility exists that sending them to a device which does not understand the protocol could result in corruption of that device’s firmware. To guard against this possibility, the TI USB boot loader supports an additional USB request which is used to query the device capabilities and allow a host to determine whether or not the device supports the TI commands. A device which does not support the commands will either stall the request or return unexpected data.

To determine whether a target DFU device supports the TI-specific DFU commands, send the following IN request to the DFU interface:

bmRequest-Type	bRequest	wValue	wIndex	wLength	Data
10100001b	0x42	0x23	Interface	4	Protocol Info

where the protocol information returned is a 4 byte structure, the first two bytes of which are 0x4D, 0x4C and where the second group of two bytes indicates the protocol version supported, currently 0x01 and 0x20 respectively.

3.2.2 Download Command Definitions

The following commands may be sent to the USB boot loader as the first 8 bytes of the payload to a DFU_DNLOAD request. The boot loader will expect any DFU_DNLOAD request received while

in IDLE state to contain a command header but will not look for command unless the state is IDLE. This allows an application which is unaware of the command header to download a DFU-wrapped binary image using a standard sequence of multiple DFU_DNLOAD and DFU_GETSTATUS requests without the need to insert additional command headers during the download.

The commands defined here and their parameter block structures can be found in header file `usbdfu.h`. In all cases where multi-byte numbers are specified, the numbers are stored in little-endian format with the least significant byte in the lowest addressed location. The following definitions specify the command byte ordering unambiguously but care must be taken to ensure correct byte swapping if using the command structure types defined in `usbdfu.h` on big-endian systems.

DFU_CMD_PROG

This command is used to provide the USB boot loader with the address at which the next download should be written and the total length of the firmware image which is to follow. This structure forms the header that is written to the DFU-wrapped file generated by the `dfuwrap` tool.

The start address is provided in terms of 1024 word flash blocks. To convert a word address to a block address, merely divide by 1024. The start address must always be on a 1024 word boundary. For example if you wanted to program data at address 0x3D8000 (start of flash) the block number sent would be 0xF60.

This command may be followed by up to 1016 bytes of firmware image data, this number being the maximum transfer size minus the 8 bytes of the command structure. Keep in mind that while data is transferred over USB in bytes it is programmed into the device flash as words (2 bytes). The image size field should contain the number of bytes to be programmed (not words).

Data following this command in the following format 0xXX, 0xYY will be programmed into flash as 0xXXYY (i.e. the most significant byte of a word should be transmitted first).

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_PROG (0x01)
ucData[1] = Reserved - set to 0x00
ucData[2] = Start Block Number [7:0];
ucData[3] = Start Block Number [15:8];
ucData[4] = Image Size [7:0];
ucData[5] = Image Size [15:8];
ucData[6] = Image Size [23:16];
ucData[7] = Image Size [31:24];
```

DFU_CMD_READ

This command is used to set the address range whose content will be returned on subsequent DFU_UPLOAD requests from the host.

The start address is provided in terms of 1024 words flash blocks. To convert a word address to a block address, merely divide by 1024. The start address must always be on a 1024 byte boundary.

To read back the contents of a region of flash, the host should send a DFU_DNLOAD request with command DFU_CMD_READ, start address set to the 1KW block start address and length set to the number of bytes to read. The host should then send one or more DFU_UPLOAD requests to receive the current flash contents from the configured addresses. Data returned will include an 8 byte DFU_CMD_PROG prefix structure unless the prefix has been disabled by sending a DFU_CMD_BIN command with the bBinary parameter set to 1. The host should, therefore, be prepared to read 8 bytes more than the length specified in the READ command if the prefix is enabled.

By default, the 8 byte prefix is enabled for all upload operations. This is required by the DFU class specification which states that uploaded images must be formatted to allow them to be directly downloaded back to the device at a later time.

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_READ (0x02)
ucData[1] = Reserved - set to 0x00
ucData[2] = Start Block Number [7:0];
ucData[3] = Start Block Number [15:8];
ucData[4] = Image Size [7:0];
ucData[5] = Image Size [15:8];
ucData[6] = Image Size [23:16];
ucData[7] = Image Size [31:24];
```


DFU_CMD_CHECK

This command is used to check a region of flash to ensure that it is completely erased.

The start address is provided in terms of 1024 word flash blocks. To convert a word address to a block address, merely divide by 1024. The start address must always be on a 1024 word boundary. The region size is transmitted in words.

To check that a region of flash is erased, the DFU_CMD_CHECK command should be sent with the required start address and region length set then the host should issue a DFU_GETSTATUS request. If the erase check was successful, the returned bStatus value will be OK (0x00), otherwise it will be `erCheckErased` (0x05).

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_CHECK (0x03)
ucData[1] = Reserved - set to 0x00
ucData[2] = Start Block Number [7:0];
ucData[3] = Start Block Number [15:8];
ucData[4] = Region Size [7:0];
ucData[5] = Region Size [15:8];
ucData[6] = Region Size [23:16];
ucData[7] = Region Size [31:24];
```

DFU_CMD_ERASE

This command is used to erase a region of flash.

The start address is provided in terms of 1024 word flash blocks. To convert a word address to a block address, merely divide by 1024. The start address must always be on a 1024 word boundary.

The size of the region to erase is expressed in terms of 1024 word flash blocks.

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_ERASE (0x04)
ucData[1] = Reserved - set to 0x00
ucData[2] = Start Block Number [7:0];
ucData[3] = Start Block Number [15:8];
ucData[4] = Number of Blocks [7:0];
ucData[5] = Number of Blocks [15:8];
ucData[6] = Reserved - set to 0x00
ucData[7] = Reserved - set to 0x00
```

DFU_CMD_INFO

This command is used to query information relating to the target device and programmable region of flash. The device information structure, `tDFUDevice-Info`, is returned on the next `DFU_UPLOAD` request following this command.

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_INFO (0x05)
ucData[1] = Reserved - set to 0x00
ucData[2] = Reserved - set to 0x00
ucData[3] = Reserved - set to 0x00
ucData[4] = Reserved - set to 0x00
ucData[5] = Reserved - set to 0x00
ucData[6] = Reserved - set to 0x00
ucData[7] = Reserved - set to 0x00
```

```
//*****  
//  
// Payload returned in response to the DFU_CMD_INFO command.  
//  
// This structure is returned in response to the first DFU_UPLOAD  
// request following a DFU_CMD_INFO command. Note that byte ordering  
// of multi-byte fields is little-endian.  
//  
//*****  
typedef struct  
{  
    //  
    // The size of a flash block in bytes.  
    //  
    unsigned short usFlashBlockSize;  
  
    //  
    // The number of blocks of flash in the device. Total  
    // flash size is usNumFlashBlocks * usFlashBlockSize.  
    //  
    unsigned short usNumFlashBlocks;  
  
    //  
    // Information on the part number, family, version and  
    // package as read from the PARTID register  
    //  
    unsigned long ulPartInfo;  
  
    //  
    // Information on the part class and revision as read  
    // from the CLASSID  
    //  
    unsigned long ulClassInfo;  
  
    //  
    // Address 1 byte above the highest location the boot  
    // loader can access.  
    //  
    unsigned long ulFlashTop;  
  
    //  
    // Lowest address the boot loader can write or erase.  
    //  
    unsigned long ulAppStartAddr;  
  
    //  
    // Features supported by the bootloader  
    //  
    tLong ulFeatures;  
  
    //  
    // If true the device is locked and flash reads/writes are disallowed  
    //  
    unsigned char ucLocked;  
}  
PACKED tDFUDeviceInfo;
```

DFU_CMD_BIN

By default, data returned in response to a DFU_UPLOAD request includes an 8 byte DFU_CMD_PROG prefix structure. This ensures that an uploaded image can be directly downloaded again without the need to further wrap it but, in cases where pure binary data is required, can be awkward. The DFU_CMD_BIN command allows the upload prefix to be disabled or enabled under host control.

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_BIN (0x06)
ucData[1] = 0x01 to disable upload prefix, 0x00 to enable
ucData[2] = Reserved - set to 0x00
ucData[3] = Reserved - set to 0x00
ucData[4] = Reserved - set to 0x00
ucData[5] = Reserved - set to 0x00
ucData[6] = Reserved - set to 0x00
ucData[7] = Reserved - set to 0x00
```

DFU_CMD_RESET

This command may be sent to the USB boot loader to cause it to perform a soft reset of the board. This will reboot the system and, assuming that the main application image is present, run the main application. Note that a reboot will also take place if a firmware download operation completes and the host issues a USB reset to the DFU device.

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_RESET (0x07)
ucData[1] = Reserved - set to 0x00
ucData[2] = Reserved - set to 0x00
ucData[3] = Reserved - set to 0x00
ucData[4] = Reserved - set to 0x00
ucData[5] = Reserved - set to 0x00
ucData[6] = Reserved - set to 0x00
ucData[7] = Reserved - set to 0x00
```

DFU_CMD_CSM

This command may be sent to the USB boot loader to cause it to lock or unlock the device's code security module. Unlocking the device is accomplished by first sending the CSM command with all fields set to 0. When the device receives this command it will generate a seed which can be retrieved by performing a DFU Upload. The host should then perform encryption on this seed using a pre-negotiated key. To finish authentication and unlock the device the host should again send a CSM command but with the key size field populated and the encrypted seed following the command. Success can be checked by using the info command. The device will automatically lock when reset if the CSM locations aren't all 0xFF, but the device can also be manually locked by sending the CSM command with the lock field a non-zero value.

The public release of the bootloader does not contain this feature due to export restrictions on the encryption technology used to implement the seed/key exchange. If you are interested in obtaining the full bootloader sources with AES encryption and decryption libraries please contact TI via email or the e2e forums.

The format of the command is as follows:

```
unsigned char ucData[8];

ucData[0] = DFU_CMD_RESET (0x08)
ucData[1] = Reserved - set to 0x00
ucData[2] = Lock device if true
ucData[3] = Key size following this command
ucData[4] = Reserved - set to 0x00
ucData[5] = Reserved - set to 0x00
ucData[6] = Reserved - set to 0x00
ucData[7] = Reserved - set to 0x00
```


4 Customization

This bootloader contains many advanced features that are on par with many professionally supported 3rd party bootloaders. All of the features can be turned on or off by configuring defines in `bl_config.h`.

■ `ENABLE_WATCHDOG`

- If defined the watchdog will be enabled and kicked in the main update loop.

■ `ENABLE_CSM_CONTROL`

- If defined the bootloader will include mechanisms to lock and unlock the code security module. AES encryption libraries are used to do a seed key exchange to authenticate the host. The passwords to be programmed into flash can be found immediately below this define. Please note that the public release of the bootloader doesn't contain the encryption library necessary to implement this feature due to export restrictions. Please contact TI if you are interested in this feature.

■ `ENABLE_READ`

- Enables the upload of flash memory contents. Applications that want their code to be secure should not define this, but keep in mind the programmed code cannot then be verified.

■ `ENABLE_CRC_CHECK`

- If defined, before booting the application the bootloader will examine the `ulAppSig` location for a pointer to a linker generated CRC table in the application. The bootloader will then iterate through this table checking each CRC record. If all records pass then the application is booted.

■ `ENABLE_FAILSAFE`

- If defined the bootloader will generate two flash entry points and relocate itself in flash during erase operations. This minimizes the critical time where if power is pulled the device becomes bricked. This is an EXTREMELY advanced feature and should only be used by those with a great deal of embedded programming experience.

■ `ENABLE_DECRYPTION`

- Enables a call to `DecryptData` in `bl_decrypt.c` whenever data to be programmed is received. The `DecryptData` function is a stub that can be populated with the user's own decryption routine.

■ `ENABLE_UPDATE_CHECK`

- If defined before checking for a valid application, the bootloader will check a GPIO pin for a given state. If the state matches the defined state in `bl_config.h` the bootloader will start and wait for an update to be performed.

5 Configuration

There are a number of defines that are used to configure the operation of the boot loader. These defines are located in the `bl_config.h` header file.

The configuration options are:

CRYSTAL_FREQ	This defines the crystal frequency used by the microcontroller running the boot loader. This frequency is used to properly setup PLL2 for operation with the USB controller. The user should ensure that 120MHz divided by the crystal frequency is an integer.
APP_START_ADDRESS	The starting address of the application. <ul style="list-style-type: none">■ This value must be defined.
APP_END_ADDRESS	The ending address of the application. <ul style="list-style-type: none">■ This value must be defined.
FLASH_PAGE_SIZE	The size of a single, erasable page in the flash. This must be a power of 2. The default value of 32KB (16K Words) represents the page size for the internal flash on all C2000 MCUs. <ul style="list-style-type: none">■ This value must be defined.
FLASH_END_ADDR	The starting address of flash.
FLASH_END_ADDR	The ending address of flash.
USB_VENDOR_ID	The USB vendor ID published by the DFU device. This value is the TI vendor ID. Change this to the vendor ID you have been assigned by the USB-IF.
USB_PRODUCT_ID	The USB device ID published by the DFU device. If you are using your own vendor ID, chose a device ID that is different from the ID you use in non-update operation. If you have sublicensed TI's vendor ID, you must use an assigned product ID here.
USB_DEVICE_ID	Selects the BCD USB device release number published in the device descriptor.
USB_MAX_POWER	Sets the maximum power consumption that the DFU device will report to the USB host in the configuration descriptor. Units are milliamps.
USB_BUS_POWERED	Specifies whether the DFU device reports to the host that it is self-powered (defined as 0) or bus-powered (defined as 1).

USB_HAS_MUX	Specifies whether the target board uses a multiplexer to select between USB host and device modes.
USB_MUX_PIN	<p>Specifies the GPIO pin number used to select between USB host and device modes. Valid values are 0 through 64.</p> <ul style="list-style-type: none">■ This value must be defined if <code>USB_HAS_MUX</code> is defined.
USB_MUX_DEVICE	<p>Specifies the state of the GPIO pin required to select USB device-mode operation. Valid values are 0 (low) or 1 (high).</p> <ul style="list-style-type: none">■ This value must be defined if <code>USB_HAS_MUX</code> is defined.
BL_HW_INIT_FN_HOOK	Performs application-specific low level hardware initialization on system reset. If hooked, this function will be called immediately after the boot loader code relocation completes. An application may perform any required low-level hardware initialization during this function. Note that the system clock has not been set when this function is called. Initialization that assumes the system clock is set may be performed in the <code>BL_INIT_FN_HOOK</code> function instead.
BL_INIT_FN_HOOK	Performs application-specific initialization on system reset. If hooked, this function will be called during boot loader initialization to perform any board- or application-specific initialization which is required. The function is called following a reset immediately after the selected boot loader peripheral has been configured and the system clock has been set.
BL_REINIT_FN_HOOK	Performs application-specific reinitialization on boot loader entry via SVC. If hooked, this function will be called during boot loader reinitialization to perform any board- or application-specific initialization which is required. The function is called following boot loader entry from an application, after any system clock rate adjustments have been made.
BL_START_FN_HOOK	Informs an application that a download is starting. If hooked, this function will be called when a firmware download is about to begin. The function is called after the first data packet of the download is received but before it has been written to flash.

BL_PROGRESS_FN_HOOK	<p>Notifies an application of download progress. If hooked, this function will be called periodically during a firmware download to provide progress information. The function is called after each data packet is received from the host. Parameters provide the number of bytes of data received and, in cases other than Ethernet update, the expected total number of bytes in the download (the TFTP protocol used by the Ethernet boot loader does not send the final image size before the download starts so in this case the ulTotal parameter is set to 0 to indicate that the size is unknown).</p>
BL_END_FN_HOOK	<p>Notifies an application that a download has completed. If hooked, this function will be called when a firmware download has just completed. The function is called after the final data packet of the download has been written to flash.</p>
BL_DECRYPT_FN_HOOK	<p>Allows an application to perform in-place data decryption during download. If hooked, this function will be called to perform in-place decryption of each data packet received during a firmware download.</p> <ul style="list-style-type: none">■ This value takes precedence over <code>ENABLE_DECRYPTION</code>. If both are defined, the hook function defined using <code>BL_DECRYPT_FN_HOOK</code> is called rather than the previously-defined <code>DecryptData()</code> stub function.
BL_CHECK_UPDATE_FN_HOOK	<p>Allows an application to force a new firmware download. If hooked, this function will be called during boot loader initialization to determine whether a firmware update should be performed regardless of whether a valid main code image is already present. If the function returns 0, the existing main code image is booted (if present), otherwise the boot loader will wait for a new firmware image to be downloaded.</p> <ul style="list-style-type: none">■ This value takes precedence over <code>ENABLE_UPDATE_CHECK</code> if both are defined. If you wish to perform a GPIO check in addition to any other update check processing required, the GPIO code must be included within the hook function itself.

6 Failsafe Mode

The purpose of the failsafe bootloader mode is twofold. Because the flash sector size is 0x4000kw and the bootloader is only ~0x1500kw large a tradition bootloader which protects the sector it resides in would waste a sizable piece of otherwise usable flash memory. To overcome this limitation the bootloader must copy itself into another flash sector such that its original flash sector can be erased and reused for the user application. This is the first reason for the failsafe mode.

During any bootloading scenario there exists a time during erase where the device can potentially be corrupted and caused to not boot correctly. This can happen if power is removed during an erase or program operation of Sector A (the location of the BootROM boot vector). To minimize the chances of this occurring the erase and program of sector are ordered such that an erase of Sector A is immediately followed by a reprogramming of the reset vector. This is the second reason for the failsafe mode.

To better understand the failsafe mode, let's walk through a typical erase operation. Keep in mind that while in failsafe mode the erase command's address and size arguments are ignored and the entire flash is always erased.

1. Erase Sectors B-G. This erases most of the application leaving only the bootloader and reset vector in flash. Device will boot normally if power is removed at this point.
2. Copy the bootloader into Sector G.
3. Erase Sector A and program reset vector to point to the failsafe entry point in flash Sector G. During this operation if power is removed the device may not boot on the next powerup. If power is removed after this operation completes successfully but before the bootloader is copied back into Sector H, then the device will boot into the failsafe mode which requires an application update.
4. Erase Sector H, the original location of the bootloader.
5. Copy the bootloader back into Sector H.
6. Erase Sector A and program reset vector to point to the normal entry point in flash Sector H. During this operation if power is removed the device may not boot on the next powerup. If power is removed after this operation completes successfully, then the device will boot into the normal mode and will require an application update because the pAppEntry vector will be null.

After these operations complete the flash will be completely erased (except for the area occupied by the bootloader) and ready for the application to be programmed.

6.0.3 Program and Data Allocation

To accomplish the above functionality the bootloader has been carefully partitioned to ensure that it is as robust as possible. There are 3 main allocations of program code:

- Program code that runs from flash in Sector H (normal boot, application check, normal memory copy).
- Program code that runs from flash in Sector G (failsafe boot, failsafe memory copy).
- Program code that runs from SRAM and is copied from Sector G or H depending on whether the device is in failsafe mode at the time or not.

Please refer to figure 5.1 for a graphic representation of the memory with failsafe mode enabled.

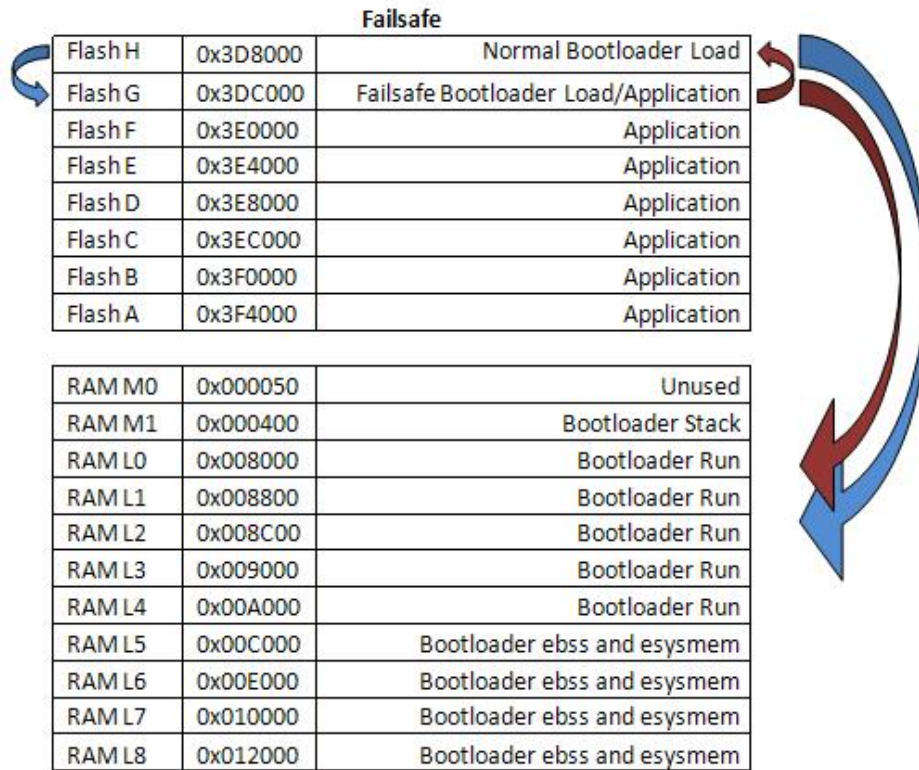


Figure 6.1: Failsafe Bootloader Mode Memory Allocation

6.0.4 Memory Copies

Care must be taken when modifying the bootloader to ensure everything lines up in memory where it should. Several of the copies performed are based on the normal and failsafe copies of code being spaced 0x4000 apart. During the copy of bootloader image from Sector H to Sector G the entire bootloader image is copied up in the address space by 0x4000. The failsafe initialization functions in the rts2800_bl library expect the cinit and pinit tables to be at a location 0x4000 higher than where the original ones were linked to. When the failsafe flash entry functions are copied they are copied to 0x3DE000. If modifications are made to the bootloader that increase its size, care should be taken to ensure that the bootloader when copied to Sector G doesn't overlap the failsafe flash entry functions at 0x3DE000. Please refer to figure 5.2 for a graphical representation of the copies that occur.

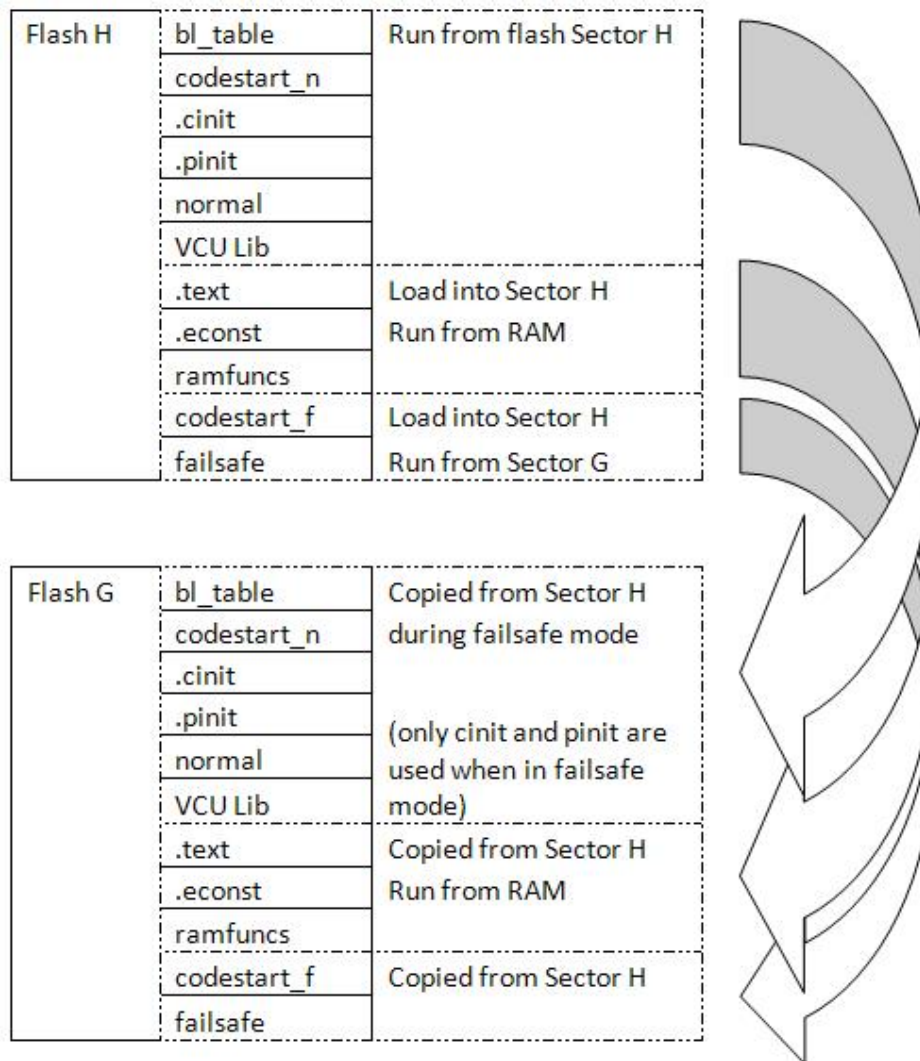


Figure 6.2: Failsafe Bootloader Memory Copies

7 Source Details

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7.1 Decryption Functions

Functions

- void [DecryptData](#) (unsigned char *pucBuffer, unsigned long ulSize)

7.1.1 Detailed Description

The following functions are provided in `bl_decrypt.c` and are used to optionally decrypt the firmware data as it is received.

7.1.2 Function Documentation

7.1.2.1 DecryptData

Performs an in-place decryption of downloaded data.

Prototype:

```
void  
DecryptData(unsigned char *pucBuffer,  
            unsigned long ulSize)
```

Parameters:

pucBuffer is the buffer that holds the data to decrypt.

ulSize is the size, in bytes, of the buffer that was passed in via the `pucBuffer` parameter.

Description:

This function is a stub that could provide in-place decryption of the data that is being downloaded to the device.

Returns:

None.

7.2 Update Check Functions

Functions

- unsigned char [CheckCRCTable](#) (volatile CRC_TABLE *pCRCTable)

- unsigned long [CheckForceUpdate](#) (void)
- unsigned long [CheckGPIOForceUpdate](#) (void)

7.2.1 Detailed Description

The following functions are provided in `bl_check.c` and are used to check if a firmware update is required.

7.2.2 Function Documentation

7.2.2.1 CheckCRCTable

Checks a Linker Generated CRC table against memory

Prototype:

```
unsigned char  
CheckCRCTable(volatile CRC_TABLE *pCRCTable)
```

Parameters:

pCRCTable CRC Table to be checked

Description:

This function iterates through a CRC table performing the checks specified against the memory map.

Returns:

Returns 1 on failure, 0 on success

7.2.2.2 CheckForceUpdate

Checks if an update is needed or is being requested.

Prototype:

```
unsigned long  
CheckForceUpdate(void)
```

Description:

This function detects if an update is being requested or if there is no valid code presently located on the microcontroller. This is used to tell whether or not to enter update mode.

Returns:

Returns a non-zero value if an update is needed or is being requested and zero otherwise.

7.2.2.3 CheckGPIOForceUpdate

Checks a GPIO for a forced update.

Prototype:

```
unsigned long  
CheckGPIOForceUpdate(void)
```

Description:

This function checks the state of a GPIO to determine if a update is being requested.

Returns:

Returns a non-zero value if an update is being requested and zero otherwise.

7.3 USB Device Functions

Data Structures

- [tConfigDescriptor](#)
- [tLong](#)
- [tShort](#)
- [tString0Descriptor](#)
- [tStringDescriptor](#)
- [tUSBRequest](#)

Defines

- [readLong\(ptr\)](#)
- [readShort\(ptr\)](#)
- [writeLong\(ptr, value\)](#)
- [writeShort\(ptr, value\)](#)

Functions

- void [AppCheck](#) (void)
- void [AppUpdaterUSB](#) (void)
- void [CompactBuffer](#) (unsigned char *pucBuffer, unsigned long ulBufferSize)
- void [ConfigureUSB](#) (void)
- void [ConfigureUSBInterface](#) (void)
- void [CopyBLGtoH](#) (void)
- void [CopyBLHtoG](#) (void)
- void [FailsafeEntry](#) (void)
- void [FlashAPICallback](#) (void)
- unsigned long [FlashAPIIndex](#) (unsigned long ulAddress, unsigned long ulSize)
- void [FlashAPIInit](#) (void)
- tBoolean [FlashRangeCheck](#) (unsigned long ulStart, unsigned long ulLength)
- void [HandleConfigChange](#) (unsigned long ullInfo)
- void [HandleDisconnect](#) (void)
- void [HandleEP0Data](#) (unsigned long ulSize)

- void [HandleRequestDnloadIdle](#) (tUSBRequest *pUSBRequest)
- void [HandleRequestDnloadSync](#) (tUSBRequest *pUSBRequest)
- void [HandleRequestError](#) (tUSBRequest *pUSBRequest)
- void [HandleRequestIdle](#) (tUSBRequest *pUSBRequest)
- void [HandleRequestManifestSync](#) (tUSBRequest *pUSBRequest)
- void [HandleRequests](#) (tUSBRequest *pUSBRequest)
- void [HandleRequestUploadIdle](#) (tUSBRequest *pUSBRequest)
- void [HandleReset](#) (void)
- void [HandleSetAddress](#) (void)
- void [main](#) (void)
- tBoolean [ProcessDFUDnloadCommand](#) (tDFUDownloadHeader *pcCmd, unsigned long ulSize)
- void [ProgramBLFailsafeVector](#) (void)
- void [ProgramBLNormalVector](#) (void)
- void [SendDFUState](#) (void)
- void [SendDFUStatus](#) (void)
- tBoolean [SendUploadData](#) (unsigned short usLength, tBoolean bAppendHeader)
- void [UpdaterUSB](#) (void)
- __interrupt void [USB0DeviceIntHandler](#) (void)
- void [USBBLInit](#) (void)
- void [USBBLSendDataEP0](#) (unsigned char *pucData, unsigned long ulSize)
- void [USBBLStallEP0](#) (void)
- void [WatchdogEnable](#) (void)

7.3.1 Detailed Description

The following functions are provided in `bl_usb.c` and `bl_usbfuncs.c` and are used to communicate over the USB interface.

7.3.2 Data Structure Documentation

7.3.2.1 tConfigDescriptor

Definition:

```
typedef struct
{
    unsigned char bLength;
    unsigned char bDescriptorType;
    tShort wTotalLength;
    unsigned char bNumInterfaces;
    unsigned char bConfigurationValue;
    unsigned char iConfiguration;
    unsigned char bmAttributes;
    unsigned char bMaxPower;
}
tConfigDescriptor
```

Members:

- bLength*** The length of this descriptor in bytes. All configuration descriptors are 9 bytes long.
- bDescriptorType*** The type of the descriptor. For a configuration descriptor, this will be USB_DTYPE_CONFIGURATION (2).
- wTotalLength*** The total length of data returned for this configuration. This includes the combined length of all descriptors (configuration, interface, endpoint and class- or vendor-specific) returned for this configuration.
- bNumInterfaces*** The number of interface supported by this configuration.
- bConfigurationValue*** The value used as an argument to the SetConfiguration standard request to select this configuration.
- iConfiguration*** The index of a string descriptor describing this configuration.
- bmAttributes*** Attributes of this configuration.
- bMaxPower*** The maximum power consumption of the USB device from the bus in this configuration when the device is fully operational. This is expressed in units of 2mA so, for example, 100 represents 200mA.

Description:

This structure describes the USB configuration descriptor as defined in USB 2.0 specification section 9.6.3. This structure also applies to the USB other speed configuration descriptor defined in section 9.6.4.

7.3.2.2 tLong

Definition:

```
typedef struct
{
    tShort LSW;
    tShort MSW;
}
tLong
```

Members:

LSW
MSW

Description:

This struct is used to ensure that data passed up from the driver layer is interpreted correctly by the protocol stack. This is a workaround specifically for C2000 devices.

7.3.2.3 tShort

Definition:

```
typedef struct
{
    unsigned short LSB;
    unsigned short MSB;
}
tShort
```

Members:

LSB

MSB**Description:**

This struct is used to ensure that data passed up from the driver layer is interpreted correctly by the protocol stack. This is a workaround specifically for C2000 devices.

7.3.2.4 tString0Descriptor**Definition:**

```
typedef struct
{
    unsigned char bLength;
    unsigned char bDescriptorType;
    tShort wLANGID[1];
}
tString0Descriptor
```

Members:

bLength The length of this descriptor in bytes. This value will vary depending upon the number of language codes provided in the descriptor.

bDescriptorType The type of the descriptor. For a string descriptor, this will be USB_DTYPE_STRING (3).

wLANGID The language code (LANGID) for the first supported language. Note that this descriptor may support multiple languages, in which case, the number of elements in the wLANGID array will increase and bLength will be updated accordingly.

Description:

This structure describes the USB string descriptor for index 0 as defined in USB 2.0 specification section 9.6.7. Note that the number of language IDs is variable and can be determined by examining bLength. The number of language IDs present in the descriptor is given by $((bLength - 2) / 2)$.

7.3.2.5 tStringDescriptor**Definition:**

```
typedef struct
{
    unsigned char bLength;
    unsigned char bDescriptorType;
    unsigned char bString;
}
tStringDescriptor
```

Members:

bLength The length of this descriptor in bytes. This value will be 2 greater than the number of bytes comprising the UNICODE string that the descriptor contains.

bDescriptorType The type of the descriptor. For a string descriptor, this will be USB_DTYPE_STRING (3).

bString The first byte of the UNICODE string. This string is not NULL terminated. Its length (in bytes) can be computed by subtracting 2 from the value in the bLength field.

Description:

This structure describes the USB string descriptor for all string indexes other than 0 as defined in USB 2.0 specification section 9.6.7.

7.3.2.6 tUSBRequest

Definition:

```
typedef struct
{
    unsigned char bmRequestType;
    unsigned char bRequest;
    tShort wValue;
    tShort wIndex;
    tShort wLength;
}
tUSBRequest
```

Members:

bmRequestType Determines the type and direction of the request.

bRequest Identifies the specific request being made.

wValue Word-sized field that varies according to the request.

wIndex Word-sized field that varies according to the request; typically used to pass an index or offset.

wLength The number of bytes to transfer if there is a data stage to the request.

Description:

The standard USB request header as defined in section 9.3 of the USB 2.0 specification.

7.3.3 Define Documentation

7.3.3.1 readLong

This define is used to read data from a [tLong](#) variable. This is a is a workaround specific to C2000 devices.

7.3.3.2 #define readShort(ptr)

Definition:

```
#define readLong(ptr)
```

Description:

This define is used to read data from a [tShort](#) variable. This is a is a workaround specific to C2000 devices.

7.3.3.3 #define writeLong(ptr, value)

This define is used to write data to a [tLong](#) variable. This is a is a workaround specific to C2000 devices.

7.3.3.4 #define writeShort(ptr, value)

This define is used to write data to a [tShort](#) variable. This is a is a workaround specific to C2000 devices.

7.3.4 Function Documentation

7.3.4.1 void AppCheck (void)

Application Check function

This function checks the application entry table and if requested the associated CRC table to ensure that a valid application is programmed before jumping to it. If any of the checks fail, the bootloader is entered so that an application image may be programmed.

7.3.4.2 void AppUpdaterUSB (void)

This is the application entry point to the USB updater.

This function should only be entered from a running application and not when running the bootloader with no application present. If the calling application supports any USB device function, it must remove itself from the USB bus prior to calling this function. This function assumes that the calling application has already configured the system clock to run from the PLL.

Returns:

None.

7.3.4.3 CompactBuffer

Definition:

```
void CompactBuffer (unsigned char *pucBuffer , unsigned long
ulBufferSize )
```

Description:

Compact a byte array (0x00XX, 0x00YY) into a word array (0xXXYY)

Parameters:

pucBuffer Buffer to compact

ulBufferSize Buffer size before compaction

7.3.4.4 ConfigureUSB

Definition:

```
void ConfigureUSB (void)
```

Description:

Generic configuration is handled in this function.

This function is called by the start up code to perform any configuration necessary before calling the update routine. It is responsible for setting the system clock to the expected rate and setting flash programming parameters prior to calling [ConfigureUSBInterface\(\)](#) to set up the USB hardware and place the DFU device on the bus.

IMPORTANT: If using a F28069M Launchpad, the Launchpad doesn't have an external oscillator populated. Running this will result in a missing clock NMI. Although for USB an external oscillator is recommended, for Launchpad use, switch the following code to use the internal oscillator or XCLKINs.

Returns:

None.

7.3.4.5 ConfigureUSBInterface

Definition:

```
void ConfigureUSBInterface (void)
```

Description:

Configure the USB controller and place the DFU device on the bus.

This function configures the USB controller for DFU device operation, initializes the state machines required to control the firmware update and places the device on the bus in preparation for requests from the host. It is assumed that the main system clock has been configured at this point.

Returns:

None.

7.3.4.6 CopyBLGtoH

Definition:

```
void CopyBLGtoH (void)
```

Description:

Copy the bootloader from flash sector G to flash sector H.

7.3.4.7 CopyBLHtoG

Definition:

```
void CopyBLHtoG (void)
```

Description:

Copy the bootloader from flash sector H to flash sector G.

7.3.4.8 FailsafeEntry

Definition:

```
void FailsafeEntry (void)
```

Description:

This is the failsafe bootloader entry point

Returns:

None.

7.3.4.9 FlashAPICallback

Definition:

```
void FlashAPICallback (void)
```

Description:

Flash API callback (used to kick the watchdog).

7.3.4.10 FlashAPIIndex

Definition:

```
unsigned long FlashAPIIndex (unsigned long ulAddress , unsigned long  
ulSize )
```

Description:

Get the sector index given a start address and size

Parameters:

ulAddress is the address of the block of flash to erase.

ulSize is the size of the block of memory to return the index for

This function converts an address and size into the index format used by the flash erase function.

Returns:

Index for use with flash erase function

7.3.4.11 FlashAPIInit

Definition:

```
void FlashAPIInit (void)
```

Description:

Initialize variables needed by the flash api.

7.3.4.12 FlashRangeCheck

Definition:

```
tBoolean FlashRangeCheck (unsigned long ulStart , unsigned long  
ulLength )
```

Description:

Check that a range of addresses passed is within the region of flash that the boot loader is allowed to access.

Parameters:

ulStart Starting address of flash range to be checked

ulLength Length of flash range to be checked

Returns:

True if the address range is accessible or false otherwise.

7.3.4.13 HandleConfigChange

Definition:

```
void HandleConfigChange (unsigned long ulInfo )
```

Description:

Handle cases where the host sets a new USB configuration.

Parameters:

ulInfo Is not used in this implementation.

7.3.4.14 HandleDisconnect

Definition:

```
void HandleDisconnect (void)
```

Description:

Handle cases where the USB host disconnects.

7.3.4.15 HandleEP0Data

Definition:

```
void HandleEP0Data (unsigned long ulSize )
```

Description:

EP0 Data callback

Parameters:

ulSize The size of data available in EP0.

This callback function is called when data is received for the DATA phase of an EP0 OUT transaction. This data will either be a block of download data (if we are in STATE_DNLOAD_IDLE) or a new command (if we are in STATE_IDLE).

7.3.4.16 HandleRequestDnloadIdle

Definition:

```
void HandleRequestDnloadIdle (tUSBRequest tUSBRequest  
*pUSBRequest )
```

Description:

Download Idle request handler

Parameters:

pUSBRequest USB request to handle.

Handle all incoming DFU requests while in state STATE_DNLOAD_IDLE.

7.3.4.17 HandleRequestDnloadSync

Definition:

```
void HandleRequestDnloadSync (tUrbRequest tUrbRequest  
*pUrbRequest )
```

Description:

Download Sync request handler

Parameters:

pUSBRequest USB request to handle.

Handle all incoming DFU requests while in state STATE_DNLOAD_SYNC or STATE_DNBUSY.

7.3.4.18 HandleRequestError

Definition:

```
void HandleRequestError (tUrbRequest tUrbRequest *pUrbRequest )
```

Description:

Error request handler

Parameters:

pUSBRequest USB request to handle.

Handle all incoming DFU requests while in state STATE_ERROR.

7.3.4.19 HandleRequestIdle

Definition:

```
void HandleRequestIdle (tUrbRequest tUrbRequest *pUrbRequest )
```

Description:

Idle request handler

Parameters:

pUSBRequest USB request to handle.

Handle all incoming DFU requests while in state STATE_IDLE.

7.3.4.20 HandleRequestManifestSync

Definition:

```
void HandleRequestManifestSync (tUrbRequest tUrbRequest  
*pUrbRequest )
```

Description:

Manifest Sync request handler

Parameters:

pUSBRequest USB request to handle.

Handle all incoming DFU requests while in state STATE_MANIFEST_SYNC.

7.3.4.21 HandleRequests

Definition:

```
void HandleRequests (tUstructtUSBRequest tUSBRequest *pUSBRequest )
```

Description:

Handle USB requests sent to the DFU device.

Parameters:

pUSBRequest is a pointer to the USB request that the device has been sent.

This function is called to handle all non-standard requests received by the device. This will include all the DFU endpoint 0 commands along with the TI-specific request we use to query whether the device supports our flavor of the DFU binary format. Incoming DFU requests are processed by request handlers specific to the particular state of the DFU connection. This state machine implementation is chosen to keep the software as close as possible to the USB DFU class documentation.

Returns:

None.

7.3.4.22 HandleRequestUploadIdle

Definition:

```
void HandleRequestUploadIdle (tUstructtUSBRequest tUSBRequest  
*pUSBRequest )
```

Description:

Upload Idle request handler

Parameters:

pUSBRequest USB request to handle.

Handle all incoming DFU requests while in state STATE_UPLOAD_IDLE.

7.3.4.23 HandleReset

Definition:

```
void HandleReset (void)
```

Description:

Handle bus resets

This function is called if the USB controller detects a reset condition on the bus. If we are not in the process of downloading a new image, we use this as a signal to reboot and run the main application image.

7.3.4.24 HandleSetAddress

Definition:

```
void HandleSetAddress (void)
```

Description:

Setting the device address indicates that we are now connected to the host and can expect some DFU communication so we use this opportunity to clean out our state just in case we were not idle last time the host disconnected.

7.3.4.25 main

Definition:

```
void main (void)
```

Description:

This is the normal bootloader entry point

Returns:

None.

7.3.4.26 ProcessDFUDnloadCommand

Definition:

```
tBoolean ProcessDFUDnloadCommand (tDFUDownloadHeader *pcCmd ,  
unsigned long ulSize )
```

Description:

Process TI-specific commands passed via DFU download requests.

Parameters:

pcCmd is a pointer to the first byte of the **DFU_DNLOAD** payload that is expected to hold a command.

ulSize is the number of bytes of data pointed to by **pcCmd**. This function is called when a DFU download command is received while in **STATE_IDLE**. New downloads are assumed to contain a prefix structure containing one of several TI-specific commands and this function is responsible for parsing the download data and processing whichever command is contained within it.

Returns:

Returns **true** on success or **false** on failure.

7.3.4.27 ProgramBLFailsafeVector

Definition:

```
void ProgramBLFailsafeVector (void)
```

Description:

Erase and program sector A of flash with the entry point for the failsafe bootloader.

7.3.4.28 ProgramBLNormalVector

Definition:

```
void ProgramBLNormalVector (void)
```

Description:

Erase and program sector A of flash with the entry point for the normal bootloader.

7.3.4.29 SendDFUState

Definition:

```
void SendDFUState (void)
```

Description:

Send the current state back to the host.

7.3.4.30 SendDFUStatus

Definition:

```
void SendDFUStatus (void)
```

Description:

Send the current state or status structure back to the host. This function also acknowledges the request which causes us to send back this data.

7.3.4.31 SendUploadData

Definition:

```
tBoolean SendUploadData (unsigned short usLength , tBoolean  
bAppendHeader )
```

Description:

Send the next block of upload data back to the host assuming data remains to be sent.

Parameters:

usLength is the requested amount of data.

bAppendHeader is **true** to append a tDFUDownloadProgHeader at the start of the uploaded data or **false** if no header is required.

Returns **true** if a full packet containing DFU_TRANSFER_SIZE bytes was sent and data remains to be sent following this transaction, or **false** if no more data remains to be sent following this transaction.

7.3.4.32 UpdaterUSB

Definition:

```
void UpdaterUSB (void)
```

Description:

This is the main routine for handling updating over USB.

This function forms the main loop of the USB DFU updater. It polls for commands sent from the USB request handlers and is responsible for erasing flash blocks, programming data into erased blocks and resetting the device.

Returns:

None.

7.3.4.33 USB0DeviceIntHandler

Definition:

```
void USB0DeviceIntHandler (void)
```

Description:

The USB device interrupt handler.

This function is called to process USB interrupts when in device mode. This handler will branch the interrupt off to the appropriate application or stack handlers depending on the current status of the USB controller.

Returns:

None.

7.3.4.34 USBBLInit

Definition:

```
void USBBLInit (void)
```

Description:

Initialize the boot loader USB functions.

This function initializes the boot loader USB functions and places the DFU device onto the USB bus.

Returns:

None.

7.3.4.35 USBBLSendDataEP0

Definition:

```
void USBBLSendDataEP0 (unsigned char *pucData , unsigned long ulSize  
)
```

Description:

This function requests transfer of data to the host on endpoint zero.

Parameters:

pucData is a pointer to the buffer to send via endpoint zero.

ulSize is the amount of data to send in bytes.

This function handles sending data to the host when a custom command is issued or non-standard descriptor has been requested on endpoint zero.

Returns:

None.

7.3.4.36 USBBLStallEP0

Definition:

```
void USBBLStallEP0 (void)
```

Description:

This function generates a stall condition on endpoint zero.

This function is typically called to signal an error condition to the host when an unsupported request is received by the device. It should be called from within the callback itself (in interrupt context) and not deferred until later since it affects the operation of the endpoint zero state machine.

Returns:

None.

7.3.4.37 WatchdogEnable

Definition:

```
void WatchdogEnable (void)
```

Description:

Enable the watchdog timer.

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