m-Consensus Objects Are Pretty Powerful

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— Abstract

A recent paper by Afek, Ellen, and Gafni introduced a family of deterministic objects $O_{m,k}$, for $m,k \geq 2$, with consensus numbers m such that, for each $k \geq 2$, $O_{m,k}$ is computationally less powerful than $O_{m,k+1}$ in systems with at least mk+m+k processes. This paper gives a wait-free implementation of $O_{m,k}$ from (m+1)-consensus objects and registers in systems with any finite number of processes. In order to do so, it introduces a new family of objects which helps us to understand the power of m-consensus among more than m processes.

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1 Introduction

The consensus problem is a fundamental problem in distributed computing that has long been used to categorize the computational powers of shared objects. Herlihy [5] defined the consensus number of an object, which is the largest number of processes for which wait-free consensus can be achieved using only instances of the object and registers. Thus an object O with consensus number n cannot be implemented in a wait-free manner by an object O' with consensus number n' < n in a system with more than n' processes. The consensus hierarchy classifies objects by their consensus numbers.

Herlihy also proved that any object can be implemented by n-consensus objects and registers (and, hence, by any objects with consensus number n) in systems with n or fewer processes. However, the relative computational powers of objects with the same consensus number n in systems of more than n processes is not entirely understood.

Afek, Gafni, Tromp, and Vitányi [3] showed that test-and-set objects, which have consensus number 2, can be implemented from 2-consensus objects and registers in a system with any finite number of processes. Afek, Weisberger, and Weisman [4] and Afek, Gafni, and Morrison [2] proved that this is also true for other well-known objects of consensus number 2, such as fetch-and-increment objects, swap objects, and stacks. It was conjectured [4] that this is true for any object with consensus number 2. This is known as the *Common2 Conjecture*. More generally, the *Consensus Hierarchy Conjecture* asserts that for $n \geq 2$, every shared object of consensus number $n' \leq n$ has a wait-free implementation from n-consensus objects and registers in every system with a finite number of processes.

Rachman [6] disproved the Consensus Hierarchy Conjecture for nondeterministic objects. He showed that for any m' and m, with $m' \ge m \ge 1$, there exists a nondeterministic object X with consensus number m, such that X cannot be implemented using only m'-consensus objects and registers in systems with at least 2m' + 1 processes. This means that the

consensus hierarchy, at least on its own, is not very useful in characterizing the computational powers of nondeterministic objects.

Afek, Ellen, and Gafni [1] proved that the Consensus Hierarchy Conjecture does not even hold for the class of deterministic objects. They introduced the $O_{m,k}$ object, for $m,k \geq 2$, and showed that each $O_{m,k}$ object has consensus number m, but cannot be implemented (in a non-blocking manner) from m-consensus objects and registers in any system with at least km + k - 1 processes. More surprisingly, they showed that an $O_{m,k+1}$ object cannot be implemented (in a non-blocking manner) from $O_{m,k}$ objects and registers in any system with at least mk + m + k processes, meaning that $O_{m,2}, O_{m,3}, \ldots$ is an infinite sequence of objects with increasing computational power, all with consensus number m.

This paper determines the relationship between $O_{m,k}$ objects and (m+1)-consensus objects. Section 4 presents a wait-free implementation of every $O_{m,k}$ object from (m+1)-consensus objects and registers among any finite number of processes. Thus, $O_{m,k}$ objects lie strictly between m-consensus objects and (m+1)-consensus objects in terms of computational power. This provides additional understanding of the consensus hierarchy for deterministic objects and is a step towards a characterization of their computational power.

For our implementation, we introduce a new family of deterministic objects, Q_r , for $r \geq 0$, which serves as a crucial synchronization mechanism. The Q_r object is a generalization of the test-and-set object: it has an operation which allows the first process that performs it to win and all subsequent processes to fail. In addition, there is another operation that returns the identity of the winner to the first r processes who perform it after the object has been won. Section 3 formally defines the Q_r object, proves that it has consensus number r+2, and proves that it has a wait-free implementation from (r+2)-consensus objects and registers in any system with a finite number of processes. It is hoped that the Q_r object will be a useful tool for determining the power of (r+2)-consensus objects in systems of more than r+2 processes.

2 Model

We consider an asynchronous shared memory system, with n processes, p_1, p_2, \ldots, p_n , which communicate by applying operations to shared objects. A *step* by any process consists of an operation it is performing on a shared object as well as the response received from the operation.

A configuration of the shared memory system consists of the current state of every process, as well as the current value of every shared object. An initial configuration is a configuration where all processes and shared objects are in one of their initial states. An execution is specified by an alternating sequence of configurations and steps by processes, beginning at an initial configuration, such that if a configuration C is immediately followed by a step s of process p_i , which is immediately followed by a configuration C', then p_i performing step s in configuration C yields the configuration C'.

An implementation of a sequentially specified shared object O from a set of shared base objects is given by providing an algorithm for each operation of O in which processes only access the base objects. The implementation is linearizable if, in any execution \mathcal{E} , we can order each completed operation as well a subset of incomplete operations on O such that the results of each operation in this order are consistent with the sequential specification of O, and, moreover, an operation that completes before another operation begins comes earlier in the order. Equivalently, the implementation is linearizable if, in any execution \mathcal{E} , we can assign a (distinct) linearization point to each completed operation as well as

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a subset of incomplete operations such that the linearization point of every operation is within the execution interval of that operation and the results of each operation in the order induced by the linearization points are consistent with the sequential specification of O. The implementation is wait-free if every process that performs any operation of O completes the operation in a finite number of its own steps. The implementation is non-blocking if, from every configuration of any execution, there is some process that completes its operation in a finite number of steps.

Consensus can be solved by n processes, p_1, p_2, \ldots, p_n , if there exists an algorithm such that, if every process p_i is assigned some input x_i , each process outputs at most one value, satisfying the following conditions:

- validity: If p_i outputs y_i , then there exists some j such that $y_i = x_j$.
- **a** agreement: If p_i outputs y_i and p_j outputs y_j , then $y_i = y_j$.
- **termination:** Every process that takes sufficiently many steps outputs a value.

The m-consensus object is a shared object with a single operation PROPOSE that takes one argument. The first m PROPOSE operations to an m-consensus object return the argument of the first PROPOSE operation. We say that this value is the decision of the m-consensus object. All other operations return \bot .

The test-and-set object is a shared object with a single operation T&S, which returns true for the first operation and false for all subsequent operations.

The fetch-and-increment object is a shared object and has a single operation F&I, which returns the value a + i - 1 to the i^{th} operation, where a was the initial value of the object.

Throughout this paper, we assume that the initial value of every fetch-and-increment object is 1 and the initial value of every register is \perp .

3 The Q_r object

We now formally define the Q_r object and explain how it can be used together with registers to solve consensus among r+2 processes. Then, in Section 3.1, we prove that it can be implemented from (r+2)-consensus objects and registers in a system with any finite number of processes.

The Q_r object, for $r \ge 0$, has two operations, COMPETE and QUERY, with the following specifications:

- The first COMPETE operation returns *true* and the process that performs it is called the *winner* of the object. All subsequent COMPETE operations return *false*.
- The first r QUERY operations after the first COMPETE operation return the id of the winner. All other QUERY operations return \perp .

If processes perform only COMPETE operations, then a Q_r object behaves like a test-and-set object. In particular, Q_0 is equivalent to a test-and-set object and, thus, has consensus number 2. The additional power of a Q_r object for r>0 is due to the r query operations that can be used to determine the winner.

The Q_r object can solve consensus among r+1 processes: Each process announces its input in a single writer register before calling COMPETE on a shared Q_r object. The winner decides its own input, whereas the r losers call QUERY to find the identity of the winner, and then read and decide the winner's announced value.

It is only slightly more difficult to see that the Q_r object can solve consensus among r+2 processes. As before, each of the processes, $p_1, p_2, \ldots, p_{r+2}$, first announces its input in a single writer register. Next, processes perform COMPETE on a Q_r object and the winner

decides its own input. The problem is that there are r+1 processes that are not the winner of the Q_r object and may need to learn the identity of the winner. However, the Q_r object can only return the identity of the winner to at most r processes. To resolve this, each process that loses its compete operation first overwrites its announced value with \perp before calling QUERY on the Q_r object. If its QUERY operation is successful, then, as before, it reads and decides the announced value of the winner. However, if its QUERY operation was unsuccessful, then r+1 processes have already called QUERY on the Q_r object by this point. Prior to calling QUERY, these processes overwrote their announced values. Thus, exactly one value remains in the announcement array: the value of the winner. The code is provided in Algorithm 1.

Algorithm 1 A solution to (r+2)-consensus

```
Shared variables:
q is a Q_r object
announce[1...r+2] is an array of registers
p1: function PROPOSE(v) by process p_i for i \in \{1, ..., r+2\}
p2:
       announce[i].WRITE(v)
       if q.COMPETE() then
p3:
           return v
p4:
p5:
       end if
       announce[i].WRITE(\bot)
p6:
p7:
       winner \leftarrow q.QUERY()
       if winner \neq \bot then
p8:
           return announce[winner].READ()
p9:
        end if
p10:
        for j \leftarrow 1 to r + 2 do
p11:
            value \leftarrow announce[j].READ()
p12:
p13:
            if value \neq \bot then
                return value
p14:
            end if
p15:
p16:
        end for
p17: end function
```

- **Description 1.** Algorithm 1 solves the consensus task among r+2 processes
- ▶ **Lemma 2.** The Q_r object has consensus number at least r+2.

An implementation from (r+2)-consensus objects

We now give a wait-free implementation of a Q_r object shared among any finite number n of processes using only (r+2)-consensus objects and registers. In particular, this shows that the Q_r object has consensus number at most r+2.

Our implementation uses an array cons[1...n] of (r+2)-consensus objects, a register gate, and a fetch-and-increment object count. Note that fetch-and-increment objects have a wait-free implementation from 2-consensus objects (and, hence, from (r+2)-consensus objects, since $r \geq 0$) and registers among any finite number of processes [4].

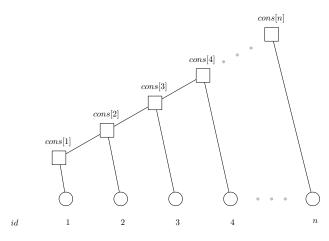
Processes that call COMPETE participate in a tournament to decide which operation returns true. However, we must prevent the situation where, after a COMPETE operation A. Qadri

returns false, another COMPETE operation begins and returns true. No linearization of such an execution would be consistent with the sequential specifications of COMPETE.

To prevent this issue, a process p_i performing COMPETE first checks the value of the shared register gate. If $gate \neq \bot$, the COMPETE operation returns false. Otherwise, p_i writes its own id, i, to gate. This ensures all processes calling COMPETE that write their id to gate are concurrent. This idea was used in the wait-free implementation of an n-process test-and-set object from 2-process test-and-set objects and registers [3].

After process p_i writes to gate, it continues by entering a tournament. It proposes i to cons[i] through cons[n] in order. If it receives a response other than i from one of these consensus objects, it immediately returns false and does not propose i to any further consensus objects. If the responses it receives from cons[i] through cons[n] are all i, then p_i returns true. The tournament is depicted in Figure 1. Note that cons[1] is only used for simplifying the code and proof of correctness. It is otherwise unnecessary.

Figure 1 Tournament to determine winner



To perform QUERY, a process p_i first reads the value i' in gate. If $i' = \bot$, then no process performing COMPETE has written its id to gate and taken part in the tournament, so p_i returns \bot . If $i' \neq \bot$, p_i performs F&I on count and, if the value returned is greater than r, returns \bot . Note that at most r QUERY operations proceed past this point. If a COMPETE operation has already returned true, p_i could just propose to cons[n] to get the id of the winner. However, this is not guaranteed. The competing processes may be slow or the winning process may have crashed before proposing to cons[n]. Thus, p_i attempts to assist participants in the tournament by propagating their ids. It begins by proposing i', the id it read from gate, to cons[i']. Then it proposes the decision of cons[j-1] to cons[j] for $i' < j \le n$ in order. Finally, it returns the decision of cons[n], which is the id of the winner.

We now prove the correctness of the implementation of a Q_r object given in Algorithm 2. Let \mathcal{E} be any execution of the implementation.

The code for COMPETE and QUERY is presented in Algorithm 2.

We will say that a COMPETE or QUERY operation performs a step σ in the execution if the process performing the operation executes σ during the operation.

We consider three cases.

In the first case, suppose that no operation in execution \mathcal{E} ever writes to gate. That is, suppose no COMPETE operation executes line c5 during execution \mathcal{E} . Then no COMPETE operation returns, since the value of gate remains \bot throughout execution \mathcal{E} . Thus, line c3 is not executed, nor are lines c8 or c11. All COMPETE operations are therefore incomplete and

Algorithm 2 An implementation of Q_r

Shared variables:

```
cons[1...n] is an array of (r+2)-consensus objects gate is a register initialized to \bot count is a fetch-and-increment object initialized to 1
```

```
q1: function QUERY()
c1: function COMPETE() by process p_i
                                                                  i' \leftarrow gate.READ()
        if gate.READ() \neq \bot then
                                                          q2:
c2:
                                                                  if i' = \bot then
            return false
                                                         q3:
c3:
c4:
        end if
                                                          q4:
                                                                      return \perp
                                                                  end if
        gate.WRITE(i)
                                                          q5:
c5:
                                                                  if count.F\&I() > r then
        for j \leftarrow i to n do
                                                          q6:
c6:
                                                                      return \perp
            if cons[j].PROPOSE(i) \neq i then
                                                         q7:
c7:
                                                                  end if
c8:
                return false
                                                          q8:
                                                                  start \leftarrow i'
c9:
            end if
                                                         q9:
                                                                   for j \leftarrow start to n do
                                                         q10:
c10:
         end for
                                                         q11:
                                                                       i' \leftarrow cons[j].PROPOSE(i')
         return true
c11:
                                                                   end for
c12: end function
                                                         q12:
                                                                   return i'
                                                         q13:
                                                         q14: end function
```

we do not linearize any of them. All QUERY operations that complete return \bot on line q4. We can define the linearization point of each of these QUERY operations to be the time at which the operation executes line q2. Since all linearized QUERY operations return \bot and no COMPETE operation has been linearized, this linearization is consistent with the sequential specifications of a Q_T object.

In the second case, suppose that line c5 is executed by some operation in execution \mathcal{E} , but no value is ever proposed to any consensus object. That is, neither line c7 nor line q11 is executed by any operation in \mathcal{E} . Then let C be the COMPETE operation during which the first write to gate takes place and let p_w be the process that performs operation C. Define the linearization point of operation C to be the step at which it writes to gate in line c5. In this execution, every COMPETE operation that completes returns false on line c3. For every such completed COMPETE operation, define its linearization point to be the step at which it reads from gate in line c2. It follows that for every completed COMPETE operation C', operation C is linearized before operation C', since the read operation performed by C' in line c2 returned a value other than \bot , meaning that the first write to gate, in line c5 of C, had already taken place.

We also linearize the QUERY operations as follows: Every QUERY operation that returns \bot on line q4 is linearized at the point it executes the read of gate in line q2. Thus, every such operation Q is linearized before C, since Q reads \bot from gate. The QUERY operations that perform F&I on count are linearized at the point they execute line q6. Each of these QUERY operations is linearized after C, since it reads a value other than \bot from gate in line q2. Moreover, if one of these QUERY operations Q returns \bot , it does so after count has already been incremented r times by r other QUERY operations that executed line q6. So there at least r QUERY operations linearized after C and before every such operation Q. This linearization is consistent with the sequential specifications of a Q_r object.

Finally, we consider any execution \mathcal{E} where some value is proposed to a consensus object on line c7 or q11 during some operation in \mathcal{E} . Processes are referred to as *competitors* while

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they execute lines c5–c11 and as queriers while they execute lines q9–q13. Note that only competitors and queriers access consensus objects, and there are at most r queriers.

▶ Observation 3. A process can only be a competitor in its first invocation of COMPETE, so every competitor has a distinct id.

We say that i is accepted by a consensus object if it is the decision of the consensus object. If i is proposed, but is not accepted, we say it is rejected from the consensus object.

Competitor p_i only proposes its id, i, to cons[j] if j = i or if i was accepted by cons[j-1]. Every querier begins by reading some competitor's id, i', in gate. It proposes this value i' to cons[i'] in the first iteration of the for loop in line q10. In every subsequent iteration, it proposes the value accepted by cons[j-1] to cons[j]. This gives us the following observation:

▶ **Observation 4.** For any j > 1, the only possible values proposed to cons[j] are j and the value accepted by cons[j-1]. The only possible value proposed to cons[1] is 1.

From Observation 4, we get the following useful results:

▶ **Lemma 5.** If i < j is proposed to cons[j], then i was accepted by $cons[\ell]$, for all $i \le \ell < j$.

Proof. Suppose not. Consider the largest $\ell < j$ such that i was not accepted by $cons[\ell]$. If $\ell < j-1$, this means that i was accepted by $cons[\ell+1]$ and, hence, from the semantics of PROPOSE, was proposed to $cons[\ell+1]$. If $\ell = j-1$, then i was proposed to $cons[\ell+1]$ by assumption. In either case, since $i < \ell+1$, it follows from Observation 4 that the value i was accepted by $cons[\ell]$. This is a contradiction.

▶ **Lemma 6.** No process that proposes to the (r + 2)-consensus object cons[j] receives a response of \bot .

Proof. By Observation 4, there are at most two distinct values proposed to cons[j]. Since every competitor only proposes its own id, by Observation 3, we conclude that there are at most 2 competitors that propose to cons[j]. No competitor proposes to cons[j] more than once. Additionally, there are at most r queriers and each querier proposes to cons[j] at most once. It follows that there are at most r + 2 propose operations performed on cons[j] and, hence, none of them receive a response of \bot .

By examining the code, we can learn the following fact about the values proposed to consensus objects:

▶ **Observation 7.** The value i is only proposed to cons[j] if there exists a competitor with id i that has already written i to gate on line c5.

We will now show that execution \mathcal{E} is linearizable.

Recall that during execution \mathcal{E} , some value is proposed to some consensus object. Consider the smallest j such that some value is proposed to cons[j]. By Observation 4, the only value proposed to cons[j] is j. It follows that j is accepted by cons[j]. Let w be the greatest value such that w is accepted by cons[w] in execution \mathcal{E} . Let C_w be the first COMPETE operation of process p_w . By Observations 3 and 7, C_w exists and writes w to gate in line c5 (after reading \bot from gate in line c2). Thus, operation C_w is concurrent with the first write to gate and we linearize it at that point. Every COMPETE operation that returns on line c3 is linearized at the point it executes line c2 and every COMPETE operation that returns on line c8 is linearized at the point of its preceding proposal to a consensus object in line c7.

We now show that C_w is the only COMPETE operation that can return on line c11. This means that we have linearized every completed COMPETE operation.

▶ **Lemma 8.** If i is accepted by cons[n], then i = w.

Proof. Since i is accepted by cons[n], then, by Lemma 5, it is also accepted by $cons[\ell]$, for all $i \leq \ell < n$. Thus i was accepted by cons[i] and, for any j > i, j was not accepted by cons[j]. So i = w.

Corollary 9. The only COMPETE operation that can return true is operation C_w .

Proof. If COMPETE operation C by process p_i returns true, then i is accepted at cons[n] so, by Lemma 8, i = w. By Observation 3, only the first COMPETE operation of any process can return true, so $C = C_w$.

▶ **Lemma 10.** Any linearized COMPETE operation $C \neq C_w$ is linearized after C_w .

Proof. Consider any such operation C. Since $C \neq C_w$ is linearized, C has completed and so it returns on line c3 or line c8 by Corollary 9. If operation C returns on line c3, it is linearized when it reads some value other than \bot from gate in line c2. Since C_w is linearized at the earliest write to gate in execution \mathcal{E} , C_w is linearized before C. On the other hand, if operation C returns on line c8, then it performs a write to gate in line c5, which is at or after the linearization point of C_w . Operation C is linearized later, when it performs its last proposal to a consensus object in line c7. Thus, C_w is linearized before C.

It follows that p_w is the winner in the linearization of execution \mathcal{E} . From Corollary 9, we know that C_w is the only operation that can return true. We must also argue that it does not return false:

▶ Lemma 11. Operation C_w does not return false.

Proof. For COMPETE operation C_w to return false, w must be rejected from cons[j], for some j > w. Consider any such j. By Observation 4, w was accepted by cons[j-1] and j was the only other value proposed to cons[j]. Since w was rejected from cons[j], it follows that j was accepted by cons[j]. But this contradicts the definition of w.

Finally, we can show that it is possible to linearize the QUERY operations. As in the second case, every QUERY operation that returns on line q4 is linearized at the point it reads \bot from gate in line q2. This is before the first write to gate, which is when C_w is linearized. Every QUERY operation that calls F&I on count in line q6 is linearized at the point it executes line q6, which occurs after it reads a value other than \bot from gate in line q2 and, thus, after the linearization point of C_w . Note that all completed QUERY operations either return on q4 or execute line q6. By the semantic of F&I, the QUERY operations that execute line q6 are linearized in increasing order of the values they receive from count. In particular, if some such QUERY operation receives a value greater than r, at least r other QUERY operations have been linearized before it (and after C_w).

▶ Corollary 12. Every QUERY operation that receives a value of r or less from count can only return the id of the winner p_w .

Proof. Any such QUERY operation can only return in line q13 and it returns the value accepted by cons[n], which, by Lemma 8, is w.

Thus, the linearization of execution \mathcal{E} is consistent with the sequential specifications of a Q_r object. Since \mathcal{E} was chosen arbitrarily, every execution of Algorithm 2 is linearizable. Note that the implementations of COMPETE and QUERY in Algorithm 2 are wait-free. Therefore, we have shown the following theorem:

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▶ Theorem 13. For $r \ge 0$, Q_r has consensus number r + 2 and can be implemented in a wait-free manner from (r + 2)-consensus objects and registers in a system with any finite number of processes.

4 Implementing $O_{m,k}$ from (m+1)-consensus objects

In this section, we present the formal definition of the $O_{m,k}$ object from [1], followed by a description of a natural, but incorrect, approach for implementing the $O_{m,k}$ object from (m+1)-consensus objects and registers for any number of processes. We then give our wait-free implementation and prove that it is correct.

4.1 Sequential Specifications of $O_{m,k}$

The $O_{m,k}$ object, for $m, k \geq 2$, has a single operation SUGGEST, which takes a non-negative argument, and has the following specifications, where, for $j \in \{1, ..., k\}$, a_j is the argument of the $(j-1)m+1^{st}$ SUGGEST operation:

- For $j \in \{1, ..., k\}$, the $(j-1)m+1^{st}$ through jm^{th} SUGGEST operations return a_j .
- For $j \in \{1, ..., k-1\}$, the $km + j^{th}$ SUGGEST operation returns a_{k-j} .
- For j > km + k 1, the j^{th} SUGGEST operation returns \perp .

The first km SUGGEST operations performed on an $O_{m,k}$ object are called *prefix operations* and the next k-1 SUGGEST operations are called *suffix operations*. A more intuitive way to visualize the behaviour of SUGGEST is with the string $S_{m,k} = A_1^m A_2^m \dots A_k^m A_{k-1} A_{k-2} \dots A_1$. For $1 \leq j \leq km + k - 1$, if A_g is the j^{th} character in $S_{m,k}$, then the j^{th} SUGGEST operation returns a_g , and we say it *belongs to group g*. For j > km + k - 1, the j^{th} SUGGEST operation returns \bot .

4.2 An incorrect approach

A simple algorithm, due to Faith Ellen, for implementing $O_{m,2}$ from (m+1)-consensus objects and registers for any number of processes is as follows:

- Each time a process p_i performs SUGGEST(v), it first accesses a fetch-and-increment object to receive a distinct value x.
- If x > 2m + 1, then p_i returns \perp .
- If $1 \le x \le m$, then p_i proposes v to an (m+1)-consensus object C_1 . It writes the response to a shared register R_1 before returning it.
- If $m+1 \le x \le 2m$, then p_i proposes v to an (m+1)-consensus object C_2 . It writes the response to a shared register R_2 before returning it.
- If x = 2m + 1, p_i reads R_1 and then R_2 . It returns the first non- \bot value it reads. If both R_1 and R_2 are \bot , this means that all processes that received values at most 2m + 1 from the fetch-and-increment object are concurrent. In this case, p_i proposes v to C_1 , and returns the response.

This algorithm correctly implements an $O_{m,2}$ object from (m+1)-consensus objects registers. For each of the consensus objects C_1 and C_2 , the SUGGEST operation that first proposes a value to the consensus object can be linearized before the rest of the SUGGEST operations that propose to it.

However, this approach does not scale to k > 2. Consider the natural extension of this algorithm to $O_{m,3}$:

- Once again, each time a process p_i performs SUGGEST(v), it first accesses a fetch-and-increment object to receive a distinct value x.
- If x > 3m + 2, then p_i returns \perp .
- If $(j-1)m+1 \le x \le jm$ for $j \in \{1,2,3\}$, then p_i proposes v to an (m+1)-consensus object C_j . It writes the response to a shared register R_j before returning it.
- If $x \in \{3m+1, 3m+2\}$, then p_i will propose to the consensus object associated with some group and return the response.

The problem with the above approach arises from the operations that receive 3m+1 and 3m+2 from the fetch-and-increment object. Firstly, these operations must propose to the consensus objects associated with different groups. This can be achieved as in [1] by using test-and-set objects. The more difficult issue is ensuring linearizability:

Consider an execution in which some process p_i receives 3m+1 from the fetch-and-increment object, reads $R_1=R_2=R_3=\bot$, proposes v to some consensus object C_j , and returns the decision. Next, the m operations that received $(j-1)m+1,\ldots,jm$ from the fetch-and-increment object complete their operations, writing to R_j and returning the decision of C_j . Next, another process p_ℓ begins its SUGGEST operation with an argument that is different from the arguments of all preceding SUGGEST operations and receives 3m+2 from the fetch-and-increment object. Note that since an entire group (of m+1 SUGGEST operations) has returned before p_ℓ began, p_ℓ must be performing a suffix operation when this execution is linearized. In particular, it cannot return the argument of its own SUGGEST operation.

If the other prefix operations have not made any progress (i.e. they have not taken any steps since receiving a value from the fetch-and-increment object), then p_{ℓ} cannot determine any of their arguments, unless it waits for them, which it cannot do. Even if each SUGGEST operation announces its argument before it accesses the fetch-and-increment object, p_{ℓ} does not know which prefix operations belong to the same group as p_i 's operation and, so, cannot determine a value to return.

4.3 A wait-free implementation

The following implementation starts by assigning m prefix operations to each of the k groups, and then assigns the k-1 suffix operations to the first k-1 groups. It ensures that suffix operations can determine and propose the argument of some prefix operation in their group. To do this, we require a stronger synchronization mechanism than a fetch-and-increment object: namely, the Q_1 object.

To implement the $O_{m,k}$ object in a system with any finite number of processes, n, from (m+1)-consensus objects and registers, we use an array $cons[1 \dots k]$ of (m+1)-consensus objects and an array $position[1 \dots km]$ of Q_1 objects. Note that since the Q_1 object can be implemented by 3-consensus objects and registers for any finite number of processes and $m+1 \geq 3$, (m+1)-consensus objects and registers can also implement the Q_1 object for any finite number of processes.

A process p_i performing SUGGEST(v) will perform COMPETE on objects position[1] through position[km] in order, until it wins one of them or loses all km of them.

If p_i is the winner of the Q_1 object position[j], it is performing a prefix operation. It will propose v to the consensus object $cons[\lceil \frac{j}{m} \rceil]$ associated with its group and return its response.

If p_i fails to win any Q_1 object, it is either a suffix operation or it returns \perp . It accesses a fetch-and-increment object count that is initially 1. Note that fetch-and-increment objects

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have a wait-free implementation for any finite number of processes from 2-consensus objects and registers and, consequently, since m+1>2, also from (m+1)-consensus objects and registers. Let x be the response from count that p_i receives. If x>k-1, p_i returns \bot . Otherwise, it is performing the suffix operation associated with group k-x. It performs QUERY on position[(k-x)m] to get the identity i' of some process that performed a prefix operation associated with group k-x. If each process announces the argument of its SUGGEST operation at the beginning of the operation, then p_i could read the value announced by $p_{i'}$, propose this value to cons[k-x], the consensus object associated with its group, and return the response. This ensures that the arguments of prefix operations are the only non- \bot values returned.

There is a slight problem with this approach. Process $p_{i'}$ could have performed another SUGGEST operation afterwards that overwrote the value it announced before winning position[(k-x)m]. Instead, we use an array $A_j[1\dots n]$ of n registers associated with each position[j]. Before performing a COMPETE operation on position[j], each process p_ℓ writes the argument of its current SUGGEST operation to $A_j[\ell]$, provided it has not previously written there. Then process p_i can read $A_{(k-x)m}[i']$ to find the argument of a prefix operation in group k-x.

The code for the implementation is given in Algorithm 3.

Algorithm 3 An implementation of $O_{m,k}$

```
Shared variables:
```

```
cons[1 \dots k] is an array of (m+1)-consensus objects A_j[1 \dots n] is an array of registers initialized to \bot, for j \in \{1, \dots, km\} position[1 \dots km] is an array of Q_1 objects count is a fetch-and-increment object initialized to 1
```

```
s1: function SUGGEST(v) by process p_i
s2:
         for j \leftarrow 1 to km do
            if A_i[i].READ() = \bot then
s3:
                 A_i[i].WRITE(v)
s4:
                 if position[j].COMPETE() then
s5:
                     return cons[\lceil \frac{j}{m} \rceil].PROPOSE(v)
s6:
                 end if
s7:
            end if
s8:
         end for
s9:
         x \leftarrow count.F\&I()
s10:
         if x > k - 1 then
s11:
             return \perp
s12:
s13:
         end if
         group \leftarrow k - x
s14:
         member \leftarrow position[group \times m].QUERY()
s15:
         value \leftarrow A_{group \times m}[member]
s16:
         return cons[group].PROPOSE(value)
s17:
s18: end function
```

4.4 Correctness

We will show that the implementation of an $O_{m,k}$ object given in Algorithm 3 is linearizable. Consider any execution \mathcal{E} of this implementation.

We will say that a SUGGEST operation performs a step σ in the execution if the process performing the operation executes σ during the operation.

A suggest operation S fills the Q_1 object position[j] if it performs the compete operation on position[j] that returns true. In this case, operation S will be ordered as one of the m prefix operations belonging to group $\lceil \frac{j}{m} \rceil$.

If a SUGGEST operation S performs the F&I on line s10, receiving x < k, then S will be ordered as the suffix operation belonging to group k-x.

▶ Lemma 14. When a SUGGEST operation completes iteration j of the for loop on line s2, position[j] is filled.

Proof. Let S be a SUGGEST operation by process p_i that completes iteration j. If, during SUGGEST operation S, p_i reads $A_i[i] = \bot$, then it performs the COMPETE operation on position[j] in line s5 before iteration j completes. If, on the other hand, p_i reads $A_j[i] \neq \bot$ on line s3, then there must have been a SUGGEST operation S' by process p_i that completed before p_i began operation S, in which the COMPETE operation on position[j] in line s5 was executed. In either case, by the time that S completes iteration j, at least one COMPETE operation has been performed on position[j]. The first of these COMPETE operations must have returned true, so position[j] is filled.

From Lemma 14, we get the following important corollaries:

▶ Corollary 15. All SUGGEST operations that perform line s10 can be ordered after all SUGGEST operations that fill some position.

Proof. A SUGGEST operation S that performs line s10 must first perform all km iterations of the for loop on line s2. It follows from Lemma 14 that there is no SUGGEST operation that fills a position and starts after S completes.

▶ Corollary 16. For j < j', a SUGGEST operation that fills position[j] can be ordered before a SUGGEST operation that fills position[j'].

Proof. Consider a SUGGEST operation S that fills position[j] and a SUGGEST operation S' that fills position[j'], with j < j'. To fill position[j'], S' must have first completed iteration j of the for loop in line s2. Thus, by Lemma 14, position[j] was already filled before S' completed. By assumption, position[j] was filled by operation S. Hence, S can be linearized before S'.

 \triangleright Observation 17. If the F&I operation performed on line s10 by SUGGEST operation S returns x, and the F&I operation performed on line s10 by SUGGEST operation S' returns x' > x, then S can be ordered before S'.

We are now able to order the SUGGEST operations in execution \mathcal{E} . In particular, by Corollary 16, the SUGGEST operations that fill $position[\ell]$, for $(j-1)m+1 \le \ell \le jm$, can be ordered as the m prefix operations of group j. Moreover, by Corollary 15 and Observation 17, the SUGGEST operation that receives x < k from the F&I on line s10 can be ordered as the suffix operation of group k-x and any SUGGEST operation that receives x>k-1 from the F&I on line s10 can be ordered after the first km + k - 1 operations.

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All that remains is to order the prefix operations belonging to each group with respect to each other and show that the results of the operations in this ordering are consistent with the specifications of $O_{m,k}$. We first make the following two observations:

- ▶ **Observation 18.** If any SUGGEST operation that belongs to group g returns a value, it returns the decision of cons[g].
- ▶ **Observation 19.** If the suffix operation belonging to group g proposes to cons[g], it proposes the value of the SUGGEST operation that fills position[gm].

In execution \mathcal{E} , if no SUGGEST operation belonging to group g proposed to cons[g], then, by Corollary 16, we can order the prefix operations in order of the indices of the Q_1 objects they fill.

Otherwise, one or more values were proposed to cons[g]. By Observation 19, only the arguments of the prefix operations belonging to group g are proposed to cons[g]. Let v be the value first proposed to (and, hence, decided by) cons[g] and let j be the smallest index, with $(g-1)m+1 \leq j \leq gm$, such that the prefix operation S that fills position[j] has argument v. No prefix operation in group g that fills position[j'], for j' < j, finished before S began, since v is the value first proposed to cons[g]. It follows that we can order every other prefix operation belonging to group g after S, in order of the indices of the Q_1 objects they fill.

By Observations 18 and 19, the results of the SUGGEST operations in this ordering are consistent with the sequential specifications of the $O_{m,k}$ object. Note that the implementation of SUGGEST in Algorithm 3 is wait-free. Thus, we have shown the following theorem:

▶ **Theorem 20.** There is a wait-free implementation of the $O_{m,k}$ object from (m+1)-consensus objects and registers for any $m \geq 2$ and any $k \geq 2$.

5 Conclusions

In this paper, we introduced the Q_r object for $r \geq 0$, showed that it has consensus number r+2, and presented a wait-free implementation of Q_r from (r+2)-consensus objects and registers in a system with any finite number of processes. Using this object, we showed that, for any $m,k\geq 2$, there is a wait-free implementation of $O_{m,k}$ from (m+1)-consensus objects and registers in a system with any finite number of processes. This means that there is an infinite sequence $O_{m,2},O_{m,3},\ldots$ of objects with increasing computational power, all of which have consensus number m and are computationally less powerful than the (m+1)-consensus object. From Rachman's result, we know that for every $m'>m\geq 1$, there exists a nondeterministic object X with consensus number m which cannot be implemented using m'-consensus objects and registers in some system with a finite number of processes. If the same property is true when restricted to deterministic objects, our implementation of $O_{m,k}$ from (m+1)-consensus objects and registers shows that $O_{m,k}$ objects cannot be used to prove this.

The $O_{m,k}$ objects, for $k \geq 2$, are the only known deterministic objects of consensus number m that cannot be implemented in a wait-free manner by m-consensus objects and registers for some finite number of processes. It may be the case that any deterministic object with consensus number m has a wait-free implementation from (m+1)-consensus objects in a system with any finite number of processes. One approach to proving this is to show that, for every object O with consensus number m, there exists $k \geq 2$ such that O is computationally less powerful than $O_{m,k}$. Another interesting question is whether there exists some deterministic object with consensus number m that can implement any

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other deterministic object with consensus number m in a system with any finite number of processes.

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