

# MATLAB 1001

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SLOT-L19 L20

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```
>> a=1
```

```
a =
```

```
1
```

```
>> b=2
```

```
b =
```

```
2
```

```
>> c=a+b
```

```
c =
```

```
3
```

```
>> d=cos(a)
```

```
d =
```

```
0.5403
```

```
>> e=sin(a)
```

```
e =
```

```
0.8415
```

```
>> e=a*b
```

```
e =
```

```
2
```

```
>> a=[1 2 3 4]
```

```
a =
```

```
1 2 3 4
```

```
>> a[123;456;789]
```

```
a[123;456;789]
```

```
↑
```

Error: Unbalanced or unexpected parenthesis or bracket.

```
>> a=[1 2 3;4 5 6;7 8 9]
```

```
a =
```

```
1 2 3
```

```
4 5 6
```

```
7 8 9
```

```
>> z=zeros(5,1)
```

```
z =
```

0

0

0

0

0

>> a+10

ans =

11 12 13

14 15 16

17 18 19

>> sin(a)

ans =

0.8415 0.9093 0.1411

-0.7568 -0.9589 -0.2794

0.6570 0.9894 0.4121

>> a'

ans =

1 4 7

2 5 8

3 6 9

```
>> p=a*inv(a)
```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.202823e-18.

p =

```
0 1 0
-4 2 0
-4 3 2
```

```
>> p=a*inv(a)
```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.202823e-18.

p =

```
0 1 0
-4 2 0
-4 3 2
```

```
>> inv(a)
```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.202823e-18.

ans =

1.0e+16 \*

```
0.3153 -0.6305 0.3153
-0.6305 1.2610 -0.6305
```

0.3153 -0.6305 0.3153

```
>> p=a*inv(a)
```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.202823e-18.

p =

0 1 0  
-4 2 0  
-4 3 2

```
>> formatlmg
```

Undefined function or variable 'formatlmg'.

```
>> format long
```

```
>> p=a*inv(a)
```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.202823e-18.

p =

0 1 0  
-4 2 0  
-4 3 2

```
>> a=[1 2 3;4 5 6;7 8 9]
```

a =

1 2 3

```
4 5 6
7 8 9
```

```
>> a=[1 2 3;4 5 6;7 8 10]
```

```
a =
```

```
1 2 3
4 5 6
7 8 10
```

```
>> inv(a)
```

```
ans =
```

```
-0.6666666666666666 -1.3333333333333333 1.0000000000000000
-0.6666666666666667 3.6666666666666666 -1.9999999999999999
1.0000000000000000 -2.0000000000000000 1.0000000000000000
```

```
>> p=a*inv(a)
```

```
p =
```

```
1.0000000000000000 -0.0000000000000000 -0.0000000000000000
0.0000000000000001 0.9999999999999999 -0.0000000000000000
0.0000000000000002 -0.0000000000000003 1.0000000000000000
```

```
>> format long
```

```
>> p=a*inv(a)
```



p =

```
1.0000000000000000 -0.0000000000000000 -0.0000000000000000
0.0000000000000001 0.9999999999999999 -0.0000000000000000
0.0000000000000002 -0.0000000000000003 1.0000000000000000
```

>> p=a.\*a

p =

```
1    4    9
16   25   36
49   64  100
```

>> a.^a

ans =

```
1.0e+10 *
0.000000000100000 0.000000000400000 0.000000000270000
0.000000002560000 0.000000312500000 0.000004665600000
0.000082354300000 0.001677721600000 1.000000000000000
```

>> a.^ a

ans =

1.0e+10 \*

0.000000000100000	0.000000000400000	0.0000000002700000
0.000000025600000	0.000000312500000	0.000004665600000
0.000082354300000	0.001677721600000	1.0000000000000000

>> p=a.^a

p =

1.0e+10 \*

0.000000000100000	0.000000000400000	0.0000000002700000
0.000000025600000	0.000000312500000	0.000004665600000
0.000082354300000	0.001677721600000	1.0000000000000000

>> a,^ a

a,^ a

↑

Error: Unexpected MATLAB operator.

>> a,^a

a,^a

↑

Error: Unexpected MATLAB operator.

>> a.^a

ans =

1.0e+10 \*

0.000000000100000 0.000000000400000 0.0000000002700000  
0.0000000025600000 0.000000312500000 0.000004665600000  
0.000082354300000 0.001677721600000 1.0000000000000000

>> p=a.\*a

p =

1 4 9  
16 25 36  
49 64 100

>> A=[a, a]

A =

1 2 3 1 2 3  
4 5 6 4 5 6  
7 8 10 7 8 10

>> A=[a,a]

A =

1 2 3 1 2 3  
4 5 6 4 5 6

```
7 8 10 7 8 10
```

```
>> A=[a;a]
```

```
A =
```

```
1 2 3
4 5 6
7 8 10
1 2 3
4 5 6
7 8 10
```

```
>> sqrt(-1)
```

```
ans =
```

```
0.0000000000000000 + 1.0000000000000000i
```

```
>> c=[3+4i,4+3j;-i,10j]
```

```
c =
```

```
3.0000000000000000 + 4.0000000000000000i 4.0000000000000000 + 3.0000000000000000i
0.0000000000000000 - 1.0000000000000000i 0.0000000000000000 + 10.0000000000000000i
```

```
>>
```

Amlan Nayak

has successfully completed

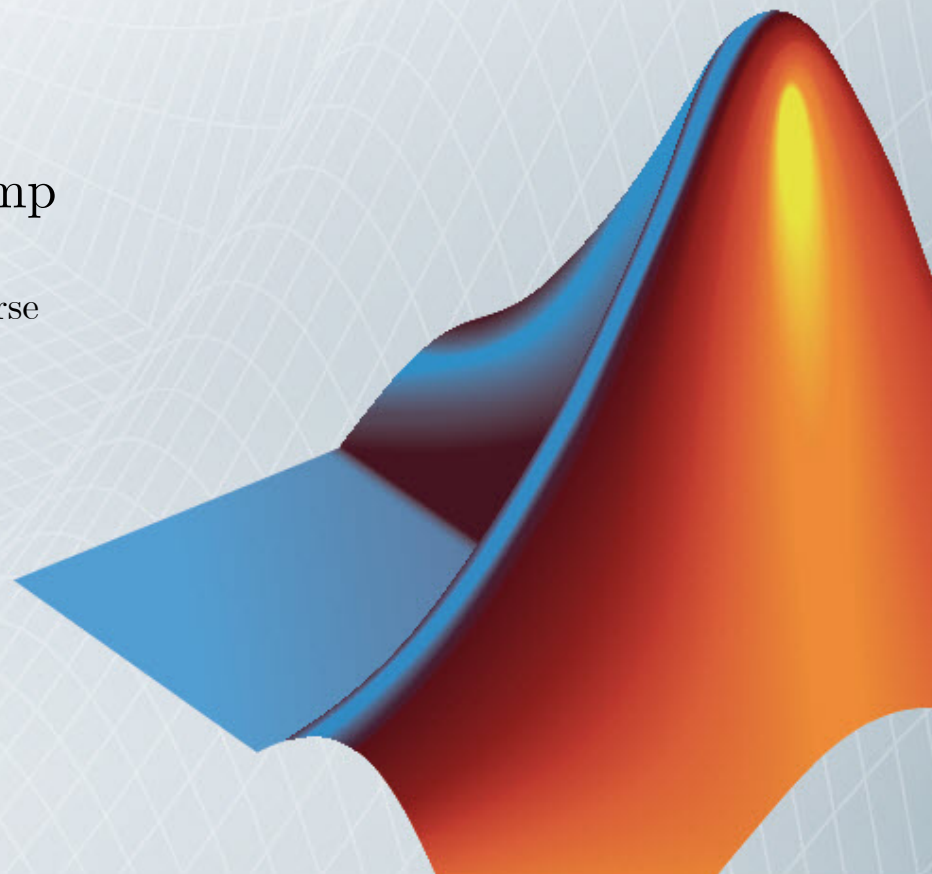
100%

of the

MATLAB Onramp

self-paced training course

21-Jul-2019



---

```
clc
clear all
syms x y
z = 2*x+4*y-x^2-y^2+4;
d1=diff(z,x);
d2=diff(d1,x);
r = solve(d1,x)
for i=1:length(r)
    r(i) = subs(d2,x,r(i));end
    if(r(i)<0)
        fprintf('z has maximum value at x =%f',r(i))
    else
        fprintf('z has minimum value at x =%f',r(i))
    end
end
```

```
r =
```

```
1
```

```
z has maximum value at x =-2.000000
```

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---

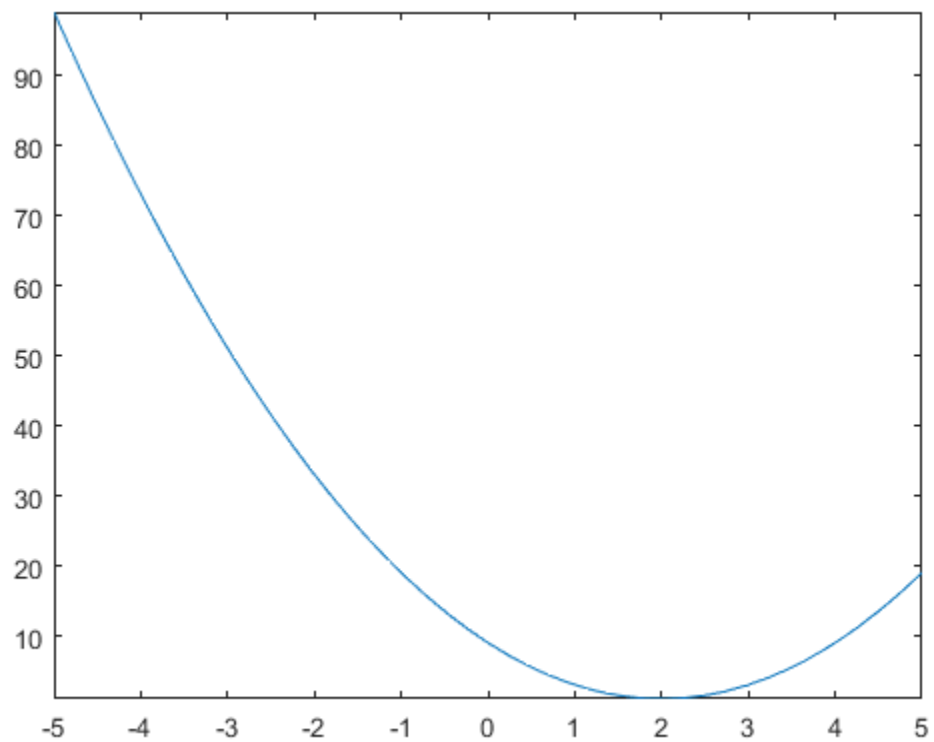
```
% name-amlan nayak
% reg. no.-19bcd7143
% date-2/8/19
syms x
y = 2*x^2-8*x+9;
g = diff(y);
f = solve(g)
a = subs(y,f)
fplot(y)
```

$f =$

2

$a =$

1



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---

```
% name-amlna nayak
% reg. no -19bcd7143
% date-9/8/19
syms x y
f=sin(pi*x)+sin(pi*y)
u=diff(f,x)
v=diff(u,x)
w=diff(f,y)
x=diff(w,y)
v+x

f =

sin(pi*x) + sin(pi*y)

u =

pi*cos(pi*x)

v =

-pi^2*sin(pi*x)

w =

pi*cos(pi*y)

x =

-pi^2*sin(pi*y)

ans =

- pi^2*sin(pi*x) - pi^2*sin(pi*y)
```

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---

```

% name-amlan nayak
% reg. no.-19bcd7143
% date-9/8/19
syms x y
f(x,y) = 10*x*y*exp(-(x^2 + y^2));
fx = diff(f,x)
fy = diff(f,y)
[xc,yc] = solve(fx,fy,x,y)
fxx = diff(fx,x)
fxy = diff(fx,y)
fyy = diff(fy,y)
D = fxx*fyy - fxy^2
k = solve(D)
figure(1); fsurf(f,[-2,2,-2,2]);

fx(x, y) =

10*y*exp(- x^2 - y^2) - 20*x^2*y*exp(- x^2 - y^2)

fy(x, y) =

10*x*exp(- x^2 - y^2) - 20*x*y^2*exp(- x^2 - y^2)

xc =

      0
-2^(1/2)/2
 2^(1/2)/2
-2^(1/2)/2
 2^(1/2)/2

yc =

      0
-2^(1/2)/2
-2^(1/2)/2
 2^(1/2)/2
 2^(1/2)/2

fxx(x, y) =

40*x^3*y*exp(- x^2 - y^2) - 60*x*y*exp(- x^2 - y^2)

fxy(x, y) =

10*exp(- x^2 - y^2) - 20*x^2*exp(- x^2 - y^2) - 20*y^2*exp(- x^2 -
y^2) + 40*x^2*y^2*exp(- x^2 - y^2)

```

---

---


$$f_{yy}(x, y) =$$

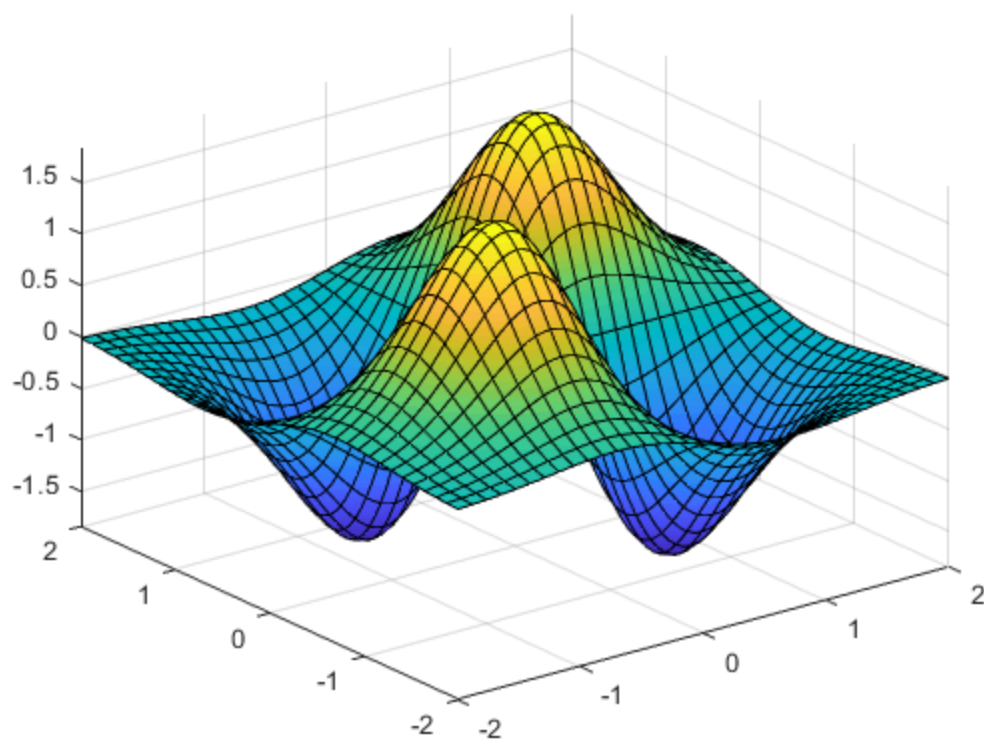
$$40*x*y^3*\exp(-x^2 - y^2) - 60*x*y*\exp(-x^2 - y^2)$$

$$D(x, y) =$$

$$(60*x*y*\exp(-x^2 - y^2) - 40*x^3*y*\exp(-x^2 - y^2))*(60*x*y*\exp(-x^2 - y^2) - 40*x^3*y*\exp(-x^2 - y^2)) - (10*\exp(-x^2 - y^2) - 20*x^2*\exp(-x^2 - y^2) - 20*y^2*\exp(-x^2 - y^2) + 40*x^2*y^2*\exp(-x^2 - y^2))^2$$

$$k =$$

$$\begin{aligned} & ((5*y^2 - 2*y^4 + y*(-(2*y^2 - 3)*(-2*y^4 + 11*y^2 + 4)))^{(1/2)} + 1)/(2*(2*y^2 + 1))^{(1/2)} \\ & ((5*y^2 - 2*y^4 - y*(-(2*y^2 - 3)*(-2*y^4 + 11*y^2 + 4)))^{(1/2)} + 1)/(2*(2*y^2 + 1))^{(1/2)} \\ & - ((5*y^2 - 2*y^4 + y*(-(2*y^2 - 3)*(-2*y^4 + 11*y^2 + 4)))^{(1/2)} + 1)/(2*(2*y^2 + 1))^{(1/2)} \\ & - ((5*y^2 - 2*y^4 - y*(-(2*y^2 - 3)*(-2*y^4 + 11*y^2 + 4)))^{(1/2)} + 1)/(2*(2*y^2 + 1))^{(1/2)} \end{aligned}$$



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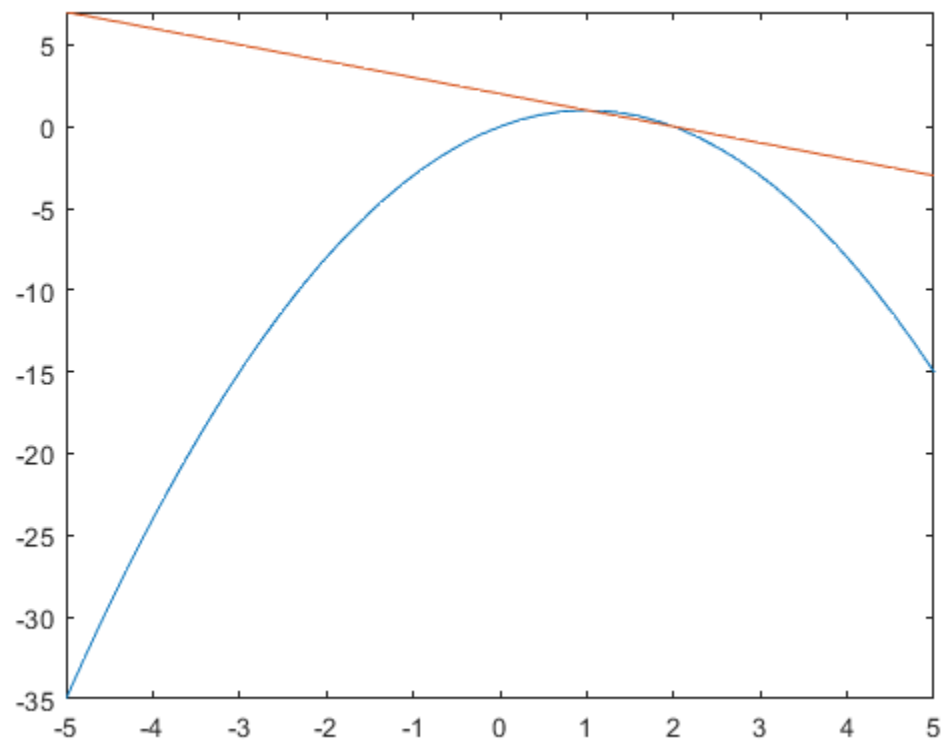
```
% name-amlan nayak
% reg no.-19bcd7143
% date-16/8/19
syms x
a = 2*x-x^2;
b = 2-x;
c = solve(a-b)
z = int(a-b,c)
fplot(a)
hold on
fplot(b)
```

$c =$

$1$   
 $2$

$z =$

$1/6$





```
% Name=Amlan Nayak
% Reg. no=19BCD7143
% Date=30/8/19

clc

clear all
syms x y z
z1= 4 - x^2 - y^2;
z2= x^2 + y^2;
d= 1 + x;
ry=solve(z1-z2,y);
ylim1=ry(1);
ylim2=ry(2);
rx=solve(ry(1),x);
xlim1=rx(1);
xlim2=rx(2);
volume=int(int(int(1,z,z2,z1),y,ylim2,ylim1),x,xlim1,xlim2)
vpa(volume)
M=int(int(int(d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)
Myz=int(int(int(x*d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)
Mxz=int(int(int(y*d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)
Mxy=int(int(int(z*d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)

C=[Myz/M , Mxz/M , Mxy/M]
```

```

Ix=int(int(int((y^2+z^2)*d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)
Iy=int(int(int((x^2+z^2)*d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)
Iz=int(int(int((x^2+y^2)*d,z,z1,z2),y,ylim2,ylim1),x,xlim2,xlim1)

```

```
viewSolid(z,z2,z1,y,ylim2,ylim1,x,-2^(1/2),2^(1/2))
rotate3d on
```

volume =

 $4\pi$ 

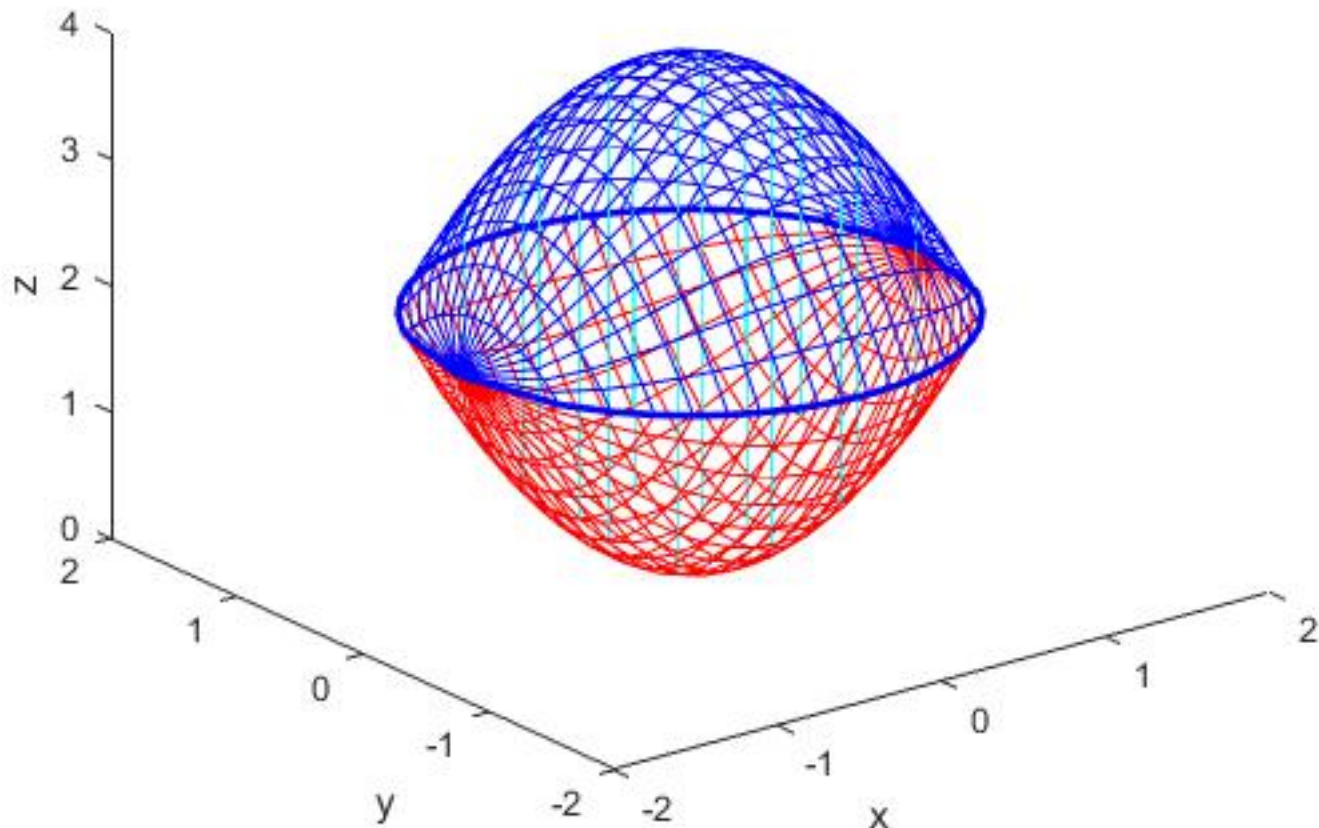
```
ans =  
12.566370614359172953850573533118
```

$$M =$$
 $4\pi$ 
$$M_{yz} = (4\pi)/3$$
$$M_{xz} =$$

0

$$M_{xy} =$$

C =

$$[1/3, 0, 2]$$
$$I_X =$$
 $20\pi$ 
$$I_Y =$$
 $20\pi$ 
$$I_Z =$$
$$(8\pi)/3$$
[illegible]

---

```
% name-amlan nayak
% reg. no.-19bcd7143
% date-6/9/19
syms x y z
f=x*y + y*z + z*x;
gradient(f,[x,y,z])
```

```
ans =
```

```
 y + z
 x + z
 x + y
```

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---

```
% name-amlan nayak
% reg. no.-19bcd7143
% date-6/9/19
syms x y z
f=[3*x^2*y y*z x*y];
vars=[x y z];
divergence(f,vars)
```

```
ans =
```

```
z + 6*x*y
```

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---

```
% name-amlan nayak
% reg. no.-19bcd7143
% date-6/9/19
syms x y z
f=[x^2*y*z x*y^2*z x*y*z^2];
curl(f,[x,y,z])
```

```
ans =
```

$$\begin{aligned} & x^2z^2 - x^2y^2 \\ & y^2x^2 - y^2z^2 \\ & - z^2x^2 + z^2y^2 \end{aligned}$$

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---

```
% name-amlan nayak
% reg no-19BCD7143
% date-13/9/19

syms x y z t
f = [z x*y -y^2]
r = [t^2 t sqrt(t)]
l=0
u=1
dr1 = diff(r,t)
f1 = subs(f,[x,y,z],[r(1),r(2),r(3)])
nf = f1.*dr1
nf1 = sum(nf)
i = int(nf1,t,l,u)
```

$f =$

$[z, x*y, -y^2]$

$r =$

$[t^2, t, t^{(1/2)}]$

$l =$

0

$u =$

1

$dr1 =$

$[2*t, 1, 1/(2*t^{(1/2)})]$

$f1 =$

$[t^{(1/2)}, t^3, -t^2]$

$nf =$

$[2*t^{(3/2)}, t^3, -t^{(3/2)}/2]$

$nf1 =$

---

$$t^3 + (3*t^{(3/2)})/2$$

$$i =$$

$$17/20$$

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```
% name-amlan nayak  
% reg no.-19bcd7143  
% date- 20/9/19
```

```
clc  
clear all  
syms x y t  
F = [x-y x];  
r = [cos(t) sin(t)]
```

```
r = (cos(t) sin(t))
```

```
l = 0
```

```
l = 0
```

```
u = 2*pi
```

```
u = 6.2832
```

```
dr1 = diff(r,t)
```

```
dr1 = (-sin(t) cos(t))
```

```
f1 = subs(F,[x,y],[r(1),r(2)])
```

```
f1 = (cos(t) - sin(t) cos(t))
```

```
nf = f1.*dr1
```

```
nf = (-sin(t) (cos(t) - sin(t)) cos(t)^2)
```

```
nf1 = sum(nf)
```

```
nf1 = cos(t)^2 - sin(t) (cos(t) - sin(t))
```

```
i = int(nf1,t,l,u)
```

```
i = 2 pi
```

```
P = inline(vectorize(F(1)), 'x', 'y')
```

```
P =
```

```
Inline function:  
P(x,y) = x - y
```

```
Q = inline(vectorize(F(2)), 'x', 'y')
```

```
Q =
```

```
Inline function:  
Q(x,y) = x
```

```
x = linspace(0,2*pi,10);y=x
```

```
y = 1x10
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869 ...
```

```
[X,Y] = meshgrid(x,y)
```

```
X = 10x10
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869 ...
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
```

```
Y = 10x10
    0    0    0    0    0    0    0    0 ...
    0.6981    0.6981    0.6981    0.6981    0.6981    0.6981    0.6981    0.6981
    1.3963    1.3963    1.3963    1.3963    1.3963    1.3963    1.3963    1.3963
    2.0944    2.0944    2.0944    2.0944    2.0944    2.0944    2.0944    2.0944
    2.7925    2.7925    2.7925    2.7925    2.7925    2.7925    2.7925    2.7925
    3.4907    3.4907    3.4907    3.4907    3.4907    3.4907    3.4907    3.4907
    4.1888    4.1888    4.1888    4.1888    4.1888    4.1888    4.1888    4.1888
    4.8869    4.8869    4.8869    4.8869    4.8869    4.8869    4.8869    4.8869
    5.5851    5.5851    5.5851    5.5851    5.5851    5.5851    5.5851    5.5851
    6.2832    6.2832    6.2832    6.2832    6.2832    6.2832    6.2832    6.2832
```

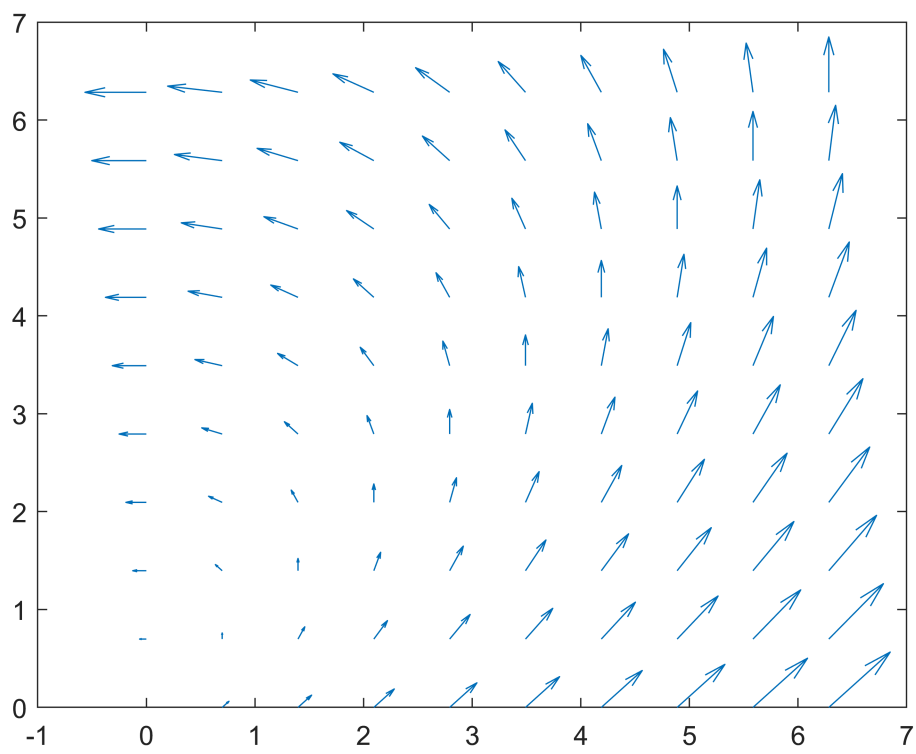
```
U = P(X,Y)
```

```
U = 10x10
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869 ...
   -0.6981    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888
   -1.3963   -0.6981    0    0.6981    1.3963    2.0944    2.7925    3.4907
   -2.0944   -1.3963   -0.6981    0    0.6981    1.3963    2.0944    2.7925
   -2.7925   -2.0944   -1.3963   -0.6981    0    0.6981    1.3963    2.0944
   -3.4907   -2.7925   -2.0944   -1.3963   -0.6981    0    0.6981    1.3963
   -4.1888   -3.4907   -2.7925   -2.0944   -1.3963   -0.6981    0    0.6981
   -4.8869   -4.1888   -3.4907   -2.7925   -2.0944   -1.3963   -0.6981    0
   -5.5851   -4.8869   -4.1888   -3.4907   -2.7925   -2.0944   -1.3963   -0.6981
   -6.2832   -5.5851   -4.8869   -4.1888   -3.4907   -2.7925   -2.0944   -1.3963
```

```
V = Q(X,Y)
```

```
V = 10x10
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869 ...
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
    0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869
```

```
quiver(x,y,U,V)
```



```
% name-amlan nayak
% reg no.-19BCD7143
% date-20/9/19
```

```
clc
clear all
syms x y z t
F = [x z y];
r = [cos(t) sin(t) t]
```

```
r = (cos(t) sin(t) t)
```

```
l = 0
```

```
l = 0
```

```
u = pi/2
```

```
u = 1.5708
```

```
dr1 = diff(r,t)
```

```
dr1 = (-sin(t) cos(t) 1)
```

```
f1 = subs(F,[x,y,z],[r(1),r(2),r(3)])
```

```
f1 = (cos(t) t sin(t))
```

```
nf = f1.*dr1
```

```
nf = (-cos(t) sin(t) t cos(t) sin(t))
```

```
nf1 = sum(nf)
```

```
nf1 = sin(t) - cos(t) sin(t) + t cos(t)
```

```
i = int(nf1,t,l,u)
```

```
i =
```

$$\frac{\pi}{2} - \frac{1}{2}$$

```
P = inline(vectorize(F(1)), 'x', 'y', 'z')
```

```
P =
```

```
Inline function:
P(x,y,z) = x
```

```
Q = inline(vectorize(F(2)), 'x', 'y', 'z')
```

```
Q =
```

```
Inline function:
Q(x,y,z) = z
```

```
R = inline(vectorize(F(3)), 'x', 'y', 'z')
```

```
R =
```

```
Inline function:
```

```
R(x,y,z) = y
```

```
x = linspace(0,2*pi,10);y=x;z=x
```

```
z = 1×10
```

```
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869 ...
```

```
[X,Y,Z] = meshgrid(x,y,z)
```

```
X =
```

```
X(:, :, 1) =
```

```
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
```

```
X(:, :, 2) =
```

```
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
```

```
X(:, :, 3) =
```

```
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
```

```
X(:, :, 4) =
```

```
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
0    0.6981    1.3963    2.0944    2.7925    3.4907    4.1888    4.8869    5.5851    6.2832
```

















[illegible][illegible][illegible][illegible][illegible]







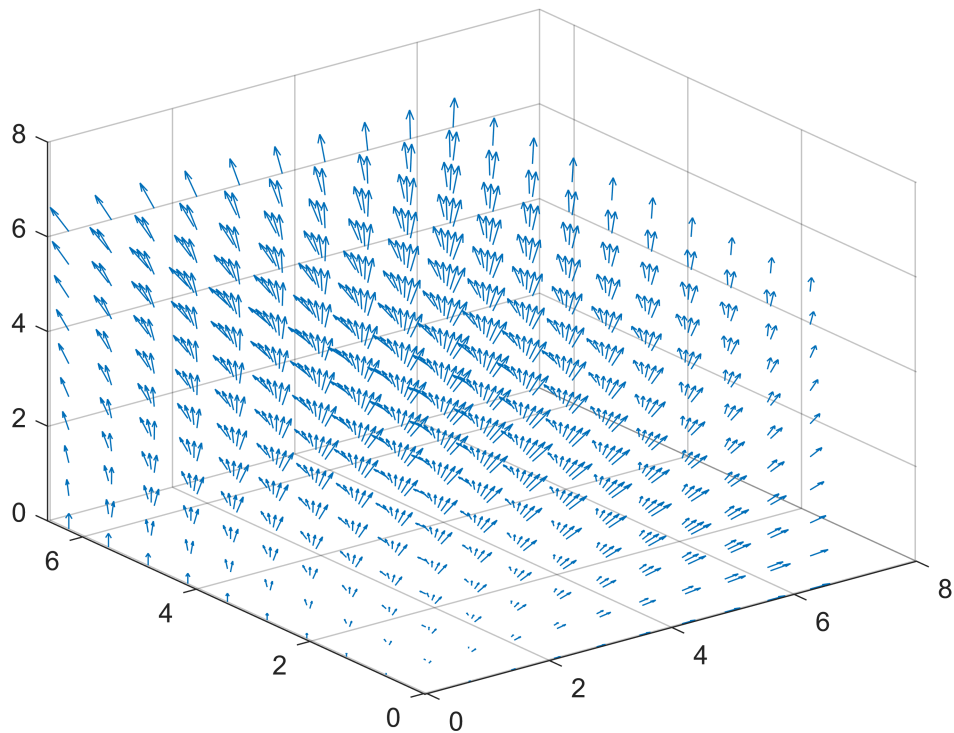




W(:, :, 10) =

0	0	0	0	0	0	0	0	0	0
0.6981	0.6981	0.6981	0.6981	0.6981	0.6981	0.6981	0.6981	0.6981	0.6981
1.3963	1.3963	1.3963	1.3963	1.3963	1.3963	1.3963	1.3963	1.3963	1.3963
2.0944	2.0944	2.0944	2.0944	2.0944	2.0944	2.0944	2.0944	2.0944	2.0944
2.7925	2.7925	2.7925	2.7925	2.7925	2.7925	2.7925	2.7925	2.7925	2.7925
3.4907	3.4907	3.4907	3.4907	3.4907	3.4907	3.4907	3.4907	3.4907	3.4907
4.1888	4.1888	4.1888	4.1888	4.1888	4.1888	4.1888	4.1888	4.1888	4.1888
4.8869	4.8869	4.8869	4.8869	4.8869	4.8869	4.8869	4.8869	4.8869	4.8869
5.5851	5.5851	5.5851	5.5851	5.5851	5.5851	5.5851	5.5851	5.5851	5.5851
6.2832	6.2832	6.2832	6.2832	6.2832	6.2832	6.2832	6.2832	6.2832	6.2832

quiver3(X,Y,Z,U,V,W)



```
% name - amlan nayak
% reg no.-19BCD7143
% date-20/9/19
syms x y t m n
F = [m,n]
```

$$F = \begin{pmatrix} m & n \end{pmatrix}$$

$$x = \cos(t)$$

$$x = \cos(t)$$

$$y = \sin(t)$$

$$y = \sin(t)$$

$$dx = \text{diff}(x,t)$$

$$dx = -\sin(t)$$

$$dy = \text{diff}(y,t)$$

$$dy = \cos(t)$$

$$m = x - y$$

$$m = \cos(t) - \sin(t)$$

$$n = x$$

$$n = \cos(t)$$

$$i = \text{int}(m*dy,t,0,2*\pi)$$

$$i = \pi$$

$$j = \text{int}(n*dx,t,0,2*\pi)$$

$$j = 0$$

$$\text{flux} = i-j$$

$$\text{flux} = \pi$$

---

```
% name-amlan shivam nayak
% reg no.-19bcd7143
% date-11/10/19
clear all
clc
syms x y t
f = [x-y x]
m = x-y
n = x
p = diff(n,y)
q = diff(m,x)
x = cos(t)
y = sin(t)
s = int(p+q,t,0,2*pi)
```

$f =$

$[x - y, x]$

$m =$

$x - y$

$n =$

$x$

$p =$

$0$

$q =$

$1$

$x =$

$\cos(t)$

$y =$

$\sin(t)$

$s =$

---

$2\pi i$

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---

```
% name-amlan shivam nayak
% reg no.-19bcd7143
% date-11/10/19
clear all
clc
syms x y t
f = [x-y x]
m = x-y
n = x
p = diff(n,x)
q = diff(m,y)
x = cos(t)
y = sin(t)
s = int(p-q,t,0,2*pi)
```

$f =$

$[x - y, x]$

$m =$

$x - y$

$n =$

$x$

$p =$

$1$

$q =$

$-1$

$x =$

$\cos(t)$

$y =$

$\sin(t)$

$s =$

---

$4\pi i$

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---

```
% name-Amlan Shivam Nayak
% reg no.-19bcd7143
% date-18/10/19
clear all
clc
syms v(x) c b
ode = v*diff(v,x) + b*v^2 + c*x == 0;
vSol(x) = dsolve(ode)
vSol(0)

vSol(x) =

    ((exp(-2*b*x)*(C3 + c*exp(2*b*x) - 2*b*c*x*exp(2*b*x)))/
(2*b^2))^(1/2)
    -((exp(-2*b*x)*(C3 + c*exp(2*b*x) - 2*b*c*x*exp(2*b*x)))/
(2*b^2))^(1/2)

ans =

    ((C3 + c)/(2*b^2))^(1/2)
    -((C3 + c)/(2*b^2))^(1/2)
```

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---

```
% name-Amlan Shivam Nayak
% reg no.-19bcd7143
% date-18/10/19
clear all
clc
syms i(t) r l v e
l=0.5
e=20
r=100
f=e/l==(r/l)*i + diff(i,t)
F(t)=dsolve(f,i(0)==0)
F(0.5)

l =

    0.5000

e =

    20

r =

    100

f(t) =

40 == 200*i(t) + diff(i(t), t)

F(t) =

1/5 - exp(-200*t)/5

ans =

1/5 - exp(-100)/5
```

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```
% name-amlan nayak
% reg no.-19bcd7143
% date-25/10/19
clear all
clc
syms y(t)
ode = diff(y,t) + (y/(10+t))*2 == 0;
y(t) = dsolve(ode,y(0)==20)
```

y(t) =  
$$\frac{2000}{(t + 10)^2}$$

```
vpa(y(5))
```

```
ans = 8.8888888888888888888888888888889
```

```

% name-amlan nayak
% reg no.-19bcd7143
% date-25/10/19
clear all
clc
syms y(x)
Dy = diff(y);
ode = diff(y,x,2) -3*diff(y,x) +2*y ==x^2 + exp(x);
ySol(x) = dsolve(ode)

```

ySol(x) =

$$C_3 e^x - e^{2x} \left( e^{-x} + e^{-2x} \left( \frac{x^2}{2} + \frac{x}{2} + \frac{1}{4} \right) \right) + e^x (2 e^{-x} - x + 2 x e^{-x} + x^2 e^{-x}) + C_4 e^{2x}$$

```

% name-amlan nayak
% reg no.-19bcd7143
% date-25/10/19
clear all
clc
syms y(x) x
Dy = diff(y);
ode = diff(y,x,2) +y == 2*cos(x);
ySol(x) = dsolve(ode)

```

ySol(x) =

$$\frac{\cos(3x)}{4} + \frac{3\cos(x)}{4} + C_3 \cos(x) - C_4 \sin(x) + \sin(x) \left( x + \frac{\sin(2x)}{2} \right)$$