## Assignment 4 - Convolutional Neural Network

In this assignment we will develop a neural network with fully-connected layers to perform classification

```
In [1]: import numpy as np
         import matplotlib.pyplot as plt
         import sys
         from sklearn import datasets
         if sys.version_info >= (3, 0):
    def xrange(*args, **kwargs):
                  return iter(range(*args, **kwargs))
In [2]:
         #load dataset
         def load dataset():
             iris = datasets.load_iris()
             X = iris.data
             y = iris.target
             return X, y
         def train_test_split(X, y):
             idx = np.arange(len(X))
             train_size = int(len(X) * 2/3)
             val\_size = int(len(X) * 1/6)
             np.random.shuffle(idx)
             X = X[idx]
             y = y[idx]
             X train, X val, X test = X[:train size], X[train size:train size+val size], X[train size+val size:]
             y_train, y_val, y_test = y[:train_size], y[train_size:train_size+val_size], y[train_size+val_size:]
              return X_train, y_train, X_val, y_val, X_test, y_test
```

We will use the following class TwoLayerCNN to represent instances of our network. The network parameters are stored in the instance variable self.params where keys are string parameter names and values are numpy arrays. Below, we initialize toy data and a toy model that we will use to develop your implementation. You need to complete the functions.

```
In [11]:
          class TwoLayerCNN(object):
            A two-layer fully-connected neural network. The net has an input dimension of
            N, a hidden layer dimension of H, and performs classification over C classes.
            We train the network with a softmax loss function and L2 regularization on the
            weight matrices. The network uses a ReLU nonlinearity after the first fully
            connected layer.
            In other words, the network has the following architecture:
            input - fully connected layer - ReLU - fully connected layer - softmax
            The outputs of the second fully-connected layer are the scores for each class.
                  init (self, input size, hidden size, output size, std=1e-4):
              Initialize the model. Weights are initialized to small random values and
              biases are initialized to zero. Weights and biases are stored in the
              variable self.params, which is a dictionary with the following keys:
              W1: First layer weights; has shape (D, H)
              b1: First layer biases; has shape (H,)
              W2: Second layer weights; has shape (H, C)
              b2: Second layer biases; has shape (C,)
              - input size: The dimension D of the input data.
              hidden_size: The number of neurons H in the hidden layer.
               - output_size: The number of classes C.
              self.params = {}
              self.params['W1'] = std * np.random.randn(input_size, hidden_size)
              self.params['b1'] = np.zeros(hidden size)
              self.params['W2'] = std * np.random.randn(hidden_size, output_size)
              self.params['b2'] = np.zeros(output_size)
            def loss(self, X, y=None, reg=0.0):
              Compute the loss and gradients for a two layer fully connected neural
              network.
               - X: Input data of shape (N, D). Each X[i] is a training sample.
              - y: Vector of training labels. y[i] is the label for X[i], and each y[i] is an integer in the range 0 <= y[i] < C. This parameter is optional; if it
                is not passed then we only return scores, and if it is passed then we
                instead return the loss and gradients.
               - reg: Regularization strength.
```

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Returns:
If y is None, return a matrix scores of shape (N, C) where scores[i, c] is
the score for class c on input X[i].
If y is not None, instead return a tuple of:
- loss: Loss (data loss and regularization loss) for this batch of training
- grads: Dictionary mapping parameter names to gradients of those parameters
with respect to the loss function; has the same keys as self.params.
# Unpack variables from the params dictionary
W1, b1 = self.params['W1'], self.params['b1']
W2, b2 = self.params['W2'], self.params['b2']
N, D = X.shape
# Compute the forward pass
scores = None
# Full Mark: 1
# TODO: Perform the forward pass, computing the class scores for the input. #
# Store the result in the scores variable, which should be an array of
# shape (N. C).
# Using ReLUs as the Activation Function
raw_input = np.dot(X,W1) + b1
relu_activation = np.array(np.maximum(0, (raw_input)))
scores = np.array(np.dot(relu activation, W2) + b2)
END OF YOUR CODE
# If the targets are not given then jump out, we're done
if y is None:
 return scores
# Compute the loss
loss = None
scores -= np.max(scores, axis=1, keepdims=True) # avoid numeric instability
# Full Mark: 2
# TODO: Finish the forward pass, and compute the loss. This should include
# both the data loss and L2 regularization for W1 and W2. Store the result #
# in the variable loss, which should be a scalar. Use the Softmax
# classifier loss.
# softmax
exp_scores = np.exp(scores)
scores = exp scores / exp scores.sum()
# Loss
y matrix = y.reshape(-1)
y_matrix = np.eye(3)[y_matrix]
reg_term = (reg / (2 * y.size)) * (np.sum(np.square(W1)) + np.sum(np.square(W2)))
loss = (-1 / y.size) * np.sum((np.log(scores) * y_matrix) +
                np.log(1 - scores) * (1 - y matrix)) + reg term
END OF YOUR CODE
# Backward pass: compute gradients
arads = {}
# Full Mark: 2
# TODO: Compute the backward pass, computing the derivatives of the weights #
# and biases. Store the results in the grads dictionary. For example,
# grads['W1'] should store the gradient on W1, and be a matrix of same size #
out a diff = scores
out_a_diff[np.arange(N), y] -= 1
# W2 gradient
dW2 = np.dot(relu activation.T, out a diff) / N + reg * W2
# b2 gradient
db2 = np.sum(out_a_diff, axis=0) / N
delta = np.dot(out a diff, W2.T)
delta_z = np.dot(out_a_diff, W2.T) * (raw_input > 0)
# W1 gradient
dW1 = np.dot(X.T, delta_z) / N + reg * W1
```

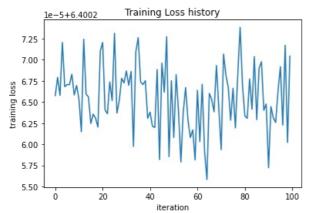
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# b1 gradient
 db1 = np.sum(delta_z , axis=0) / N
 # store the results in the grads dictionary
grads = {'W1':dW1, 'b1':db1, 'W2':dW2, 'b2':db2}
 # store the results in the grads dictionary
 grads = \{'W1':dW1, 'b1':db1, 'W2':dW2, 'b2':db2\}
 # store the results in the grads dictionary
 grads = \{'W1':dW1, 'b1':db1, 'W2':dW2, 'b2':db2\}
 END OF YOUR CODE
 return loss, grads
def train(self, X, y, X_val, y_val,
        learning_rate=1e-3, learning_rate_decay=0.95,
        reg=5e-6, num iters=100,
       batch_size=200, verbose=False):
 Train this neural network using stochastic gradient descent.
 Inputs:
 - X: A numpy array of shape (N, D) giving training data.
 - y: A numpy array f shape (N,) giving training labels; y[i] = c means that
  X[i] has label c, where 0 \le c < C.
 - X val: A numpy array of shape (N val, D) giving validation data.
 - y val: A numpy array of shape (N val,) giving validation labels.
 - learning_rate: Scalar giving learning rate for optimization.
 - learning rate decay: Scalar giving factor used to decay the learning rate
  after each epoch.
 - reg: Scalar giving regularization strength.
 - num_iters: Number of steps to take when optimizing.
 - batch_size: Number of training examples to use per step.
  verbose: boolean; if true print progress during optimization.
 num train = X.shape[0]
 iterations per epoch = max(num train / batch size, 1)
 # Use SGD to optimize the parameters in self.model
 loss history = []
 train acc history = []
 val_acc_history = []
 for it in xrange(num iters):
   ++++
   # Full Mark: 0.5
   # TODO: Create a random minibatch of training data and labels using
   # given num_train and batch_size, storing them in X_batch and y_batch
                                                            #
   # respectively.
   rand_id = np.random.choice(num_train, batch_size)
   X batch = X[rand id]
   y batch = y[rand id]
   END OF YOUR CODE
   # Compute loss and gradients using the current minibatch
   loss, grads = self.loss(X_batch, y=y_batch, reg=reg)
   loss_history.append(loss)
   # Full Mark: 0.5
   # TODO: Use the gradients in the grads dictionary to update the
                                                            #
   # parameters of the network (stored in the dictionary self.params)
   # using stochastic gradient descent. You'll need to use the gradients
   # stored in the grads dictionary defined above.
   self.params['W1'] -= learning_rate * grads['W1']
self.params['W2'] -= learning_rate * grads['W2']
   self.params['b1'] -= learning_rate * grads['b1']
   self.params['b2'] -= learning_rate * grads['b2']
   END OF YOUR CODE
   if verbose and it % 10 == 0:
    print('iteration %d / %d: loss %f' % (it, num iters, loss))
```

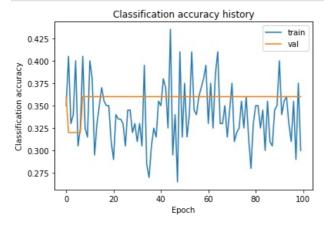
```
# Every epoch, check train and val accuracy and decay learning rate.
   if it % iterations_per_epoch == 0:
     # Check accuracy
    train acc = (self.predict(X batch) == y batch).mean()
    val_acc = (self.predict(X_val) == y_val).mean()
    train_acc_history.append(train_acc)
    val acc history.append(val acc)
    # Decay learning rate
    learning_rate *= learning_rate_decay
 return {
   'loss_history': loss_history,
   'train acc history': train acc history,
   'val acc history': val acc history,
def predict(self, X):
 Use the trained weights of this two-layer network to predict labels for
 data points. For each data point we predict scores for each of the C
 classes, and assign each data point to the class with the highest score.
 - X: A numpy array of shape (N, D) giving N D-dimensional data points to
  classify.
 - y_pred: A numpy array of shape (N,) giving predicted labels for each of
   the elements of X. For all i, y_pred[i] = c means that X[i] is predicted
   to have class c, where 0 <= c < C.
 # Full Mark: 1
 # TODO: Implement this function
 ++++
 h_z = np.dot(X, self.params['W1']) + self.params['b1']
 h_a = np.maximum(0, h_z)
 o_z = np.dot(h_a, self.params['W2']) + self.params['b2']
 oa = np.exp(oz) / np.exp(oz).sum()
 y pred = np.argmax(o a, axis=1)
 END OF YOUR CODE
 return y pred
```

```
In [81]: # To check your implementations.
      X,y =load dataset()
      X_train, y_train, X_val, y_val, X_test, y_test=train test_split(X, y)
      # Full Mark: 1
      # TODO: 1. Using TwoLayerCNN to train on given datasets
            2. Print out the final loss
                                                       #
           3. Print out the test accuracy
      input_size = 4
      hidden size = 12
      num_classes = 3
      net = TwoLayerCNN(input size, hidden size, num classes)
      NN_model = net.train(X_train,y_train,X_val,y_val)
      print ('Final training loss: ', NN_model['loss_history'][-1])
      val acc = (net.predict(X val) == y val).mean()
      print ('Validation accuracy: ', val_acc)
      END OF YOUR CODE
```

Final training loss: 6.400271245193619 Validation accuracy: 0.44

The loss function and the accuracies on the training and validation sets would give more insight views.





```
# Full Mark: 1
        # TODO: Describe or using codes to show how you tune your hyperparameters
        # (hidden layer size, learning rate, numer of training epochs, regularization #
        # strength and so on). Is your result good? Does it look underfiting?
         # Overfiting?
        # Type 1
        input size = 4
        hidden size = 15
        num_classes = 3
        net = TwoLayerCNN(input size, hidden size, num classes)
        NN\_model = net.train(X\_train, y\_train, X\_val, y\_val, learning\_rate = le-2, learning\_rate\_decay = 0.95, reg = le-3, num\_ite_archive.
                   batch_size=100, verbose=False)
        print ('Final training loss: ', NN_model['loss_history'][-1])
        val_acc = (net.predict(X_val) == y_val).mean()
print ('Validation accuracy: ', val_acc)
         # Type 2
        input_size = 4
        hidden_size = 9
        num classes = 3
        net = TwoLayerCNN(input_size, hidden_size, num_classes)
```

Final training loss: 5.710700459295474 Validation accuracy: 0.44 Final training loss: 5.698047987642522 Validation accuracy: 0.32

## Explain your hyperparameter tuning process below.

\$\color{blue}{\textit Your Answer:}\$ As the number of iterations increase, the accuracy increases. The model with smaller batch size lead to convolving quicker but the model can overfit due to frequent updation of weights with smaller batches. A smaller learning late with a high iteration helps us reach a better accuracy rate.